Fine-tune models with Trainer

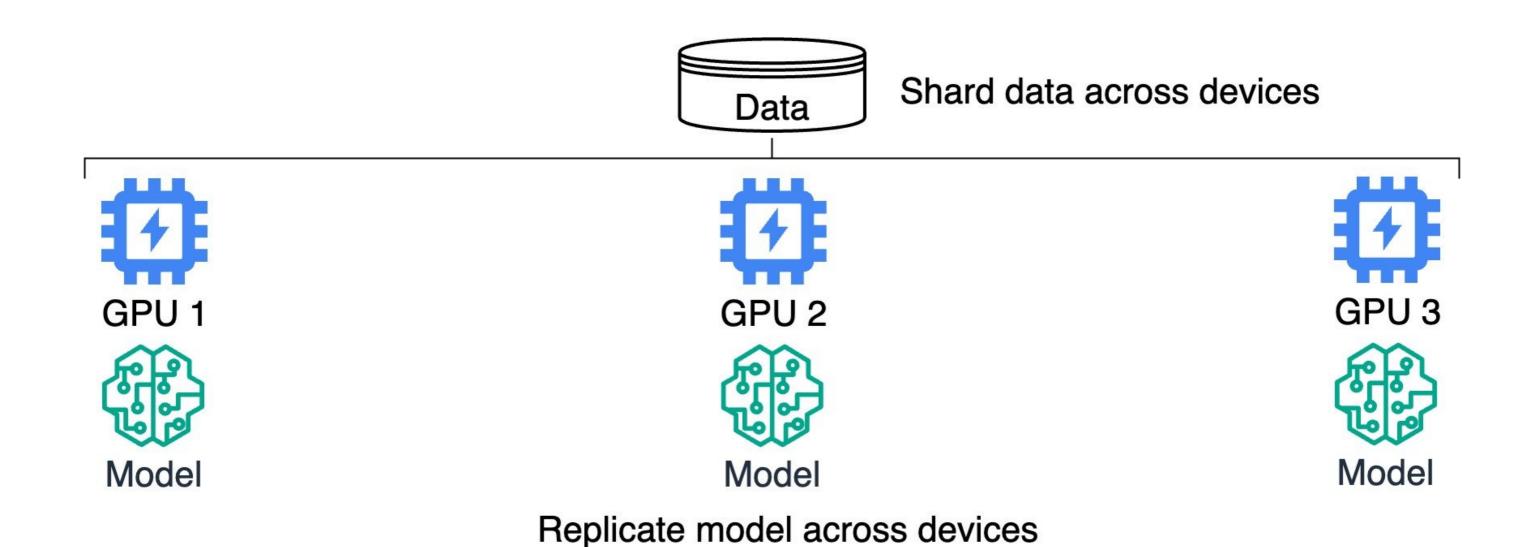
EFFICIENT AI MODEL TRAINING WITH PYTORCH



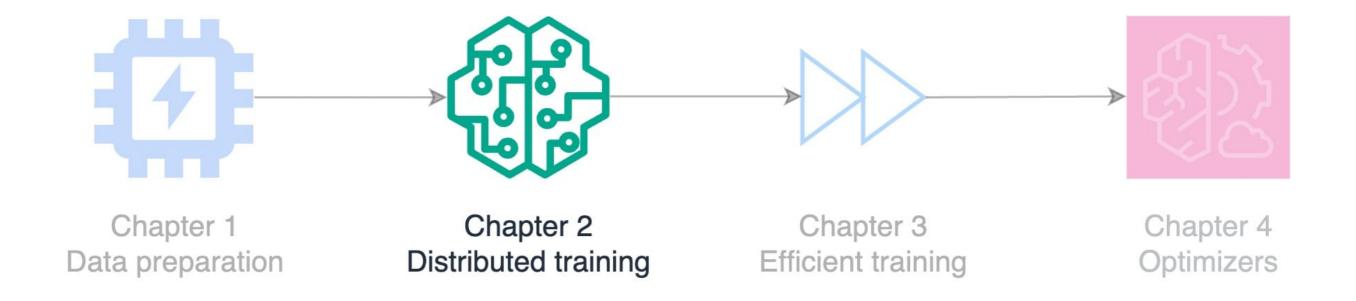
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Data preparation



Distributed training



Trainer and Accelerator

Ability to Customize





Ease of Use



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Ease of Use



Turbocharge training with Trainer

Trainer library

from transformers import Trainer

- Run model on each device in parallel
- Speed up training, like assembly lines
- Review inputs: dataset, model, metrics
- Develop sentiment analysis for e-commerce



Product review sentiment dataset

```
print(dataset)
```

```
DatasetDict({
    train: Dataset({
        features: ['Text', 'Label'],
        num_rows: 1000
    }), ...})
```

```
print(f'"{dataset["train"]["Text"][0]}": {dataset["train"]["Label"][0]}')
```

```
"I love this product!": positive
```

Convert labels to integers

```
def map_labels(example):
    if example["Label"] == "negative":
        return {"labels": 0}
    else:
        return {"labels": 1}

dataset = dataset.map(map_labels)
print(f'First label: {dataset["train"]["labels"][0]}')
```

```
First label: 1
```

Define the tokenizer and model

Load pre-trained model and tokenizer:

Apply tokenizer to the text field:

```
The first tokenized review is [101, 1045, 2293, 2023, 4031, 999, 102].
```



Define evaluation metrics

```
import evaluate
def compute_metrics(eval_predictions):
    load_accuracy = evaluate.load("accuracy")
    load_f1 = evaluate.load("f1")
    logits, labels = eval_predictions
    predictions = np.argmax(logits, axis=-1)
    accuracy = load_accuracy.compute(predictions=predictions, references=labels)[
        "accuracy"
    f1 = load_f1.compute(predictions=predictions, references=labels)["f1"]
    return {"accuracy": accuracy, "f1": f1}
```

Training arguments

- output_dir: Where to save model
- Specify hyperparameters (e.g.,
 learning_rate and weight_decay)
- save_strategy : Save after each epoch
- evaluation_strategy : Evaluate metrics after each epoch

```
from transformers import (
    TrainingArguments)
training_args = TrainingArguments(
    output_dir="output_folder",
    learning_rate=2e-5,
    per_device_train_batch_size=16,
    per_device_eval_batch_size=16,
    num_train_epochs=2,
    weight_decay=0.01,
    save_strategy="epoch",
    evaluation_strategy="epoch",
```

Setting up Trainer

```
{'epoch': 1.0, 'eval_loss': 0.79, 'eval_accuracy': 0.00, 'eval_f1': 0.00}
{'epoch': 2.0, 'eval_loss': 0.65, 'eval_accuracy': 0.11, 'eval_f1': 0.15}
```

```
print(trainer.args.device)
```

сри



Running sentiment analysis for e-commerce

```
sample_review = "This product is amazing!"
input_ids = tokenizer.encode(sample_review, return_tensors='pt')
print(f"Tokenized review: {input_ids}")
```

```
Tokenized review: tensor([[ 101, 2023, 4031, 2003, 6429, 999, 102 ]])
```

Running sentiment analysis for e-commerce

```
output = model(input_ids)
print(f"Output logits: {output.logits}")
Output logits: tensor([[ -0.0538, 0.1300 ]])
predicted_label = torch.argmax(output.logits, dim=1).item()
print(f"Predicted label: {predicted_label}")
Predicted label: 1
sentiment = "Negative" if predicted_label == 0 else "Positive"
print(f'The sentiment of the product review is "{sentiment}."')
The sentiment of the product review is "Positive."
```



Checkpoints with Trainer

• Resume from the latest checkpoint, like pausing a movie

```
trainer.train(resume_from_checkpoint=<mark>True</mark>)
```

```
{'epoch': 3.0, 'eval_loss': 0.29, 'eval_accuracy': 0.37, 'eval_f1': 0.51}
{'epoch': 4.0, 'eval_loss': 0.23, 'eval_accuracy': 0.46, 'eval_f1': 0.58}
```

Resume from specific checkpoint saved in output directory

```
trainer.train(resume_from_checkpoint="model/checkpoint-1000")
```

Let's practice!

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Train models with Accelerator

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Trainer and Accelerator

Ability to Customize



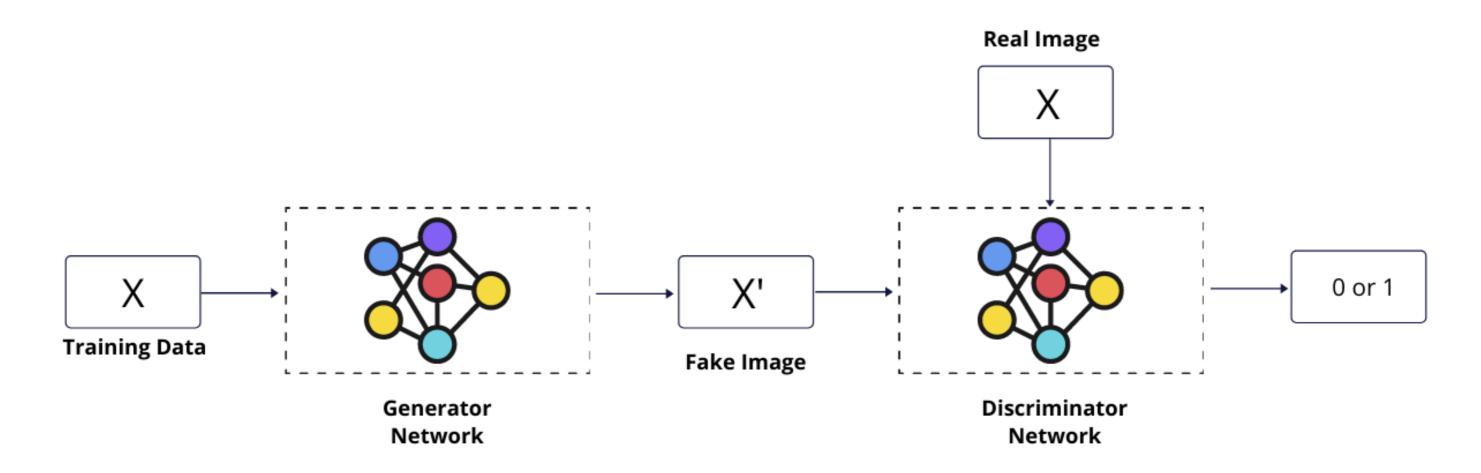


Ease of Use



Custom training loops

- Trainer: no custom training loops
- Some advanced tasks in generative AI require two networks



¹ https://www.aitude.com/basics-of-generative-adversarial-network-model/



Trainer and Accelerator

Ability to Customize





Ease of Use



Modifying a basic training loop

```
for batch in dataloader:
    optimizer.zero_grad()
    inputs, targets = batch
    inputs = inputs.to(device)
    targets = targets.to(device)
    outputs = model(inputs)
    loss = outputs.loss
    loss.backward()
    optimizer.step()
    scheduler.step()
```

- Zero the gradients
- Move data to a specified device:
 .to(device)
- Perform forward pass
- Compute cross-entropy loss
- Compute gradients in a backward pass
- Update model parameters, learning rate

Create an Accelerator object

Accelerator provides an interface for distributed training

```
from accelerate import Accelerator
accelerator = Accelerator(
    device_placement=True
)
```

• device_placement (bool, default True): Handle device placement by default

Define the model and optimizer

Load a pre-trained model

```
from transformers import AutoModelForSequenceClassification

model = AutoModelForSequenceClassification.from_pretrained(
   "distilbert-base-cased", return_dict=True)
```

Optimize model parameters with Adam

```
from torch.optim import Adam

optimizer = Adam(params=model.parameters(), lr=2e-5)
```

Define the scheduler

```
from transformers import get_linear_schedule_with_warmup

lr_scheduler = get_linear_schedule_with_warmup(
    optimizer=optimizer,
    num_warmup_steps=num_warmup_steps,
    num_training_steps=num_training_steps)
```

- optimizer (obj): PyTorch optimizer, like Adam
- num_warmup_steps (int): steps to linearly increase lr, set to
 int(num_training_steps * 0.1)
- num_training_steps (int): total training steps, set to
 len(train_dataloader) * num_epochs

Prepare the model for efficient training

• The prepare method handles device placement

```
for batch in dataloader:
    optimizer.zero_grad()
    inputs, targets = batch
    inputs = inputs.to(device)
    targets = targets.to(device)
```

- Zero the gradients
- Previously moved data to the device

```
for batch in dataloader:
    optimizer.zero_grad()
    inputs, targets = batch
```

- Zero the gradients
- Previously moved data to the device
- Remove lines that manually move data

```
for batch in dataloader:
    optimizer.zero_grad()
    inputs, targets = batch
    outputs = model(inputs)
    loss = outputs.loss
    loss.backward()
```

- Zero the gradients
- Previously moved data to the device
- Remove lines that manually move data
- Perform a forward pass
- Compute cross-entropy loss and gradients

```
for batch in dataloader:
    optimizer.zero_grad()
    inputs, targets = batch
    outputs = model(inputs)
    loss = outputs.loss
    accelerator.backward(loss)
    optimizer.step()
    scheduler.step()
```

- Zero the gradients
- Previously moved data to the device
- Remove lines that manually move data
- Perform a forward pass
- Compute cross-entropy loss and gradients
- Replace loss.backward with accelerator
- Update model parameters, learning rate

Summary of changes

Before Accelerator

- Need to manually move data to devices
 - o inputs.to(device)
 - o targets.to(device)
- Compute gradients with loss.backward()

After Accelerator

- Automatic device placement and data parallelism
 - o accelerator.prepare(model)
 - o accelerator.prepare(dataloader)
- Handle gradient synchronization with accelerator.backward(loss)
- Customizable loop
- User-friendly, hardware-agnostic, scalable, and maintainable

Let's practice!

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Evaluate models with Accelerator

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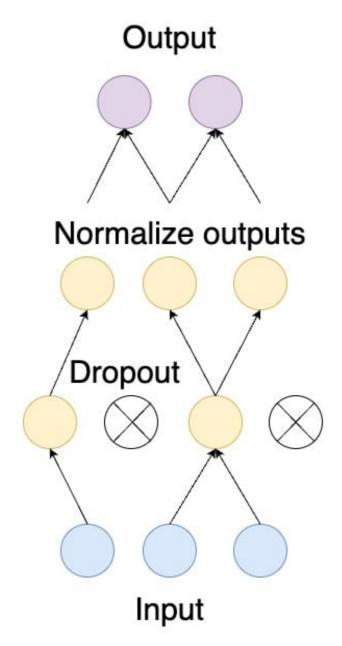
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Why put a model in evaluation mode?

- Training mode
 - Dropout: Set neurons to zero
 - Batch normalization

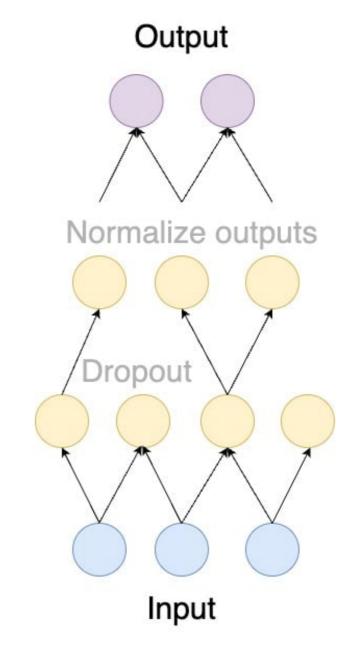
Dropout and batch normalization



Why put a model in evaluation mode?

- Training mode
 - Dropout: Set neurons to zero
 - Batch normalization
- Evaluation mode disables these layers
- model.eval() activates evaluation mode

Dropout and batch normalization

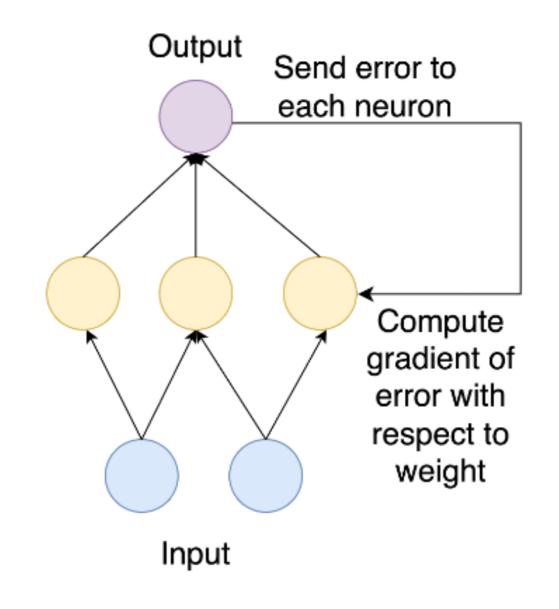


Disable gradients with torch.no_grad()

- Training requires gradient computation
- torch.no_grad() disables gradients
- Call both model.eval and torch.no_grad:

```
model.eval()
with torch.no_grad():
   outputs = model(**inputs)
```

Computing gradients in backpropagation



Prepare a validation dataset

Load validation split of the MRPC dataset

```
validation_dataset = load_dataset("glue", "mrpc", split="validation")
```

Tokenize the validation dataset

Life of an epoch: training and evaluation loops

- For each epoch, iterate over the train and validation datasets
- First run the model in training mode
- Then run the model in evaluation mode and log metrics after evaluation

```
for epoch in range(num_epochs):
    model.train()
    for step, batch in enumerate(train_dataloader):
        # Perform training step
    model.eval()
    for step, batch in enumerate(eval_dataloader):
        # Perform evaluation step
# Log evaluation metrics
```

Inside the evaluation loop

```
metric = evaluate.load("glue", "mrpc")
model.eval()
for step, batch in enumerate(eval_dataloader):
    with torch.no_grad():
        outputs = model(**batch)
    predictions = outputs.logits.argmax(dim=-1)
    predictions, references = accelerator.gather_for_metrics((predictions, batch["labels"]))
    metric.add_batch(predictions=predictions, references=references)
eval_metric = metric.compute()
print(f"Eval metrics: \n{eval_metric}")
```

```
Eval metrics:
{'accuracy': 0.81, 'f1': 0.77}
```



Log metrics after evaluation

- Tracking tools: notebooks that log metrics; examples are TensorBoard and MLflow
- log_with : use all experiment tracking tools
- .init_trackers(): initialize tracking tools
- .log():track accuracy, f1, epoch
- .end_training(): finish tracking

```
accelerator = Accelerator(project_dir=".",
                          loq_with="all")
accelerator.init_trackers("my_project")
for epoch in range(num_epochs):
   # Training loop is here
   # Evaluation loop is here
    accelerator.log({
        "accuracy": eval_metric["accuracy"],
        "f1": eval_metric["f1"],
   }, step=epoch)
accelerator.end_training()
```

Let's practice!

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