Homework 1

MLE, MAP ESTIMATES; LINEAR AND LOGISTIC REGRESSION

CMU 10-701: MACHINE LEARNING (SPRING 2017)

OUT: Jan 31 DUE: Feb 10, 11:59 PM NAME: Mengwen He ADREW ID: mengwenh

Part A: Multiple Choice Questions

- 1. For each case listed below, what type of machine learning problem does it belong to?
 - (a) Advertisement selection system, which can predict the probability whether a customer will click on an ad or not based on the search history.

Answer: B. Supervised learning: Regression

A task, with ads click statistics and search history as input data, outputs the prediction of continuous probability of clicking an ad.

(b) U.S post offices use a system to automatically recognize handwriting on the envelope.

Answer: A. Supervised learning: Classification

A task, with handwriting samples and their labels as input data, outputs the prediction of discrete numbers/letters of a handwriting on the envelope.

(c) Reduce dimensionality using principal components analysis (PCA).

Answer: C. Unsupervised learning

A task, without training data as input, outputs a description of reduced dimensionality.

(d) Trading companies try to predict future stock market based on current market conditions.

Answer:

• A. Supervised learning: Classification

A task, with current market conditions as input, outputs the prediction of discrete stock market conditions, say bull or bear market.

• B. Supervised learning: Regression

A task, with current market conditions as input, outputs the prediction of continuous stock market conditions, say stock price.

(e) Repair a digital image that has been partially damaged.

Answer:

• A. Supervised learning: Classification

A task, with digital images database as input, outputs the prediction of discrete pixel value in the damaged zone.

• B. Supervised learning: Regression

A task, with digital images database as input, outputs the prediction of continuous parameters of a color distribution model to form a discrete patch to cover the damaged zone.

• C. Unsupervised learning

A task, without training data as input, outputs a description of a damaged pixel according to its surrounding pixel values, e.g. interpolation or extrapolation.

Type of machine learning problem:

A. Supervised learning: Classification

- B. Supervised learning: Regression
- C. Unsupervised learning
- 2. For four statements below, which one is wrong?
 - A. In maximum a posterior (MAP) estimate, data overwhelms the prior if we have enough data.
 - B. There are no parameters in non-parameter models.
 - C. $P(X \cap Y \cap Z) = P(Z|X \cap Y)P(Y|X)P(X)$.
 - D. Compared with parametric models, non-parameter models are flexible, since they don't make strong assumptions.

Answer: B. There are no parameters in non-parametirc models. is wrong.

Non-parametric model still needs parameters to describe the model, but the number of model's parameters is not fixed and will grow with the data size. The non-parametric only means that there is weak assumption on the model's type defined by a fixed number of parameters.

3. There are about 12% people in U.S. having breast cancer during their lifetime. One patient has a positive result for the medical test. Suppose the sensitivity of this test is 90%, meaning the test will be positive with probability 0.9 if one really has cancer. The false positive is likely to be 2\%. Then what is the probability this patient actually having cancer based on Bayes Theorem? C. 12%

A. 90%

B. 86%

D. 43%

Answer: B. 86%

- P(C=1)=0.12
- P(T=1|C=1) = 0.90
- P(T=1|C=0) = 0.02

$$\begin{array}{lcl} P(C=1|T=1) & = & \frac{P(T=1|C=1)P(C=1)}{P(T=1|C=1)P(C=1)+P(T=1|C=0)P(C=0)} \\ & = & \frac{0.90\times0.12}{0.90\times0.12+0.02\times0.88} \\ & = & 0.86 \end{array}$$

- 4. What is the most suitable error function for gradient **descent** using logistic regression?
 - A. The negative log-likelihood function
 - B. The number of mistakes
 - C. The squared error
 - D. The log-likelihood function

Answer: A. The negative log-likelihood function

The negative log-likelihood function of a logistic regression is a convex function.

Part B, Problem 1: Bias-Variance Decomposition

Consider a p-dimensional vector $\vec{x} \in \mathbb{R}^p$ drawn from a Gaussian distribution with an identity covariance matrix $\Sigma = I_p$ and an unknown mean $\vec{\mu}$, i.e. $\vec{x} \sim \mathcal{N}(\vec{\mu}, I_p)$. Our goal is to evaluate the effectiveness of an estimator $\hat{\vec{\mu}} = f(\vec{x})$ of the mean from only a single sample (i.e. n = 1) by measuring its mean squared error $\mathbb{E}[||\hat{\vec{\mu}} - \vec{\mu}||^2]$, where $||\cdot||^2$ is the squared Euclidean norm and the expectation is taken over the data generating distribution.

Note that for any estimator $\hat{\vec{\theta}}$ of a parameter vector $\vec{\theta}$, its mean squared error can be decomposed as:

$$\mathbb{E}[||\hat{\vec{\theta}} - \vec{\theta}||^2] = ||Bias[\hat{\vec{\theta}}]||^2 + trace(Var[\hat{\vec{\theta}}])$$

where,

$$Bias[\hat{\vec{\theta}}] = \mathbb{E}[\hat{\vec{\theta}}] - \vec{\theta} \ and \ Var[\hat{\vec{\theta}}] = \mathbb{E}[(\hat{\vec{\theta}} - \vec{\theta})(\hat{\vec{\theta}} - \vec{\theta})]$$

1. Derive the maximum likelihood estimator:

$$\hat{\vec{\mu}}_{MLE} = \arg\max_{\vec{\mu}} P(\vec{x}|\vec{\mu})$$

Answer:

What is its mean squared error?

Answer:

2. Derive the ℓ_2 -regularized maximum likelihood estimator:

$$\hat{\vec{\mu}}_{MLE} = \arg\max_{\vec{\mu}} \log P(\vec{x}|\vec{\mu}) - \lambda ||\vec{\mu}||^2$$

Answer:

What is its mean squared error?

Answer:

3. Consider an estimator of the form $\hat{\vec{\mu}}_{SCALE} = c\vec{x}$ where $c \in \mathbb{R}$ is a constant scaling factor. Find the value c^* that minimizes its mean squared error:

$$c^* = \arg\min_{c} \mathbb{E}[||c\vec{x} - \vec{\mu}||^2]$$

Answer:

What is the corresponding minimum mean squared error?

Answer:

4. Consider the James-Stein estimator:

$$\hat{\vec{\mu}}_{JS} = \left(1 - \frac{p-2}{||\vec{x}||^2}\right)\vec{x}$$

Note that $\hat{\vec{\mu}}_{JS}$ can be written as $\vec{x} - g(\vec{x})$ where $g(\vec{x}) = \frac{p-2}{||\vec{x}||^2} \vec{x}$. This allows us to separate the mean squared error into three parts:

$$\begin{array}{lcl} \mathbb{E}[||\hat{\vec{\mu}} - \vec{\mu}||^2] & = & \mathbb{E}[||\vec{x} - g(\vec{x} - \vec{\mu})||^2] \\ & = & \mathbb{E}[\vec{x}^T\vec{x} - 2\vec{x}^T\vec{\mu} + \vec{\mu}^T\vec{\mu} + g(\vec{x}^Tg(\vec{x}) - 2\vec{x}^Tg(\vec{x}) + 2\vec{\mu}^Tg(\vec{x})] \\ & = & \mathbb{E}[||\vec{x} - \vec{\mu}||^2] + \mathbb{E}[||g(\vec{x})||^2] - 2\mathbb{E}[(\vec{x} - \vec{\mu})^Tg(\vec{x})] \end{array}$$

Furthermore, from Stein's lemma, we know that:

$$\mathbb{E}[(\vec{x} - \vec{\mu})^T g(\vec{x})] = \mathbb{E}\left[\sum_{j=1}^p \frac{\partial}{\partial x_j} g_j(\vec{x})\right]$$

- Find $\mathbb{E}[||\vec{x} \vec{\mu}||^2]$. **Answer:**
- Find $\mathbb{E}[||g(\vec{x})||^2]$. (Hint: your answer will include $\mathbb{E}[||\vec{x}||^{-2}]$) **Answer:**
- Show that:

$$\frac{\partial}{\partial x_j}g_j(\vec{x}) = \frac{||\vec{x}||^2 - 2x_j^2}{||\vec{x}||^4}$$

where x_j is the jth element of x and $g_j(\vec{x})$ is the jth element of $g(\vec{x})$.

Answer:

- What is the resulting mean squred error. (Hint: your answer will include $\mathbb{E}[||\vec{x}||^{-2}]$) Answer:
- 5. Qualitatively compare these estimators, noting any similarities between them. How does regularization affect an estimator's bias and variance? Which estimator would you choose to approximate $\vec{\mu}$ from real data about which you have no prior knowledge? How does the data dimensionality p affect your answer?

Answer:

Part B, Problem 2: Linear Regression

Suppose we observe N data pairs $\{(x_i, y_i)\}_{i=1}^N$, where y_i is generated by the following rule:

$$y_i = \vec{x}_i^T \vec{\beta} + \epsilon_i$$

where $\vec{x}_i, \vec{\beta} \in \mathbb{R}^d$, and ϵ_i is an i.i.d random noise drawn from the Gaussian Distribution:

$$\epsilon_i \sim \mathcal{N}(0, \sigma^2)$$

with a known constant σ . We further denote $\vec{Y} = [y_1, y_2, ..., y_N]^T$ and $X = [\vec{x}_1, \vec{x}_2, ..., \vec{x}_N]^T$.

Now, we are interested in estimating $\vec{\beta}$ from the observed data.

- Derive the likelihood function $\mathcal{L}(\vec{\beta})$
- Show that the MLE estimator $\hat{\vec{\beta}}_{MLE}$ of $\vec{\beta}$ is equivalent to the solution of the following linear regression problem:

$$\min_{\vec{\beta}} \frac{1}{2} ||\vec{Y} - X\vec{\beta}||_2^2 \tag{1}$$

Part B, Problem 3: MLE, MAP and Logistic Regression

Part C: Programming Exercise