

Course Code: EEE 4101
Course Title: Electrical Engineering

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Ref. Book: Fundamental of Electrical Circuit: Alexander Sadiku

Sinusoids

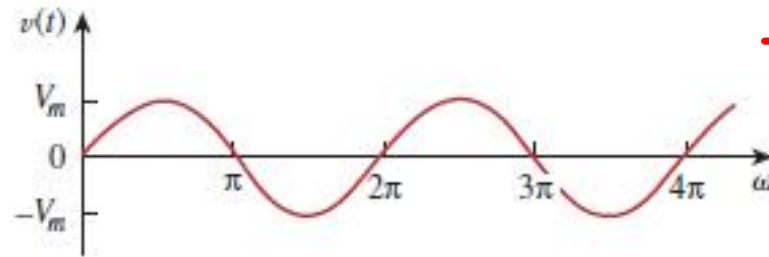
A sinusoid is a signal that has the form of the sine or cosine function.

- A sinusoidal current is usually referred to as alternating current (ac).
- Such a current reverses at regular time intervals and has alternately positive and negative values.
- Circuits driven by sinusoidal current or voltage sources are called ac circuits.

Consider the sinusoidal voltage $v(t) = v_m \sin \omega t$ [V]

where

- V_m = the *amplitude* of the sinusoid [V]
- ω = Angular frequency of the sinusoid [rad s⁻¹]
- ! ωt = the argument of the sinusoid



$$\omega = 2\pi f = \frac{2\pi}{T}$$
$$= \frac{2\pi N}{t}$$
$$f = \frac{1}{T}$$

* The argument of a function is the “input” to the function. In the case of $\sin(x)$ consider this: $f(x) = \sin(x)$ x is the argument.

Sinusoids

Let us now consider a more general expression for the sinusoid,



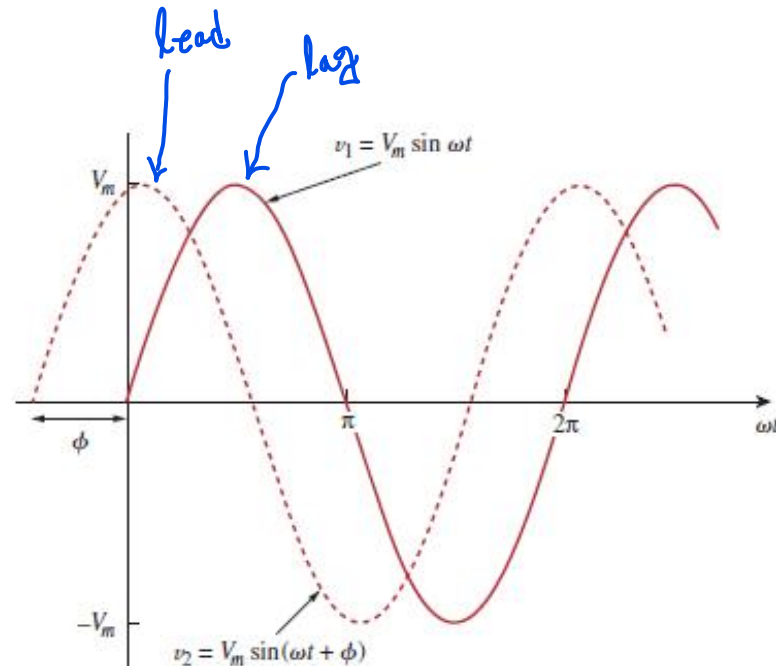
$$v(t) = v_m \sin(\omega t + \phi)$$

$$\text{or, } v(t) = v_m \cos(\omega t + \phi)$$

Where $(\omega t + \phi)$ is the argument and ϕ is the phase. Both argument and phase can be in radians or degrees.

Let us examine the two sinusoids,

$$v_1(t) = v_m \sin \omega t \text{ and } v_2(t) = v_m \sin(\omega t + \phi)$$



Sinusoids and Phasors

Q. Find the amplitude, phase, period, and frequency of the sinusoid $v(t) = 12 \cos(50t + 10^\circ)$

V_m

ϕ

$T = \frac{1}{f}$

$= \frac{\pi}{25} \text{ s}$

f

V_m

$\omega = 2\pi f$

ϕ

$f = \frac{25}{\pi} \text{ Hz}$

Q. Calculate the phase angle between $v_1 = -10 \cos(\omega t + 50^\circ)$ and $v_2 = 12 \sin(\omega t - 10^\circ)$.

State which sinusoid is leading.

$= 10 \cos(\omega t + 50^\circ - 180^\circ)$
 $= 10 \cos(\omega t - 130^\circ)$

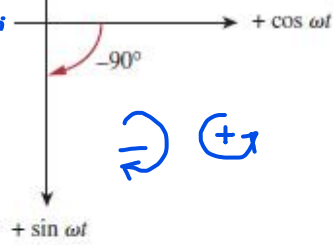
$\phi_{v_2} > \phi_{v_1} \therefore v_2 \text{ leads}$

$= 12 \cos(\omega t - 10^\circ - 90^\circ) = 12 \cos(\omega t - 100^\circ)$

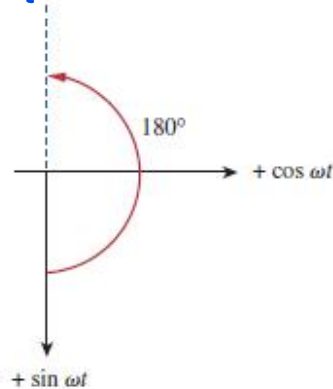
bring both of them to (+)cos while rotating in the same direction

phase $= \phi_{v_1} - \phi_{v_2} = -130^\circ - (-100^\circ) = -30^\circ$
 $[(-)(v_1 - v_2) \rightarrow v_2 \text{ leads } v_1 \text{ by } \phi^\circ$
 $(+)(v_1 - v_2) \rightarrow v_1 \text{ leads } v_2 \text{ by } \phi^\circ$

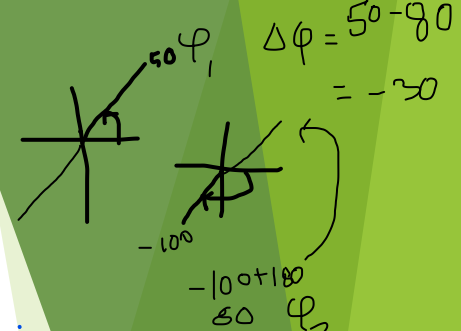
$\phi_{v_1} - \phi_{v_2} < 0 \therefore \phi_{v_1} < \phi_{v_2}$



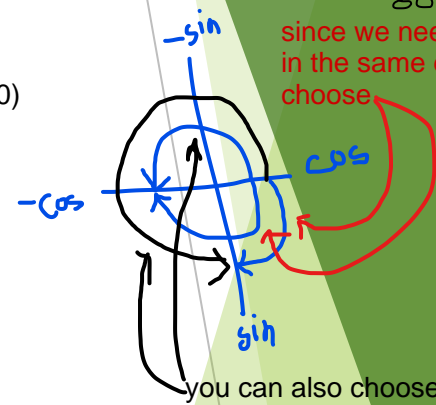
(a)



(b)



since we need to rotate both in the same direction, \therefore choose



you can also choose

Phasors

A phasor is a complex number that represents the amplitude and phase of a sinusoid.

$$j = \sqrt{-1}$$

A complex number z can be written in rectangular form as $z = x + jy$

The complex number z can also be written in polar or exponential form as $z = r\angle\phi = re^{j\phi}$

where r is the magnitude of z , and ϕ is the phase of z . We notice that z can be represented in three ways:

$$z = x + jy \quad \text{Rectangular form} \quad /$$

$$z = r\angle\phi \quad \text{Polar form} \quad /$$

$$z = re^{j\phi} \quad \text{Exponential form} \quad /$$

$$r = \sqrt{x^2 + y^2}, \quad \phi = \tan^{-1} \frac{y}{x}$$

$$x = r \cos \phi, \quad y = r \sin \phi$$

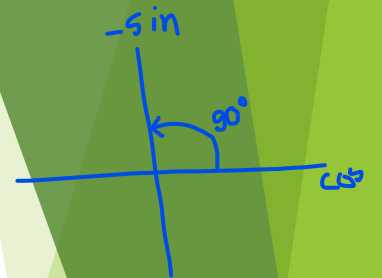
$$z = x + jy = r\angle\phi = r(\cos \phi + j \sin \phi)$$

Phasors

$\underline{v} = V_m \cos(\omega t + \underline{\varphi})$ V the phasor form of this sinusoids is $\underline{V} = V_m \angle \underline{\varphi}$ A. ✓

$\underline{i} = I_m \cos(\omega t + \underline{\varphi})$ A the phasor form of this sinusoids is $\underline{I} = I_m \angle \underline{\varphi}$ A.

✓ Q. Express these sinusoids as phasors: (a) $v = 7 \cos(2t + 40^\circ)$ V, (b) $i = -4 \sin(10t + 10^\circ)$
 $\underline{V} = 7 \angle 40^\circ$ V
 $\underline{I} = 4 \angle 100^\circ$



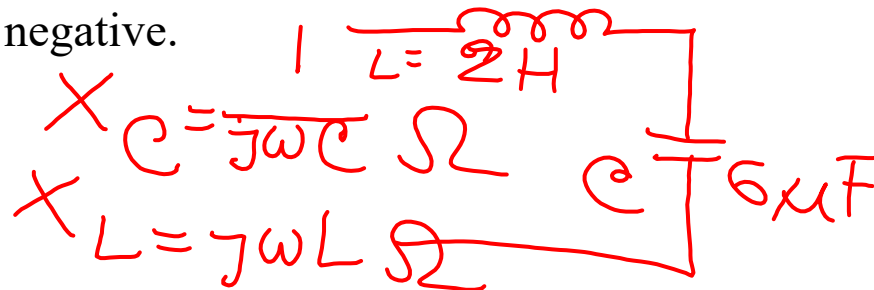
Impedance

The **impedance** Z of a circuit is the ratio of the phasor voltage V to the phasor current I , measured in ohms (Ω).

$$Z = \frac{V}{I} \quad \text{or} \quad V = ZI$$

As a complex quantity, the impedance may be expressed in rectangular form as $Z = R + jX$

where $R = \text{Re } Z$ is the *resistance* and $X = \text{Im } Z$ is the *reactance*. The reactance X may be positive or negative. We say that the impedance is inductive when X is positive or capacitive when X is negative.

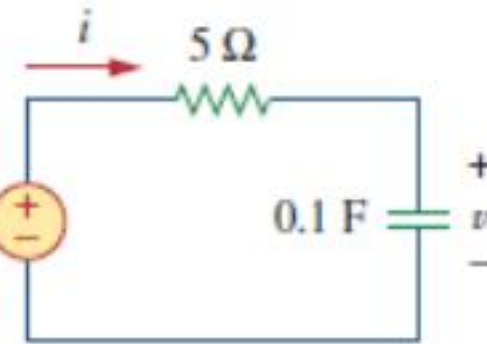


Impedances and admittances of passive elements.

Element	Impedance	Admittance
R	$Z = R$	$Y = \frac{1}{R}$
L	$Z = j\omega L$	$Y = \frac{1}{j\omega L}$
C	$Z = \frac{1}{j\omega C}$	$Y = j\omega C$

Impedance

Q. Find $i(t)$ and $v(t)$ in the circuit shown in the figure.



$$V_s = V_m \cos(\omega t + \phi)$$

\downarrow \downarrow \downarrow
 10 4 rad/s 0°

$$V = IZ$$

$$= I(R + jX)$$

$$= I(R + j(X_L - X_C))$$

$$X_L = j\omega L \Omega$$

$$X_C = \frac{1}{j\omega C} \Omega$$

$$= \frac{1}{-j\omega C}$$

$$= \frac{1}{\omega C} \angle -90^\circ$$

$$j = \angle 90^\circ = -j(\omega C)^{-1}$$

$$I = \frac{V_s}{Z}$$

$$= \frac{10 \angle 0^\circ}{5 - j25}$$

$$= 1.6 + j0.8$$

$$= 1.78 \angle 26.56^\circ \text{ A}$$

time domain signal

$$V_s = 10 \angle 0^\circ \text{ V}$$

$V =$

$$V = V_m \cos(\omega t + \phi)$$

$$I = 1.78 \angle 26.56^\circ \text{ A}$$

$$= 1.78 \cos(4t + 26.56^\circ)$$

$$V = I X_C$$

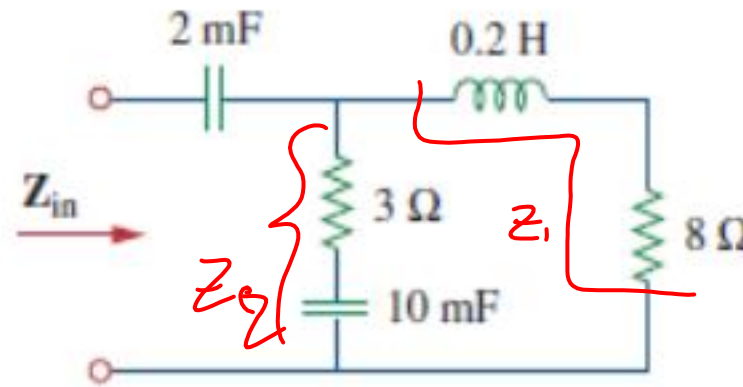
$$= \frac{I}{j\omega C}$$

$$= \frac{1.78 \angle 26.56^\circ}{j40}$$

$$= -j2.5 \times 10^{-2} \text{ V}$$

Impedance

Q. Find the input impedance of the circuit in the Fig. Assume that the circuit operate at $\omega = 50$ rad/s.



$$Z_1 = 8 + j\omega L$$

$$= (8 + j10) \Omega$$

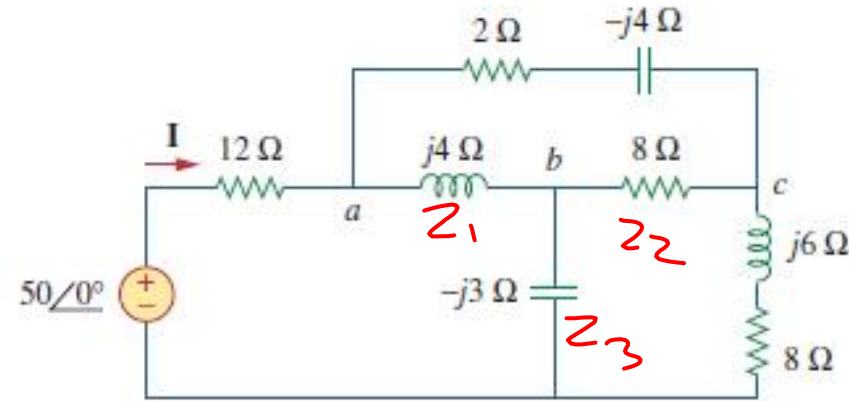
$$Z_2 = 3 + \frac{1}{j\omega C}$$

$$Z_2 = \frac{3 - j20}{j\omega \times 2 \times 10^{-3}} = -j0.1$$

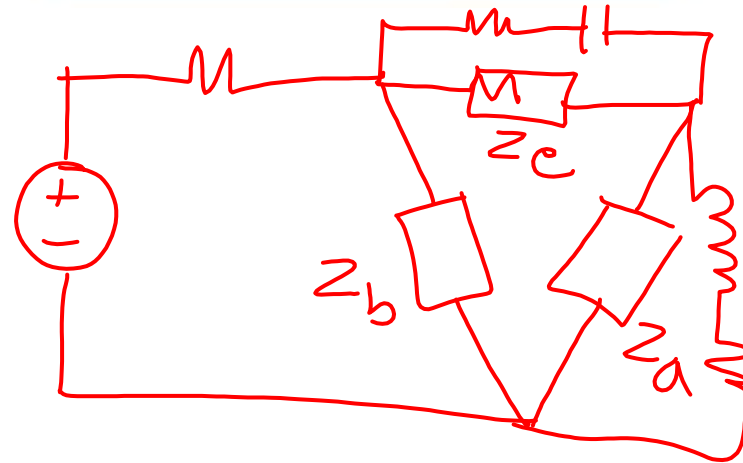
$$Z_{in} = Z_3 + (Z_1 || Z_2)$$

Impedance

Q. Find current I in the circuit of the Fig.



$$Z_a = \frac{Z_1 Z_2 + Z_2 Z_3 + Z_3 Z_1}{Z_1}$$



Thank You