

E-8

8.2, 8.3

8.5, 8.6

### \* key points from lecture

- discrete-event systems
  - to model control computations
- model and analyze
  - deterministic / nondeterministic automata
  - deadlock, livelock, blocking
  - safety

### \* extra notes

- definition  $A = (Q, E, \delta, q_0, Q_m)$ 
  - $E^*$  denotes all finite strings of elements of  $E$ , together with  $\epsilon$   
 $E = \{a, d\}$ ,  $E^* = \{\epsilon, a, d, aa, ad, da, aaa, \dots\}$
  - $q = \delta(q_0, \underline{s})$ ,  $\underline{s} \in E^*$ . state reached after executing the string  $\underline{s}$
  - language  $L$ , a set of finite strings.  $L \subseteq E^*$ 
    - Concatenation of  $L_1, L_2$
  - language generated by  $A$   
 $L(A) = \{s \in E^* : \delta(q_0, s) \text{ is defined}\}$
  - language marked by  $A$   
 $L_m(A) = \{s \in E^* : \delta(q_0, s) \in Q_m\}$
- equivalent Automata
  - $A_1$  equivalent to  $A_2$  if  $L(A_1) = L(A_2)$   
 $L_m(A_1) = L_m(A_2)$

- deadlock:

unmarked states can be reached and, no further event can be executed

- livelock

a subset of unmarked states can be reached, but no transition is going out from the subset.

- prefix-closure of  $L_m(A)$

$$\overline{L_m(A)} = \{s \in E^* : \exists s' \in E^*, ss' \in L_m(A)\}$$

$$L_m(A) \subseteq \overline{L_m(A)} \subseteq L(A)$$

- blocking

automaton<sup>A</sup> is **blocking** if  $\overline{L_m(A)}$  is a strict subset of  $L(A)$ .

**nonblocking** if  $\overline{L_m(A)} = L(A)$

- nondeterministic

$$\delta: Q \times E \cup \{\epsilon\} \rightarrow 2^Q$$

$Q_0$  is a set

- automaton with smallest number of states that mark a language  
minimal realization

- equivalent states

$$L_m(A(x)) = L_m(A(y)), \text{ } A(x) \text{ the same automaton as } A \text{ with initial state } x$$

- safety

make sure reachable states avoid bad states

## Ex. 8.2

### extra notes

(a) model the vending machine using a discrete-event system

$$A = (Q, E, S, q_0, q_m) \quad P_6 \text{ of } \angle 8$$

analyze:

soda: \$0.45

accepts: \$0.10 (dime) \$0.25 (quarter)

soda dispensed only if \$0.45 is inserted

otherwise: no soda, no return change

states:  $Q = \{0, 10, 25, 35, 45, 20, 30, 40, \square\}$  overflow

event:  $E = \{D, Q\}$

initial state:  $q_0 = 0$ , marked state / final state  $q_m = 45$

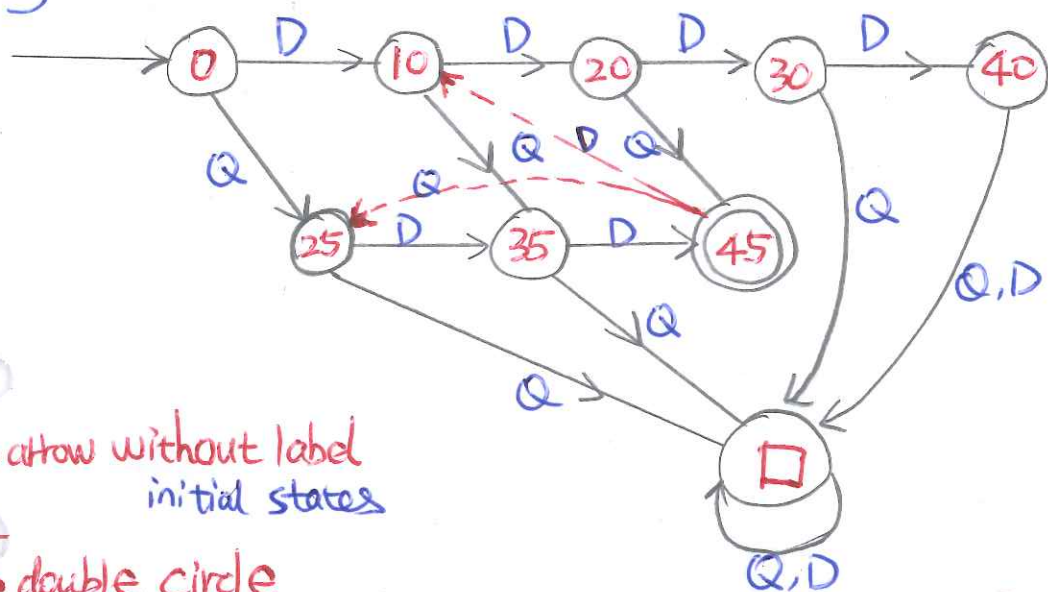
transition map:  $S(0, D) = 10, S(0, Q) = 25$

$S(10, D) = 20, S(10, Q) = 35, S(25, D) = 35$

$S(25, Q) = \square, S(20, D) = 20, S(30, D) = 40$



$S(20, Q) = 45$ ,  $S(35, D) = 45$ ,  $S(35, Q) = \square$   
 $S(30, Q) = \square$ ,  $S(40, D) = \square$ ,  $S(40, Q) = \square$   
 $S(\square, Q) = \square$ ,  $S(\square, D) = \square$   $\leftarrow$  typo, attention in the solution diagram



$S(45, D) = 10$   
 $S(45, Q) = 25$   
 (I think alright)

• arrow without label  
initial states

• double circle  
marked states

(b) is it possible that the machine does not dispense soda?

sure, (might be should be asking .... does dispense .... :))

Livelock at the "overflow" state  $\square$  P14 of L8

formally, once state  $\square$  is reached, no transition is going out from (leaving) this state.

## Ex 8.3

extra notes

(a) describe formally the DES

$$A = (Q, E, \delta, q_0, Q_m)$$

where: states  $Q = \{q_1, q_2\}$   
events  $E = \{0, 1\}$

transition  $\delta$ :  $\delta(q_1, 0) = q_2, \delta(q_2, 1) = q_1$   
initial state  $q_0$ , marked state  $q_2$

(b) marked language  $L_m(A)$

def:  $L_m(A) = \{s \in E^* : \delta(q_0, s) \in Q_m\}$

(the set of finite strings ~~that~~ of events  
that drive the system to marked states)  
one of the

generated language  $L(A)$

def:  $L(A) = \{s \in E^* : \delta(q_0, s) \text{ is defined}\}$

(the set of finite string of events that drives the system starting from ~~one of the~~ the initial state)

In our case

$$L(A) = \{ \underbrace{0(10)^*}_{\text{ends in } q_2}, \underbrace{(01)^*}_{\text{ends in } q_1} \}$$

\* : asterisk

(finite repetition)

$$L_m(A) = \{ 0(10)^* \}$$

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Ex. 8.5

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extra notes

typo in the diagram,  $S(h, 0) = g$

(not bi-directional)

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• given a discrete-event system

determine the minimum state automaton



- equivalent states

P<sub>24</sub> of L8

states 'x' and 'y' are equivalent

if  $L_m(A(x)) = L_m(A(y))$

where  $A(x)$  is the same automaton as  $A$  with initial state  $x$

- two states are equivalent if they have the same behavior in terms of marked language. (in other words, given an input string  $S(x, l)$  is a marked state if and only if  $S(y, l)$  is a marked state)
- two equivalent states can be replaced by a single aggregate state

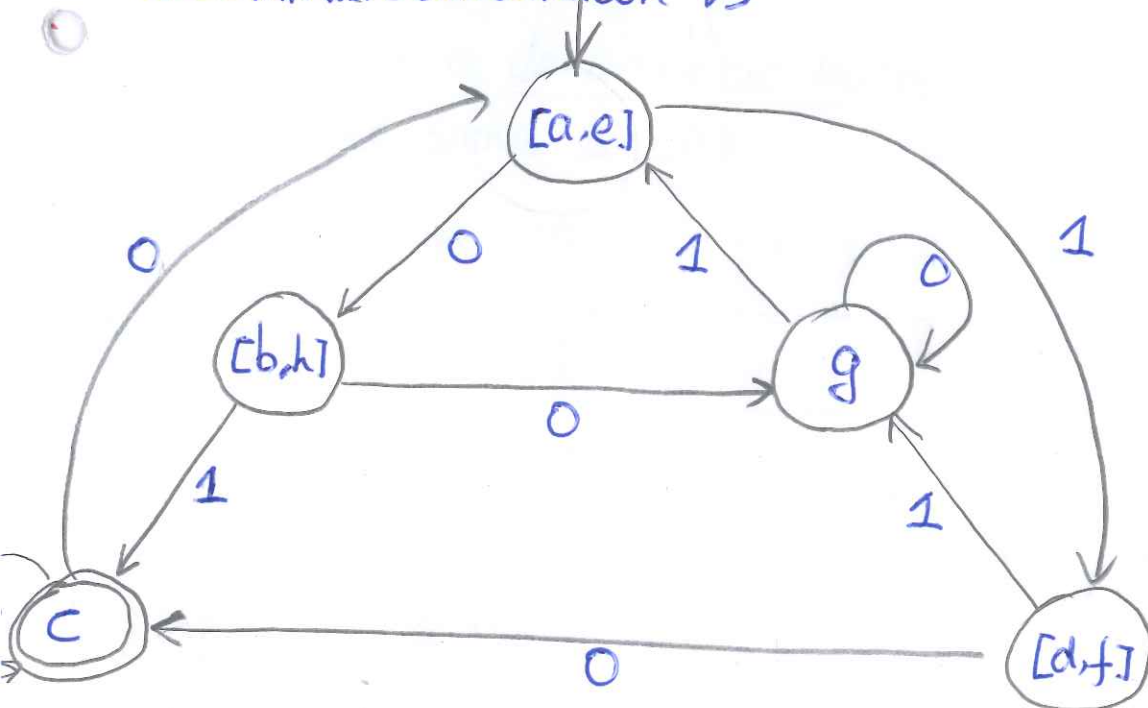
we build a table to indicate if it's possible for each pair of states to be equivalent

h								
e						0	01	1
d					0	✓	0	0
c				1	1	1	1	001
b			010	1	1	1	1	✓
a		1	1	0	✓	0	10	1
	a	b	c	d	e	f	g	h

it turns out

$a \equiv e, b \equiv h, d \equiv f$

the minimal automaton is



## Ex 8.6

- Construct equivalent DFA from an NFA (not in the lecture)  
Subset Construction

- critical points

☆ • final states = all those with a member of  $F$

☆ • transitions

$$S_D([q_1, \dots, q_k], a) = \bigcup_{i=1}^k S_N(q_i, a)$$

union over all  $q_i$

extra notes:

not taught in the lecture

- Construct DFA from NFA
- equivalent language

Given the nondeterministic automaton

$$A = (\{q_0, q_1\}, \{0, 1\}, \delta, q_0, \{q_1\})$$

where

$$\delta(q_0, 0) = \{q_0, q_1\}, \delta(q_0, 1) = \{q_1\}$$

$$\delta(q_1, 0) = \delta(q_1, 1) = \{q_0, q_1\}$$

Prob: Construct a deterministic automaton  $A'$ , which accepts the same  $L_m(A)$ .

Idea: build/treat  $\{q_0, q_1\}$  as a new states

Namely, build  $Q'$  as all subsets of  $Q$

$$Q' = \{[q_0], [q_1], [q_0, q_1]\} \leftarrow \text{names, symbols}$$

initial state  $[q_0]$ , final state  $[q_1], [q_0, q_1]$

events  $\{0, 1\}$



## transitions

$$\delta'([q_0], 0) = [q_0, q_1]$$

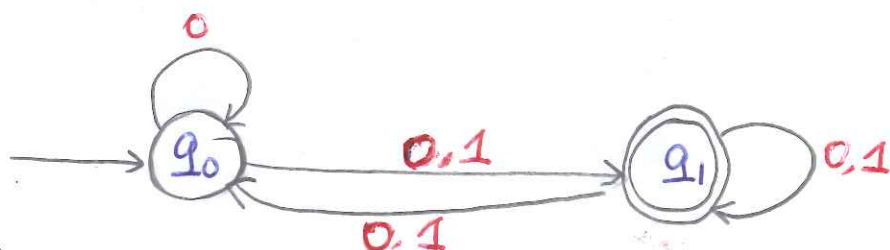
$$\delta'([q_0], 1) = [q_1]$$

$$\delta'([q_1], 0) = \delta'([q_1], 1) = [q_0, q_1]$$

$$\begin{aligned}\delta'([q_0, q_1], 0) &= \delta(q_0, 0) \cup \delta(q_1, 0) \\ &= \{q_0, q_1\} = [q_0, q_1]\end{aligned}$$

$$\begin{aligned}\delta'([q_0, q_1], 1) &= \delta(q_0, 1) \cup \delta(q_1, 1) \\ &= \{q_1\} \cup \{q_1, q_0\} = \{q_0, q_1\} = [q_0, q_1]\end{aligned}$$

original automaton A



deterministic automaton A'

