

# Embedded Systems

## 1. Introduction

Lothar Thiele

# Organization

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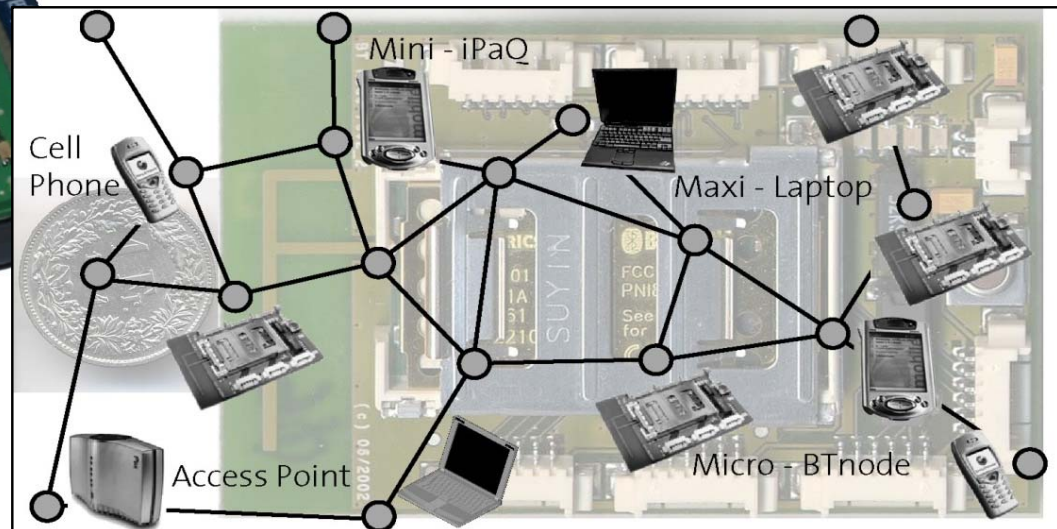
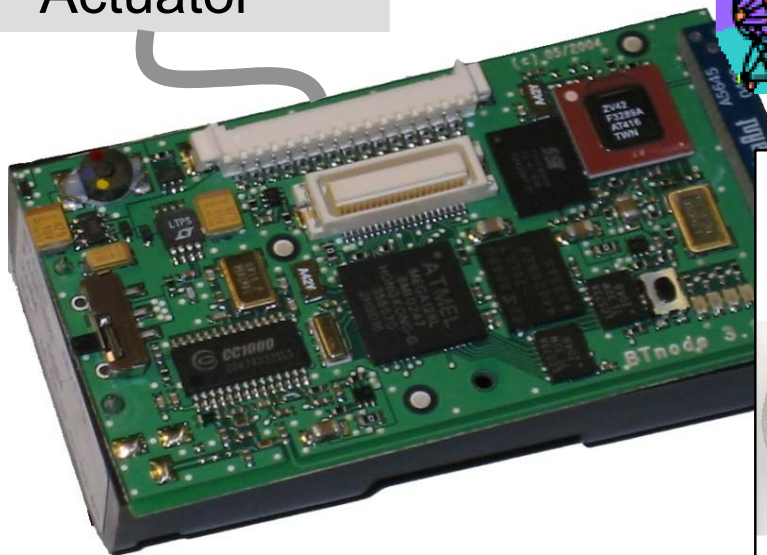
- ▶ **WWW:** <http://www.tik.ee.ethz.ch/tik/education/lectures/ES/>
- ▶ **Lecture:** Lothar Thiele, thiele@ethz.ch
- ▶ **Coordination:** Olga Saukh, olga.saukh@tik.ee.ethz.ch
- ▶ **References:**
  - *P. Marwedel: Embedded System Design (paperback), Springer Verlag, December 2011, ISBN: 978-94-007-0256-1.*
  - *G.C. Buttazzo: Hard Real-Time Computing Systems. Springer Verlag, 2011.*
  - W. Wolf: Computers as Components – Principles of Embedded System Design. Morgan Kaufman Publishers, 2012.
  - J. Teich: Digitale Hardware/Software Systeme, Springer Verlag, 2007.
- ▶ The slides contain material of J. Rabaey, K. Keuzer, Wayne Wolf, Peter Marwedel, Philip Koopman and from the above books of J. Teich, G.C. Buttazzo, W. Wolf and P. Marwedel.

# Communicating Embedded Systems

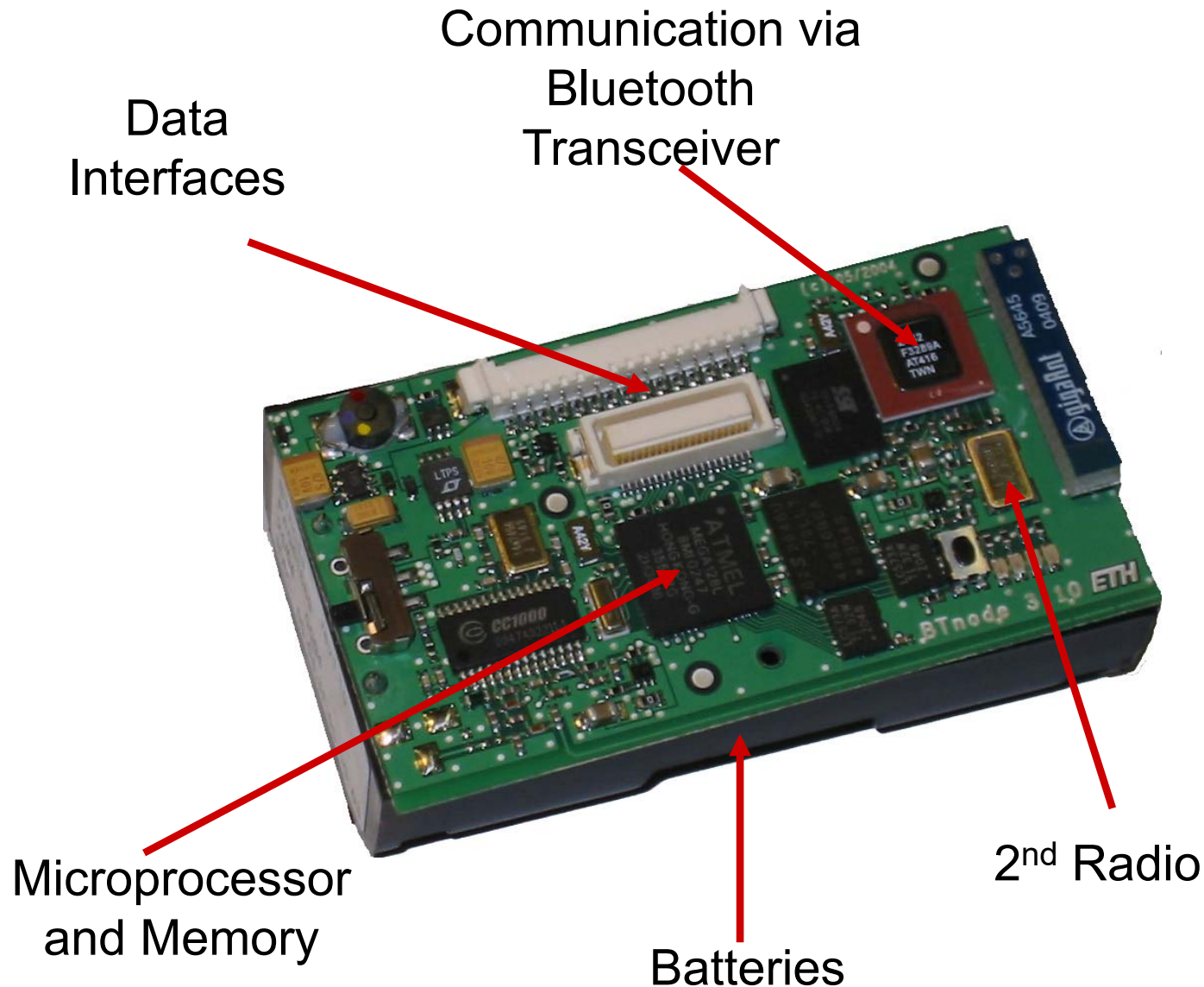
- ▶ Example: BTnodes
  - complete platform including OS
  - especially suited for pervasive computing applications



Sensor  
Actuator



# BTnode Platform



- ▶ generic platform for wireless distributed embedded computing
- ▶ complete platform including OS
- ▶ especially suited for pervasive computing applications (IoT)

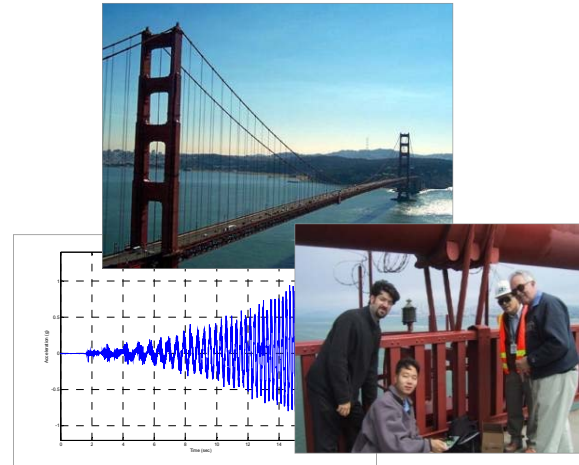


# Where are sensor nodes used?

## Logistics



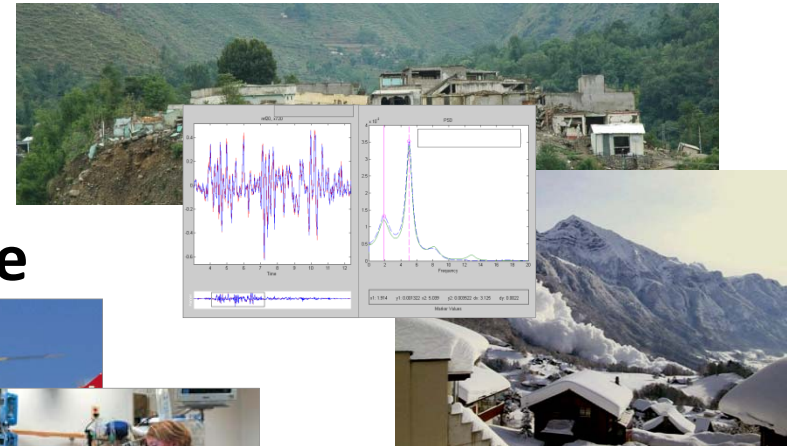
## Maintenance



## Factory Automation



## Natural Hazards



## Building Automation



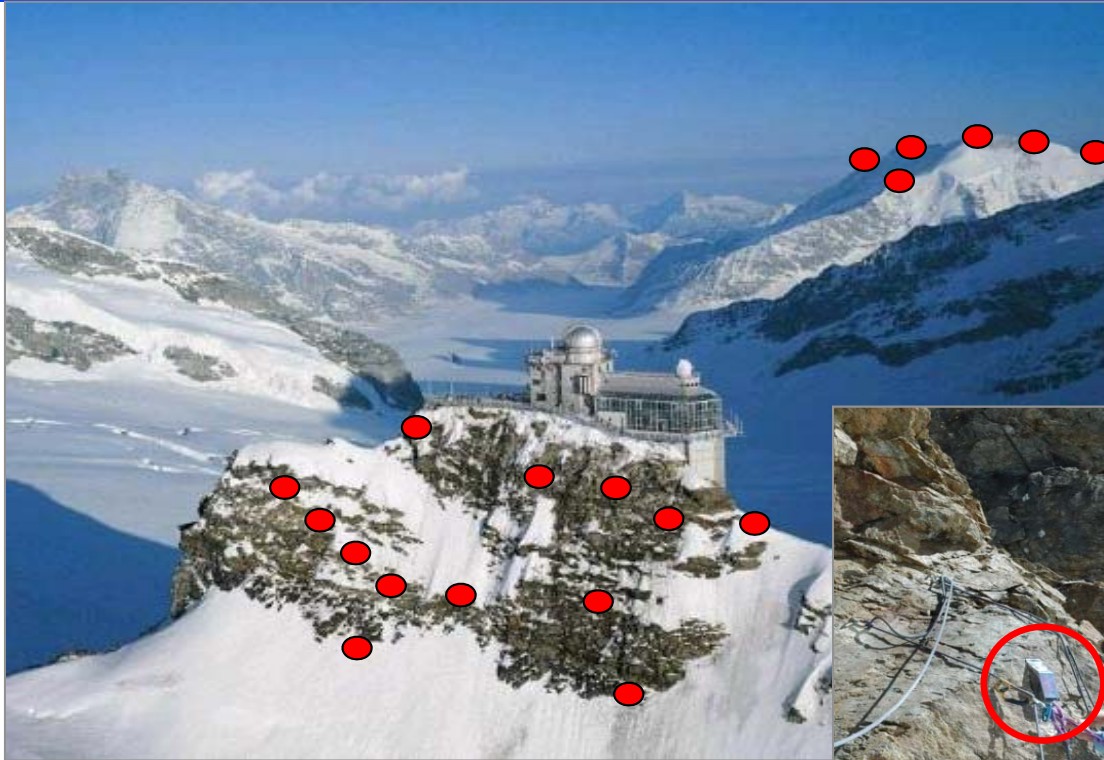
## Health Care



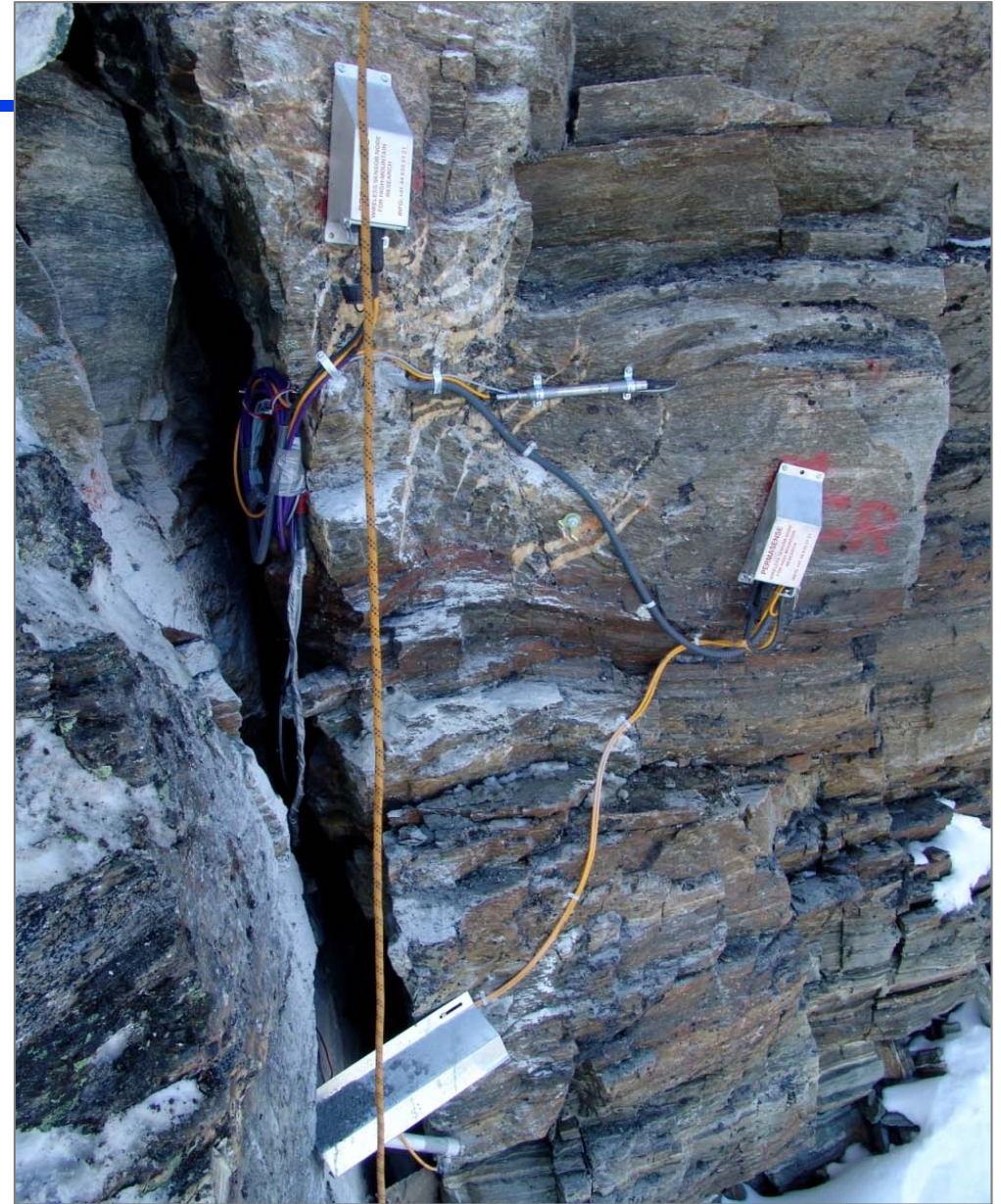


# PermaSense Project

► Jan Beutel – ETH Zurich



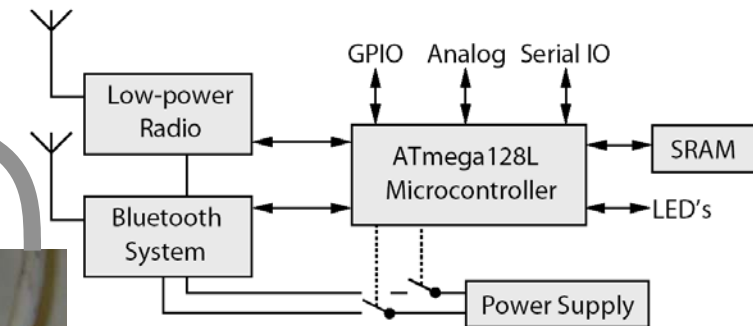
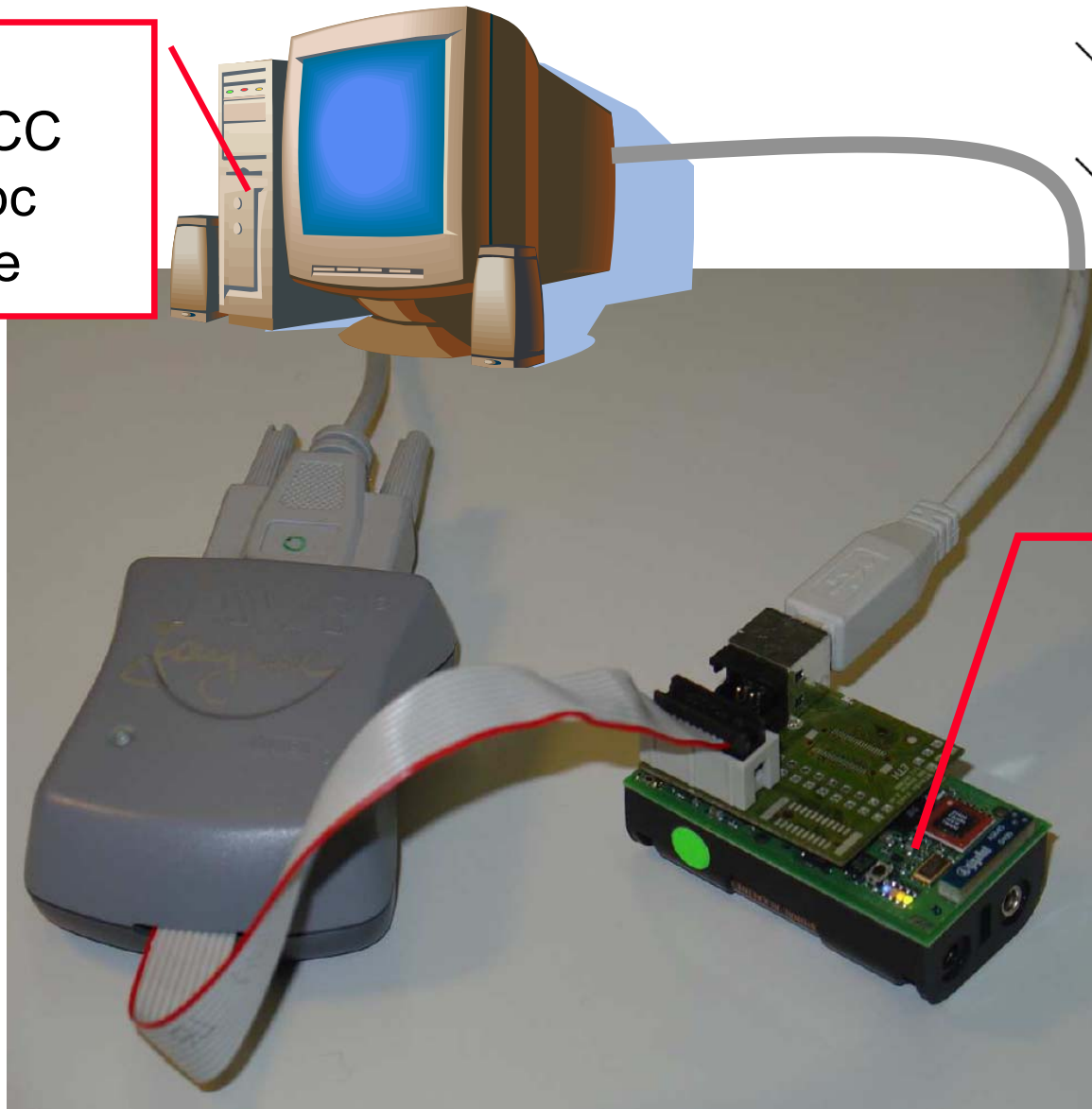






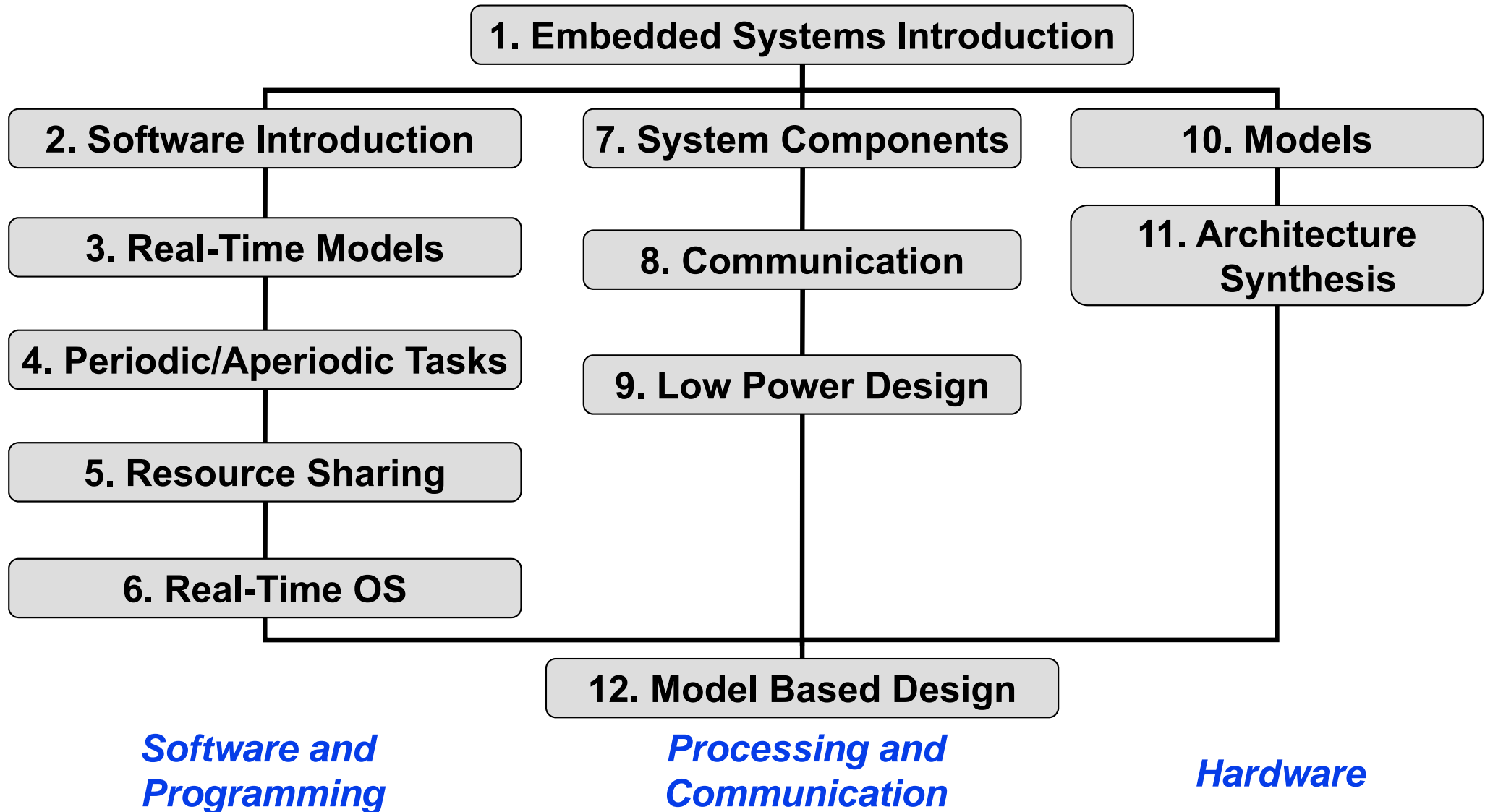
# Development in ES Exercise

Linux  
GNU GCC  
AVR libc  
Eclipse

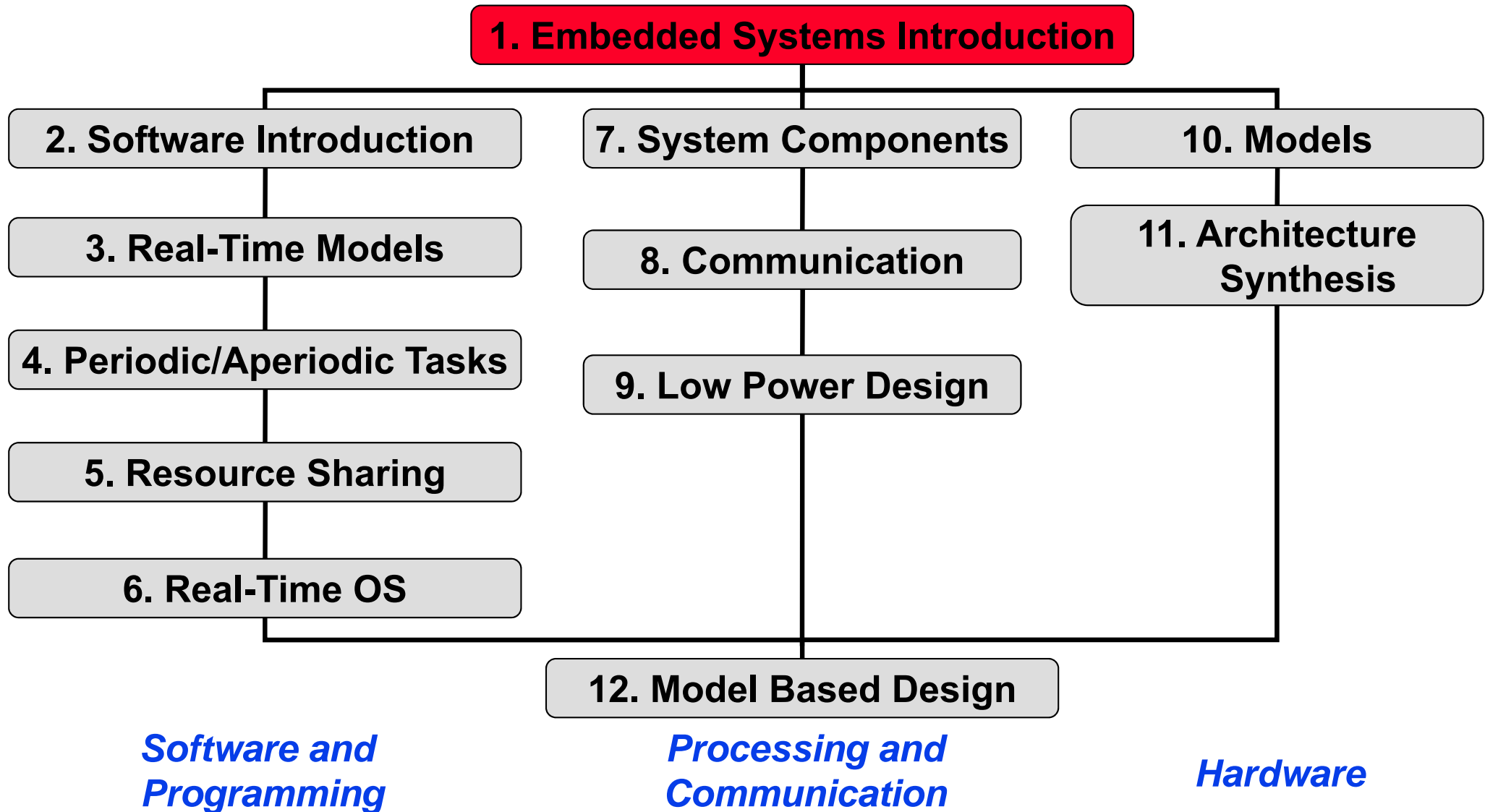




# Contents of Course

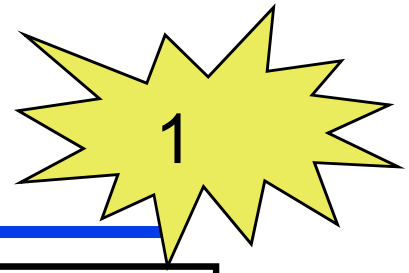


# Contents of Course



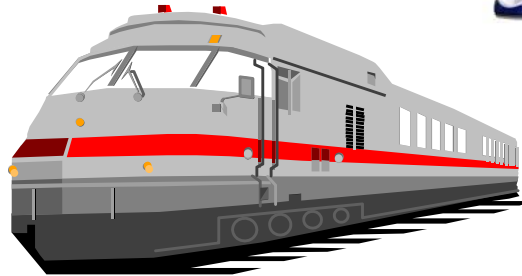


# Embedded Systems



Embedded systems (ES) = **information processing systems embedded into a larger product**

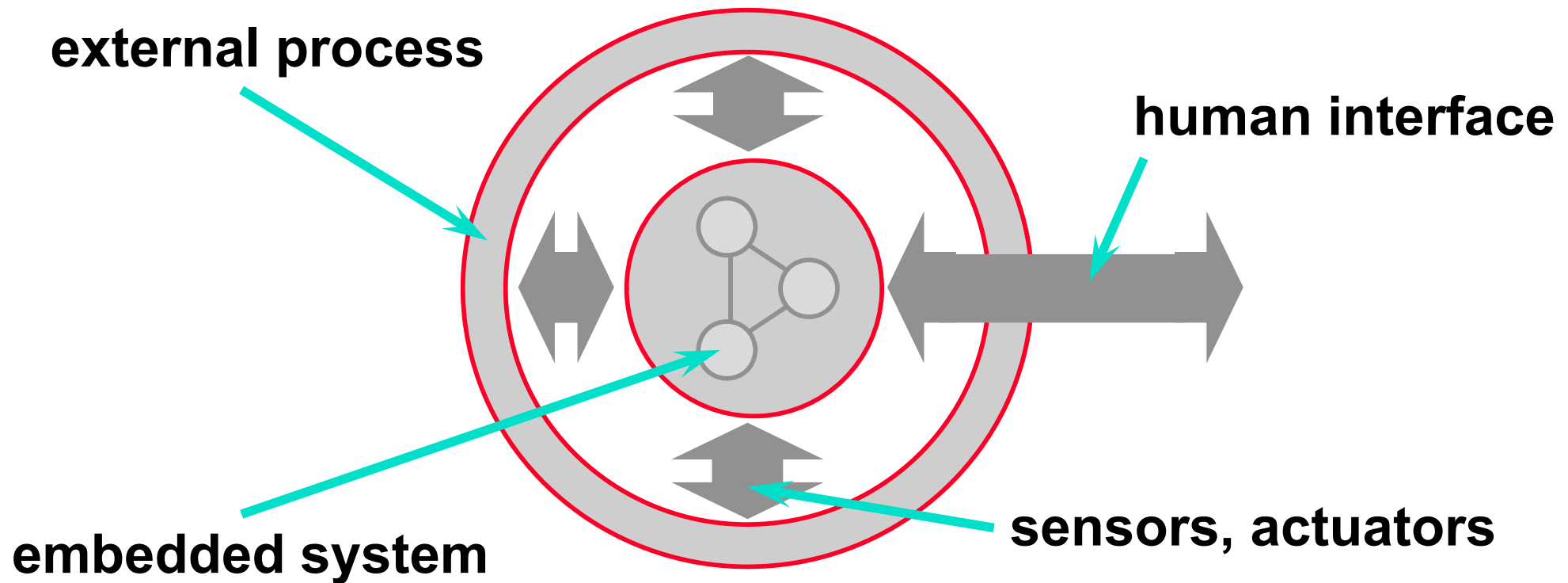
Examples:



Main reason for buying often is **not** information processing

# Embedded Systems

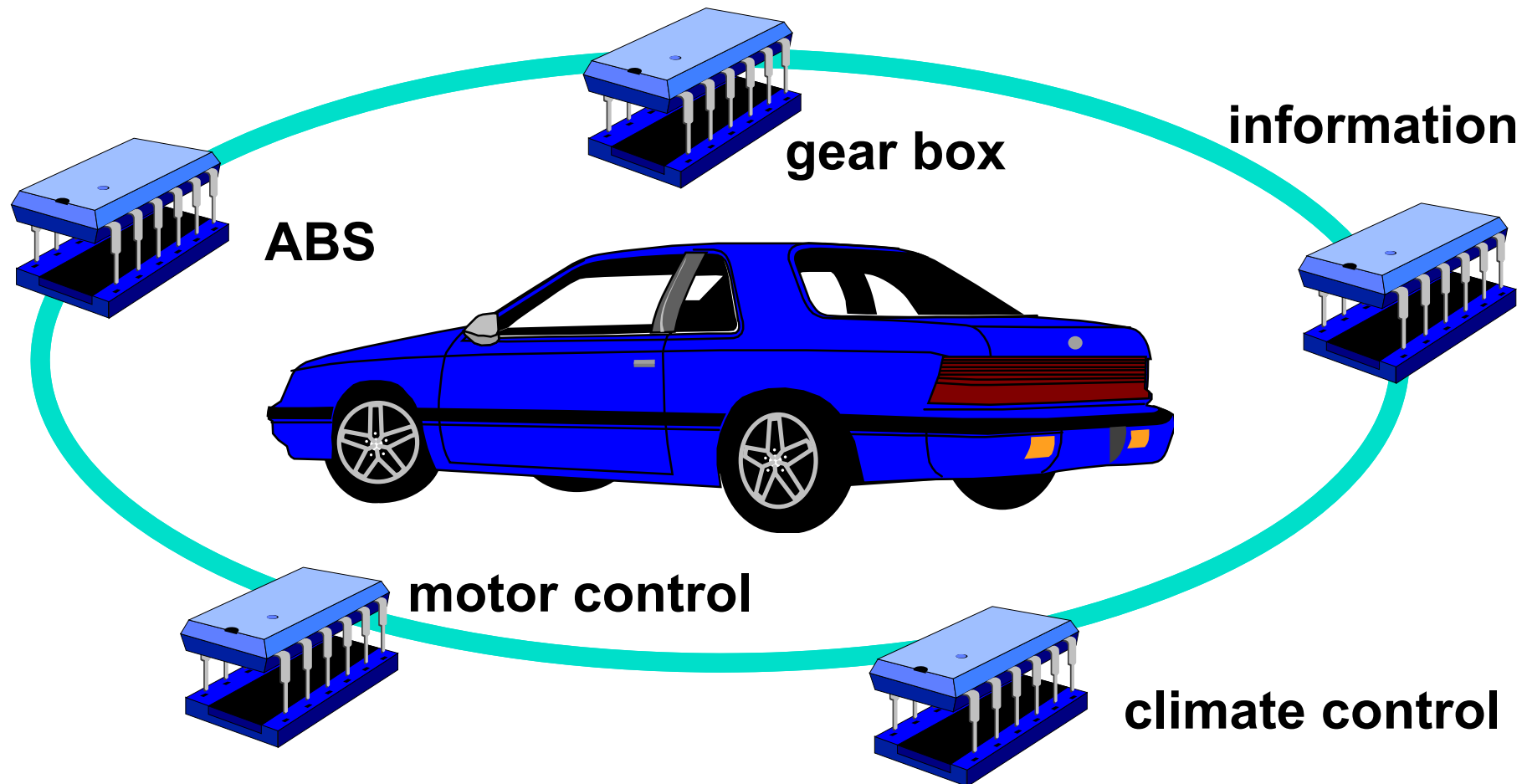
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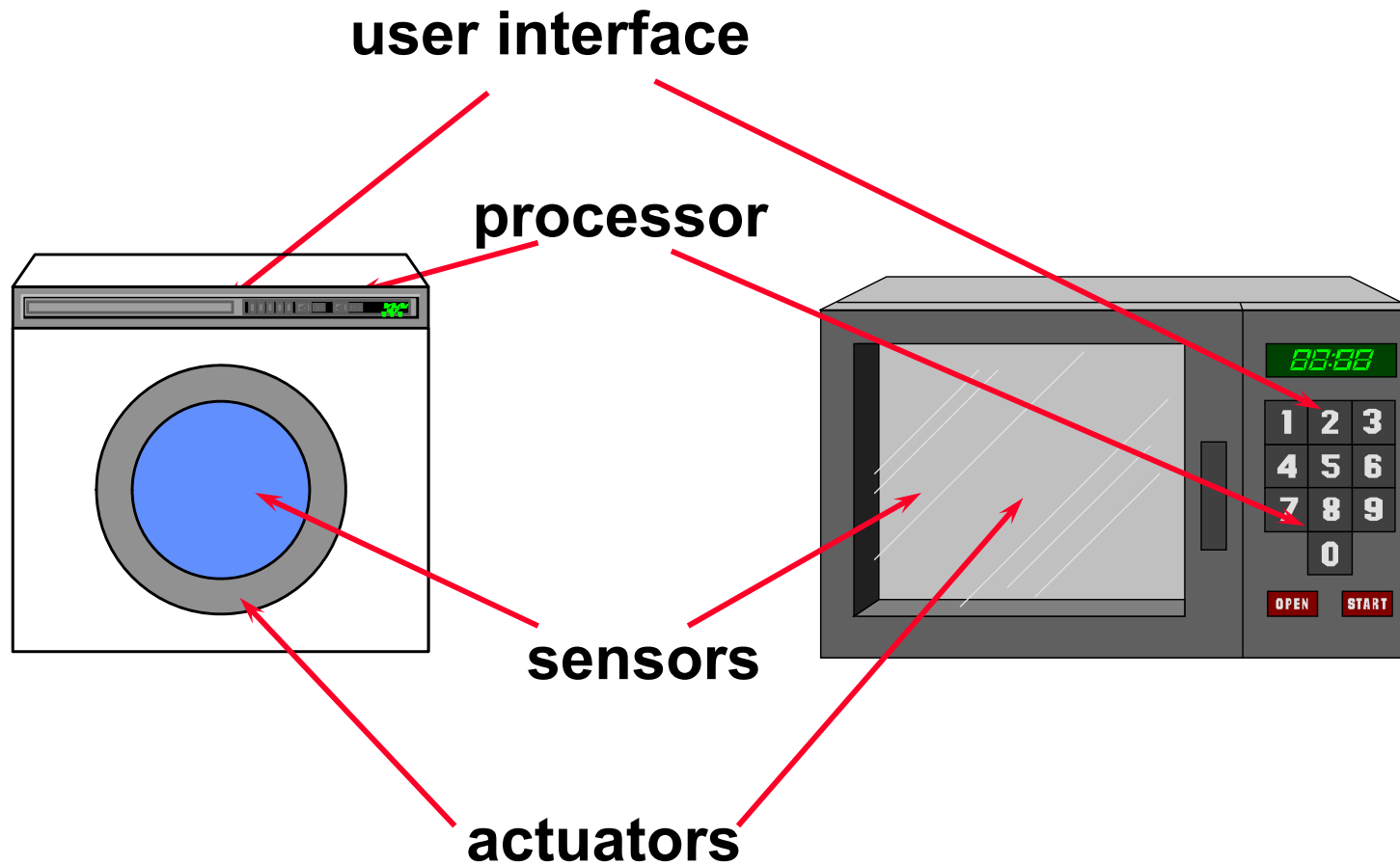
# Examples of Embedded Systems

Car as an integrated control-, communication and information system.



# Examples of Embedded Systems

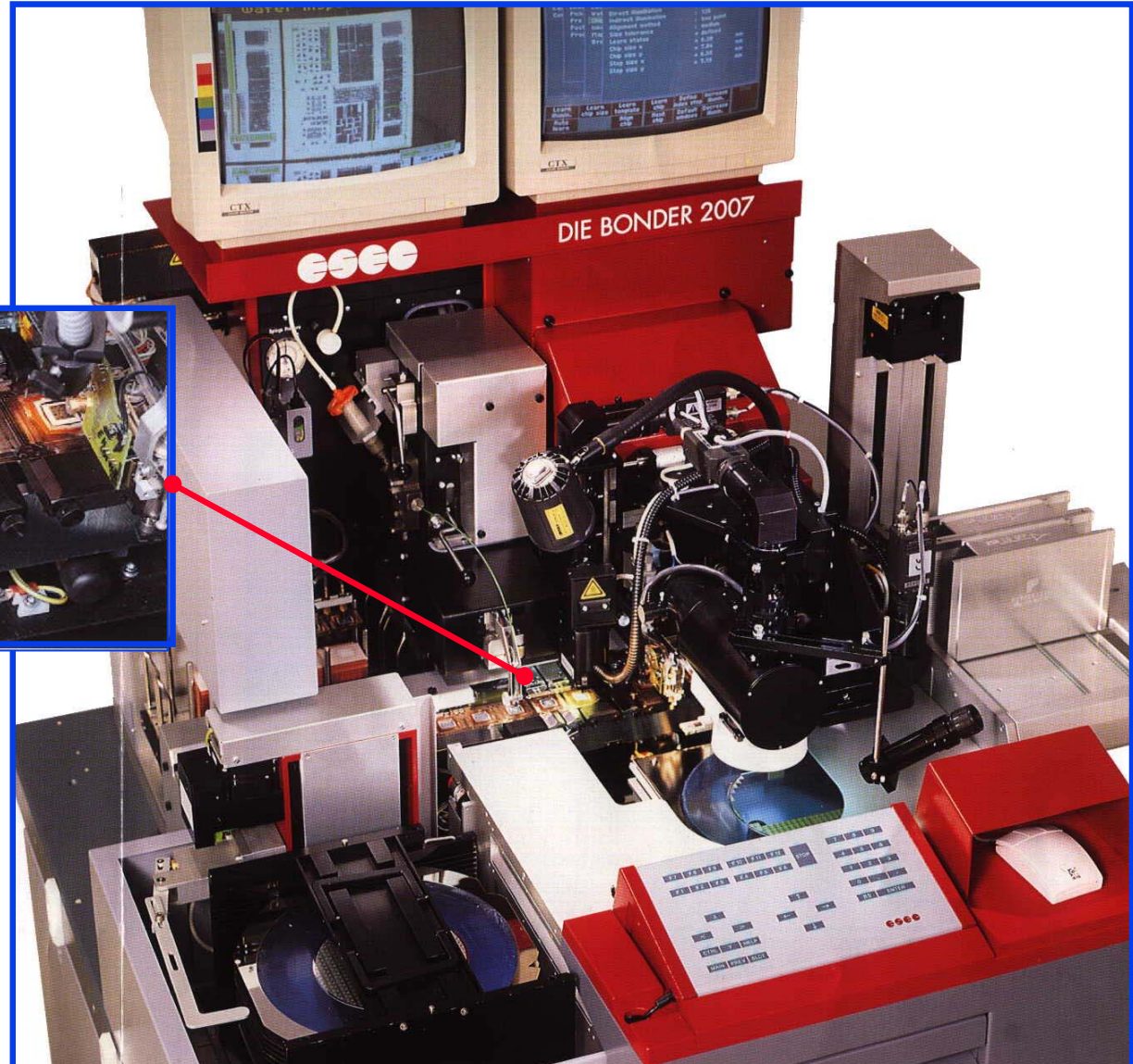
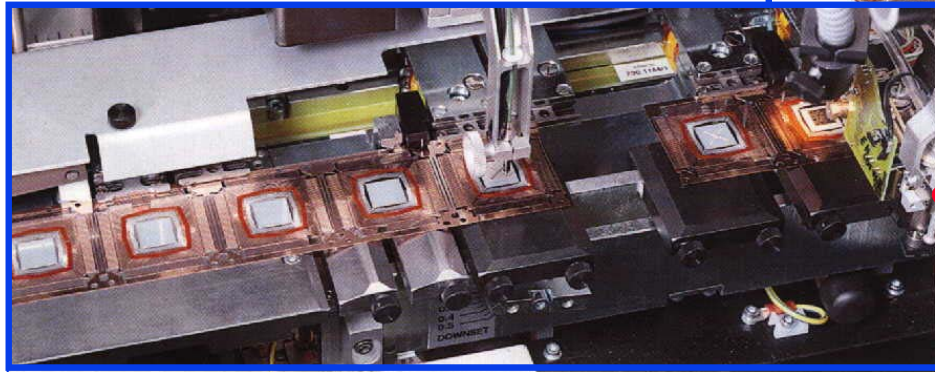
Consumer electronics, for example MP3 Audio, digital camera, home electronics, ....





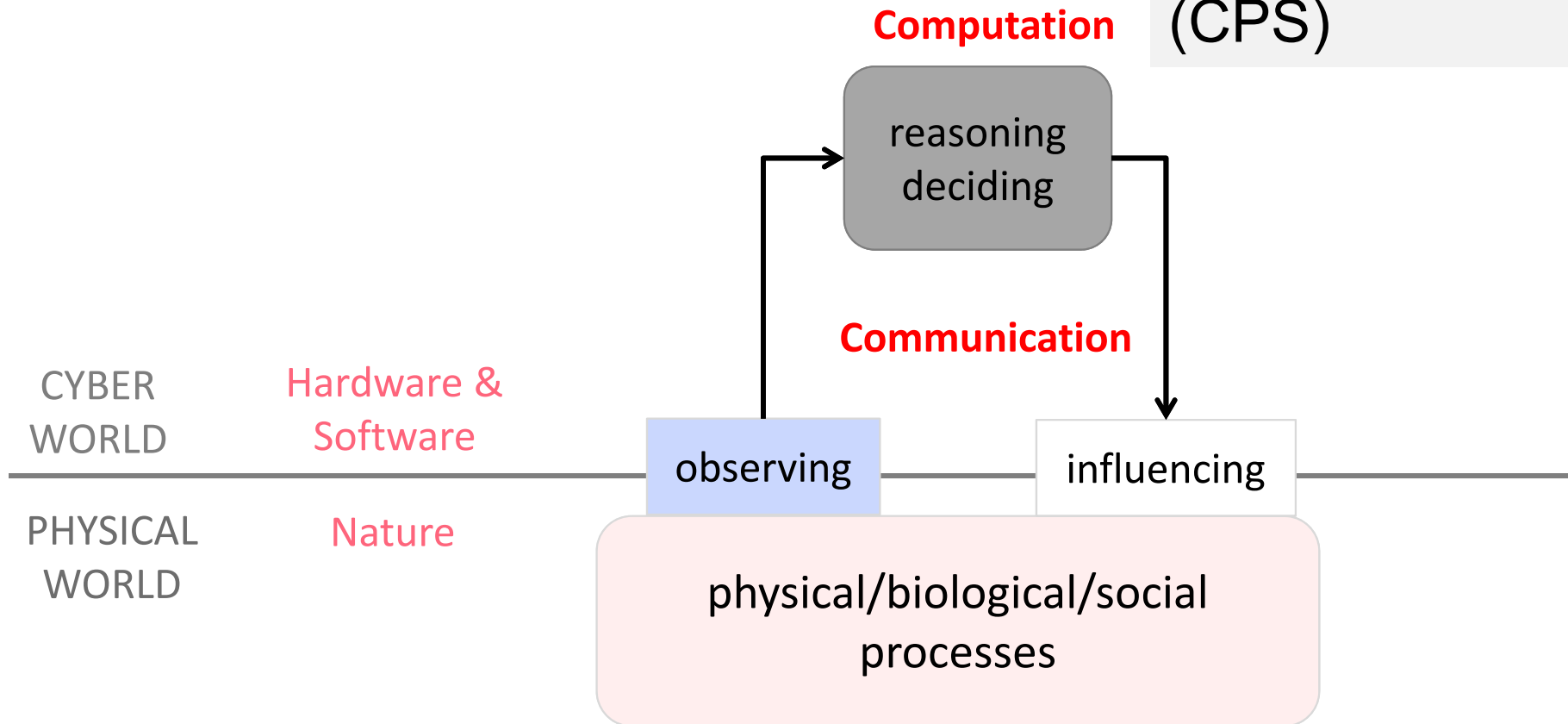
# Examples of Embedded Systems

Production systems

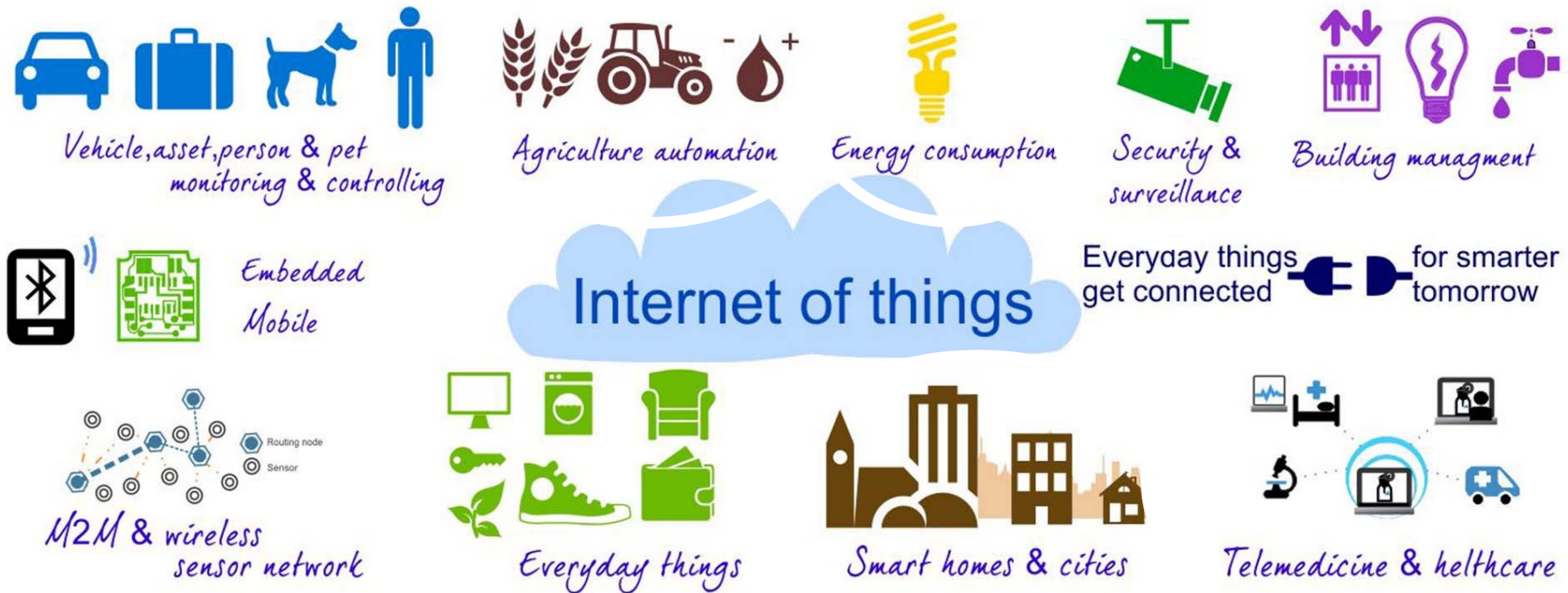


# Smart World

Sometimes denoted as:  
cyber-physical system  
(CPS)



Use feedback to influence the dynamics of the physical world by taking smart decisions in the cyber world

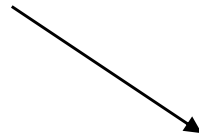


Internet of Things (IoT) infrastructure will be omnipresent.

# Predictability & Dependability

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CPS = cyber-physical system



“It is essential to **predict** how a CPS is going to behave under any circumstances [...] **before** it is deployed.”<sup>Maj14</sup>

“CPS must **operate dependably**, safely, securely, efficiently and in real-time.”<sup>Raj10</sup>

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<sup>Maj14</sup> R. Majumdar & B. Brandenburg (2014). Foundations of Cyber-Physical Systems.

<sup>Raj10</sup> R. Rajkumar et al. (2010). Cyber-Physical Systems: The Next Computing Revolution.



# Characteristics of Embedded Systems (1)

- ▶ Must be **dependable**:
  - **Reliability**:  $R(t)$  = probability of system working correctly provided that it was working at  $t=0$
  - **Maintainability**:  $M(d)$  = probability of system working correctly  $d$  time units after error occurred.
  - **Availability**: probability of system working at time  $t$
  - **Safety**: no harm to be caused
  - **Security**: confidential and authentic communication

Making the system dependable must not be an after-thought, it must be considered from the very beginning.

# Characteristics of Embedded Systems (2)

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- ▶ Must be *efficient*:
  - *Energy* efficient
  - *Code-size* and *data memory* efficient
  - *Run-time* efficient
  - *Weight* efficient
  - *Cost* efficient
- ▶ *Dedicated* towards a certain *application*: Knowledge about behavior at design time can be used to minimize resources and to maximize robustness.

# Characteristics of Embedded Systems (3)

- ▶ Many ES must meet *real-time constraints*:
  - A real-time system must *react to stimuli* from the controlled object (or the operator) within the time interval dictated by the environment.
  - For real-time systems, right answers arriving too late are wrong.

*„A real-time constraint is called hard, if not meeting that constraint could result in a catastrophe“ [Kopetz, 1997].*

- All other time-constraints are called soft.
- A *guaranteed system response* has to be explained without statistical arguments.

# Characteristics of Embedded Systems (4)

- ▶ Typically, ES are *reactive systems*:

*„A reactive system is one which is in continual interaction with its environment and executes at a pace determined by that environment“ [Bergé, 1995]*

- ▶ Frequently *connected to physical environment* through sensors and actuators (CPS).
- ▶ In these cases, the analog and digital system aspects need to be considered: *hybrid systems*.



# Comparison

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## ► Embedded Systems

- Few applications that are known at design-time.
- Not programmable by end user.
- Fixed run-time requirements (additional computing power not useful).
- Criteria:
  - cost
  - power consumption
  - predictability
  - ...

## ► General Purpose Computing

- Broad class of applications.
- Programmable by end user.
- Faster is better.
- Criteria:
  - cost
  - power consumption
  - average speed

# Trends ...

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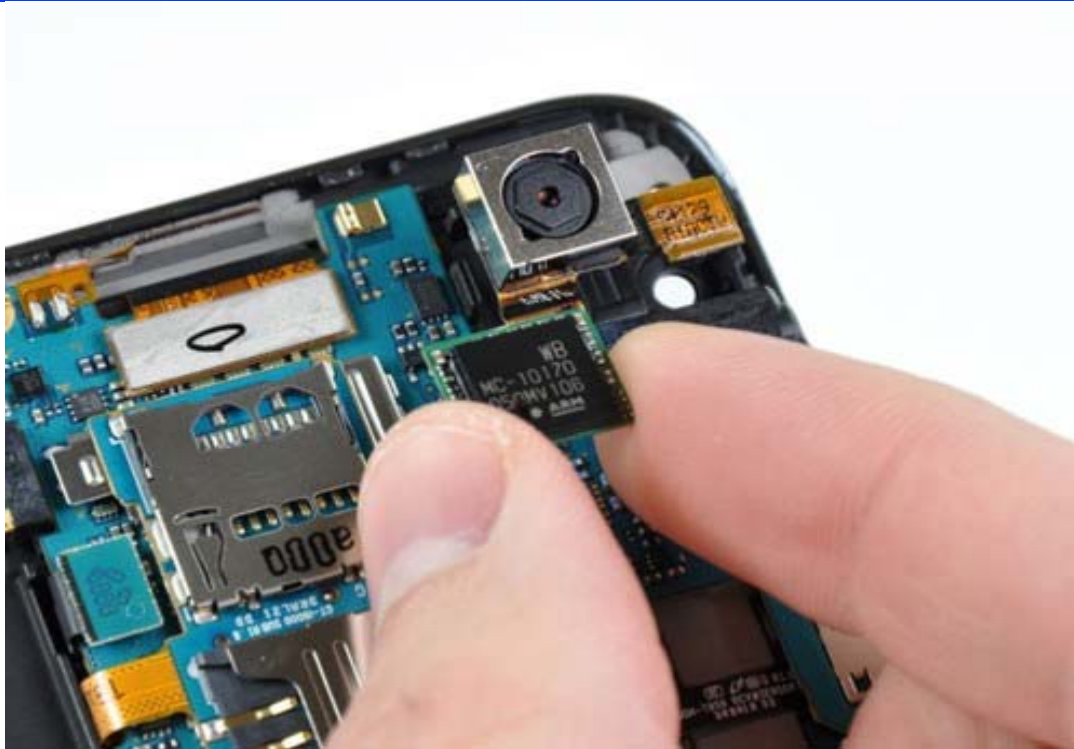
- ▶ Since long time, embedded systems overtook the market of PCs and Laptops.
- ▶ Ubiquitous and pervasive computing, Internet of Things:
  - Information anytime, anywhere; building ambient intelligence into our environment; internet of things:
    - Wearable computers
    - “Smart Labels” on consumer products
    - Intelligent buildings
    - Environmental Monitoring
    - Traffic control and communicating automobiles
  - Embedded systems provide the basic technology.

# Trends ...

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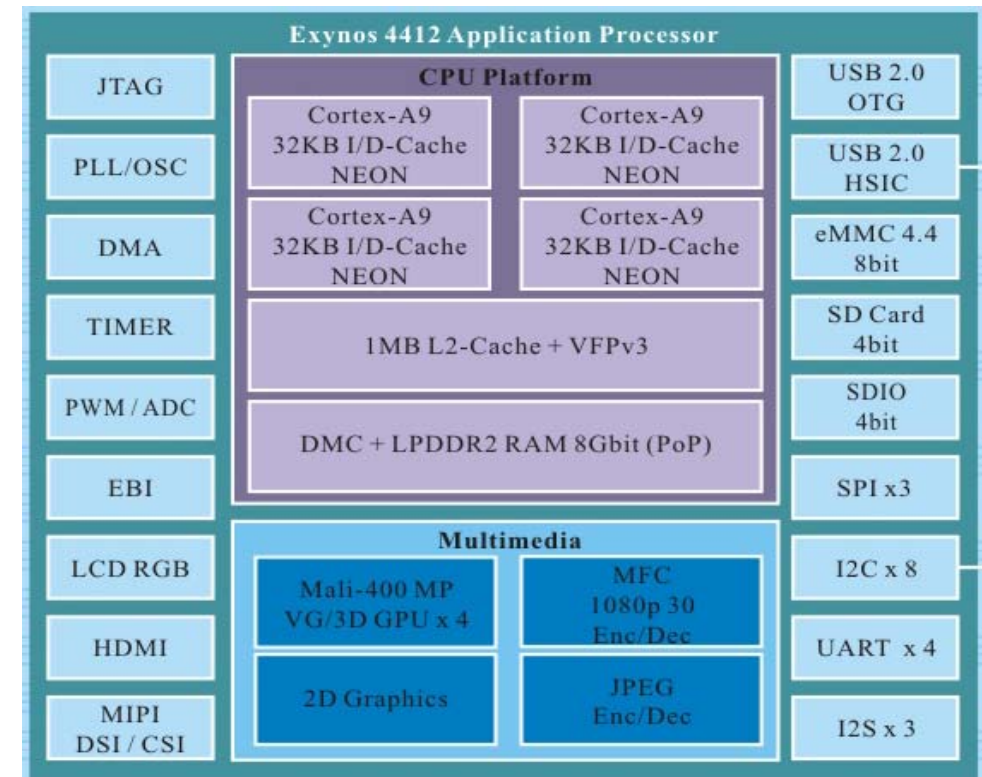
- ▶ Embedded systems are communicating, very often wireless.
- ▶ Higher degree of integration on a single chip:
  - Memory + processor + I/O-units + (wireless) communication.
  - Network on chip for communication between units.
  - Multiprocessor Systems on a Chip (MPSoC).
  - Microsystems that contain energy harvesting, energy storage, sensing, processing and communication (“zero power systems”).
  - Software increasing (amount and complexity).
- ▶ Low power and energy constraints (portable or unattended devices) are increasingly important, as well as temperature constraints (overheating). Increased interest in energy harvesting to achieve long term autonomous operation.

# Multiprocessor systems-on-a-chip (MPSoCs)



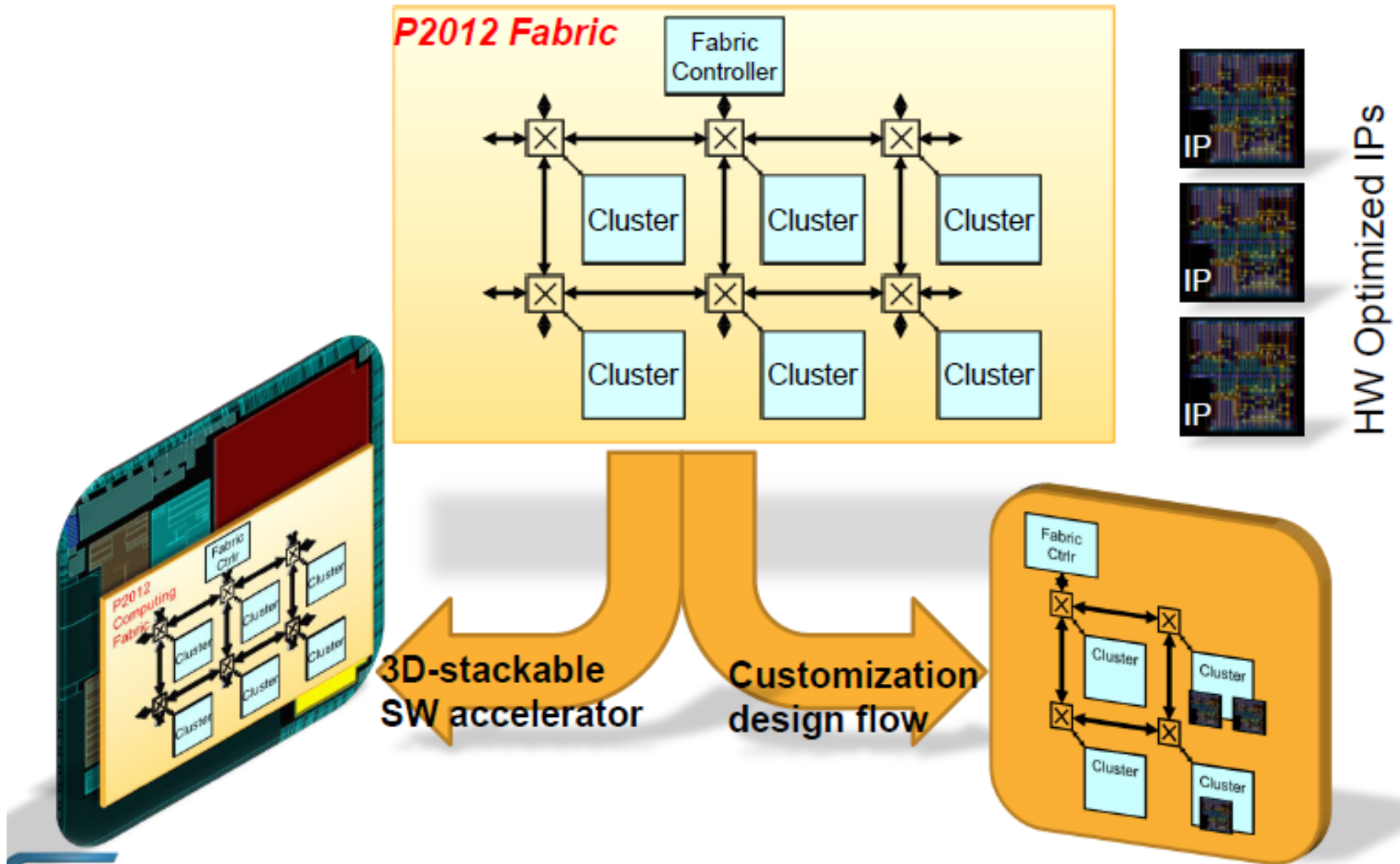
## Samsung Galaxy Note II

- Eynos 4412 System on a Chip (SoC)
- ARM Cortex-A9 processing core
- 32 nanometer: transistor gate width
- Four processing cores

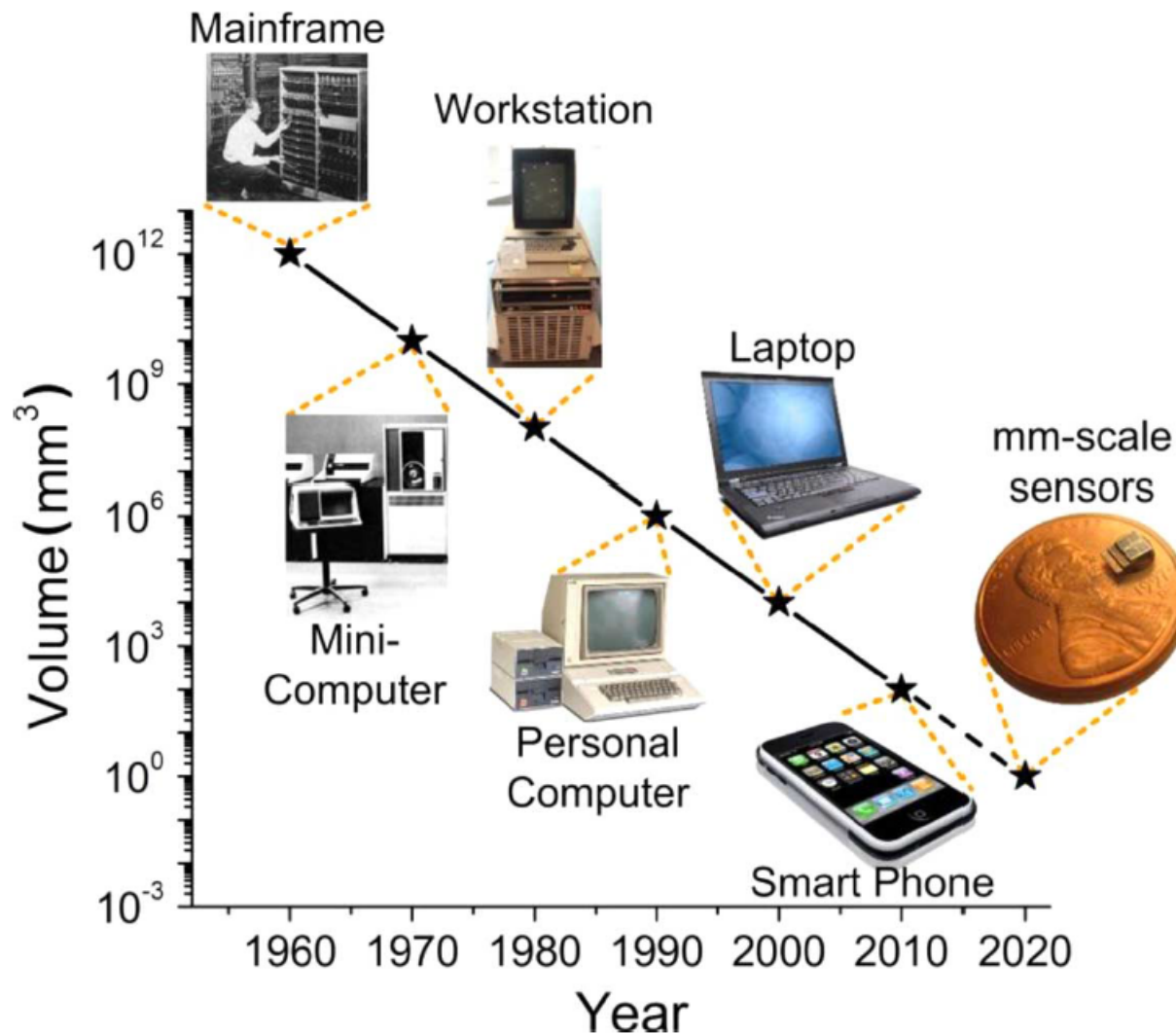




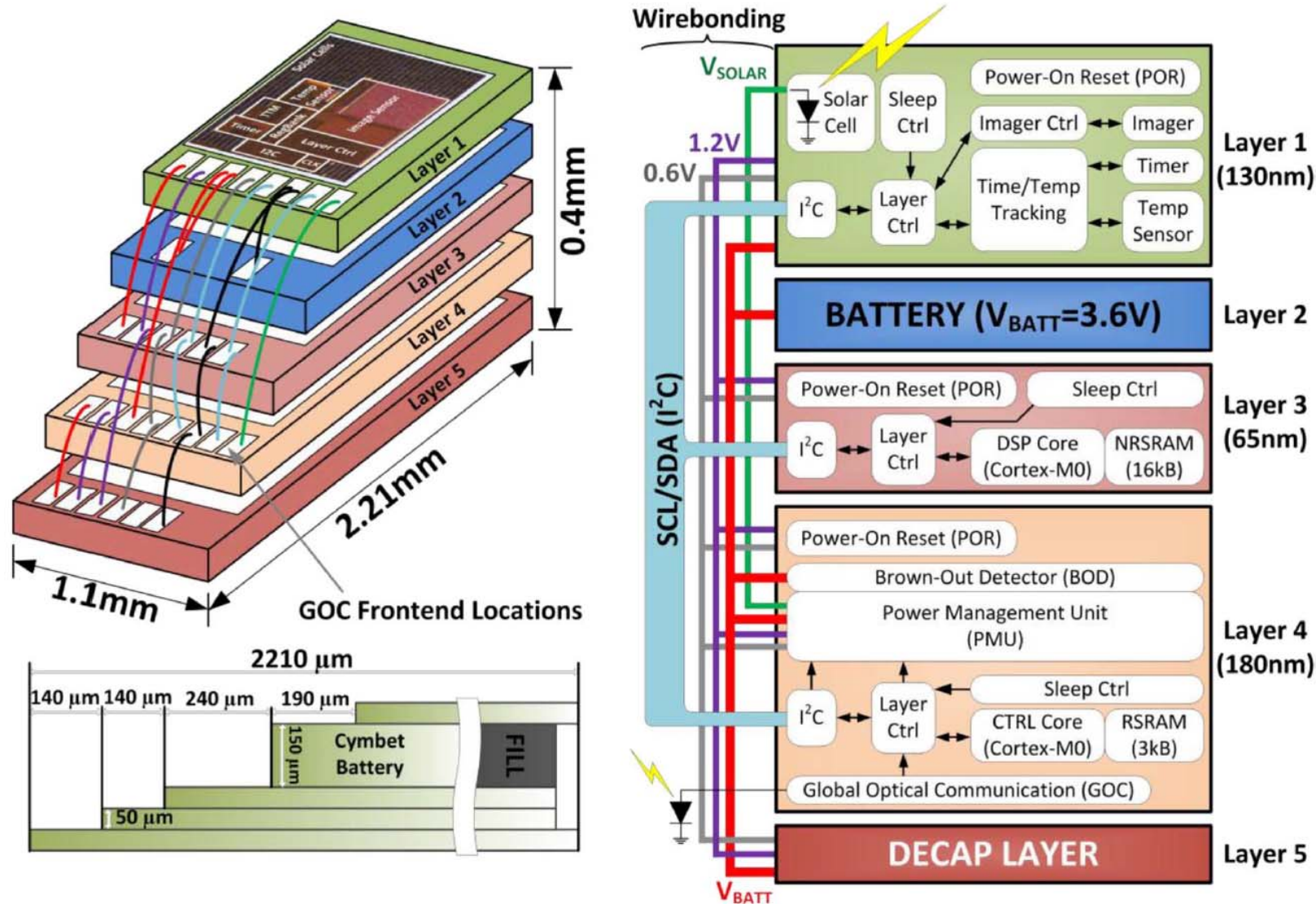
# Example ST2012/STHORM



# Zero Power Systems and Sensors



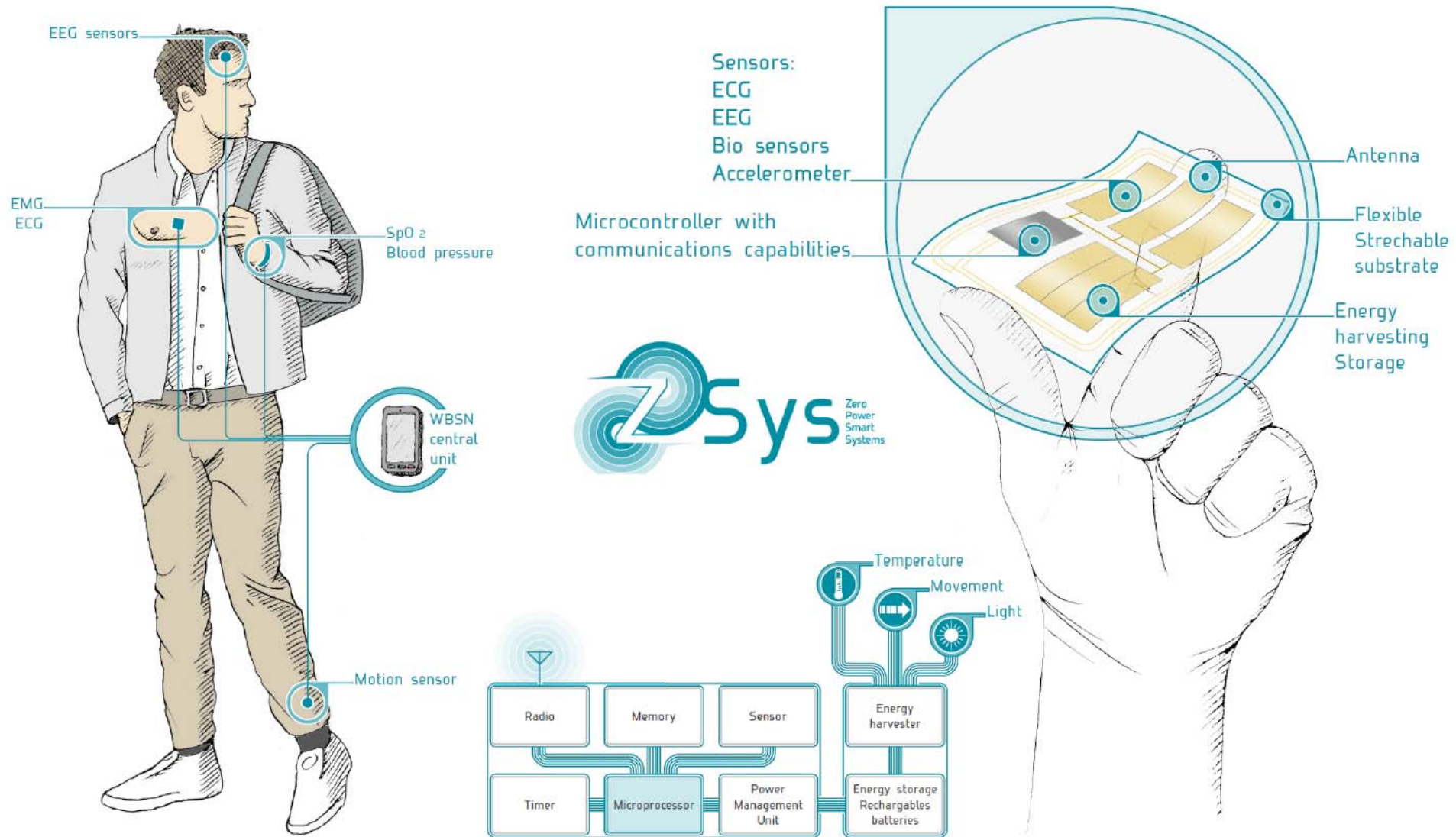
# Zero Power Systems and Sensors



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# Zero Power Systems and Sensors



Z-Sys and Guardian Angel Research Proposals 2013