Practice 5. Introduction to using MPLAB X IDE

Objectives

The student will become familiar with the MPLAB integrated development environment tools. The student will create his (her) first program using the MPLAB software and will put it into the PIC microcontroller making use of the Curiosity development/evaluation board.

Introduction

Microcontrollers are all around he world. Each day, Microcontrollers, are more present in the many aspects of our lives: in our work, inside our houses, and in more. We can find them controlling small devices like cellphones, microwaves, washing machines, and televisions.

A microcontroller is one device or chip that is used to govern one or more processes. For example, the controller that regulates the room temperature of an air conditioner; it has a sensor that continuously measures the internal temperature and, when the preset limits are exceeded, it generates the necessary signals to adjust the temperature

Results

Image of the successful build:

```
make -f nbproject/Makefile-default.mk SUBPROJECTS= .build-conf
make[1]: Entering directory 'C:/Users/SAGARPA/MPLABXProjects/Ptr6.X'
make -f nbproject/Makefile-default.mk dist/default/debug/Ptr6.X.debug.elf
make[2]: Entering directory 'C:/Users/SAGARPA/MPLABXProjects/Ptr6.X'
make[2]: 'dist/default/debug/Ptr6.X.debug.elf' is up to date.
make[2]: Leaving directory 'C:/Users/SAGARPA/MPLABXProjects/Ptr6.X'
make[1]: Leaving directory 'C:/Users/SAGARPA/MPLABXProjects/Ptr6.X'

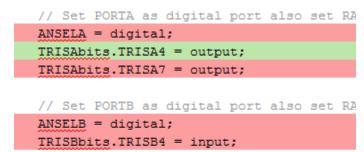
BUILD SUCCESSFUL (total time: 456ms)
Symbols unmodified. Previously loaded from C:/Users/SAGARPA/MPLABXProjects/Ptr6.X/dist/default/debug/Ptr6.X.debug.elf...
Loading code from C:/Users/SAGARPA/MPLABXProjects/Ptr6.X/dist/default/debug/Ptr6.X.debug.elf...
Loading completed
```

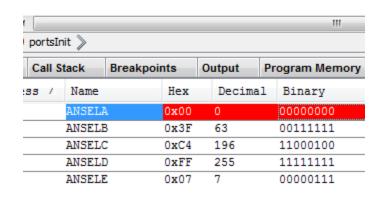
Image of Ports registers initialization:

```
// Set PORTA as digital port also
ANSELA = digital;
TRISAbits.TRISA4 = output;
TRISAbits.TRISA7 = output;

// Set PORTB as digital port also
ANSELB = digital;
TRISBbits.TRISB4 = input;
```

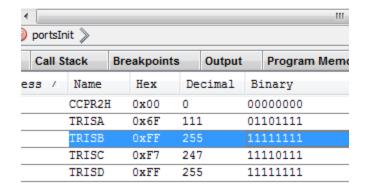
② portsInit ≫										
Call Stack			Breakpoints			Output		Progran		
iress	3 A	Name		Hex	De	cimal	Bi	nary		
1		ANSELA	1	0 x 2F	47		00	101111		
		ANSELE		0 x 3F	63		00	111111		
		ANSELO	:	0xC4	196		11	000100		
		ANSELI		0xFF	255		11	111111		
		ANSELE		0x07	7		00	000111		





```
ANSELA = digital;
TRISAbits.TRISA4 = output;
TRISAbits.TRISA7 = output;

// Set PORTB as digital port also set
ANSELB = digital;
TRISBbits.TRISB4 = input;
```

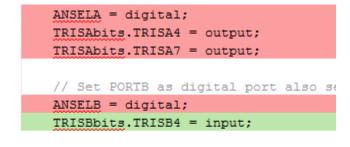


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		= digi							
TRISAbits.TRISA4 = output;									
TRI	SAbi	its.TR	ISA'	7 = outpi	ıt;				
//	Set	PORTB	as	digital	port	also	set	1	
		= digi		l; 4 = input	t;				

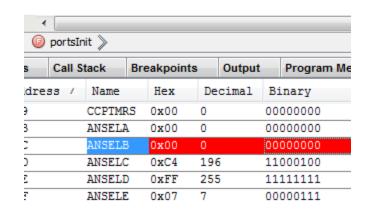
portsInit >									
Call Stack		Breakpoints		Output		Program Memor			
ess /	Name		Hex	Decim		1	Binary		
	CCPR2H				0		00000000		
	TRISA		0xEF		239		11101111		
	TRISB				255		11111111		
	TRISC				247		11110111		
	TRISD		0xFF		255		11111111		

```
// Set PORTA as digital port also
ANSELA = digital;
TRISAbits.TRISA4 = output;
TRISAbits.TRISA7 = output;

// Set PORTB as digital port also
ANSELB = digital;
TRISBbits.TRISB4 = input;
}
```



Call Stack Breakpoints Output Progran ress / Name Hex Decimal Binary CTMUCONH 0x00 00000000 CCPR2 0x0000 0 00000000 0x0000000000 CCPR2L CCPR2H 0x00 0 00000000 0x6F 111 01101111 TRISB 0xFF 255 11111111



Link of demonstration: https://youtu.be/dra_E4VN1-w

Conclusion:

With this practice it is clarifies the way to use the debug and the SFR memory view to track how the program variables are changing and registers being modified, which despite of the simplicity of this exercise lead to the use of an indispensable tool for programming the micron roller, because it is easier to see directly how the code behaves than trying to find a bug or mistake by reading the code, compiling and executing it to remember the differences between each run after.

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