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1 Introduction

2 Decision Theory

2.1 Terms

- Feature Space:
 - Feature: a distinctive characteristic or quality of the object
 - Feature vector: combine more than one feature as a vector
 - **Feature space**: The space defined by the feature vectors
- Classifiers:
 - **Decision regions**: a classifier partitions the feature space into class-corresponding decision regions.
 - **Decision boundaries**: the borders between the decision regions.

2.2 Bayes Rule

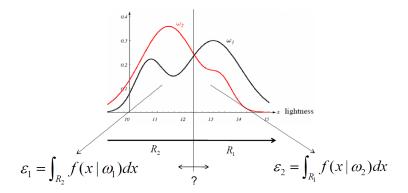
$$P(w_i|x) = \frac{P(x,w_i)}{P(x)} = \frac{P(x|w_i)P(w_i)}{\sum_{k=1}^{C} P(x|w_k)P(w_k)}$$
(1)

- Posterior Probability $P(w_i|x)$: the conditional probability of correct class being w_i given that feature value x has been observed.
- Evidence P(x): the total probability of observing the feature value of x.
- **Likelihood** $P(x|w_i)$: the conditional probability of observing a feature value of x given that the correct class is w_i .

- Prior Probability $P(w_i)$: the probability of class w_i , $\sum_{k=1}^{C} P(w_k) = 1$.
- Bayes Classifiers decide on the class that has the largest posterior probability $(\max_{w_i} P(w_i|x))$. They are statistically the best classifiers i.e. they are minimum error classifiers (optimal).

2.3 Minimum Probability of Error

- $\epsilon = P(error|class)$: probability of assigning x to the wrong class w.
- $P_e = \sum_{k=1}^{C} P(w_k) \epsilon_k$: total probability of error.



For the two class case shown above, we want to minimize P_e as below:

$$P_{e} = P(w_{1})\epsilon_{1} + P(w_{2})\epsilon_{2}$$

$$= P(w_{1})\int_{R_{2}} f(x|w_{1})dx + P(w_{2})\int_{R_{1}} f(x|w_{2})dx$$

$$= P(w_{1})(1 - \int_{R_{1}} f(x|w_{1})dx) + P(w_{2})\int_{R_{1}} f(x|w_{2})dx$$

$$= P(w_{1}) + \int_{R_{1}} (P(w_{2})f(x|w_{2}) - P(w_{1})f(x|w_{1}))dx$$
(2)

To minimize P_e , we want $P(w_2)f(x|w_2) - P(w_1)f(x|w_1)$ to be always negative (< 0) in the region R_1 :

$$P(w_1)f(x|w_1) - P(w_2)f(x|w_2) > 0 \Rightarrow w_1 P(w_1)f(x|w_1) - P(w_2)f(x|w_2) < 0 \Rightarrow w_2$$
(3)

2.4 Likelihood Ratio

- Likelihood ratio: $l(x) = \frac{f(x|w_1)}{f(x|w_2)}$
- Log likelihood ratio: $ln(l(x)) = ln(\frac{f(x|w_1)}{f(x|w_2)}) = ln(f(x|w_1)) ln(f(x|w_2))$
- Ratio of a priori probabilities: $T = \frac{P(w_2)}{P(w_1)}$
- Log ratio of a priori probabilities: $ln(T) = ln(\frac{P(w_2)}{P(w_1)}) = ln(P(w_2)) ln(P(w_1))$

$$ln(l(x)) = ln(\frac{f(x|w_1)}{f(x|w_2)}) > ln(\frac{P(w_2)}{P(w_1)}) = ln(T) \quad \Rightarrow \quad w_1$$

$$ln(l(x)) = ln(\frac{f(x|w_1)}{f(x|w_2)}) < ln(\frac{P(w_2)}{P(w_1)}) = ln(T) \quad \Rightarrow \quad w_2$$

$$(4)$$

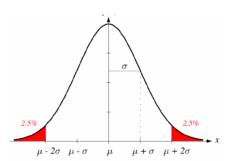
2.4.1 Likelihood as Gaussian distribution

Assume likelihood $f(x|w_i)$ are Gaussian distributions with mean μ_i and variance σ_i^2 .

$$f(x|w_i) = \frac{1}{\sqrt{2\pi\sigma_i^2}} \exp\left(-\frac{(x-\mu_i)^2}{2\sigma_i^2}\right)$$
 (5)

The log likelihood ratio:

$$f(x \mid \omega_i)$$



$$ln(l(x)) = ln\left(\frac{\frac{1}{\sqrt{2\pi\sigma_1^2}}\exp\left(-\frac{(x-\mu_1)^2}{2\sigma_1^2}\right)}{\frac{1}{\sqrt{2\pi\sigma_2^2}}\exp\left(-\frac{(x-\mu_2)^2}{2\sigma_2^2}\right)}\right)$$

$$= ln\left(\frac{\sigma_2}{\sigma_1}\right) + \frac{(x-\mu_2)^2}{2\sigma_2^2} - \frac{(x-\mu_1)^2}{2\sigma_1^2}$$
(6)

Case: $\sigma_1 = \sigma_2 = \sigma$

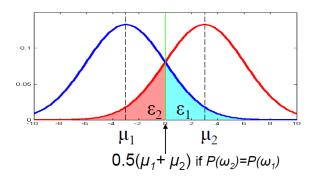
$$ln(l(x)) = \frac{2x(\mu_1 - \mu_2) - (\mu_1^2 - \mu_2^2)}{2\sigma^2}$$
 (7)

$$x(\mu_{1} - \mu_{2}) - \frac{\mu_{1}^{2} - \mu_{2}^{2}}{2} > \sigma^{2} ln(\frac{P(w_{2})}{P(w_{1})}) \Rightarrow w_{1}$$

$$x(\mu_{1} - \mu_{2}) - \frac{\mu_{1}^{2} - \mu_{2}^{2}}{2} < \sigma^{2} ln(\frac{P(w_{2})}{P(w_{1})}) \Rightarrow w_{2}$$
(8)

If $P(w_1) = P(w_2)$

$$x = \frac{\mu_1 + \mu_2}{2} \tag{9}$$



Case: $\sigma_1 \neq \sigma_2$

$$\ln\left(\frac{\sigma_2}{\sigma_1}\right) + \frac{1}{2}\left(\frac{x-\mu_2}{\sigma_2}\right)^2 - \frac{1}{2}\left(\frac{x-\mu_1}{\sigma_1}\right)^2 \underset{\omega_2}{\overset{\omega_1}{\gtrless}} \ln\left(\frac{P(\omega_2)}{P(\omega_1)}\right)$$

$$ax^2 + bx + c \ge 0$$

$$(x-x_1)(x-x_2) \ge 0$$