

ArducAM Working with Raspberry Pi

Configure the network

- 1、Scan the available WIFI connection

Run command: `sudo iwlist wlan0 scan`

result:

```
wlan0      Scan completed :
           Cell 01 - Address: 78:A1:06:FF:7F:96
                   ESSID:"JL_network"
                   Protocol:IEEE 802.11bgn
                   Mode:Master
                   Frequency:2.412 GHz (Channel 1)
                   Encryption key:on
                   Bit Rates:300 Mb/s
```

.....

- 2、Configure wpa-supPLICANT.conf :

Run command: `sudo nano /etc/wpa_supplicant/wpa_supplicant.conf`

input:

```
country=GB
ctrl_interface=DIR=/var/run/wpa_supplicant GROUP=netdev
update_config=1
network={
    ssid="JL_network" //put your ssid
    psk="00180605"    //put your password
}
```

- 3、Ctrl +X then Y, then finally press Enter to save the file
- 4、At this point, wpa-supPLICANT will normally notice a change has occurred within a few seconds, and it will try and connect to the network. If it does not, either manually restart the interface with `sudo ifdown wlan0` and `sudo ifup wlan0`, or reboot your Raspberry Pi with `sudo reboot`.
- 5、Test the wifi connection

Run command ping 8.8.8.8

result:

```
64 bytes from 8.8.8.8: icmp_seq=4 ttl=45 time=58.4 ms
64 bytes from 8.8.8.8: icmp_seq=10 ttl=45 time=58.2 ms
64 bytes from 8.8.8.8: icmp_seq=13 ttl=45 time=65.1 ms
64 bytes from 8.8.8.8: icmp_seq=14 ttl=45 time=62.0 ms
.....
```

Download the code library and compile

- 1、Make a working directory

Run command: `sudo mkdir /home/test`

Run command: `cd /home/test`

- 2、Download the library

Run command:

`sudo git clone https://github.com/arducam/raspberrypi.git`

3、Compile the library

Run command: `cd raspberry/ArduCAM4Pi/`

Run command: `sudo make`

There will be the following error message:

```
gcc      -o      ov2640_playback      default_fonts_spi.o      utft_spi.o      arducam.o
arducam_arch_raspberrypi.o arducam_ov2
640_playback.o -lwiringPi -Wall
arducam_arch_raspberrypi.o: In function `arducam_i2c_word_write':
arducam_arch_raspberrypi.c:(.text+0x384):      undefined      reference      to
`i2c_smbus_write_word_data'
arducam_arch_raspberrypi.o: In function `arducam_i2c_word_read':
arducam_arch_raspberrypi.c:(.text+0x400):      undefined      reference      to
`i2c_smbus_write_byte_data'
arducam_arch_raspberrypi.c:(.text+0x428):      undefined      reference      to
`i2c_smbus_read_byte'
collect2: error: ld returned 1 exit status
Makefile:6: recipe for target 'ov2640_playback' failed
make: *** [ov2640_playback] Error 1
```

solution:

run commands below:

sudo apt-get install wiringpi

sudo apt-get install i2c-tools

sudo apt-get install libi2c-dev

sudo apt-get install python-smbus

sudo make clean

sudo make

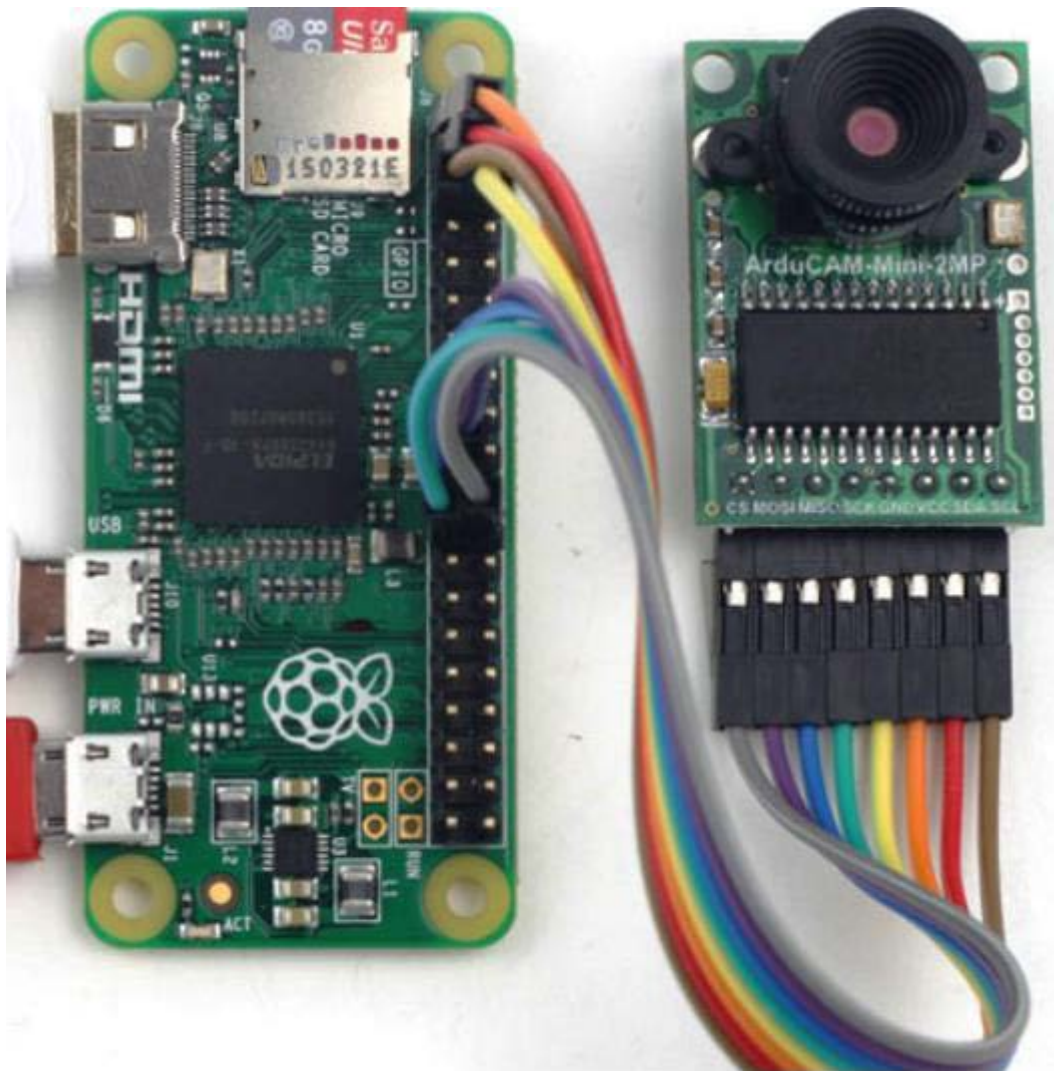
4、Hardware connection

| Pin connection between ArduCAM and Raspberry pi | | | | | | | | |
|---|----|------|------|-----|-----|----|-----|-----|
| Raspberry | 24 | 19 | 21 | 23 | 6 | 1 | 3 | 5 |
| ArduCAM-Mini | CS | MOSI | MISO | SCK | GND | 5V | SDA | SCL |



Raspberry Pinout

| | | | |
|----------------|----|----|---------------|
| 3v3 Power | 1 | 2 | 5v Power |
| BCM 2 (SDA) | 3 | 4 | 5v Power |
| BCM 3 (SCL) | 5 | 6 | Ground |
| BCM 4 (GPICLK) | 7 | 8 | BCM 14 (TXD) |
| Ground | 9 | 10 | BCM 15 (RXD) |
| BCM 17 | 11 | 12 | BCM 18 (PWM0) |
| BCM 27 | 13 | 14 | Ground |
| BCM 22 | 15 | 16 | BCM 23 |
| 3v3 Power | 17 | 18 | BCM 24 |
| BCM 10 (MOSI) | 19 | 20 | Ground |
| BCM 9 (MISO) | 21 | 22 | BCM 25 |
| BCM 11 (SCLK) | 23 | 24 | BCM 8 (CEO) |
| Ground | 25 | 26 | BCM 7 (CE1) |
| BCM 0 (ID_SD) | 27 | 28 | BCM 1 (ID_SC) |
| BCM 5 | 29 | 30 | Ground |
| BCM 6 | 31 | 32 | BCM 12 (PWM0) |
| BCM 13 (PWM1) | 33 | 34 | Ground |
| BCM 19 (MISO) | 35 | 36 | BCM 16 |
| BCM 26 | 37 | 38 | BCM 20 (MOSI) |
| Ground | 39 | 40 | BCM 21 (SCLK) |



5、 Using examples

Make sure the I2C and SPI is enabled before run any command.

sudo nano /boot/config.txt

打开 SPI

#-----

dtparam=i2c_arm=on

dtparam=spi=on

#-----

Reboot is required

Run command to take a picture from one camera:

sudo ./ov2640_capture -c test.jpg 320x240

Run command to take a picture from 4 cameras:

sudo ./ov2640_4cams_capture -c test1.jpg test2.jpg test3.jpg test4.jpg 320x240