DDA3020 Machine Learning

Assignment 1 Written & Report

1. Written Question

1.1

i) consider y^TXW is a scalar function

1xh dxl

$$y^{T}xw = [x^{T}y]^{T}w = z^{T}w = [z_{1},z_{2},...,z_{d}]\begin{bmatrix} w_{1} \\ w_{2} \\ \vdots \\ w_{d} \end{bmatrix} = z^{T}z_{1}w_{1}$$

$$\therefore \frac{dy^{T}xw}{dw} = \frac{dz^{T}w}{dw} = \begin{bmatrix} \frac{\partial z^{T}w}{\partial w_{1}} \\ \frac{\partial z^{T}w}{\partial w_{2}} \end{bmatrix} = \begin{bmatrix} z_{1} \\ z_{2} \\ \vdots \\ \vdots \\ \frac{\partial z^{T}w}{\partial w_{2}} \end{bmatrix} = z^{T}z_{2} = z^{T}y$$

$$\frac{9m_{1}}{9m_{2}} = \begin{bmatrix} \frac{9m_{1}}{9m_{2}} \\ \frac{9m_{1}}{9m_{1}} \\ \frac{9m_{1}}{9m_{2}} \end{bmatrix} = \begin{bmatrix} 5m_{1} \\ 5m_{1} \\ \vdots \\ 5m_{1} \end{bmatrix} = 5m$$

3) Let w = [w1, W2, ... Wd] T

$$X = \begin{bmatrix} X_{11} & X_{12} \cdots & X_{1d} \\ \vdots & & \vdots \\ X_{d1} & \cdots & X_{dd} \end{bmatrix}$$

$$= \underset{i=1}{W} \sum_{i=1}^{N} w_{i} \times i_{1} + w_{2} \sum_{i=1}^{N} w_{i} \times i_{2} + \cdots + w_{d} \sum_{i=1}^{N} w_{i} \times i_{d}$$

$$= \underset{i=1}{\overset{d}{\bigvee}} w_{i}^{2} \times i_{i} + \underset{i\neq j}{\sum_{i\neq j}} \sum_{i \leq a} scalar function$$

$$\vdots \xrightarrow{dw^{T} \times w} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \end{bmatrix} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \end{bmatrix} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \end{bmatrix} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \end{bmatrix} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \end{bmatrix} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \end{bmatrix} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \end{bmatrix} = \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} \times i_{j} + x_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} + x_{j} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} \times i_{j} \times i_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} \times i_{j} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} \times i_{j} \times i_{j} \times i_{j} \\ \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} \times i_{j} \times i_{j} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial w^{T} \times w}{\partial w_{i}} \times i_{j} \times i_$$

consider $(x+x^T)w$ $[\{x_{ij}+x_{ji}\}] \cdot [w_1,w_2,...w_d]^T$ $= \begin{bmatrix} \sum w_i(x_{ij}+x_{ji}) \\ \sum w_i(x_{2j}+x_{j2}) \\ \vdots \\ \sum w_i(x_{dj}+x_{jd}) \end{bmatrix} = \frac{dw^T x w}{dw}$

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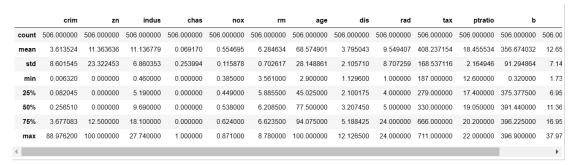
121090408 Ma Xinxian

2. Programming Question

Description: In this assignment, we need to use appropriate attributes in 'crim, zn, indus, chas, nox, rm, age, dis, rad, tax, ptratio, b, lstat' to predict the last attributes 'MEDV' by the linear regression model.

2.1. Loading data [Step1]

By using *pandas.isna().sum()*, we find that there is not incomplete data point in the dataset. And also *pandas.describe()* and *shape()* function are used to summarized the data: there are 506 data samples and 14 feature columns, get more information from the table below (not complete).

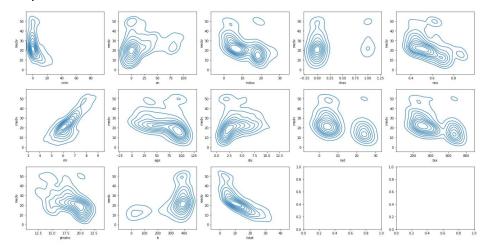


Besides, I guess 'lstat' is the most relevant attribute for MEDV due to their relatively similar characteristic and my personal understanding about MEDV.

2.2. Data visualized [Step2&3&4]

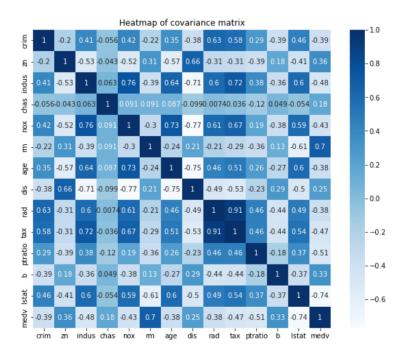
In order to correct prediction, we use seaborn to visualized the data:

I) Kdeplot() with bivariate distribution



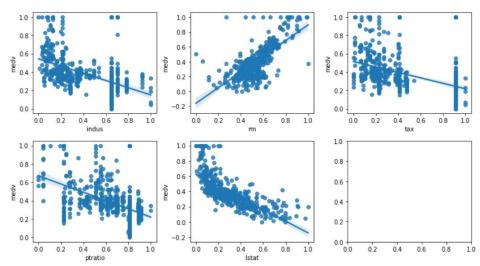
This bivariate distribution figures clearly display the relationship between different attributes. Considering that an oblate image indicates a potential linear relationship between them, we guess "crim", "nox", "rm", "age', "dis", "ptratio" and "lstat" are relatively higher relevant attributes for MEDV.

II) Heatmap() with pairwise correlation matrix



Just focus on the last column. Larger the absolute value of corrcoefficient is, more linear correlation with MEDV. We set 0.45 be a threshold value. As a result, "indus", "rm", "tax", "ptratio" and "lstat" are selected as the good indications of using as predictors.

III) Regplot() plot the relevance against MEDV with 95% confidence interval



They all have a relatively strong linear relationship with MEDV (You can see it more obvious by using *estimator=mean()* in my code file). So our selection is good.

2.3. Linear model(Step5&6)

I) Linear hypothesis function:

for a given data x with d dimension:

$$f_{\mathbf{w},b}(\mathbf{x}) = \mathbf{x}^T \mathbf{w} + b$$

where **w** is a d-dimensional vector of parameters, bias b is a real number.

for a given data set X with shape $m^*(d+1)$:

We can modify first equation into:

$$f_{\mathbf{w}}(\mathbf{X}) = X\mathbf{w}$$

where w contains the bias and becomes a (d+1) *1 matrix. (m is the number of data) and the

output is a m*1 result matrix.

$$X = egin{bmatrix} 1 & x_{11} & x_{12} & \dots & x_{1d} \ 1 & x_{21} & x_{22} & \dots & x_{2d} \ \dots & \dots & \dots & \dots & \dots \ 1 & x_{m1} & x_{m2} & \dots & x_{md} \end{bmatrix} \qquad \mathbf{w} = egin{bmatrix} b \ w_1 \ w_2 \ \dots \ w_d \end{bmatrix}$$

II) Cost function:

For a given dataset defined in I), the cost function for linear regression model J(w) is defined as:

$$J(w) = \frac{1}{2m}(Xw - y)^2 = \frac{1}{2m}(Xw - y)^T(Xw - y)$$

Where y is a m*1 result matrix, the output is somehow an average error.

We divide m in the equation to make it easier to get RMSE later. In the code, the cost function is defined in the function called Lossf(X, w, y)

III) Split data

IV) Training with Gradient Descent method (hyperparameter settings):

-According to Gradient Descent algorithms, **w** is updated with following equations:

$$\mathbf{w} \leftarrow \mathbf{w} - lpha rac{\partial J(\mathbf{w})}{\partial \mathbf{w}} \quad rac{\partial J(\mathbf{w})}{\partial \mathbf{w}} = rac{1}{m} \mathbf{X}^T (\mathbf{X} \mathbf{w} - \mathbf{y})$$

Where α is called step-size or learning rate.

Stopping criterion: practically, when the iteration times is reached.

(There are also some other ways, but I choose it here since it is practical)

-This leads to our hyperparameter settings:

1. **Initial parameter matrix** *w* is randomly set by using *init_w*() function:

```
def init_w():
    np.random.seed(1674)
    return np.random.randint(-15, 15, (6, 1))
```

(-15, 15) can be changed. This w is the initial parameter matrix being updated.

- **2. Step size** α is set to 10^{-3} as default. It will affect the learning rate of the model. One can also use exact line search and backtracking line search method.
- 3. **Iteration times** is set to 20 as default. This is related to the stopping criterion.

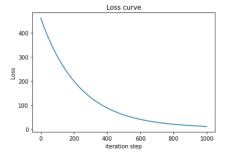
-We start training now and get the error in *RMSE*:

$$RMSE = \sqrt{\frac{1}{N} \sum_{i=1}^{n} (Y_i - f(x_i))^2}$$

$$RMSE = \sqrt{2 \times J(\mathbf{w})}$$
 so

Result:

Training error (in RMSE): 4.918903212701808 Testing error (in RMSE): 5.065365234927568



-Repeat above process for 10 times with different parameters (step size and iteration times).

```
Training with step_size: 0.100000, iter_step: 100.000000
Training error (in RMSE): 1.874967132778799
Testing error (in RMSE): 1.655495863381605
Training with step_size: 0.100000, iter_step: 1000.000000
Training error (in RMSE): 0.37858995185572913
Testing error (in RMSE): 0.33936676905205876
Training with step_size: 0.100000, iter_step: 10000.000000
Training error (in RMSE): 0.11214575047920258
Testing error (in RMSE): 0.12938042094504554
Training with step size: 0.010000, iter step: 100.000000
Training error (in RMSE): 4.865927680715569
Testing error (in RMSE): 5.007801030888095
Training with step size: 0.010000, iter step: 1000.000000
Training error (in RMSE): 1.8781304713538647
Testing error (in RMSE): 1.658541165908951
Training with step_size: 0.010000, iter_step: 10000.000000
Training error (in RMSE): 0.37882949491158496
Testing error (in RMSE): 0.33958351450917607
Training with step_size: 0.001000, iter_step: 100.000000
Training error (in RMSE): 24.678588858265723
Testing error (in RMSE): 25.015909721289443
Training with step_size: 0.001000, iter_step: 10000.000000
Training error (in RMSE): 1.878446466556454
Testing error (in RMSE): 1.6588455195540677
Training with step_size: 0.000100, iter_step: 100.000000
Training error (in RMSE): 29.818428226604894
Testing error (in RMSE): 30.14854772576647
Training with step_size: 0.000100, iter_step: 1000.000000
Training error (in RMSE): 24.683560499994265
Testing error (in RMSE): 25.020874873154447
```

Influence of different parameters on *RMSE*:

1. Step size α :

focus on iteration 1,4,7,9 where iteration times are 100, we find that as α become smaller, the error in training and testing are become larger. For other iteration times like 1000, 10000, we get the same observation but the difference gap become smaller. This is because the α affects the velocity of learning the parameter. Considering that we make α be a constant in our training, the larger it is, larger distance will the parameter move on the better position, the RMSE error $\underline{\mathbf{may}}$ become smaller faster. But this may not correct since if α is too large, it may move over and hard to move to the optimal w. We should be care about it in different specific training or use other method like exact line search and backtracking line search.

2. Iteration times:

focus on iteration 1,2,3 where α are 100000, we find that as **iteration times** become larger, the error in training and testing are become smaller. For other α , we get the same observation. This is because **iteration times** is related to the stopping criterion. If **iteration times** is large, more work will w do to approach the optimal one, then the error \underline{may} be smaller. But as we discuss in α , its influence also depends other parameter setting.