

Team 17 DVAPAC: Queensland Rail Maintenance and Track Visualisation Study

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Summary

Track Recording Car (TRC) data collected quarterly over 1m intervals by Queensland Rail (QR). This data details **track geometry** and is used to inform **ballast maintenance decisions**. In combination with Ground Penetrating Radar (GPR) and culvert location data, the team used **machine learning** algorithms to predict:

- Track geometry in the next quarter**
- Track maintenance needs in the upcoming quarter(s)**

Data Exploration

TRC data: [1m precision]

- 3 track lines' worth of data over 22 quarters
- 16 measures of track position and geometry
- Combined measure follows Exponentiated Weibull distribution (fig 1.)

GPR data: [5m precision]

- Data for all lines available from 2015 run
- 32 measures of deeper physical track properties

Culvert data: Geospatial drainage information

Work order data: Time and type of maintenance work for 2 track lines. Certain areas are prone to higher work orders (fig 2.)

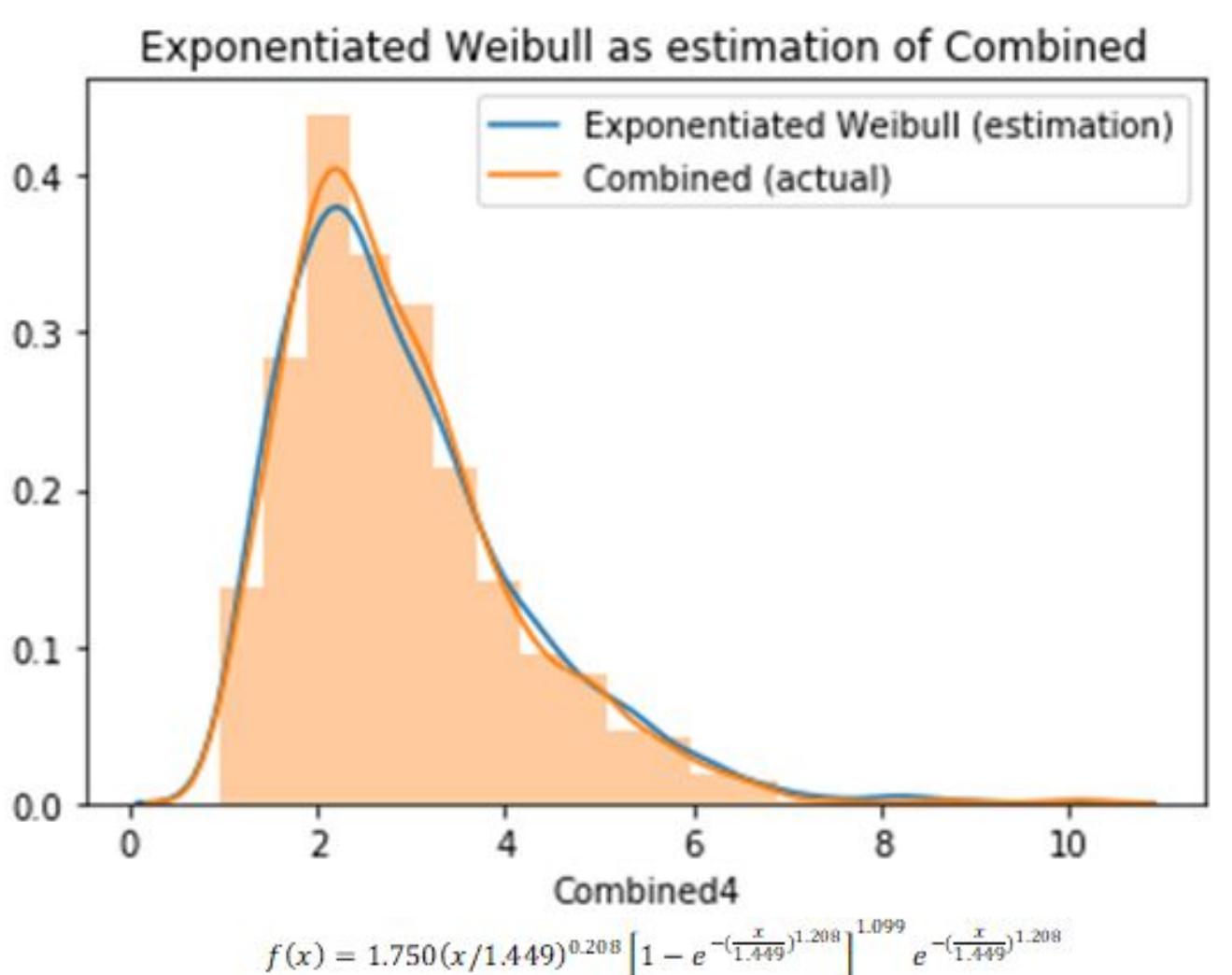


Figure 1. TRC combined measures follow a Weibull distribution

Web App with Interactive Visualisations

- Visualising GPR and TRC data – GPR data in geospatial heatmap, TRC calculated combined metric scrolling heatmap (fig 3)
- ML model predictions - user uploaded TRC data outputs model predictions on upcoming track maintenance, represented in heatmap and geospatial form

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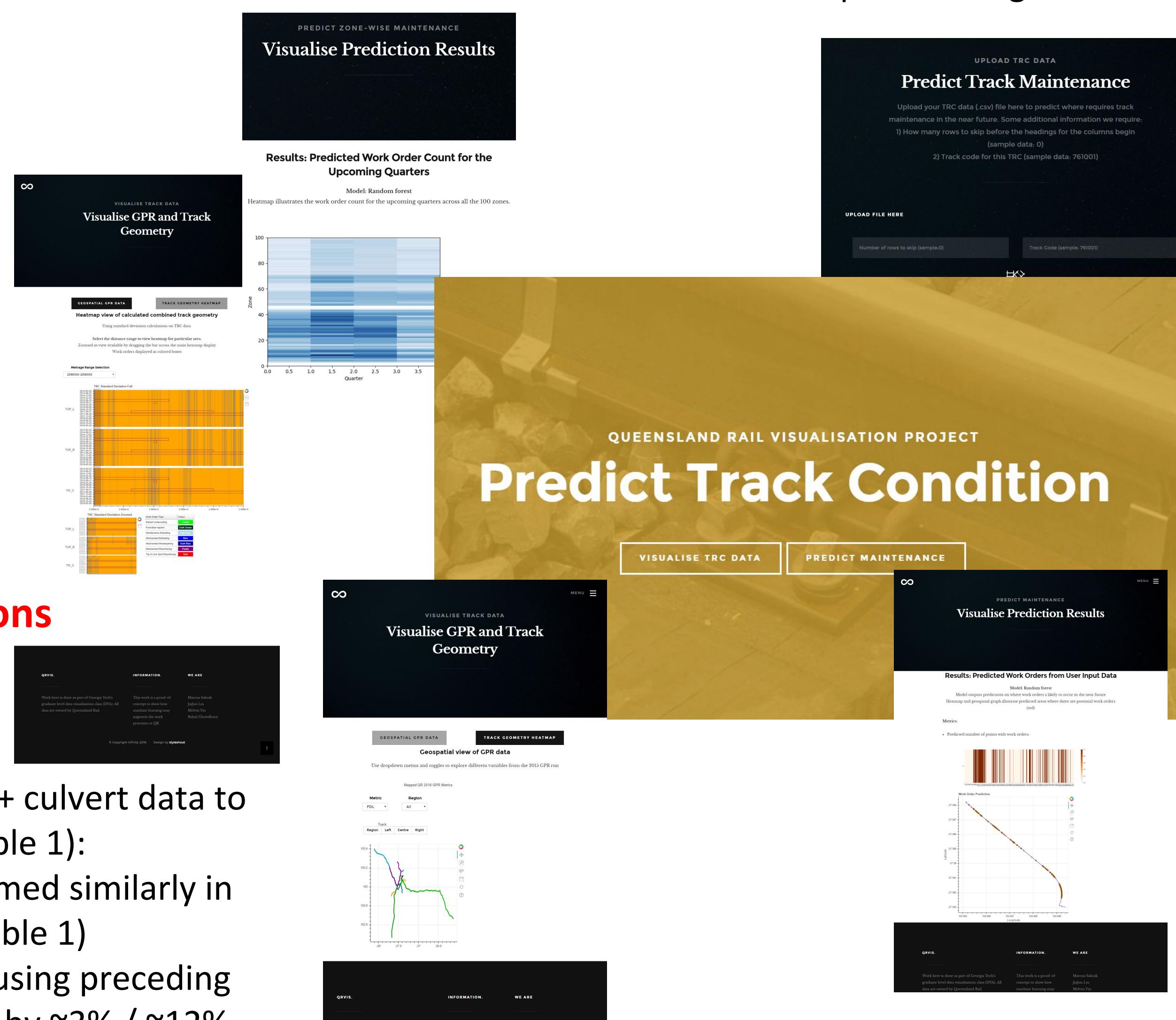


Figure 2. Uneven distribution of work orders over track

Pre-processing data

TRC alignment tool: Fix mis-alignment across time.

- Comparing SUPER and GAUGE across time and minimising deviation for each TRC run

Joining datasets for analysis:

- Data joins performed using pandas library
- Track codes, distance measures used for joining across datasets

Missing values Imputation:

- Missing values were imputed with either '0' or with surrounding values

Binning data into zones and quarters: High speed data aggregation using parallel processing to handle huge quantity of data

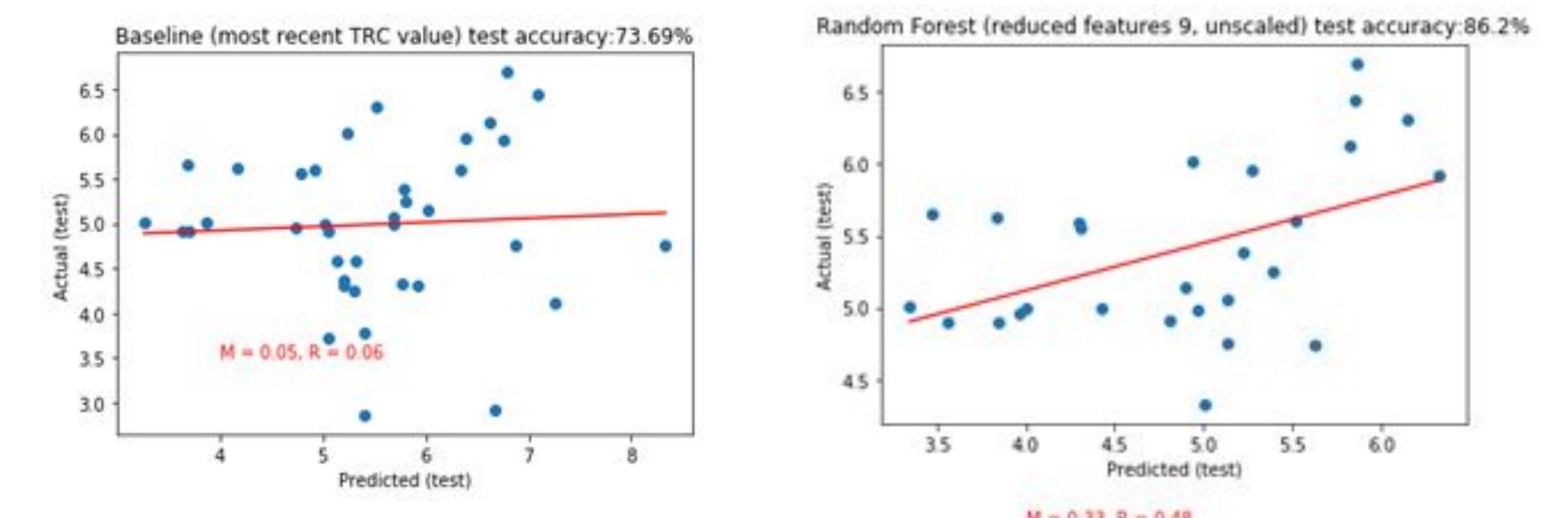


Figure 4. Predicting "high priority" points track geometry 1-quarter ahead. Random Forest (86.2% accuracy) outperformed baseline model which projected the preceding quarter response variable (73.69%).

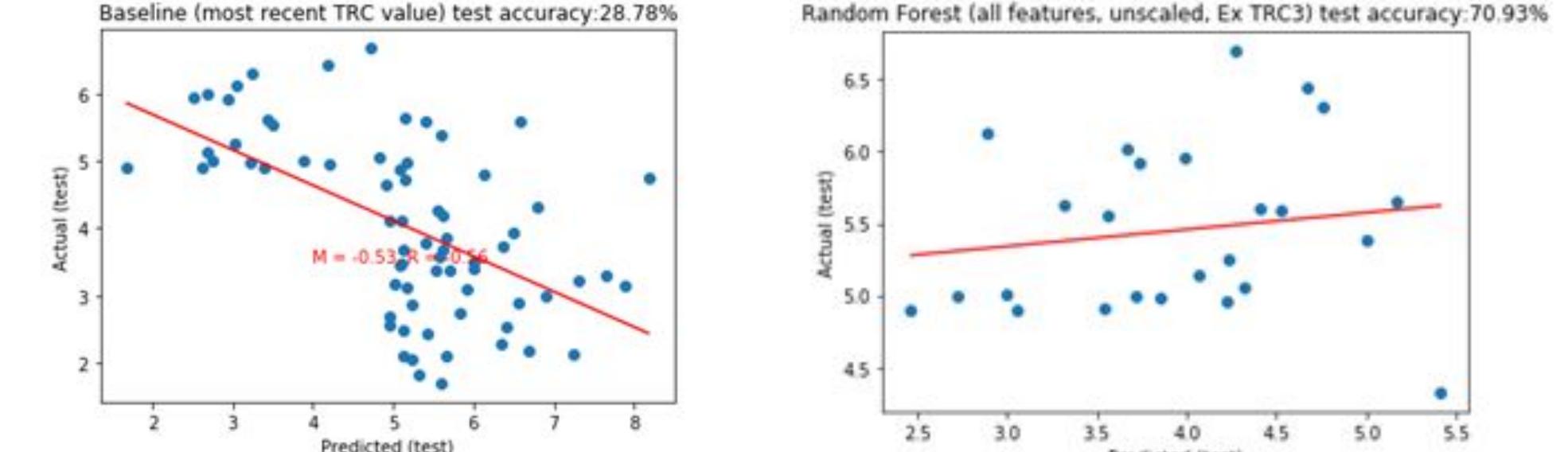


Figure 5. Predicting "high priority" track geometry points 2-quarters ahead. Baseline model unable to predict 2 quarters ahead (28.78% accuracy) vs. Random Forest (70.93% accuracy)

| Model | Best Test Accuracy | Gradient of best-fit | Best test Accuracy "high priority" | Best Correlation "high priority" |
|----------------------------|--------------------|----------------------|------------------------------------|----------------------------------|
| Baseline | 80.92% | 0.77 | 73.69% | 0.06 |
| Random Forest (9 features) | 84.35% | 0.99 | 86.2% | 0.48 |
| SVR (20 features, scaled) | 85.14% | 0.9 | 85.25% | 0.2 |
| KNN (9 features, scaled) | 82.21% | 1.02 | 81.64% | 0.23 |
| ANN (20 features, scaled) | 85.88% | 0.94 | 85.54% | 0.34 |

Figure 3. Equation of a combined measure representing changes in track geometry, most attributed to ballast condition.

Table 1. Summary of ML results for predicting future track geometry 1 quarter ahead

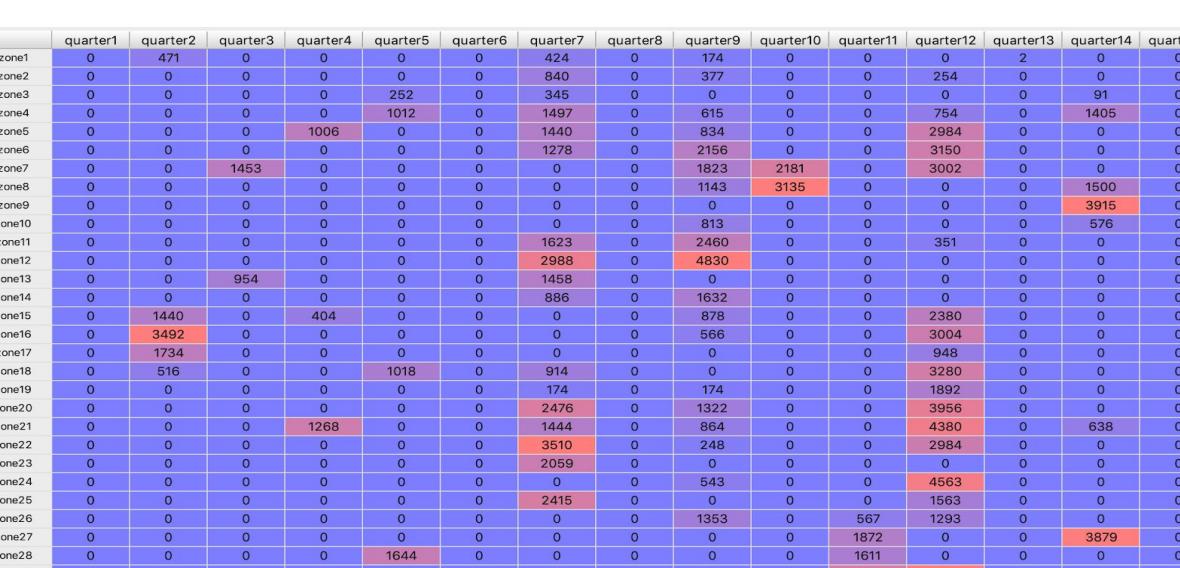


Figure 6. Maintenance work orders are binned into 100 zones and visualised as a heatmap. Some zones and quarters are more heavily maintained than others.

| Model | Accuracy (bal.) | F1 Score (bal.) | Accuracy (unbal.) | F1 Score (unbal.) |
|----------------------|-----------------|-----------------|-------------------|-------------------|
| Logistic Regression | 57.4% | 0.61 | NA | NA |
| SVM | 80.6% | 0.38 | NA | NA |
| Random Forest (base) | 87.6% | 0.44 | 65.3% | 0.37 |
| Random Forest + CV | 89.5% | 0.40 | 71.87% | 0.80 |

Table 2. Summary of ML result for predicting upcoming maintenance work. Random Forest performed the best in test accuracy with balanced class data, but suffered decrease in accuracy with unbalanced (raw) TRC data

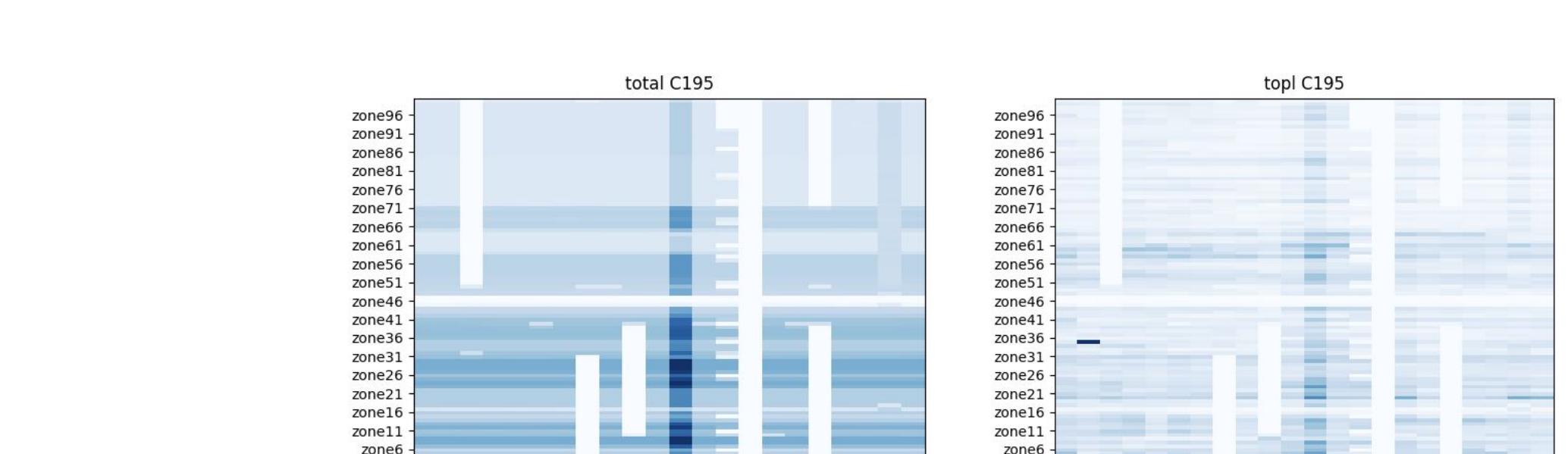


Figure 7. High correlation between work orders and track geometry indicates that maintenance carried out is effective and has immediate impact.

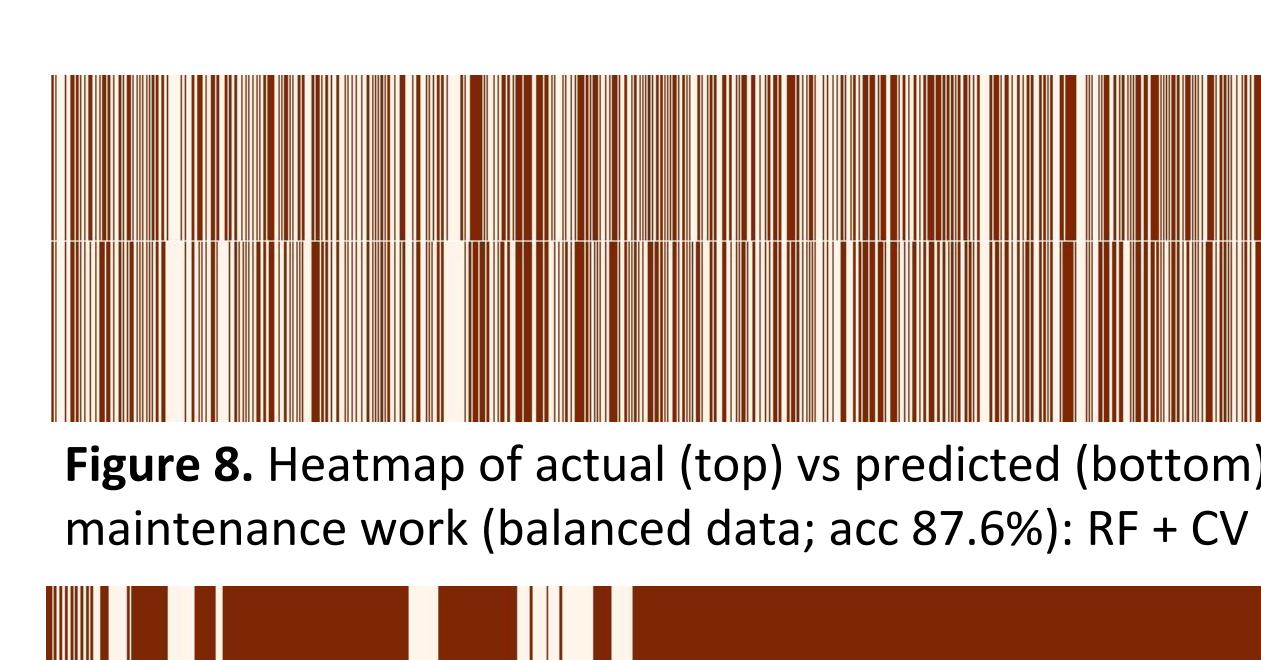


Figure 8. Heatmap of actual (top) vs predicted (bottom) maintenance work (balanced data; acc 87.6%): RF + CV



Figure 9. Heatmap of actual (top) vs predicted (bottom) maintenance work (unbalanced data; acc 72.6%) from C138 run in 2015-05-15: RF + CV model

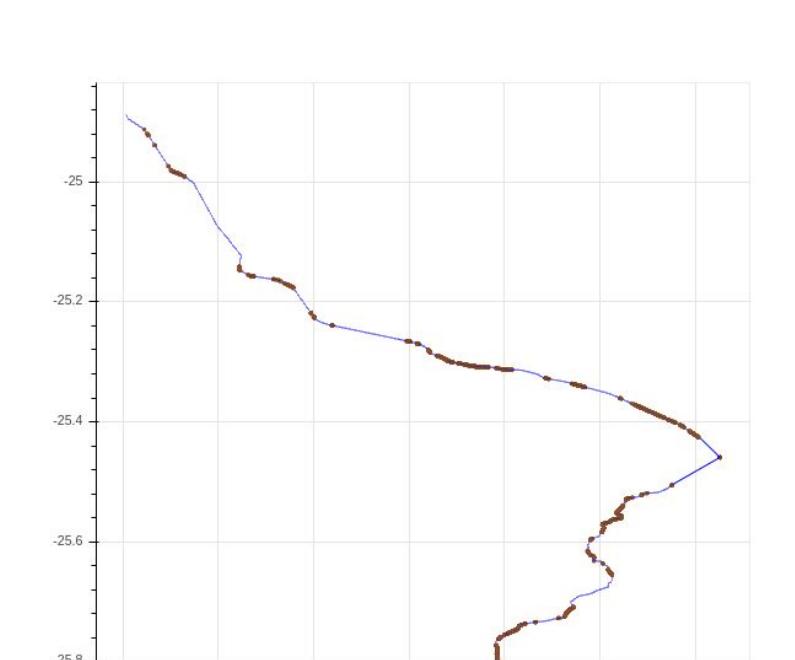


Figure 10. Geospatial visualisation of prediction output used in web app, generated in bokeh.

- Predict track maintenance through patterns in work orders
 - Location of work orders binned into 100 zones (fig 6)
- Predict presence of track maintenance each quarter using GPR + TRC data (fig 8,9).
 - Data was downsampled to balance classes
 - Random Forest displayed best test performance (table 2)
 - Accuracy reduction when using non-balanced data (whole TRC runs) indicating high variation within negative class not captured by model
- Zone-wise aggregation of quarterly work order count gave rise to patterns with high correlation to track geometry (fig 7).
 - Possible to identify troublesome zones, and predict for upcoming quarters.