

# Linear Regression

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## Resources

- [Lecture](#)
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## 1 Discrete to Continuous Labels

From classification to regression

### 1.1 Task

Given  $X \in \mathcal{X}$ , predict  $Y \in \mathcal{Y}$ , Construct prediction rule  $f : \mathcal{X} \rightarrow \mathcal{Y}$

### 1.2 Performance Measure

- Quantifies knowledge gained.
- Measure of closeness between true label  $Y$  and prediction  $f(X)$ 
  - 0/1 loss:  $loss(Y, f(X)) = 1_{f(X) \neq Y}$ . Risk: probability of error
  - square loss:  $loss(Y, f(X)) = (f(X) - Y)^2$ . Risk: mean square error
- How well does the predictor perform on average?

$$Risk R(f) = \mathbb{E}[loss(Y, f(X))], (X, Y) \sim P_{XY}$$

### 1.3 Bayes Optimal Rule

- ideal goal: Construct prediction rule  $f^* : \mathcal{X} \rightarrow \mathcal{Y}$

$$f^* = \arg \min_f E_{XY}[\text{loss}(Y, f(X))]$$

(Bayes optimal rule)

- Best possible performance:

$$\forall f, R(f^*) \leq R(f)$$

(Bayes Risk)

Problem:  $P_{XY}$  is unknown.

Solution: Training data provides a glimpse of  $P_{XY}$

(observed)  $\{(X_i, Y_i)\} \sim_{i.i.d} P_{XY}$  unknown

## 2 Machine Learning Algorithm

- Model based approach: use data to learn a model for  $P_{XY}$
- Model-free approach: use data to learn mapping directly

### 2.1 Empirical Risk Minimization (model-free)

- Optimal predictor:

$$f^* = \arg \min_f \mathbb{E}[(f(X) - Y)^2]$$

- Empirical Minimizer:

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (f(X) - Y)^2$$

$\mathcal{F}$  is the class of predictors:

- Linear
- Polynomial
- Nonlinear

## 3 Linear Regression

$$f(\vec{X}) = \sum_{i=0}^p \beta_0 X^i = \vec{X}^T \vec{\beta}, \text{ where } X^0 = 1, \vec{\beta} = [\beta_0, \dots, \beta_p]^T$$

$$\hat{\vec{\beta}} = \arg \min_{\vec{\beta}} (A^T \vec{\beta} - \vec{Y})^T (A^T \vec{\beta} - \vec{Y}), \text{ where } A = [\vec{X}_1, \dots, \vec{X}_n]$$

$$J(\beta) = (A^T \vec{\beta} - \vec{Y})^T (A^T \vec{\beta} - \vec{Y})$$

$$\begin{aligned} \frac{\partial J(\vec{\beta})}{\partial \vec{\beta}} &= \frac{\partial (A^T \vec{\beta} - \vec{Y})^T (A^T \vec{\beta} - \vec{Y})}{\partial \vec{\beta}} \\ &= \frac{\partial \vec{\beta}}{\partial \text{den}} \end{aligned}$$