

Polar Convexity in finite dimensional Euclidean spaces

Shubhankar Bhatt

(Joint work with Hristo Sendov)

Department of Mathematics

Western University, Ontario, Canada

26th Midwest Optimization Meeting

November 8th - 9th, 2024

Outline

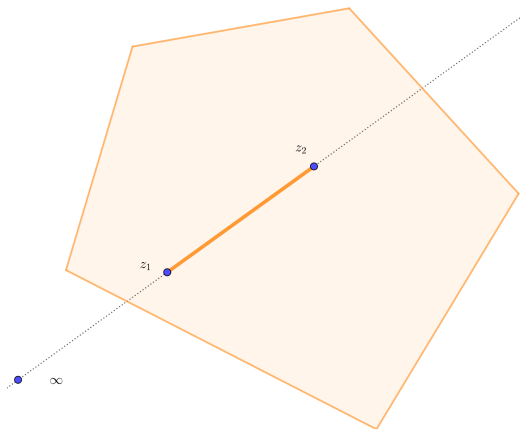
- 1 The idea
- 2 Polar Convexity in \mathbb{R}^n
- 3 Motivation
- 4 Duality theorem and its consequences
- 5 Theorems of the alternative
- 6 Polar convexity with multiple poles

The idea

- Convex sets contain the line segment between any two points in them

- Convex sets contain the line segment between any two points in them
- Lines between two points are circles passing through ∞

- Convex sets contain the line segment between any two points in them
- Lines between two points are circles passing through ∞



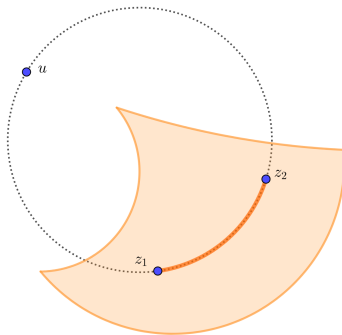
- Replace ∞ with a finite point \mathbf{u}

- Replace ∞ with a finite point \mathbf{u}
- Consider the circle passing through $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2$

- Replace ∞ with a finite point \mathbf{u}
- Consider the circle passing through $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2$
- Let $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2]$ be the arc on that circle between \mathbf{z}_1 and \mathbf{z}_2 which does not contain \mathbf{u}

- Replace ∞ with a finite point \mathbf{u}
- Consider the circle passing through $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2$
- Let $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2]$ be the arc on that circle between \mathbf{z}_1 and \mathbf{z}_2 which does not contain \mathbf{u}
- Define a \mathbf{u} -convex set to contain $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2]$ for any two points $\mathbf{z}_1, \mathbf{z}_2$ in it

- Replace ∞ with a finite point \mathbf{u}
- Consider the circle passing through $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2$
- Let $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2]$ be the arc on that circle between \mathbf{z}_1 and \mathbf{z}_2 which does not contain \mathbf{u}
- Define a \mathbf{u} -convex set to contain $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2]$ for any two points $\mathbf{z}_1, \mathbf{z}_2$ in it



Polar convexity in \mathbb{R}^n

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$
- How to parametrize a circular arc in $\hat{\mathbb{R}}^n$?

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$
- How to parametrize a circular arc in $\hat{\mathbb{R}}^n$?
- Let $\mathbf{z}^* := \frac{\mathbf{z}}{\|\mathbf{z}\|^2}$ ($0^* = \infty$ and $\infty^* = 0$) and for $\mathbf{u} \in \mathbb{R}^n$

$$T_{\mathbf{u}}(\mathbf{z}) := \begin{cases} \mathbf{u} + (\mathbf{z} - \mathbf{u})^* & \text{if } \mathbf{z} \neq \mathbf{u} \\ \infty & \text{if } \mathbf{z} = \mathbf{u} \end{cases}$$

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$
- How to parametrize a circular arc in $\hat{\mathbb{R}}^n$?
- Let $\mathbf{z}^* := \frac{\mathbf{z}}{\|\mathbf{z}\|^2}$ ($0^* = \infty$ and $\infty^* = 0$) and for $\mathbf{u} \in \mathbb{R}^n$

$$T_{\mathbf{u}}(\mathbf{z}) := \begin{cases} \mathbf{u} + (\mathbf{z} - \mathbf{u})^* & \text{if } \mathbf{z} \neq \mathbf{u} \\ \infty & \text{if } \mathbf{z} = \mathbf{u} \end{cases}$$

- Define $T_{\infty} := Id_{\hat{\mathbb{R}}^n}$

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$
- How to parametrize a circular arc in $\hat{\mathbb{R}}^n$?
- Let $\mathbf{z}^* := \frac{\mathbf{z}}{\|\mathbf{z}\|^2}$ ($0^* = \infty$ and $\infty^* = 0$) and for $\mathbf{u} \in \mathbb{R}^n$

$$T_{\mathbf{u}}(\mathbf{z}) := \begin{cases} \mathbf{u} + (\mathbf{z} - \mathbf{u})^* & \text{if } \mathbf{z} \neq \mathbf{u} \\ \infty & \text{if } \mathbf{z} = \mathbf{u} \end{cases}$$

- Define $T_{\infty} := Id_{\hat{\mathbb{R}}^n}$
- $T_{\mathbf{u}}$ is a Möbius transformation and an involution

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$
- How to parametrize a circular arc in $\hat{\mathbb{R}}^n$?
- Let $\mathbf{z}^* := \frac{\mathbf{z}}{\|\mathbf{z}\|^2}$ ($0^* = \infty$ and $\infty^* = 0$) and for $\mathbf{u} \in \mathbb{R}^n$

$$T_{\mathbf{u}}(\mathbf{z}) := \begin{cases} \mathbf{u} + (\mathbf{z} - \mathbf{u})^* & \text{if } \mathbf{z} \neq \mathbf{u} \\ \infty & \text{if } \mathbf{z} = \mathbf{u} \end{cases}$$

- Define $T_{\infty} := Id_{\hat{\mathbb{R}}^n}$
- $T_{\mathbf{u}}$ is a Möbius transformation and an involution
- $T_{\mathbf{u}}$ sends a sphere (or hyperplane) to a sphere (or hyperplane)

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$
- How to parametrize a circular arc in $\hat{\mathbb{R}}^n$?
- Let $\mathbf{z}^* := \frac{\mathbf{z}}{\|\mathbf{z}\|^2}$ ($0^* = \infty$ and $\infty^* = 0$) and for $\mathbf{u} \in \mathbb{R}^n$

$$T_{\mathbf{u}}(\mathbf{z}) := \begin{cases} \mathbf{u} + (\mathbf{z} - \mathbf{u})^* & \text{if } \mathbf{z} \neq \mathbf{u} \\ \infty & \text{if } \mathbf{z} = \mathbf{u} \end{cases}$$

- Define $T_{\infty} := Id_{\hat{\mathbb{R}}^n}$
- $T_{\mathbf{u}}$ is a Möbius transformation and an involution
- $T_{\mathbf{u}}$ sends a sphere (or hyperplane) to a sphere (or hyperplane)
- $T_{\mathbf{u}}$ sends circles (or lines) to circles (or lines)

- Let $\hat{\mathbb{R}}^n$ be the one point compactification $\mathbb{R}^n \cup \{\infty\}$
- How to parametrize a circular arc in $\hat{\mathbb{R}}^n$?
- Let $\mathbf{z}^* := \frac{\mathbf{z}}{\|\mathbf{z}\|^2}$ ($0^* = \infty$ and $\infty^* = 0$) and for $\mathbf{u} \in \mathbb{R}^n$

$$T_{\mathbf{u}}(\mathbf{z}) := \begin{cases} \mathbf{u} + (\mathbf{z} - \mathbf{u})^* & \text{if } \mathbf{z} \neq \mathbf{u} \\ \infty & \text{if } \mathbf{z} = \mathbf{u} \end{cases}$$

- Define $T_{\infty} := Id_{\hat{\mathbb{R}}^n}$
- $T_{\mathbf{u}}$ is a Möbius transformation and an involution
- $T_{\mathbf{u}}$ sends a sphere (or hyperplane) to a sphere (or hyperplane)
- $T_{\mathbf{u}}$ sends circles (or lines) to circles (or lines)
- Any sphere passing through \mathbf{u} is sent to a hyperplane

Definition

For $\mathbf{z}_1, \mathbf{z}_2, \mathbf{u} \in \mathbb{R}^n$ distinct, define

$$\begin{aligned} \text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] &:= \left\{ \mathbf{u} + (t(\mathbf{z}_1 - \mathbf{u})^* + (1-t)(\mathbf{z}_2 - \mathbf{u})^*)^* : t \in [0, 1] \right\} \\ &= \left\{ T_{\mathbf{u}}(tT_{\mathbf{u}}(\mathbf{z}_1) + (1-t)T_{\mathbf{u}}(\mathbf{z}_2)) : t \in [0, 1] \right\} \end{aligned} \quad (1)$$

If $\mathbf{z}_1 = \mathbf{u}$ or $\mathbf{z}_2 = \mathbf{u}$, define $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] := \{\mathbf{z}_1, \mathbf{z}_2\}$

Definition

For $\mathbf{z}_1, \mathbf{z}_2, \mathbf{u} \in \mathbb{R}^n$ distinct, define

$$\begin{aligned} \text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] &:= \left\{ \mathbf{u} + (t(\mathbf{z}_1 - \mathbf{u})^* + (1-t)(\mathbf{z}_2 - \mathbf{u})^*)^* : t \in [0, 1] \right\} \\ &= \left\{ T_{\mathbf{u}}(tT_{\mathbf{u}}(\mathbf{z}_1) + (1-t)T_{\mathbf{u}}(\mathbf{z}_2)) : t \in [0, 1] \right\} \end{aligned} \quad (1)$$

If $\mathbf{z}_1 = \mathbf{u}$ or $\mathbf{z}_2 = \mathbf{u}$, define $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] := \{\mathbf{z}_1, \mathbf{z}_2\}$

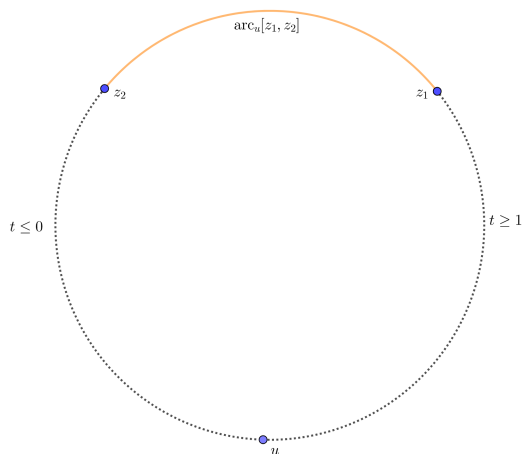
If $z_1, z_2, u \in \mathbb{C}$ (identified with \mathbb{R}^2), then (1) simplifies to

$$\text{arc}_u[z_1, z_2] = \left\{ u + \frac{1}{\frac{t}{z_1 - u} + \frac{1-t}{z_2 - u}} : t \in [0, 1] \right\}$$

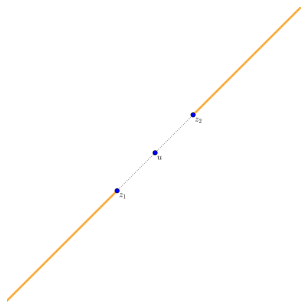
Varying the parameter t through $\mathbb{R} \cup \{\infty\}$

$$\mathbf{u} + (t(\mathbf{z}_1 - \mathbf{u})^* + (1 - t)(\mathbf{z}_2 - \mathbf{u})^*)^*$$

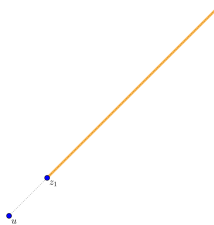
spans the following:



When \mathbf{u} is between \mathbf{z}_1 and \mathbf{z}_2



When $\mathbf{z}_2 = \infty$



Let $A \subset \hat{\mathbb{R}}^n$ and $\mathbf{u} \in \hat{\mathbb{R}}^n$

Definition

A is said to be \mathbf{u} -convex if for any $\mathbf{z}_1, \mathbf{z}_2 \in A$, $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] \subseteq A$

Let $A \subset \hat{\mathbb{R}}^n$ and $\mathbf{u} \in \hat{\mathbb{R}}^n$

Definition

A is said to be \mathbf{u} -convex if for any $\mathbf{z}_1, \mathbf{z}_2 \in A$, $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] \subseteq A$

Define $\text{conv}_{\mathbf{u}}(A)$ to be the smallest with respect to inclusion \mathbf{u} -convex set containing A

Let $A \subset \hat{\mathbb{R}}^n$ and $\mathbf{u} \in \hat{\mathbb{R}}^n$

Definition

A is said to be \mathbf{u} -convex if for any $\mathbf{z}_1, \mathbf{z}_2 \in A$, $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] \subseteq A$

Define $\text{conv}_{\mathbf{u}}(A)$ to be the smallest with respect to inclusion \mathbf{u} -convex set containing A

Define the pole set, $\mathcal{P}(A)$, as the set of all points $\mathbf{u} \in \hat{\mathbb{R}}^n$ such that A is \mathbf{u} -convex

Let $A \subset \hat{\mathbb{R}}^n$ and $\mathbf{u} \in \hat{\mathbb{R}}^n$

Definition

A is said to be \mathbf{u} -convex if for any $\mathbf{z}_1, \mathbf{z}_2 \in A$, $\text{arc}_{\mathbf{u}}[\mathbf{z}_1, \mathbf{z}_2] \subseteq A$

Define $\text{conv}_{\mathbf{u}}(A)$ to be the smallest with respect to inclusion \mathbf{u} -convex set containing A

Define the pole set, $\mathcal{P}(A)$, as the set of all points $\mathbf{u} \in \hat{\mathbb{R}}^n$ such that A is \mathbf{u} -convex

Definition

Given points $\mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ and a $\mathbf{u} \in \hat{\mathbb{R}}^n$ distinct from them, define

$$\text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\} := \left\{ \mathbf{u} + \left(\sum_{i=1}^k t_i (\mathbf{z}_i - \mathbf{u})^* \right)^* : t_i \geq 0 \text{ with } \sum_{i=1}^k t_i = 1 \right\}$$

If $\mathbf{u} \in \{\mathbf{z}_1, \dots, \mathbf{z}_k\}$ define $\text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\} := \text{conv}_{\mathbf{u}}\{\mathbf{z}_i : \mathbf{z}_i \neq \mathbf{u}, i = 1, \dots, k\} \cup \{\mathbf{u}\}$

Lemma

Given $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2 \in \mathbb{R}^n$ and $t \in [0, 1]$

$$\mathbf{u} + (t(\mathbf{z}_1 - \mathbf{u})^* + (1 - t)(\mathbf{z}_2 - \mathbf{u})^*)^* \longrightarrow t\mathbf{z}_1 + (1 - t)\mathbf{z}_2$$

as $\|\mathbf{u}\| \rightarrow \infty$

Lemma

Given $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2 \in \mathbb{R}^n$ and $t \in [0, 1]$

$$\mathbf{u} + (t(\mathbf{z}_1 - \mathbf{u})^* + (1 - t)(\mathbf{z}_2 - \mathbf{u})^*)^* \longrightarrow t\mathbf{z}_1 + (1 - t)\mathbf{z}_2$$

as $\|\mathbf{u}\| \rightarrow \infty$

The transformation $T_{\mathbf{u}}$ maps \mathbf{u} -convex sets to convex sets

Lemma

Given $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2 \in \mathbb{R}^n$ and $t \in [0, 1]$

$$\mathbf{u} + (t(\mathbf{z}_1 - \mathbf{u})^* + (1 - t)(\mathbf{z}_2 - \mathbf{u})^*)^* \longrightarrow t\mathbf{z}_1 + (1 - t)\mathbf{z}_2$$

as $\|\mathbf{u}\| \rightarrow \infty$

The transformation $T_{\mathbf{u}}$ maps \mathbf{u} -convex sets to convex sets

All of the classical results can be translated

Lemma

Given $\mathbf{u}, \mathbf{z}_1, \mathbf{z}_2 \in \mathbb{R}^n$ and $t \in [0, 1]$

$$\mathbf{u} + (t(\mathbf{z}_1 - \mathbf{u})^* + (1 - t)(\mathbf{z}_2 - \mathbf{u})^*)^* \longrightarrow t\mathbf{z}_1 + (1 - t)\mathbf{z}_2$$

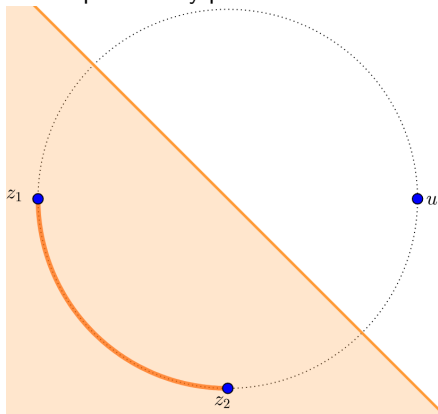
as $\|\mathbf{u}\| \rightarrow \infty$

The transformation $T_{\mathbf{u}}$ maps \mathbf{u} -convex sets to convex sets

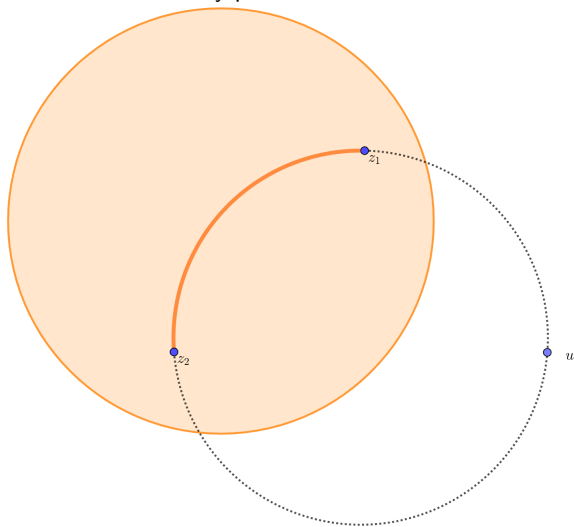
All of the classical results can be translated

Let's see some examples

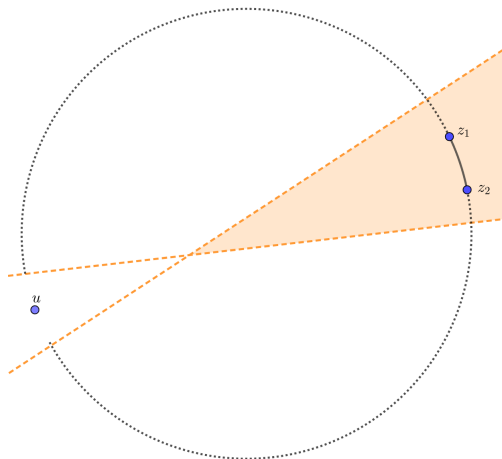
Half planes are convex with respect to any point not in their interior



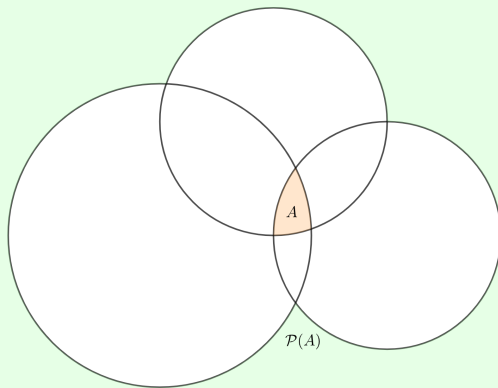
Circular domains are convex w.r.t. any point not in their interior



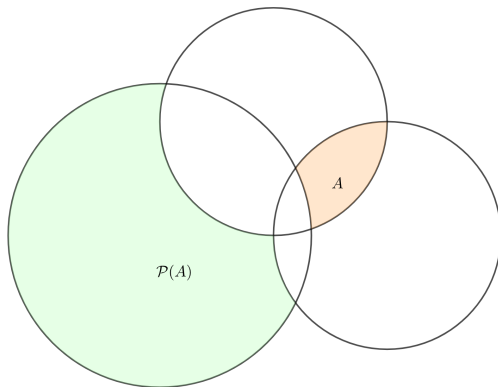
A cone is convex w.r.t. any point in its negative cone



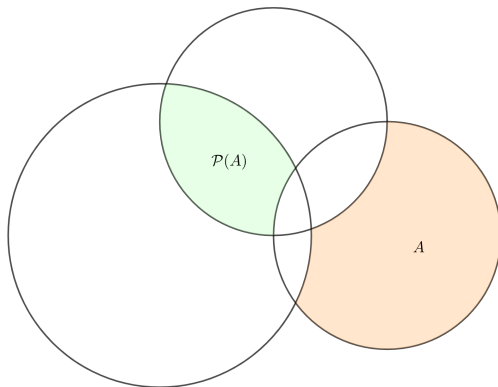
The intersection of three circular domains and its pole set



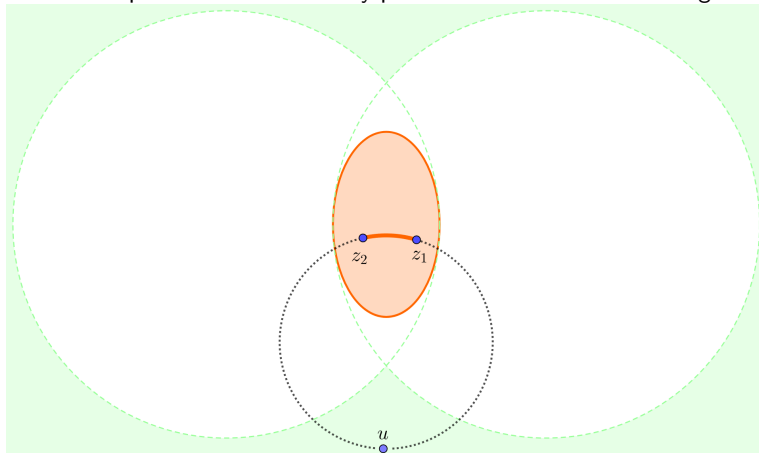
The intersection of three circular domains and its pole set



The intersection of three circular domains and its pole set



The inside of an ellipse is convex w.r.t. any point outside the two osculating circles



As one may notice, spherical domains are central to the theory

As one may notice, spherical domains are central to the theory

Let $A \subseteq \hat{\mathbb{R}}^n$ be a set not containing \mathbf{u}

As one may notice, spherical domains are central to the theory

Let $A \subseteq \hat{\mathbb{R}}^n$ be a set not containing \mathbf{u}

Proposition

Then $\text{conv}_{\mathbf{u}}(A)$ is the intersection of all spherical domains that contain A and have \mathbf{u} on their boundary, with \mathbf{u} omitted

Motivation

Take a polynomial $p(z) = (z - z_1)^{r_1} \cdots (z - z_k)^{r_k}$, where $\sum_{j=1}^k r_j = n$
with distinct zeros z_1, \dots, z_k having respective multiplicities r_1, \dots, r_k

Take a polynomial $p(z) = (z - z_1)^{r_1} \cdots (z - z_k)^{r_k}$, where $\sum_{j=1}^k r_j = n$

with distinct zeros z_1, \dots, z_k having respective multiplicities r_1, \dots, r_k

For all $i, j \in \{1, \dots, k\}$, define the points

$$g_{i,j} := \begin{cases} (r_i z_j + (n - r_i) z_i) / n & \text{if } i \neq j \\ \infty & \text{if } i = j \end{cases}$$

Take a polynomial $p(z) = (z - z_1)^{r_1} \cdots (z - z_k)^{r_k}$, where $\sum_{j=1}^k r_j = n$

with distinct zeros z_1, \dots, z_k having respective multiplicities r_1, \dots, r_k

For all $i, j \in \{1, \dots, k\}$, define the points

$$g_{i,j} := \begin{cases} (r_i z_j + (n - r_i) z_i) / n & \text{if } i \neq j \\ \infty & \text{if } i = j \end{cases}$$

Lemma (Specht [1959])

Every non-trivial critical points of $p(z)$ lies in

$$\text{conv}\{g_{i,j} : 1 \leq i, j \leq k, i \neq j\}$$

Theorem (Sendov [2021])

Every non-trivial critical points of $p(z)$ lies in

$$\text{conv}\{z_1, \dots, z_k\} \cap \bigcap_{i=1}^k \text{conv}_{z_i}\{g_{i,1}, \dots, g_{i,k}\}$$

Theorem (Sendov [2021])

Every non-trivial critical points of $p(z)$ lies in

$$\text{conv}\{z_1, \dots, z_k\} \cap \bigcap_{i=1}^k \text{conv}_{z_i}\{g_{i,1}, \dots, g_{i,k}\}$$

Define the polar derivative of $p(z)$ w.r.t. a pole u as

$$\mathcal{D}_u(p; z) := \begin{cases} np(z) - (z - u)p'(z) & \text{if } u \in \mathbb{C} \\ p'(z) & \text{if } u = \infty \end{cases}$$

Theorem (Sendov [2021])

Every non-trivial critical points of $p(z)$ lies in

$$\text{conv}\{z_1, \dots, z_k\} \cap \bigcap_{i=1}^k \text{conv}_{z_i}\{g_{i,1}, \dots, g_{i,k}\}$$

Define the polar derivative of $p(z)$ w.r.t. a pole u as

$$\mathcal{D}_u(p; z) := \begin{cases} np(z) - (z - u)p'(z) & \text{if } u \in \mathbb{C} \\ p'(z) & \text{if } u = \infty \end{cases}$$

Theorem (Sendov, Sendov, Wang [2018])

Let $p(z)$ be a polynomial of degree n with zeroes $z_1, \dots, z_n \in \mathbb{C}$

For any $u \in \mathbb{C}$ if $\mathcal{D}_u(p; z) \not\equiv 0$, then all its zeros are in $\text{conv}_u\{z_1, \dots, z_n\}$

Duality theorem and its consequences

Theorem

Let $\mathbf{u}, \mathbf{v}, \mathbf{z}_1, \dots, \mathbf{z}_k$ be distinct points in $\hat{\mathbb{R}}^n$ then

$$\mathbf{v} \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\} \text{ if and only if } \mathbf{u} \in \text{conv}_{\mathbf{v}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$$

Theorem

Let $\mathbf{u}, \mathbf{v}, \mathbf{z}_1, \dots, \mathbf{z}_k$ be distinct points in $\hat{\mathbb{R}}^n$ then

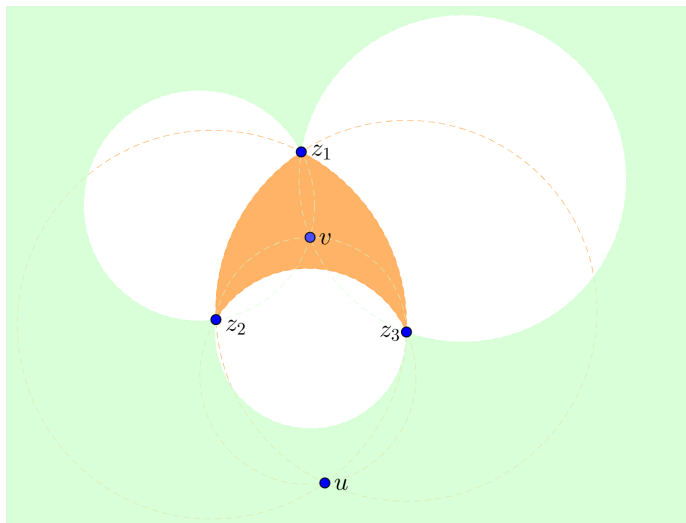
$$\mathbf{v} \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\} \text{ if and only if } \mathbf{u} \in \text{conv}_{\mathbf{v}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$$

In fact, if

$$\mathbf{v} = \mathbf{u} + \left(\sum_{i=1}^k t_i (\mathbf{z}_i - \mathbf{u})^* \right)^* \text{ for some } t_i \geq 0, 1 \leq i \leq k \text{ and } \sum_{i=1}^k t_i = 1$$

then

$$\mathbf{u} = \mathbf{v} + \left(\sum_{i=1}^k \mu_i (\mathbf{z}_i - \mathbf{v})^* \right)^* \text{ for } \mu_i = \frac{t_i \|\mathbf{z}_i - \mathbf{v}\|^2 \|\mathbf{z}_i - \mathbf{u}\|^{-2}}{\sum_{j=1}^k t_j \|\mathbf{z}_j - \mathbf{v}\|^2 \|\mathbf{z}_j - \mathbf{u}\|^{-2}}$$



Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ be distinct points

Definition

A point $\mathbf{v} \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$ is *\mathbf{u} -extreme point* if it cannot be written as a non-trivial \mathbf{u} -convex combination of any two distinct points in $\text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ be distinct points

Definition

A point $\mathbf{v} \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$ is ***u-extreme point*** if it cannot be written as a non-trivial ***u-convex*** combination of any two distinct points in $\text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$

The duality theorem gives a nice criteria to decide whether a point is ***u-extreme*** or not

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ be distinct points

Definition

A point $\mathbf{v} \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$ is ***u-extreme point*** if it cannot be written as a non-trivial ***u***-convex combination of any two distinct points in $\text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$

The duality theorem gives a nice criteria to decide whether a point is ***u***-extreme or not

Corollary

$\mathbf{z}_i \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$ is ***u***-extreme $\iff \mathbf{u} \notin \text{conv}_{\mathbf{z}_i}\{\mathbf{z}_1, \dots, \mathbf{z}_{i-1}, \mathbf{z}_{i+1}, \dots, \mathbf{z}_k\}$

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ be distinct points

Definition

A point $\mathbf{v} \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$ is ***u-extreme point*** if it cannot be written as a non-trivial ***u-convex*** combination of any two distinct points in $\text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$

The duality theorem gives a nice criteria to decide whether a point is ***u-extreme*** or not

Corollary

$\mathbf{z}_i \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$ is ***u-extreme*** $\iff \mathbf{u} \notin \text{conv}_{\mathbf{z}_i}\{\mathbf{z}_1, \dots, \mathbf{z}_{i-1}, \mathbf{z}_{i+1}, \dots, \mathbf{z}_k\}$

Corollary

For $\mathbf{u} \notin A \subseteq \hat{\mathbb{R}}^n$, $\mathbf{v} \in \text{conv}_{\mathbf{u}}(A)$ is ***u-extreme*** $\iff \mathbf{u} \notin \text{conv}_{\mathbf{v}}(A)$

Theorems of the alternative

Definition

A spherical domain $S \subseteq \hat{\mathbb{R}}^n$ is said to *separate* two sets $A, B \subseteq \hat{\mathbb{R}}^n$ if

$$A \subseteq S \text{ and } B \subseteq \text{cl}(S^c) \text{ or vice-versa}$$

Such a spherical domain (or boundary of the spherical domain) is called a *separating spherical domain* (or *separating sphere*) for the pair A, B

Definition

A spherical domain $S \subseteq \hat{\mathbb{R}}^n$ is said to *separate* two sets $A, B \subseteq \hat{\mathbb{R}}^n$ if

$$A \subseteq S \text{ and } B \subseteq \text{cl}(S^c) \text{ or vice-versa}$$

Such a spherical domain (or boundary of the spherical domain) is called a *separating spherical domain* (or *separating sphere*) for the pair A, B

We say that S *strongly separates* A and B , if in addition

$$A \cap \partial S = \emptyset = B \cap \partial S$$

Lemma (Spherical Separation)

Let $\mathbf{u} \in \hat{\mathbb{R}}^n$ and A, B be non-intersecting \mathbf{u} -convex sets in $\hat{\mathbb{R}}^n$

Then there exists a spherical domain S , with \mathbf{u} on its boundary, separating A and B

Moreover, if $\mathbf{u} \notin A \cup B$ and one of the following holds

- ① A is closed in $\hat{\mathbb{R}}^n$ and B is closed in $\hat{\mathbb{R}}^n \setminus \{\mathbf{u}\}$
- ② A and B are both open

then S can be chosen to strongly separate A and B

Lemma (Gordan's Lemma)

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{R}^n$ be distinct, such that $\mathbf{u} \neq \mathbf{0}, \infty$

Lemma (Gordan's Lemma)

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{R}^n$ be distinct, such that $\mathbf{u} \neq \mathbf{0}, \infty$

Either there are numbers $t_1, \dots, t_k \in [0, 1]$ with $\sum_{i=1}^k t_i = 1$, such that

$$(\mathbf{0} - \mathbf{u})^* = \sum_{i=1}^k t_i (\mathbf{z}_i - \mathbf{u})^*$$

Lemma (Gordan's Lemma)

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{R}^n$ be distinct, such that $\mathbf{u} \neq \mathbf{0}, \infty$

Either there are numbers $t_1, \dots, t_k \in [0, 1]$ with $\sum_{i=1}^k t_i = 1$, such that

$$(\mathbf{0} - \mathbf{u})^* = \sum_{i=1}^k t_i (\mathbf{z}_i - \mathbf{u})^*$$

or there exist some $\mathbf{a} \in \mathbb{R}^n$, $\alpha, \beta \in \mathbb{R}$, with $\beta < 0$, such that

$$\alpha \langle \mathbf{z}_i, \mathbf{z}_i \rangle + \langle \mathbf{z}_i, \mathbf{a} \rangle + \beta > 0, \text{ for all } i = 1, \dots, k$$

$$\alpha \langle \mathbf{u}, \mathbf{u} \rangle + \langle \mathbf{u}, \mathbf{a} \rangle + \beta = 0$$

Lemma

Let $\mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{R}^n$ be distinct and let $\mathbf{u} := -\sum_{i=1}^k t_i \mathbf{z}_i$ for some $t_1, \dots, t_k \in [0, \infty)$

For any $\mathbf{v} \in \mathbb{R}^n \setminus \{\mathbf{u}\}$

Lemma

Let $\mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{R}^n$ be distinct and let $\mathbf{u} := -\sum_{i=1}^k t_i \mathbf{z}_i$ for some $t_1, \dots, t_k \in [0, \infty)$

For any $\mathbf{v} \in \mathbb{R}^n \setminus \{\mathbf{u}\}$

Either there are numbers $\alpha_1, \dots, \alpha_k \in [0, \infty)$, such that

$$\mathbf{v} = \sum_{i=1}^k \alpha_i \mathbf{z}_i$$

Lemma

Let $\mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{R}^n$ be distinct and let $\mathbf{u} := -\sum_{i=1}^k t_i \mathbf{z}_i$ for some $t_1, \dots, t_k \in [0, \infty)$

For any $\mathbf{v} \in \mathbb{R}^n \setminus \{\mathbf{u}\}$

Either there are numbers $\alpha_1, \dots, \alpha_k \in [0, \infty)$, such that

$$\mathbf{v} = \sum_{i=1}^k \alpha_i \mathbf{z}_i$$

or there exist $\mathbf{a} \in \mathbb{R}^n$ and $\alpha, \beta \in \mathbb{R}$, with $\alpha \geq 0$, such that

$$\alpha \langle \mathbf{z}_i, \mathbf{z}_i \rangle + \langle \mathbf{z}_i, \mathbf{a} \rangle + \beta > 0, \text{ for all } i = 1, \dots, k$$

$$\alpha \langle \mathbf{v}, \mathbf{v} \rangle + \langle \mathbf{v}, \mathbf{a} \rangle + \beta < 0$$

$$\alpha \langle \mathbf{u}, \mathbf{u} \rangle + \langle \mathbf{u}, \mathbf{a} \rangle + \beta = 0$$

Definition

Let $\mathbf{z}_1, \dots, \mathbf{z}_k, \mathbf{u} \in \hat{\mathbb{R}}^n$ be distinct, $\mathbf{u} \neq \infty$ and define

$$\text{cone}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\} := \left\{ \mathbf{u} + \left(\sum_{i=1}^k t_i (\mathbf{u} + (\mathbf{z}_i - \mathbf{u})^*) - \mathbf{u} \right)^* : t_j \in [0, \infty) \right\} \cup \{\mathbf{u}\}$$

Definition

Let $\mathbf{z}_1, \dots, \mathbf{z}_k, \mathbf{u} \in \hat{\mathbb{R}}^n$ be distinct, $\mathbf{u} \neq \infty$ and define

$$\text{cone}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\} := \left\{ \mathbf{u} + \left(\sum_{i=1}^k t_i (\mathbf{u} + (\mathbf{z}_i - \mathbf{u})^*) - \mathbf{u} \right)^* : t_j \in [0, \infty) \right\} \cup \{\mathbf{u}\}$$

This is the image under $T_{\mathbf{u}}$ of $\text{cone}\{T_{\mathbf{u}}(\mathbf{z}_1), \dots, T_{\mathbf{u}}(\mathbf{z}_k)\} \cup \{\infty\}$

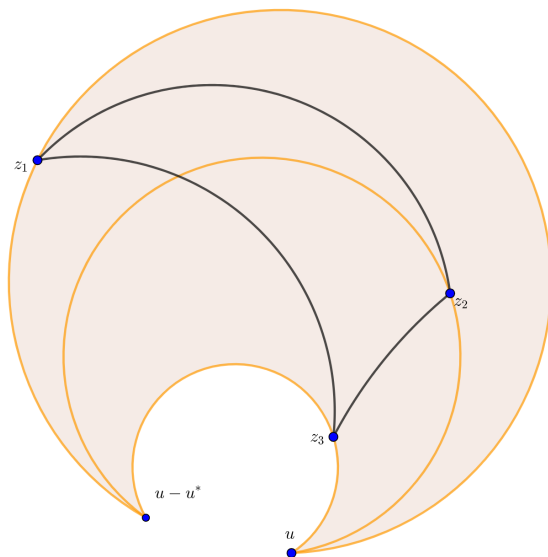
Definition

Let $\mathbf{z}_1, \dots, \mathbf{z}_k, \mathbf{u} \in \hat{\mathbb{R}}^n$ be distinct, $\mathbf{u} \neq \infty$ and define

$$\text{cone}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\} := \left\{ \mathbf{u} + \left(\sum_{i=1}^k t_i (\mathbf{u} + (\mathbf{z}_i - \mathbf{u})^*) - \mathbf{u} \right)^* : t_j \in [0, \infty) \right\} \cup \{\mathbf{u}\}$$

This is the image under $T_{\mathbf{u}}$ of $\text{cone}\{T_{\mathbf{u}}(\mathbf{z}_1), \dots, T_{\mathbf{u}}(\mathbf{z}_k)\} \cup \{\infty\}$

It is the union of all circular arcs through $\mathbf{u} - \mathbf{u}^*$, \mathbf{u} , and some $\mathbf{z} \in \text{conv}_{\mathbf{u}}\{\mathbf{z}_1, \dots, \mathbf{z}_k\}$



Lemma (Farkas' Lemma)

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ be distinct, $\mathbf{u} \neq \infty$ and let $\mathbf{v} \in \hat{\mathbb{R}}^n \setminus \{\mathbf{u}\}$

Lemma (Farkas' Lemma)

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ be distinct, $\mathbf{u} \neq \infty$ and let $\mathbf{v} \in \hat{\mathbb{R}}^n \setminus \{\mathbf{u}\}$

Either there are $t_1, \dots, t_k \in [0, \infty)$ such that

$$\mathbf{u} + (\mathbf{v} - \mathbf{u})^* = \sum_{i=1}^k t_i (\mathbf{u} + (\mathbf{z}_i - \mathbf{u})^*)$$

Lemma (Farkas' Lemma)

Let $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$ be distinct, $\mathbf{u} \neq \infty$ and let $\mathbf{v} \in \hat{\mathbb{R}}^n \setminus \{\mathbf{u}\}$

Either there are $t_1, \dots, t_k \in [0, \infty)$ such that

$$\mathbf{u} + (\mathbf{v} - \mathbf{u})^* = \sum_{i=1}^k t_i (\mathbf{u} + (\mathbf{z}_i - \mathbf{u})^*)$$

or there exist $\mathbf{a} \in \mathbb{R}^n$ and $\alpha, \beta \in \mathbb{R}$ such that

$$\alpha \langle \mathbf{z}_i, \mathbf{z}_i \rangle + \langle \mathbf{z}_i, \mathbf{a} \rangle + \beta \leq 0, \text{ for all } i = 1, \dots, k$$

$$\alpha \langle \mathbf{v}, \mathbf{v} \rangle + \langle \mathbf{v}, \mathbf{a} \rangle + \beta > 0$$

$$\alpha \langle \mathbf{u}, \mathbf{u} \rangle + \langle \mathbf{u}, \mathbf{a} \rangle + \beta = 0$$

$$\alpha \langle \mathbf{u}, \mathbf{u} \rangle - \alpha - \beta = 0$$

Polar convexity with multiple poles

Problems with a single pole can often be reduced to classical convexity

Problems with a single pole can often be reduced to classical convexity

However a set can be convex with respect to multiple poles

Problems with a single pole can often be reduced to classical convexity

However a set can be convex with respect to multiple poles

Definition

Given $U, Z \subseteq \mathbb{R}^n$ define *the convex hull of Z with respect to U* , denoted by $\text{conv}_U(Z)$, to be the smallest set in \mathbb{R}^n containing Z and convex with respect to each $\mathbf{u} \in U$

Problems with a single pole can often be reduced to classical convexity

However a set can be convex with respect to multiple poles

Definition

Given $U, Z \subseteq \hat{\mathbb{R}}^n$ define *the convex hull of Z with respect to U* , denoted by $\text{conv}_U(Z)$, to be the smallest set in $\hat{\mathbb{R}}^n$ containing Z and convex with respect to each $\mathbf{u} \in U$

If $U = \emptyset$ then $\text{conv}_U(Z) = Z$

Problems with a single pole can often be reduced to classical convexity

However a set can be convex with respect to multiple poles

Definition

Given $U, Z \subseteq \hat{\mathbb{R}}^n$ define *the convex hull of Z with respect to U* , denoted by $\text{conv}_U(Z)$, to be the smallest set in $\hat{\mathbb{R}}^n$ containing Z and convex with respect to each $\mathbf{u} \in U$

If $U = \emptyset$ then $\text{conv}_U(Z) = Z$

If $Z = \emptyset$ then $\text{conv}_U(Z) = \emptyset$

Problems with a single pole can often be reduced to classical convexity

However a set can be convex with respect to multiple poles

Definition

Given $U, Z \subseteq \hat{\mathbb{R}}^n$ define *the convex hull of Z with respect to U* , denoted by $\text{conv}_U(Z)$, to be the smallest set in $\hat{\mathbb{R}}^n$ containing Z and convex with respect to each $\mathbf{u} \in U$

If $U = \emptyset$ then $\text{conv}_U(Z) = Z$

If $Z = \emptyset$ then $\text{conv}_U(Z) = \emptyset$

It is hard to determine $\text{conv}_U(Z)$ in general

Problems with a single pole can often be reduced to classical convexity

However a set can be convex with respect to multiple poles

Definition

Given $U, Z \subseteq \hat{\mathbb{R}}^n$ define *the convex hull of Z with respect to U* , denoted by $\text{conv}_U(Z)$, to be the smallest set in $\hat{\mathbb{R}}^n$ containing Z and convex with respect to each $\mathbf{u} \in U$

If $U = \emptyset$ then $\text{conv}_U(Z) = Z$

If $Z = \emptyset$ then $\text{conv}_U(Z) = \emptyset$

It is hard to determine $\text{conv}_U(Z)$ in general

However, things are easier when U and Z are finite

For any $Z \subset \hat{\mathbb{R}}^n$

Lemma

Given distinct points $\mathbf{u}_1, \mathbf{u}_2 \in \hat{\mathbb{R}}^n$, we have

$$\text{conv}_{\{\mathbf{u}_1, \mathbf{u}_2\}}(Z) = \text{conv}_{\mathbf{u}_1}(\text{conv}_{\mathbf{u}_2}(Z)) = \text{conv}_{\mathbf{u}_2}(\text{conv}_{\mathbf{u}_1}(Z))$$

For any $Z \subset \hat{\mathbb{R}}^n$

Lemma

Given distinct points $\mathbf{u}_1, \mathbf{u}_2 \in \hat{\mathbb{R}}^n$, we have

$$\text{conv}_{\{\mathbf{u}_1, \mathbf{u}_2\}}(Z) = \text{conv}_{\mathbf{u}_1}(\text{conv}_{\mathbf{u}_2}(Z)) = \text{conv}_{\mathbf{u}_2}(\text{conv}_{\mathbf{u}_1}(Z))$$

Lemma

Given distinct points $\mathbf{u}_1, \dots, \mathbf{u}_m \in \hat{\mathbb{R}}^n$, we have

$$\text{conv}_{\{\mathbf{u}_1, \dots, \mathbf{u}_m\}}(Z) = \text{conv}_{\mathbf{u}_m}(\text{conv}_{\{\mathbf{u}_1, \dots, \mathbf{u}_{m-1}\}}(Z))$$

Let $n \geq 2$ and take distinct points $\mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$

Let the points $\mathbf{u}_1, \dots, \mathbf{u}_m \in \hat{\mathbb{R}}^n$, $m \geq 2$, be distinct

(But not necessarily distinct from $\mathbf{z}_1, \dots, \mathbf{z}_k$)

Let

$$Z := \{\mathbf{z}_1, \dots, \mathbf{z}_k\}$$

$$U := \{\mathbf{u}_1, \dots, \mathbf{u}_m\}$$

Let $n \geq 2$ and take distinct points $\mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$

Let the points $\mathbf{u}_1, \dots, \mathbf{u}_m \in \hat{\mathbb{R}}^n$, $m \geq 2$, be distinct

(But not necessarily distinct from $\mathbf{z}_1, \dots, \mathbf{z}_k$)

Let

$$Z := \{\mathbf{z}_1, \dots, \mathbf{z}_k\}$$

$$U := \{\mathbf{u}_1, \dots, \mathbf{u}_m\}$$

Consider the following family for $i \in \{1, \dots, m\}$

$$\mathcal{L}_i := \{S \subset \hat{\mathbb{R}}^n : S \text{ closed spherical domain, } Z \subset S, \mathbf{u}_i \in \partial S \text{ and}$$

$$U \subset \text{cl}(S^c) \text{ and } S \text{ is determined by } Z \cup U\}$$

Let $n \geq 2$ and take distinct points $\mathbf{z}_1, \dots, \mathbf{z}_k \in \hat{\mathbb{R}}^n$

Let the points $\mathbf{u}_1, \dots, \mathbf{u}_m \in \hat{\mathbb{R}}^n$, $m \geq 2$, be distinct

(But not necessarily distinct from $\mathbf{z}_1, \dots, \mathbf{z}_k$)

Let

$$Z := \{\mathbf{z}_1, \dots, \mathbf{z}_k\}$$

$$U := \{\mathbf{u}_1, \dots, \mathbf{u}_m\}$$

Consider the following family for $i \in \{1, \dots, m\}$

$$\mathcal{L}_i := \{S \subset \hat{\mathbb{R}}^n : S \text{ closed spherical domain, } Z \subset S, \mathbf{u}_i \in \partial S \text{ and}$$

$$U \subset \text{cl}(S^c) \text{ and } S \text{ is determined by } Z \cup U\}$$

If $\text{conv}_U(Z)$ has non-empty interior, these are finite

Theorem

If $\text{conv}_U(Z)$ has non-empty interior then the boundary of $\text{conv}_U(Z)$ is made up of pieces of the boundaries of closed spherical domains S with the following properties:

Theorem

If $\text{conv}_U(Z)$ has non-empty interior then the boundary of $\text{conv}_U(Z)$ is made up of pieces of the boundaries of closed spherical domains S with the following properties:

- *Each S lies in \mathcal{L}_i , for some $i = 1, \dots, m$*

Theorem

If $\text{conv}_U(Z)$ has non-empty interior then the boundary of $\text{conv}_U(Z)$ is made up of pieces of the boundaries of closed spherical domains S with the following properties:

- *Each S lies in \mathcal{L}_i , for some $i = 1, \dots, m$*
- *Each piece of the boundary is of the form $\text{conv}_{\partial S \cap U}(\partial S \cap Z)$*

Theorem

If $\text{conv}_U(Z)$ has non-empty interior then the boundary of $\text{conv}_U(Z)$ is made up of pieces of the boundaries of closed spherical domains S with the following properties:

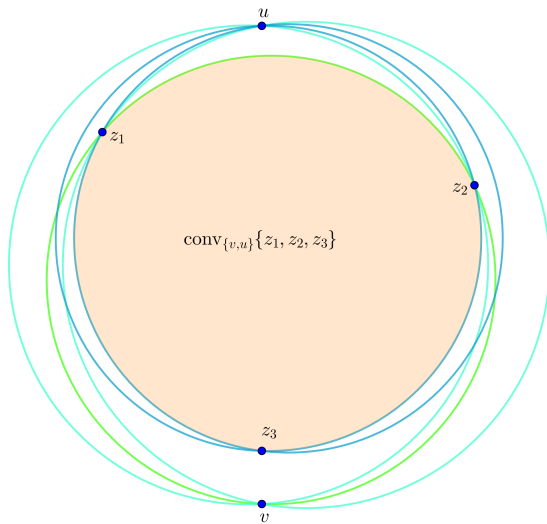
- *Each S lies in \mathcal{L}_i , for some $i = 1, \dots, m$*
- *Each piece of the boundary is of the form $\text{conv}_{\partial S \cap U}(\partial S \cap Z)$*
- $\text{conv}_U(Z) = \bigcap_{i=1}^m \bigcap_{S \in \mathcal{L}_i} S$

Theorem

If $\text{conv}_U(Z)$ has non-empty interior then the boundary of $\text{conv}_U(Z)$ is made up of pieces of the boundaries of closed spherical domains S with the following properties:

- *Each S lies in \mathcal{L}_i , for some $i = 1, \dots, m$*
- *Each piece of the boundary is of the form $\text{conv}_{\partial S \cap U}(\partial S \cap Z)$*
- $\text{conv}_U(Z) = \bigcap_{i=1}^m \bigcap_{S \in \mathcal{L}_i} S$

In other words, given a point $z \notin \text{conv}_U(Z)$, there exists a spherical domain $S \in \mathcal{L}_i$ such that $z \notin S$, for some $i = 1, \dots, m$



Recall

$$\operatorname{conv}_{\mathbf{u}}(\operatorname{conv}_{\infty}(Z)) = \operatorname{conv}_{\infty}(\operatorname{conv}_{\mathbf{u}}(Z))$$

Recall

$$\text{conv}_{\mathbf{u}}(\text{conv}_{\infty}(Z)) = \text{conv}_{\infty}(\text{conv}_{\mathbf{u}}(Z))$$

Given distinct points $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{R}^n$, and $t, \alpha_j, \beta_j \in [0, 1]$, for $1 \leq j \leq k$, such that

$$\sum_{j=1}^k \alpha_j = \sum_{j=1}^k \beta_j = 1$$

there exist $\gamma_i, \delta_{i,j} \in [0, 1]$, for $1 \leq i \leq n+1$ and $1 \leq j \leq k$, such that

$$\sum_{i=1}^{n+1} \gamma_i = \sum_{j=1}^k \delta_{i,j} = 1 \text{ for all } 1 \leq i \leq n+1$$

and satisfying

$$\left(t \left(\sum_{i=1}^k \alpha_i (\mathbf{z}_i - \mathbf{u}) \right)^* + (1-t) \left(\sum_{i=1}^k \beta_i (\mathbf{z}_i - \mathbf{u}) \right)^* \right)^* = \sum_{i=1}^{n+1} \gamma_i \left(\sum_{j=1}^k \delta_{i,j} (\mathbf{z}_j - \mathbf{u})^* \right)^*$$

Restricting it to \mathbb{C} , we get

Proposition

Given distinct points $\mathbf{u}, \mathbf{z}_1, \dots, \mathbf{z}_k \in \mathbb{C}$, and $t, \alpha_j, \beta_j \in [0, 1]$, for $1 \leq j \leq k$, such that

$$\sum_{j=1}^k \alpha_j = \sum_{j=1}^k \beta_j = 1$$

there exist $\gamma_i, \delta_{i,j} \in [0, 1]$, for $1 \leq i \leq 3$ and $1 \leq j \leq k$, such that

$$\sum_{i=1}^3 \gamma_i = \sum_{j=1}^k \delta_{i,j} = 1 \text{ for all } 1 \leq i \leq 3$$

and satisfying

$$\frac{1}{\frac{t}{\sum_{i=1}^k \alpha_i (\mathbf{z}_i - \mathbf{u})} + \frac{1-t}{\sum_{i=1}^k \beta_i (\mathbf{z}_i - \mathbf{u})}} = \frac{\gamma_1}{\sum_{j=1}^k \frac{\delta_{1,j}}{\mathbf{z}_j - \mathbf{u}}} + \frac{\gamma_2}{\sum_{j=1}^k \frac{\delta_{2,j}}{\mathbf{z}_j - \mathbf{u}}} + \frac{\gamma_3}{\sum_{j=1}^k \frac{\delta_{3,j}}{\mathbf{z}_j - \mathbf{u}}}$$

Proposition

For $A \subseteq \mathbb{R}^n$ we have $A \subseteq \mathcal{P}(\mathcal{P}(A))$

Proposition

For $A \subseteq \mathbb{R}^n$ we have $A \subseteq \mathcal{P}(\mathcal{P}(A))$

As a consequence, we get two increasing chains

Proposition

For $A \subseteq \hat{\mathbb{R}}^n$ we have $A \subseteq \mathcal{P}(\mathcal{P}(A))$

As a consequence, we get two increasing chains

$$A \subseteq \mathcal{P}(\mathcal{P}(A)) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(A)))) \subseteq \dots$$

$$\mathcal{P}(A) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(A))) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(A))))) \subseteq \dots$$

Proposition

For $A \subseteq \hat{\mathbb{R}}^n$ we have $A \subseteq \mathcal{P}(\mathcal{P}(A))$

As a consequence, we get two increasing chains

$$A \subseteq \mathcal{P}(\mathcal{P}(A)) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(A)))) \subseteq \dots$$

$$\mathcal{P}(A) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(A))) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(A))))) \subseteq \dots$$

What are the sets A, B such that $\mathcal{P}(A) \supseteq B$ and $\mathcal{P}(B) \supseteq A$?

Proposition

For $A \subseteq \mathbb{R}^n$ we have $A \subseteq \mathcal{P}(\mathcal{P}(A))$

As a consequence, we get two increasing chains

$$A \subseteq \mathcal{P}(\mathcal{P}(A)) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(A)))) \subseteq \dots$$

$$\mathcal{P}(A) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(A))) \subseteq \mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(\mathcal{P}(A))))) \subseteq \dots$$

What are the sets A, B such that $\mathcal{P}(A) \supseteq B$ and $\mathcal{P}(B) \supseteq A$?

Moreover, what are the pairs of sets A, B such that $\mathcal{P}(A) = B$ and $\mathcal{P}(B) = A$?

Thank You!

Bibliography

- R.T. Rockafellar: *Convex Analysis*, Princeton University Press, (1970)
- Bl. Sendov, H. Sendov and C. Wang: Polar convexity and critical points of polynomials, *J. Convex Anal.* 26 (2), 635–660 (2019)
- Bl. Sendov, H. Sendov: Sets in the complex plane mapped into convex ones by Möbius transformations, *J. Convex Anal.* 27(3), 791–810 (2020)
- H. Sendov: Refinements of the Gauss-Lucas theorem using rational lemniscates and polar convexity. *Proc. Amer. Math. Soc.* 149(12), 5179–5193 (2021)
- A. F. Beardon: *The Geometry of Discrete Groups*, Springer New York, (1983)
- W. Specht: Eine Bemerkung zum Satze von Gauß-Lucas, *Jahresbericht der Deutschen Mathematiker-Vereinigung*, 62, 85–92 (1959)
- S. Bhatt, H. Sendov: On polar convexity in finite dimensional euclidean spaces, *To appear, Canad. J. Math.*, (2024)