

---

**Algorithm 1 MLE.m** : Finds the minimum of  $g(V, F) = -\log P(V, F|\text{data})$  by the method of preconditioned conjugate gradients. The arguments of  $g(V, F)$  at the minimum give the maximum likelihood estimates for the parameters in our model. The minimization constraints the values of  $F(0)$  and  $F(1)$  to be 0 so that the co-variance matrix is non-singular and there is a well defined Gaussian asymptotic limit for the distribution of estimators

---

**Require:**  $\text{root} \in \mathbb{R}^{B+M+1}$  or  $\text{root} = \text{"random"}$ ,  $\alpha_{\text{root}} \in \mathbb{R}^+$ ,  $\text{counts} \in \mathcal{M}_{T \times B}(\{0, 1, \dots, M\})$ ,  $\text{gauge} \in \{0, 1\}$  and  $\tau \in \mathbb{R}^+$  (de-correlation time)

**Ensure:**  $B, M, T \in \mathbb{N}^+$

$h \leftarrow \mathcal{M}_{B \times (M+1)}(\{0\})$

**for**  $n = 0$  to  $M$  **do**

**for**  $b = 0$  to  $B - 1$  **do**

**for**  $t = 0$  to  $T - 1$  **do**

**if**  $(\text{counts})_{t,b} = n$  **then**

$(h)_{b,n} = (h)_{b,n} + (\text{counts})_{t,b} / T$

**end if**

**end for**

**end for**

**end for**

$N \leftarrow \{0, 1, \dots, M\}$

**if**  $\text{root} = \text{"random"}$  **then**

$\vec{x}_0 \leftarrow \vec{x}_{\text{rand}} \{ \vec{x}_{\text{rand}} \in \mathbb{R}^{B+M+1} : \text{entries are random samples uniformly distributed in the interval } [0, 1] \}$

**else**

$\vec{x}_0 \leftarrow \text{root}$

**end if**

$(\vec{x}_0)_0 \leftarrow 0$  {fixing the gauge to avoid singularity in the covariance matrix}

$(\vec{x}_0)_1 \leftarrow 0$  {fixing the gauge to avoid singularity in the covariance matrix}

$\vec{\Delta}_0 \leftarrow -\vec{\nabla} g(\vec{x}_0)$  { See Algorithm 2 **logligrad.m**}

$\vec{s}_0 \leftarrow \vec{\Delta}_0$  { initial conjugate direction}

$\alpha_0 \leftarrow \arg \min_{\alpha} g(\vec{x}_0 + \alpha \vec{s}_0)$  { See Algorithm 3 **linemin.m**}

$\vec{x}_1 = \vec{x}_0 + \alpha_0 \vec{\Delta}_0$

$\epsilon \leftarrow 10^{-7}$

$m \leftarrow 0$

**while**  $\|\vec{x}_m - \vec{x}_{m-1}\| / (M + B + 1) \geq \epsilon$  **do**

$m \leftarrow m + 1$

$\vec{\Delta}_m \leftarrow -\vec{\nabla} g(\vec{x}_m)$

$\beta_m \leftarrow \|\vec{\Delta}_m\|^2 / \|\vec{\Delta}_{m-1}\|^2$  { Using the Fletcher-Reeves scaling factor}

$\vec{s}_m \leftarrow \vec{\Delta}_m + \beta_m \vec{s}_{m-1}$

$\alpha_m \leftarrow \arg \min_{\alpha} g(\vec{x}_m + \alpha \vec{s}_m)$  { See Algorithm 3 **linemin.m**}

$\vec{x}_{m+1} \leftarrow \vec{x}_m + \alpha_m \vec{s}_m$

$(\vec{x}_m)_0 \leftarrow 0$  {fixing the gauge to avoid singularity in the covariance matrix}

$(\vec{x}_m)_1 \leftarrow 0$  {fixing the gauge to avoid singularity in the covariance matrix}

**end while**

---

---

```

if gauge==0 then
     $\vec{F}^* \leftarrow (\vec{x}_m)_{0 \dots M}$  {unpacking the ML values of frustration}
     $\vec{V}^* \leftarrow (\vec{x}_m)_{M+1 \dots M+B}$  {unpacking the ML values of vexation}
     $\Sigma \leftarrow \mathbf{Cov}(\vec{F}^*, \vec{V}^*)$  { See Algorithm 4 getCovMat.m, outcome depends}
else
     $\vec{F}^* \leftarrow (\vec{x}_m)_{0 \dots M} + \frac{N}{B} \sum_{j=M+1}^{M+B} ((\vec{x}_m))_j$  {unpacking the ML values of frustration and performing gauge transf.}
     $\vec{V}^* \leftarrow (\vec{x}_m)_{M+1 \dots M+B} - \frac{1}{B} \sum_{j=M+1}^{M+B} ((\vec{x}_m))_j$  {unpacking the ML values of vexation and performing gauge transf.}
     $\Sigma \leftarrow \mathbf{Cov}(\vec{F}^*, \vec{V}^*)$  { See Algorithm 4 getCovMat.m, outcome depends}
end if
 $\sigma \vec{F}^* \leftarrow (\text{diag}(\Sigma))_{0 \dots M}$  {unpacking the ML uncertainties on frustration}
 $\sigma \vec{V}^* \leftarrow (\text{diag}(\Sigma))_{M+1 \dots M+B}$  {unpacking the ML uncertainties on vexation}
return  $\vec{F}^*, \vec{V}^*, \Sigma, \sigma \vec{F}^*, \sigma \vec{V}^*$ 

```

---



---

**Algorithm 2 logligrad.m** :Calculates the gradient of the likelihood function for our specific model from the analytical formula at the value of the parameters being passed as input with a give set of data

---

**Require:**  $\vec{x}_n \in \mathbb{R}^{B+M+1}$ ,  $h \in \mathcal{M}_{B \times (M+1)}(\mathbb{R})$ ,  $N = \{0, 1, \dots, M\}$ ,  $\tau \in \mathbb{R}^+$  (de-correlation time)

**Ensure:**  $B, M, T \in \mathbb{N}^+$

```

 $\vec{F} \leftarrow (\vec{x}_m)_{0 \dots M}$  {unpacking the ML values of frustration}
 $\vec{V} \leftarrow (\vec{x}_m)_{M+1 \dots M+B}$  {unpacking the ML values of vexation}
 $(\vec{z})_b \leftarrow \left( \sum_{n=0}^M \exp(-(\vec{V})_b n - (\vec{F})_n / n!) \right)_{b \in \{0, \dots, B-1\}}$ 
 $(\langle \vec{N} \rangle)_b \leftarrow \left( \frac{1}{(\vec{z})_b} \sum_{n=0}^M n \exp(-(\vec{V})_b n - (\vec{F})_n / n!) \right)_{b \in \{0, \dots, B-1\}}$ 
 $(\vec{N}_{\text{av}})_b \leftarrow \left( \sum_{n=0}^M (h)_{b,n} n \right)_{b \in \{0, \dots, B-1\}}$ 
 $(\vec{\nabla} g)_{M+1 \dots M+B} \leftarrow \frac{T}{\tau} \times (\vec{N}_{\text{av}} - \langle \vec{N} \rangle)$  { Where  $\times$  denotes scalar multiplication}
 $(P)_{b,n} = \left( \frac{1}{(\vec{z})_b} \exp(-(\vec{V})_b n - (\vec{F})_n / n!) \right)_{b \in \{0, \dots, B-1\}, n \in \{0, \dots, M\}}$ 
 $(\vec{\nabla} g)_{0 \dots M} \leftarrow \frac{T}{\tau} \times \left( \sum_{b=0}^{B-1} (h)_{b,n} - (P)_{b,n} \right)$  { Where  $\times$  denotes scalar multiplication}
 $(\vec{\nabla} g)_0 \leftarrow 0$  {fixing the gauge to avoid singularity in the covariance matrix}
 $(\vec{\nabla} g)_1 \leftarrow 0$  {fixing the gauge to avoid singularity in the covariance matrix}
return  $\vec{\nabla} g$ 

```

---

---

**Algorithm 3 linemin.m** :performs a backtracking search to determine a "sufficiently good" step size to guarantee that we are indeed minimizing the function."Sufficiently good" is determined by the Armijo-Goldstein condition

---

**Require:**  $\vec{x}_n \in \mathbb{R}^{B+M+1}$ ,  $h \in \mathcal{M}_{B \times (M+1)}(\mathbb{R})$ ,  $N = \{0, 1, \dots, M\}$ ,  $\tau \in \mathbb{R}^+$  (de-correlation time),  $\vec{s}_n \in \mathbb{R}^{B+M+1}$  (the current conjugate direction),  $\vec{\nabla} g \cdot \in \mathbb{R}^{B+M+1}$  (gradient at the current location),  $\alpha_{\text{root}} \in \mathbb{R}^+$

**Ensure:**  $B, M, T \in \mathbb{N}^+$

$c_1 \leftarrow 0.7$  {control parameter should be between 0 and 1}

$c_2 \leftarrow 0.0001$  {control parameter should be between 0 and 1}

$m \leftarrow \vec{\nabla} g \cdot \vec{s}_n / \|\vec{s}_n\|$  {  $\cdot$  denotes the usual dot product }

$t = -c_1 m$  {parameter that serves as lower bound in the Armijo-Goldstein condition}

$\alpha \leftarrow \alpha_{\text{root}}$

$\delta \leftarrow g(\vec{x}_n) - g(\vec{x}_n + \alpha \vec{s}_n / \|\vec{s}_n\|)$  { See Algorithm 5 **logli.m** }

**while**  $\delta \leq \alpha t$  **do**

$\alpha \leftarrow \alpha c_1$

$\delta \leftarrow g(\vec{x}_n) - g(\vec{x}_n + \alpha \vec{s}_n / \|\vec{s}_n\|)$

**end while**

**return**  $\alpha$

---



---

**Algorithm 4 getCovMat.m** :Calculates the asymptotic Covariance Matrix as the inverse of the Fisher information matrix for our log-likelihood function

---

**Require:**  $\vec{F}^* \in \mathbb{R}^{M+1}$ ,  $\vec{V}^* \in \mathbb{R}^B$ ,  $N = \{0, 1, \dots, M\}$ ,  $\tau \in \mathbb{R}^+$  (de-correlation time)

**Ensure:**  $B, M, T \in \mathbb{N}^+$

$(\vec{z})_b \leftarrow \left( \sum_{n=0}^M \exp(-(\vec{V})_b n - (\vec{F})_n) / n! \right)_{b \in \{0, \dots, B-1\}}$

$(P)_{b,n} = \left( \frac{1}{(\vec{z})_b} \exp(-(\vec{V})_b n - (\vec{F})_n) / n! \right)_{b \in \{0, \dots, B-1\}, n \in \{0, \dots, M\}}$

$(\langle \vec{N} \rangle)_b \leftarrow \left( \frac{1}{(\vec{z})_b} \sum_{n=0}^M n \exp(-(\vec{V})_b n - (\vec{F})_n) / n! \right)_{b \in \{0, \dots, B-1\}}$

$(\langle \vec{N}^2 \rangle)_b \leftarrow \left( \frac{1}{(\vec{z})_b} \sum_{n=0}^M n^2 \exp(-(\vec{V})_b n - (\vec{F})_n) / n! \right)_{b \in \{0, \dots, B-1\}}$

$(\mathcal{H}_{FF})_{n,n'} = \frac{T}{\tau} \left( \delta_{n,n'} \sum_{n=0}^M (P)_{b,n} - \sum_{b=0}^{B-1} (P)_{n,b} (P)_{b,n'} \right)_{n \in \{0, \dots, M\}, n' \in \{0, \dots, M\}}$

$(\mathcal{H}_{VV})_{b,b'} = \frac{T}{\tau} \delta_{b,b'} \left( \left( \langle \vec{N}^2 \rangle \right)_b - \left( \langle \vec{N} \rangle \right)_b^2 \right)_{b \in \{0, \dots, B-1\}, b' \in \{0, \dots, B-1\}}$

$(\mathcal{H}_{VF})_{b,n} = \frac{T}{\tau} (P)_{b,n} \left( n - \left( \langle \vec{N} \rangle \right)_b \right)_{b \in \{0, \dots, B-1\}, n \in \{0, \dots, M\}}$

---

---

**if** gauge==0 **then**

$(\mathcal{H})_{i \in \{0 \dots M\}, j \in \{0 \dots M\}} \leftarrow \mathcal{H}_{FF}$  {constructing the Hessian by blocks}  
 $(\mathcal{H})_{i \in \{M+1 \dots M+B\}, j \in \{M+1 \dots M+B\}} \leftarrow \mathcal{H}_{VV}$  {constructing the Hessian by blocks}  
 $(\mathcal{H})_{i \in \{0 \dots M\}, j \in \{M+1 \dots M+B\}} \leftarrow {}^t\mathcal{H}_{VF}$  {constructing the Hessian by blocks}  
 $(\mathcal{H})_{i \in \{M+1 \dots M+B\}, j \in \{0 \dots M\}} \leftarrow \mathcal{H}_{VF}$  {constructing the Hessian by blocks}  
 $\Sigma \leftarrow \mathcal{H}^+$  {+ denotes the Moore-Penrose inverse}

**else**

$(\mathcal{H})_{i \in \{0 \dots M\}, j \in \{0 \dots M\}} \leftarrow \mathcal{H}_{FF}$  {constructing the Hessian by blocks}  
 $(\mathcal{H})_{i \in \{M+1 \dots M+B\}, j \in \{M+1 \dots M+B\}} \leftarrow \mathcal{H}_{VV}$  {constructing the Hessian by blocks}  
 $(\mathcal{H})_{i \in \{0 \dots M\}, j \in \{M+1 \dots M+B\}} \leftarrow {}^t\mathcal{H}_{VF}$  {constructing the Hessian by blocks}  
 $(\mathcal{H})_{i \in \{M+1 \dots M+B\}, j \in \{0 \dots M\}} \leftarrow \mathcal{H}_{VF}$  {constructing the Hessian by blocks}  
 $(\mathcal{G})_{i \in \{0 \dots M\}, j \in \{0 \dots M\}} \leftarrow 0$  {constructing the Gauge transformation matrix by blocks}  
 $(\mathcal{G})_{i \in \{M+1 \dots M+B\}, j \in \{M+1 \dots M+B\}} \leftarrow -1/B$  {constructing the Gauge transformation matrix by blocks}  
 $(\mathcal{G})_{i \in \{0 \dots M\}, j \in \{M+1 \dots M+B\}} \leftarrow i/B$  {constructing the Gauge transformation matrix by blocks}  
 $(\mathcal{G})_{i \in \{M+1 \dots M+B\}, j \in \{0 \dots M\}} \leftarrow 0$  {constructing the Gauge transformation matrix by blocks}  
 $\Sigma \leftarrow \mathcal{G}\mathcal{H}^+ {}^t\mathcal{G}$  {+ denotes the Moore-Penrose inverse}

**end if**

**return**  $\Sigma$

---

**Algorithm 5 logli.m**: Calculates the value of the likelihood function for a given set of parameters and data for our specific model

---

**Require:**  $\vec{x}_n \in \mathbb{R}^{B+M+1}$ ,  $h \in \mathcal{M}_{B \times (M+1)}(\mathbb{R})$ ,  $N = \{0, 1, \dots, M\}$ ,  $\tau \in \mathbb{R}^+$  (de-correlation time)

**Ensure:**  $B, M, T \in \mathbb{N}^+$

$\vec{F} \leftarrow (\vec{x}_n)_{0 \dots M}$  {unpacking the ML values of frustration}  
 $\vec{V} \leftarrow (\vec{x}_n)_{M+1 \dots M+B}$  {unpacking the ML values of vexation}  
 $(\vec{z})_b \leftarrow \left( \sum_{n=0}^M \exp(-(\vec{V})_b n - (\vec{F})_n / n!) \right)_{b \in \{0, \dots, B-1\}}$   
 $(\vec{F}_{av})_b \leftarrow \left( \sum_{n=0}^M (h)_{b,n} (\vec{F})_n \right)_{b \in \{0, \dots, B-1\}}$   
 $(\vec{N}_{av})_b \leftarrow \left( \sum_{n=0}^M (h)_{b,n} n \right)_{b \in \{0, \dots, B-1\}}$   
 $g(\vec{x}_n) \leftarrow \sum_{b=0}^{B-1} (\vec{F}_{av})_b + (\vec{N}_{av})_b (\vec{V})_b + \ln(\vec{z})_b$   
**return**  $g(\vec{x}_n)$

---

---

**Algorithm 6 predav.m** :Predicts the average number of flies in each bin using the DFT model

---

**Require:**  $\vec{F}^* \in \mathbb{R}^{M+1}, \vec{V}^* \in \mathbb{R}^B, h \in \mathcal{M}_{B \times (M+1)}(\mathbb{R}), N = \{0, 1, \dots, M\}, \hat{N}$   
 (total number of individuals in the system)

**Ensure:**  $B, M, \hat{N} \in \mathbb{N}^+$

NmaxSteps  $\leftarrow$  130 {number of steps before giving up on the search}

$\epsilon \leftarrow 10^{-7}$  {tolerance in the difference between the actual number of flies and the one that comes up with the guessed mu}

$c \leftarrow 0$

$\mu \leftarrow \max \left( \left\{ \left( \vec{V}^* \right)_b \right\}_{b \in \{0, \dots, B-1\}} \right)$  {convenient root for the search algorithm}

$\tilde{N} \leftarrow 0$

$\delta \leftarrow \left| \max \left( \left\{ \left( \vec{V}^* \right)_b \right\}_{b \in \{0, \dots, B-1\}} \right) - \min \left( \left\{ \left( \vec{V}^* \right)_b \right\}_{b \in \{0, \dots, B-1\}} \right) \right|$

$a \leftarrow \mu + 2\delta$  {guess for the highest lower bound for the chemical potential}

$b \leftarrow \mu - 2\delta$  {guess for the lowest higher bound for the chemical potential}

$\mu^* \leftarrow 0$

**while**  $c \leq \text{NmaxSteps}$  **do**

$\mu = (a + b)/2$

$(\vec{z})_b \leftarrow \left( \sum_{n=0}^M \exp(-(\vec{V})_b n - (\vec{F})_n/n!) \right)_{b \in \{0, \dots, B-1\}}$  {normalization

for probability in our model}

$\left( \langle \vec{N} \rangle \right)_b \leftarrow \left( \frac{1}{(\vec{z})_b} \sum_{n=0}^M n \exp(-(\vec{V})_b n - (\vec{F})_n/n!) \right)_{b \in \{0, \dots, B-1\}}$

{ensemble average of our model}

$\tilde{N} \leftarrow \sum_{b=0}^{B-1} \left( \langle \vec{N} \rangle \right)_b$  {total number of flies for this iteration of  $\mu$ }

**if**  $|\tilde{N} - \hat{N}| \leq \epsilon$  **then**

$\mu^* \leftarrow \mu$  {real mu in case we need it}

**break**

**end if**

$c \leftarrow c + 1$  {if the number of flies is not right counter goes up and we modify accordingly for the binary search}

**if**  $\tilde{N} < \hat{N}$  **then**

$b \leftarrow \mu$

**else**

$a \leftarrow \mu$

**end if**

**end while**

**return**  $\mu, \langle \vec{N} \rangle$

---