## Chapter 1: Curves

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#### Section 1-1: Introduction

Classical differential geometry: the study of local properties of curves and surfaces.

Global differential geometry: the study of the influence of the local properties on the behavior of the entire curve and surface.

No exercises.

#### Section 1-2: Parametrized Curves

**Exercise 1-2.1.** Find a parametrized curve  $\alpha(t)$  whose trace is the circle  $x^2 + y^2 = 1$  such that  $\alpha(t)$  runs clockwise around the circle with  $\alpha(0) = (0, 1)$ .

*Proof.*  $\alpha(t) = (\sin t, \cos t), t \in \mathbb{R}. \square$ 

**Exercise 1-2.2.** Let  $\alpha(t)$  be a parametrized curve which does not pass through the origin. If  $\alpha(t_0)$  is the point of the trace of  $\alpha$  closest to the origin and  $\alpha'(t_0) \neq 0$ , show that the position vector  $\alpha(t_0)$  is orthogonal to  $\alpha'(t_0)$ .

*Proof.* Let  $f(t) = |\alpha(t)|^2 = \alpha(t) \cdot \alpha(t)$ . f(t) is differentiable and f(t) has a local minimum at a point  $t = t_0 \in I$ . So  $f'(t_0) = 0$ . [Theorem 5.8 in W. Rudin, Principles of Mathematical Analysis, 3rd edition.] Since

$$f'(t) = 2\alpha(t) \cdot \alpha'(t),$$

 $f'(t_0) = 2\alpha(t_0) \cdot \alpha'(t_0) = 0$ , or  $\alpha(t_0) \cdot \alpha'(t_0) = 0$ . Since  $\alpha(t_0) \neq 0$  and  $\alpha'(t_0) \neq 0$ ,  $\alpha(t_0)$  is orthogonal to  $\alpha'(t_0)$ .  $\square$ 

**Exercise 1-2.3.** A parametrized curve  $\alpha(t)$  has a property that its second derivative  $\alpha''(t)$  is identically zero. What can be said about  $\alpha$ ?

 $\alpha(t)$  is a straight line.

*Proof.* Since  $\alpha''(t)$  is identically zero,  $\alpha'(t) = a$  is a constant. [Theorem 5.11 in W. Rudin, Principles of Mathematical Analysis, 3rd edition.] Define

 $f(t) = \alpha(t) - at$  (on I). Since  $f'(t) = \alpha'(t) - a = 0$ ,  $f(t) = \alpha(t) - at = b$  is a constant again. Therefore,  $\alpha(t) = at + b$ , which is a straight line (on I).  $\square$ 

**Exercise 1-2.4.** Let  $\alpha: I \to \mathbb{R}^3$  be a parametrized curve and let  $v \in \mathbb{R}^3$  be a fixed vector. Assume that  $\alpha'(t)$  is orthogonal to v for all  $t \in I$  and that  $\alpha(0)$  is orthogonal to v. Prove that  $\alpha(t)$  is orthogonal to v for all  $t \in I$ .

Need to assume that  $\alpha(t) \neq 0$  for all  $t \in I$ .

*Proof.* Given any  $t \neq 0 \in I$ . (Nothing to do at t = 0.) Define  $f: I \to \mathbb{R}$  by  $f(t) = \alpha(t) \cdot v$ . By the mean value theorem, there exists a point  $\xi$  between 0 and t such that

$$f(t) - f(0) = f'(\xi)(t - 0),$$

where  $f'(t) = \alpha'(t) \cdot v + \alpha(t) \cdot v' = \alpha'(t) \cdot v$ . Note that f(0) = 0 since  $\alpha(0)$  is orthogonal to v, and  $f'(\xi) = 0$  since  $\alpha'(t)$  is orthogonal to v. So the identity is reduced to

$$f(t) = 0,$$

or  $\alpha(t) \cdot v = 0$ , or  $\alpha(t)$  is orthogonal to v.  $\square$ 

**Exercise 1-2.5.** Let  $\alpha: I \to \mathbb{R}^3$  be a parametrized curve, with  $\alpha'(t) \neq 0$  for all  $t \in I$ . Show that  $|\alpha(t)|$  is a nonzero constant if and only if  $\alpha(t)$  is orthogonal to  $\alpha'(t)$  for all  $t \in I$ .

The same trick in Exercise 1-2.2.

*Proof.* It is equivalent to show that  $|\alpha(t)|^2$  is a nonzero constant if and only if  $\alpha(t)$  is orthogonal to  $\alpha'(t)$  for all  $t \in I$ . Let

$$f(t) = |\alpha(t)|^2 = \alpha(t) \cdot \alpha(t).$$

Notice that  $\alpha'(t) \neq 0$ , and thus

 $|\alpha(t)|$  is a nonzero constant  $\iff f(t) = |\alpha(t)|^2$  is a nonzero constant  $\iff f'(t) = 0$  and f(t) is a nonzero constant  $\iff \alpha(t) \cdot \alpha'(t) = 0$  and  $\alpha(t)$  is a nonzero constant  $\iff \alpha(t)$  is orthogonal to  $\alpha'(t)$  for all  $t \in I$ .

#### Section 1-3: Regular Curves; Arc Length

**Exercise 1-3.1.** Show that the tangent lines to the regular parametrized curve  $\alpha(t) = (3t, 3t^2, 2t^3)$  make a constant angle with the line y = 0, z = x.

*Proof.*  $\alpha'(t) = (3, 6t, 6t^2)$ . The line y = 0, z = x is  $\beta(t) = (1, 0, 1)$ . The cosine of the angle  $\theta$  between these to curves is

$$\cos \theta = \frac{(3, 6t, 6t^2) \cdot (1, 0, 1)}{|(3, 6t, 6t^2)||(1, 0, 1)|}$$

$$= \frac{3 + 6t^2}{\sqrt{3^2 + (6t)^2 + (6t^2)^2} \sqrt{2}}$$

$$= \frac{3 + 6t^2}{\sqrt{9 + 36t^2 + 36t^4} \sqrt{2}}$$

$$= \frac{3 + 6t^2}{\sqrt{(3 + 6t^2)^2} \sqrt{2}}$$

$$= \frac{1}{\sqrt{2}}.$$

(Notice  $3+6t^2>0$  for all  $t\in\mathbb{R}$ .) That is, the angle between  $\alpha'$  and  $\beta$  is a constant  $(=\pi/4)$ .  $\square$ 

Exercise 1-3.2. A circular disk of radius 1 in the plane xy rolls without slipping along the x axis. The figure described by a point of the circumference of of the disk is called a cycloid (Figure 1-7 in Mantredo P. do Carmo, Differential Geometry of Curves and Surfaces).

- (a) Obtain a parametrized curve  $\alpha : \mathbb{R} \to \mathbb{R}^2$  the trace of which is the cycloid and determine its singular points.
- (b) Compute the arc length of the cycloid corresponding to a complete rotation of the disk.

Proof of (a).

(1) Since

$$\begin{cases} x = t - \sin t \\ y = 1 - \cos t, \end{cases}$$

we define  $\alpha(t) = (t - \sin t, 1 - \cos t)$ .

(2)  $\alpha'(t) = (1 - \cos t, \sin t)$ .  $\alpha'(t) = 0$  if and only if  $t = 2n\pi$  where  $n \in \mathbb{Z}$ . That is, all singular points are  $\alpha(2n\pi) = (2n\pi, 0)$  where  $n \in \mathbb{Z}$ .

 $Proof\ of\ (b).$  The arc length of the cycloid corresponding to a complete rotation of the disk is

$$\begin{split} \int_0^{2\pi} |\alpha'(t)| dt &= \int_0^{2\pi} \sqrt{(1 - \cos t)^2 + (\sin t)^2} dt \\ &= \int_0^{2\pi} \sqrt{2} \sqrt{1 - \cos t} dt \\ &= \int_0^{2\pi} 2 \sin \frac{t}{2} dt \\ &= \left[ -4 \cos \frac{t}{2} \right]_{t=0}^{t=2\pi} \\ &= 8. \end{split}$$

Supplement. The cycloid is not an algebraic curve.

**Exercise 1-3.4.** Let  $\alpha:(0,\pi)\to\mathbb{R}^2$  be given by

$$\alpha(t) = \left(\sin t, \cos t + \log \tan \frac{t}{2}\right),$$

where t is the angle that the y axis makes with the vector  $\alpha(t)$ . The trace of  $\alpha$  is called the **tractrix**. (Figure 1-9 in Mantredo P. do Carmo, Differential Geometry of Curves and Surfaces). Show that

- (a)  $\alpha$  is a differentiable parametrized curve, regular except at  $t = \frac{\pi}{2}$ .
- (b) The length of the segment of the tangent of the tractrix between the point of tangency and the y axis is constantly equal to 1.

Proof of (a).

$$\alpha'(t) = \left(\cos t, -\sin t + \frac{1}{\tan\frac{t}{2}} \frac{1}{\cos^2\frac{t}{2}} \frac{1}{2}\right)$$
$$= \left(\cos t, -\sin t + \frac{1}{2\sin\frac{t}{2}\cos\frac{t}{2}}\right)$$
$$= \left(\cos t, \frac{\cos^2 t}{\sin t}\right)$$

exists. And  $\alpha'(t) = 0$  if and only if  $t = \frac{\pi}{2}$ . That is, there is an unique singular point at  $t = \frac{\pi}{2}$ .  $\square$ 

*Proof of (b).* The the tangent line of the tractrix through the regular point t is parametrized by  $\beta : \mathbb{R} \to \mathbb{R}^2$  which is defined by

$$\begin{split} \beta(u) &= u\alpha'(t) + \alpha(t) \\ &= \left( u\cos t + \sin t, u\frac{\cos^2 t}{\sin t} + \cos t + \log\tan\frac{t}{2} \right). \end{split}$$

By construction, this tangent line  $\beta(u)$  meets the tractrix at u=0, and meets the y-axis when  $u\cos t + \sin t = 0$  or  $u=-\tan t$ . So the length of the segment is

$$|\beta(0) - \beta(-\tan t)| = \sqrt{(-\tan t \cos t)^2 + \left(-\tan t \frac{\cos^2 t}{\sin t}\right)^2}$$
$$= \sqrt{(\sin t)^2 + (\cos t)^2}$$
$$= 1.$$

**Exercise 1-3.10.** (Straight Lines as Shortest.) Let  $\alpha: I \to \mathbb{R}^3$  be a parametrized curve. Let  $[a,b] \subseteq I$  and set  $\alpha(a) = p$ ,  $\alpha(b) = q$ .

(a) Show that, for any constant vector v, |v| = 1,

$$(q-p) \cdot v = \int_a^b \alpha'(t) \cdot v dt \le \int_a^b |\alpha'(t)| dt.$$

(b) Set

$$v = \frac{q - p}{|q - p|}$$

and show that

$$|\alpha(b) - \alpha(a)| \le \int_a^b |\alpha'(t)| dt;$$

that is, the curve of shortest length from  $\alpha(a)$  to  $\alpha(b)$  is the straight line joining these points.

Assume  $p \neq q$  (otherwise  $v = \frac{q-p}{|q-p|}$  is meaningless).

*Proof of (a).* Let  $f(t) = \alpha(t) \cdot v$  defined on I. By the fundamental theorem of calculus,

$$\int_{a}^{b} f'(t)dt = f(b) - f(a).$$

Since  $f'(t) = \alpha'(t) \cdot v$ ,

$$(\alpha(b) - \alpha(a)) \cdot v = \int_a^b \alpha'(t) \cdot v dt.$$

Therefore,

$$(q-p) \cdot v = \int_{a}^{b} \alpha'(t) \cdot v dt$$

$$\leq \int_{a}^{b} |\alpha'(t) \cdot v| dt$$

$$\leq \int_{a}^{b} |\alpha'(t)| |v| dt$$

$$= \int_{a}^{b} |\alpha'(t)| dt.$$

Proof of (b).  $|v| = \frac{|q-p|}{|q-p|} = 1$ . So,

$$(q-p) \cdot \frac{q-p}{|q-p|} \le \int_a^b |\alpha'(t)| dt,$$
  
 $|q-p| \le \int_a^b |\alpha'(t)| dt.$ 

## Section 1-4: The Vector Product in $\mathbb{R}^3$

Exercise 1-4.1. Check whether the following bases are positive:

- (a) The basis  $\{(1,3), (4,2)\}\ in \mathbb{R}^2$ .
- (b) The basis  $\{(1,3,5),(2,3,7),(4,8,3)\}$  in  $\mathbb{R}^3$ .

Proof of (a). Write u = (1,3) and v = (4,2). Then

$$\det(u, v) = \begin{vmatrix} 1 & 3 \\ 4 & 2 \end{vmatrix} = -10 < 0.$$

Thus  $\{u, v\}$  is negative w.r.t. the natural order basis  $\{e_1 = (1, 0), e_2 = (0, 1)\}$ .  $\square$ 

Proof of (b). Write u = (1,3,5), v = (2,3,7), w = (4,8,3). Then

$$\det(u, v, w) = \begin{vmatrix} 1 & 3 & 5 \\ 2 & 3 & 7 \\ 4 & 8 & 3 \end{vmatrix} = 39 > 0.$$

Thus  $\{u, v, w\}$  is positive w.r.t. the natural order basis  $\{e_1, e_2, e_3\}$ .  $\square$ 

**Exercise 1-4.2.** A plane P contained in  $\mathbb{R}^3$  is given by the equation ax + by + cz + d = 0. Show that the vector v = (a, b, c) is perpendicular to the plane and that  $|d|/\sqrt{a^2 + b^2 + c^2}$  measures the distance from the plane to the origin (0,0,0).

Say v is a normal vector of E.

In general, the distance from the plane E to any point  $(x_0, y_0, z_0) \in \mathbb{R}^3$  is

$$\frac{|ax_0 + by_0 + cz_0 + d|}{\sqrt{a^2 + b^2 + c^2}}.$$

Proof.

(1) To show v=(a,b,c) is perpendicular to the plane, it suffices to show that  $v\cdot u=0$  for any vector u lying on the plane E. Write  $u=\overrightarrow{PQ}$  where  $P=(x_1,y_1,z_1)\in E$  and  $Q=(x_2,y_2,z_2)\in E$ . Hence  $u=(x_2-x_1,y_2-y_1,z_2-z_1)$ .

$$v \cdot u = (a, b, c) \cdot (x_2 - x_1, y_2 - y_1, z_2 - z_1)$$

$$= a(x_2 - x_1) + b(y_2 - y_1) + c(z_2 - z_1)$$

$$= (ax_2 + by_2 + cz_2) - (ax_1 + by_1 + cz_1)$$

$$= (-d) - (-d)$$

$$= 0.$$

(2) Pick any point  $(x_1, y_1, z_1) \in E$ . The distance from the plane E to the point  $(x_0, y_0, z_0)$  is

$$\begin{aligned} & \left| (x_1 - x_0, y_1 - y_0, z_1 - z_0) \cdot \frac{v}{|v|} \right| \\ = & \left| (x_1 - x_0, y_1 - y_0, z_1 - z_0) \cdot \frac{(a, b, c)}{\sqrt{a^2 + b^2 + c^2}} \right| \\ = & \frac{|a(x_1 - x_0) + b(y_1 - y_0) + c(z_1 - z_0)|}{\sqrt{a^2 + b^2 + c^2}} \\ = & \frac{|(ax_1 + by_1 + cz_1) - (ax_0 + by_0 + cz_0)|}{\sqrt{a^2 + b^2 + c^2}} \\ = & \frac{|-d - (ax_0 + by_0 + cz_0)|}{\sqrt{a^2 + b^2 + c^2}} \\ = & \frac{|ax_0 + by_0 + cz_0 + d|}{\sqrt{a^2 + b^2 + c^2}}. \end{aligned}$$

**Exercise 1-4.3.** Determine the angle of intersection of the two planes 5x + 3y + 2z - 4 = 0 and 3x + 4y - 7z = 0.

Proof.

- (1) The angle of intersection of the two planes is equal to a angle between two normal vectors of planes.
- (2) Let
  - (a) the angle of intersection of the two planes be  $\theta$ .
  - (b) the normal vector of 5x + 3y + 2z 4 = 0 be  $n_1 = (5, 3, 2)$ .
  - (c) the normal vector of 3x + 4y 7z = 0 be  $n_2 = (3, 4, -7)$ .
- (3) Hence,

$$\cos \theta = \frac{n_1 \cdot n_2}{|n_1||n_2|} = \frac{13}{2\sqrt{703}}.$$

$$\theta = \cos^{-1}\left(\frac{13}{2\sqrt{703}}\right).$$

**Exercise 1-4.13.** Let  $u(t) = (u_1(t), u_2(t), u_3(t))$  and  $v(t) = (v_1(t), v_2(t), v_3(t))$  be differentiable maps from the interval (a, b) into  $\mathbb{R}^3$ . If the derivatives u'(t) and v'(t) satisfy the conditions

$$u'(t) = au(t) + bv(t), v'(t) = cu(t) - av(t),$$

where a, b, and c are constants, show that  $u(t) \wedge v(t)$  is a constant vector.

Proof. Since

$$\begin{split} \frac{d}{dt}(u(t) \wedge v(t)) &= u'(t) \wedge v(t) + u(t) \wedge v'(t) \\ &= (au(t) + bv(t)) \wedge v(t) + u(t) \wedge (cu(t) - av(t)) \\ &= au(t) \wedge v(t) + u(t) \wedge (-av(t)) \\ &= a(u(t) \wedge v(t)) + (-a)(u(t) \wedge v(t)) \\ &= (0, 0, 0), \end{split}$$

 $u(t) \wedge v(t)$  is a constant vector.  $\square$ 

# Section 1-5: The Local Theory of Curves Parametrized by Arc Length

**Exercise 1-5.2.** Show that the torsion  $\tau$  of  $\alpha$  is given by

$$\tau(s) = -\frac{\alpha'(s) \wedge \alpha''(s) \cdot \alpha'''(s)}{|\kappa(s)|^2}.$$

Proof.

(1) Take inner product n(s) to the definition of torsion  $\tau(s)n(s)=b'(s)$ , we have

$$\tau(s) = b'(s) \cdot n(s).$$

Since  $b'(s) = t(s) \wedge n'(s)$ , we have to compute n'(s) first.

(2) Compute n'(s).

$$n'(s) = \frac{d}{ds} \left( \frac{\alpha''(s)}{\kappa(s)} \right) = \frac{\alpha'''(s)}{\kappa(s)} - \frac{\alpha''(s)\kappa'(s)}{\kappa(s)^2}.$$

(3) By (1)(2),

$$\begin{split} \tau(s) &= b'(s) \cdot n(s) \\ &= (t(s) \wedge n'(s)) \cdot n(s) \\ &= \left(\alpha'(s) \wedge \left(\frac{\alpha'''(s)}{\kappa(s)} - \frac{\alpha''(s)\kappa'(s)}{\kappa(s)^2}\right)\right) \cdot \frac{\alpha''(s)}{\kappa(s)} \\ &= \left(\alpha'(s) \wedge \frac{\alpha'''(s)}{\kappa(s)}\right) \cdot \frac{\alpha''(s)}{\kappa(s)} \\ &= \frac{\alpha'(s) \wedge \alpha'''(s) \cdot \alpha''(s)}{|\kappa(s)|^2}, \end{split}$$

or

$$\tau(s) = \frac{\alpha'(s) \wedge \alpha'''(s) \cdot \alpha''(s)}{\alpha''(s)^2}.$$

### Section 1-6: The Local Canonical Form

## Section 1-7: Global Properties of Plane Curves