

# Machine Learning 2 – Group ESHG

## Assignment 03

Willi Gierke, Arik Elimelech, Mehmed Halilovic, Leon Sixt

May 11, 2017

### Exercise 1: Maximum Entropy Distributions (10+10+5+5 P)

The differential entropy  $H(x)$  for a random variable  $x \in \mathbb{R}$  with probability density function  $p(x)$  is given by

$$H(x) = - \int p(x) \log p(x) dx$$

We would like to find the probability density function  $p(x)$  that maximizes the differential entropy under the following constraints

$$\forall x : p(x) \geq 0 \quad , \quad \int p(x) dx = 1 \quad , \quad \mathbb{E}[x] = 0 \quad , \quad \text{Var}[x] = \sigma^2.$$

The first set of inequality constraints is handled by rewriting the unknown density function as  $p(x) = \exp(s(x))$  and searching for a function  $s(x)$  that maximizes the objective. Here, we view the function  $s(x)$  as an infinite-dimensional vector, and therefore can write

$$\frac{\partial \int f(s(x)) dx}{\partial s(x)} = f'(s(x)).$$

- (a) Write the Lagrange function  $\Lambda(s(x), \lambda_1, \lambda_2, \lambda_3)$  corresponding to the constrained optimization problem above, where  $\lambda_1, \lambda_2, \lambda_3$  are used to incorporate the three equality constraints.
- (b) Show that the function  $s(x)$  that maximizes the objective  $H(x)$  is quadratic in  $x$ .
- (c) Show that the function  $p(x)$  that maximizes the objective  $H(x)$  is a Gaussian probability density function with mean 0 and variance  $\sigma^2$ .
- (d) Show that for every univariate random variable  $x$  of mean 0 and variance  $\sigma^2$ , and assuming  $x^* \sim \mathcal{N}(0, \sigma^2)$ , the negentropy  $J(x) = H(x^*) - H(x)$  that independent component analysis seeks to maximize is always greater or equal to 0, and is equal to 0 when  $x$  is Gaussian-distributed.

### Exercise 2: Finding Independent Components (10+15+15 P)

We consider the joint probability distribution  $p(x, y) = p(x) p(y|x)$  with

$$p(x) \sim \mathcal{N}(0, 1),$$

$$p(y|x) = \frac{1}{2} \delta(y - x) + \frac{1}{2} \delta(y + x),$$

where  $\delta(\cdot)$  denotes the Dirac delta function. A useful property of linear component analysis for two-dimensional probability distributions is that the set of all possible directions to look for in  $\mathbb{R}^2$  is directly given by

$$\left\{ \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}, \quad 0 \leq \theta < 2\pi \right\}.$$

The projection of the random vector  $(x, y)$  on a particular component can therefore be expressed as a function of  $\theta$ :

$$z(\theta) = x \cos(\theta) + y \sin(\theta).$$

As a result, linear component analysis such as PCA or ICA in the two-dimensional space is reduced to finding the parameters  $\theta \in [0, 2\pi[$  that maximize a certain objective  $J(z(\theta))$ .

- (a) Sketch the joint probability distribution  $p(x, y)$ , along with the projections  $z(\theta)$  of this distribution for angles  $\theta = 0$ ,  $\theta = \pi/8$  and  $\theta = \pi/4$ .
- (b) Find the principal components of  $p(x, y)$ . That is, find the parameters  $\theta \in [0, 2\pi[$  that maximize the variance of the projected data  $z(\theta)$ .
- (c) Find the independent components of  $p(x, y)$ . That is, find the parameters  $\theta \in [0, 2\pi[$  that maximize the non-Gaussianity of  $z(\theta)$ . We use as a measure of non-Gaussianity the excess kurtosis defined as

$$\text{kurt}[z(\theta)] = \frac{\mathbb{E}[(z(\theta) - \mathbb{E}[z(\theta)])^4]}{(\text{Var}[z(\theta)])^2} - 3.$$

**Task 1****a**

$$\begin{aligned}
 E[x] &= \int p(x)x dx = 0 \\
 Var[x] &= \int p(x)(x - \mu)^2 dx = \int p(x)x^2 dx = \sigma^2 \\
 \int p(x) dx &= 1 \quad \Rightarrow \quad \sigma^2 = \int p(x)\sigma^2 dx
 \end{aligned}$$

$$\begin{aligned}
 \nabla(s(x), \lambda_1, \lambda_2, \lambda_3) &= - \int \exp(s(x))s(x) dx \\
 &\quad + \lambda_1 \left( \int \exp(s(x)) dx - 1 \right) \\
 &\quad + \lambda_2 \int \exp(s(x))x dx \\
 &\quad + \lambda_3 \left( \int \exp(s(x))(x^2 - \sigma^2) dx \right)
 \end{aligned}$$

**b**

$$\begin{aligned}
 \frac{\partial \nabla(s(x), \lambda_1, \lambda_2, \lambda_3)}{\partial s(x)} &= - \int \exp(s(x))(1 + s(x)) dx \\
 &\quad + \lambda_1 \int \exp(s(x)) dx \\
 &\quad + \lambda_2 \int \exp(s(x))x dx \\
 &\quad + \lambda_3 \left( \int \exp(s(x))(x^2 - \sigma^2) dx \right) \\
 &= \int \exp(s(x)) \left( -(1 + s(x)) + \lambda_1 + \lambda_2 x + \lambda_3(x^2 - \sigma^2) \right) dx
 \end{aligned}$$

By setting this derivative to zero, we can show that at the extremum,  $s(x)$  is a quadratic function.

$$\begin{aligned}
 \frac{\partial \nabla(s(x), \lambda_1, \lambda_2, \lambda_3)}{\partial s(x)} &\stackrel{!}{=} 0 \\
 \Leftrightarrow \int \exp(s(x)) \left( -(1 + s(x)) + \lambda_1 + \lambda_2 x + \lambda_3(x^2 - \sigma^2) \right) dx &= 0 \\
 \Leftrightarrow \int \exp(s(x)) \left( -1 + \lambda_1 + \lambda_2 x + \lambda_3(x^2 - \sigma^2) \right) dx &= \int \exp(s(x))s(x) dx \\
 \Rightarrow s(x) &= -1 + \lambda_1 + \lambda_2 x + \lambda_3(x^2 - \sigma^2)
 \end{aligned}$$

c

$$p(x) = \exp(s(x)) = \exp(-1 + \lambda_1 + \lambda_2 x + \lambda_3(x^2 - \sigma^2)) \quad (1)$$

Using the constraints, we can determine the  $\lambda$ -values to show that this is actually a Gaussian with zero mean and variance  $\sigma^2$ .

$$\begin{aligned} 1 &= \int p(x) dx = \int \exp(-1 + \lambda_1 + \lambda_2 x + \lambda_3(x^2 - \sigma^2)) dx \\ &= \sqrt{\frac{\pi}{-\lambda_3}} \exp\left(\frac{\lambda_2^2}{-4\lambda_3} + (\lambda_1 - 1 - \lambda_3\sigma^2)\right) \end{aligned}$$

We can then use the variance constraint

$$\begin{aligned} &\int \exp(s(x)) x^2 dx = \sigma^2 \\ \Leftrightarrow &\frac{1}{-2\lambda_3} \underbrace{\sqrt{\frac{\pi}{-\lambda_3}} \exp\left(\frac{\lambda_2^2}{-4\lambda_3} + (\lambda_1 - 1 - \lambda_3\sigma^2)\right)}_{=1} = \sigma^2 \\ \Leftrightarrow &\lambda_3 = -\frac{1}{2\sigma^2} \end{aligned}$$

Hence, our distribution becomes

$$p(x) = \exp(-1/2 + \lambda_1 + \lambda_2 x - \frac{x^2}{2\sigma^2})$$

and the first constraint

$$\begin{aligned} &\sqrt{\frac{\pi}{-\lambda_3}} \exp\left(\frac{\lambda_2^2}{-4\lambda_3} + (\lambda_1 - 1 - \lambda_3\sigma^2)\right) = 1 \\ \Leftrightarrow &\sqrt{2\pi\sigma^2} \exp\left(\lambda_2^2\sigma^2/2 + (\lambda_1 - 1/2)\right) = 1 \\ \Leftrightarrow &(\lambda_1 - 1/2) = -\ln\left(\sqrt{2\pi\sigma^2}\right) \\ \Leftrightarrow &\lambda_1 - 1/2 = -\ln\left(\sqrt{2\pi\sigma^2}\right) - \lambda_2^2\sigma^2/2 \end{aligned}$$

which yields

$$p(x) = \exp\left(-\ln\left[\sqrt{2\pi\sigma^2}\right] + \lambda_2 x - \frac{x^2}{2\sigma^2}\right) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\lambda_2 x - \frac{x^2}{2\sigma^2}\right)$$

Since the mean is zero,  $\lambda_2$  has to disappear (otherwise the Gaussian would be shifted). Therefore, in the end we obtain the expected result

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{x^2}{2\sigma^2}\right) \quad (2)$$

d

We know  $x^*$  is Gaussian distributed. From our constraints we know that  $E[x] = 0$  and  $Var[x] = \sigma^2$ . With these constraints the differential entropy  $H(x)$  for a random variable is maximized by the Gaussian distribution. Hence, there doesn't exist a random variable  $x$  with  $H(x) > H(x^*)$ . Therefore,  $J(x) \geq 0$ .

2

2a

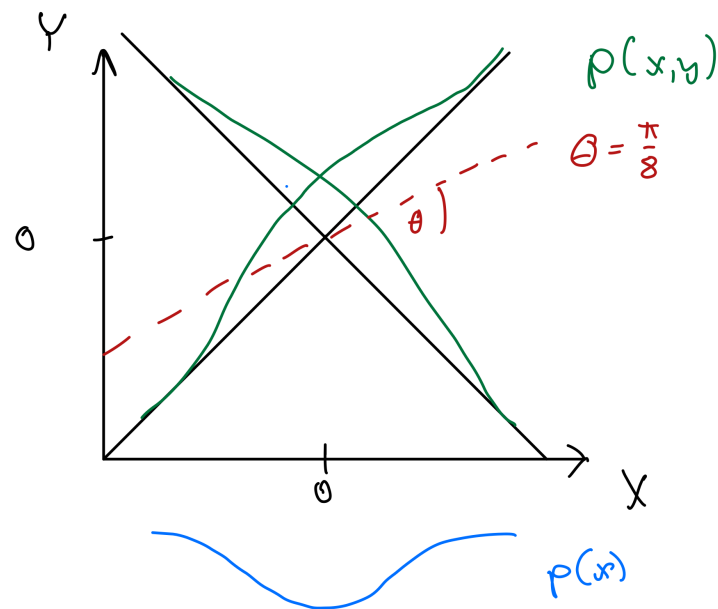


Figure 1: Sketch of  $p(x, y)$ . The black lines indicate where the mass is located and the green distributions how the mass is distributed.

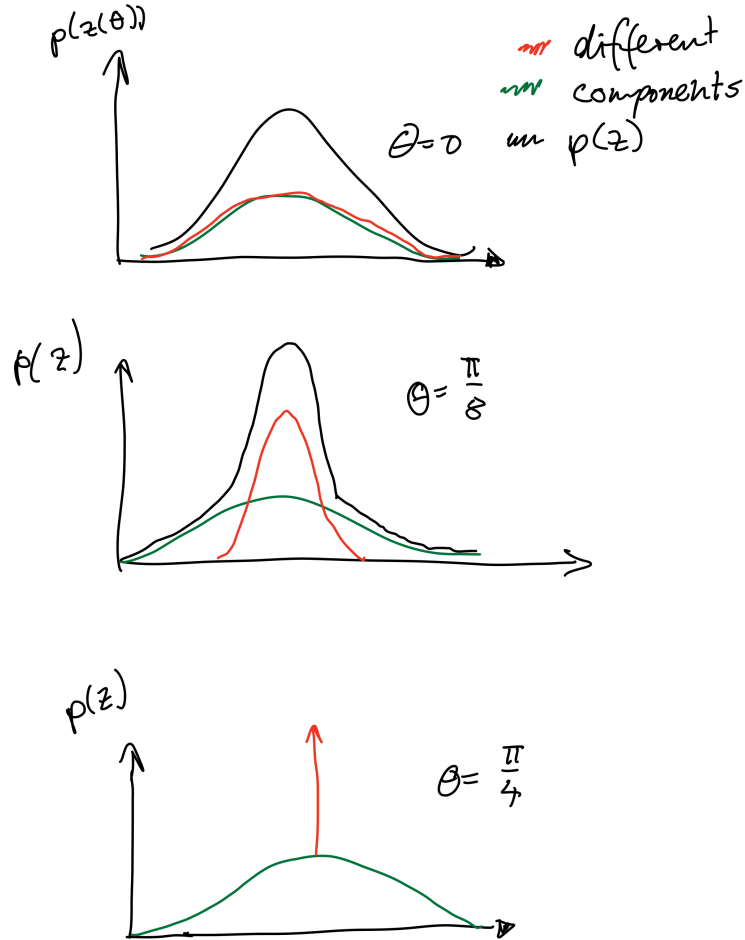


Figure 2:  $z(\theta)$  for  $\theta = 0, \theta = \frac{\pi}{8}, \theta = \frac{\pi}{4}$ . Green and red indicate the different contribution of each of the components. The arrow symbolises the dirac delta function.

## 2b

As the projection of a gaussian distribution is again a gaussian distribution, we can write the distribution  $p(z(\theta))$  as:

$$p(z(\theta)) = \frac{1}{2} \mathcal{N}_1(\theta) + \frac{1}{2} \mathcal{N}_2(\theta) \quad (3)$$

where  $\mathcal{N}_1(\theta)$  is the projection of the distribution of first component (the one with angle  $\frac{\pi}{4}$ ) and  $\mathcal{N}_2(\theta)$  analogously for angle  $-\frac{\pi}{4}$ .

To figure out  $p(z(\theta))$ , we just have to find the projection of the distribution of both components. The means are 0 and will remain 0 under the projections.

The projection of the simgas are given by:

$$\hat{\sigma}_1^2 = \left| \cos \left( \theta - \frac{\pi}{4} \right) \right| \quad (4)$$

$$\hat{\sigma}_2^2 = \left| \sin \left( \theta - \frac{\pi}{4} \right) \right| \quad (5)$$

We ignore the precise intensities in our calculations as only their relative magnitude matter.

Substituting back into  $p(z(\theta))$ :

$$p(z(\theta)) = \frac{1}{2} \mathcal{N}_1(0, \hat{\sigma}_1^2) + \frac{1}{2} \mathcal{N}(0, \hat{\sigma}_2^2) \quad (6)$$

$$\mathbb{V}[Z] = \int z^2 \left( \frac{1}{2} \mathcal{N}(0, \hat{\sigma}_1^2) + \frac{1}{2} \mathcal{N}(0, \hat{\sigma}_2^2) \right) dz = \quad (7)$$

$$= \frac{1}{2} \hat{\sigma}_1^2 + \frac{1}{2} \hat{\sigma}_2^2 \quad (8)$$

Now, we want to find the directions that maximizes the variances. We project the data and therefore  $\theta$  and  $\theta - \pi$  result in the same variance. Thus we consider only  $\cos \left( \theta - \frac{\pi}{4} \right) \geq 0$ :

$$\mathbb{V}[Z] = \frac{1}{2} \hat{\sigma}_1^2 + \frac{1}{2} \hat{\sigma}_2^2 \quad (9)$$

$$\propto \left| \cos \left( \theta - \frac{\pi}{4} \right) \right| + \left| \sin \left( \theta - \frac{\pi}{4} \right) \right| \quad (10)$$

$$= \cos \left( \theta - \frac{\pi}{4} \right) + \left| \sin \left( \theta - \frac{\pi}{4} \right) \right| = L \quad (11)$$

Here, we removed the absolute value around  $\cos$ , as we know it is always positive. For  $\theta \geq \frac{\pi}{4}$ :

$$\frac{\partial L}{\partial \theta} = -\sin \left( \theta - \frac{\pi}{4} \right) + \cos \left( \theta - \frac{\pi}{4} \right) \stackrel{!}{=} 0 \quad (12)$$

$$\iff \cos \left( \theta - \frac{\pi}{4} \right) = \sin \left( \theta - \frac{\pi}{4} \right) \quad (13)$$

$$\iff \theta = \frac{\pi}{2} \quad (14)$$

For  $\theta < \frac{\pi}{4}$ :

$$\frac{\partial L}{\partial \theta} = -\sin \left( \theta - \frac{\pi}{4} \right) - \cos \left( \theta - \frac{\pi}{4} \right) \stackrel{!}{=} 0 \quad (15)$$

$$\iff -\cos \left( \theta - \frac{\pi}{4} \right) = \sin \left( \theta - \frac{\pi}{4} \right) \quad (16)$$

$$\iff \theta = 0 \quad (17)$$

Therefore, the principal components are  $(1, 0)$  and  $(0, 1)$  with angles  $0$  and  $\frac{\pi}{2}$ .

**2c**

$$\frac{\mathbb{E}[(z(\theta) - \mathbb{E}[z(\theta)])^4]}{\mathbb{V}[z(\theta)]^2} = \quad (18)$$

$$= \frac{\mathbb{E}[z(\theta)^4]}{\mathbb{V}[z(\theta)]^2} \quad (19)$$

$$= \frac{\int z^4 \left( \frac{1}{2} \mathcal{N}_1(0, \hat{\sigma}_1^2) + \frac{1}{2} \mathcal{N}(0, \hat{\sigma}_2^2) \right) dz}{\left( \frac{1}{2} \hat{\sigma}_1^2 + \frac{1}{2} \hat{\sigma}_2^2 \right)^2} \quad (20)$$

$$= \frac{\frac{3}{2} (\hat{\sigma}_1^4 + \hat{\sigma}_2^4)}{\left( \frac{1}{2} \hat{\sigma}_1^2 + \frac{1}{2} \hat{\sigma}_2^2 \right)^2} \quad (21)$$

$$= \frac{\frac{3}{2} \cos(4\theta - \pi)}{\left( \frac{1}{2} \left| \cos \left( \theta - \frac{\pi}{4} \right) \right| + \frac{1}{2} \left| \sin \left( \theta - \frac{\pi}{4} \right) \right| \right)^2} \quad (22)$$

$$= \frac{\frac{3}{2} \cos(4\theta - \pi)}{\frac{1}{4} + \frac{1}{2} \left| \cos \left( \theta - \frac{\pi}{4} \right) \right| \left| \sin \left( \theta - \frac{\pi}{4} \right) \right|} \quad (23)$$

Observing that the denominator is minimum for  $\pm \frac{\pi}{2}$  and that the numerator is also maximal for  $\pm \frac{\pi}{2}$ , yields the two solutions  $\theta = \pm \frac{\pi}{2}$ .