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# EEDG/CE 6303: Testing and Testable Design

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## Session 05

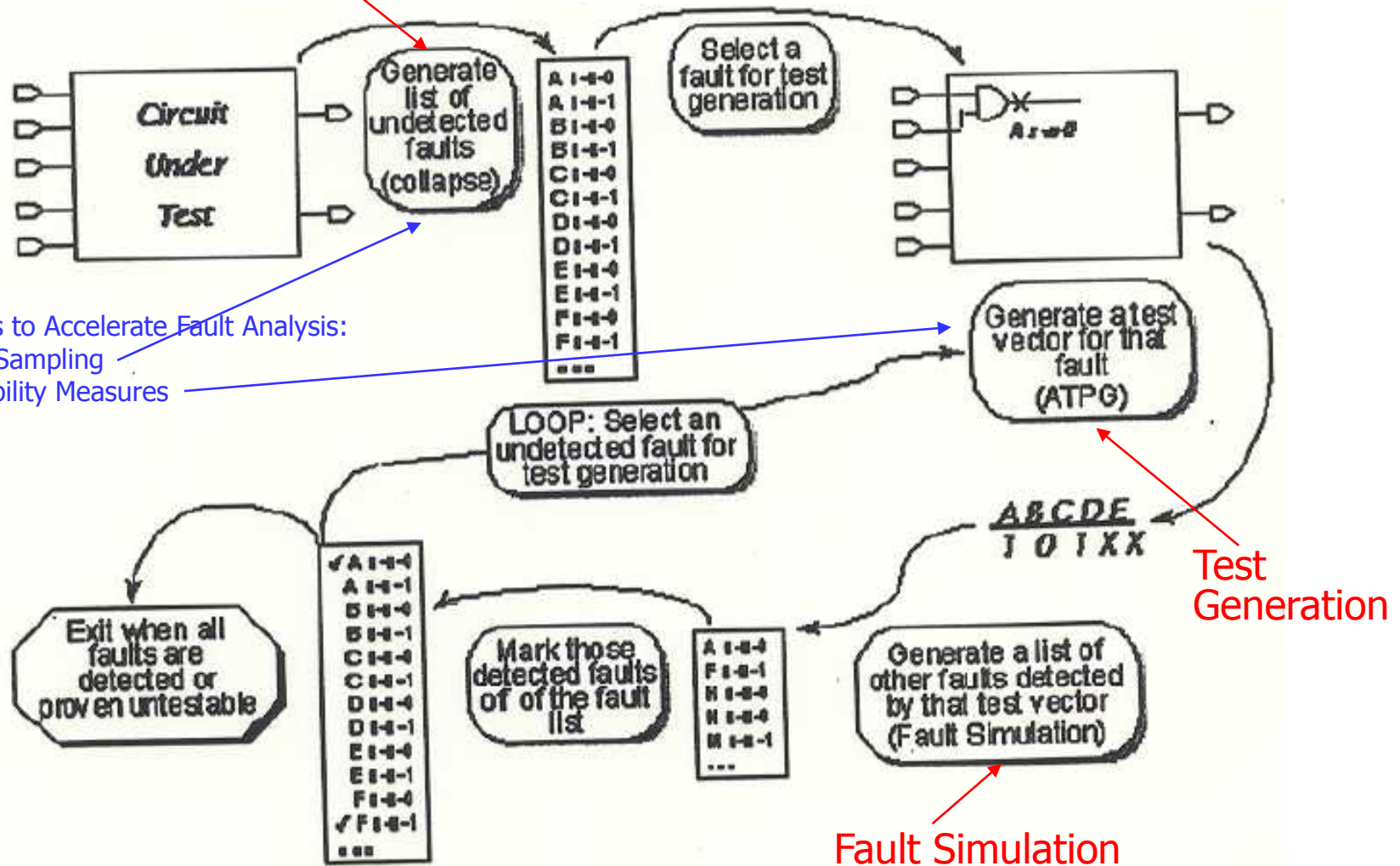
# **Acceleration Heuristics for Test Generation**

# Fault Analysis System (Review)

Fault Collapsing

Heuristics to Accelerate Fault Analysis:

- Fault Sampling
- Testability Measures



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# **Fault Sampling**

## **(A Statistical Method for Fault Simulation)**

# Basic Idea

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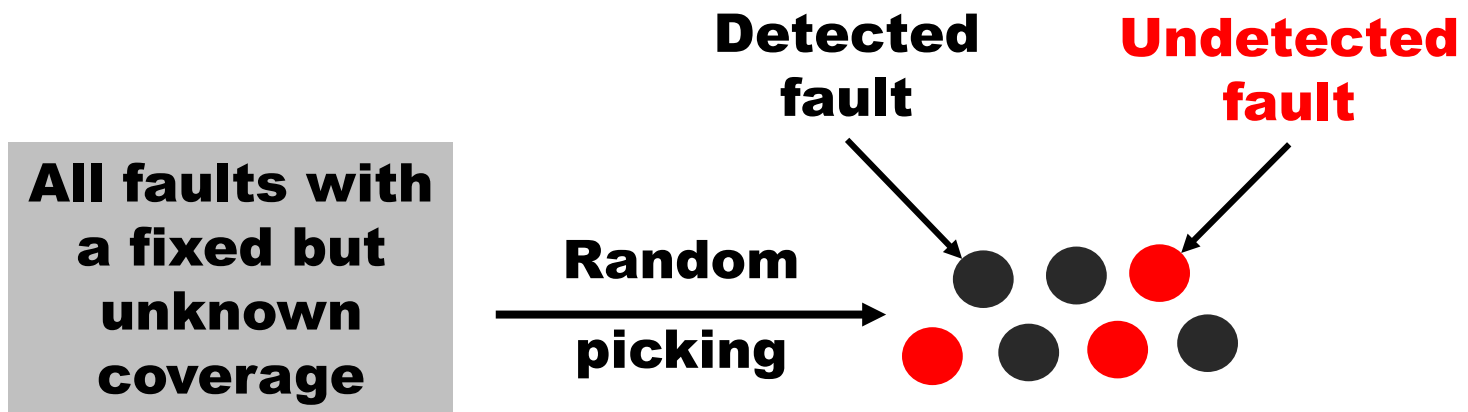
- A randomly selected subset (sample) of faults is simulated.
- Measured coverage in the sample is used to estimate fault coverage in the entire circuit.
- **Advantage:** Saving in computing resources (CPU time and memory.)
- **Disadvantage:** Limited data on undetected faults.

# Motivation for Sampling

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- Complexity of fault simulation depends on:
  - Number of gates
  - **Number of faults**
  - Number of vectors
- Complexity of fault simulation with fault sampling depends on:
  - Number of gates
  - Number of vectors

# Random Sampling Model



$N_p$  = total number of faults  
(population size)

$C$  = fault coverage  
(unknown ;  $0 \leq C \leq 1$ )

$N_s$  = sample size  
 $N_s \ll N_p$

$c$  = sample coverage  
(a random variable –  
 $0 \leq c \leq 1$ )

- The challenge is to sample enough such that
  - You save time compared to simulating all faults and
  - $c$  (estimated fault coverage) is close to  $C$  (real fault coverage).

# Key Parameters

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- **$N_p$** : Total number of faults in the circuit for which coverage is to be determined
- **$C$** : Unknown but true fault coverage of given vectors,  $0 \leq C \leq 1$ . This is the quantity being estimated.
- **$CN_p$** : Actual (but unknown) number of faults detectable by the given vectors.
- **$N_s$** : Number of randomly sampled faults from the set of  $N_p$  faults.  $N_s$  is known and normally  $N_s \ll N_p$ .
- **$c$** : Sample coverage, a random variable with range,  $0 \leq c \leq 1$ .
- **$x$** : Value of  $c$  determined from sample fault simulation,  $0 \leq x \leq 1$ .
- **$xN_s$** : Number of sampled faults detected by given vectors. This is a known quantity that is determined by the fault simulator.



# Probabilistic Analysis

- Using the key parameters:

Ways of obtaining sample of size  $N_s = \binom{N_p}{N_s} = \frac{N_p!}{N_s!(N_p - N_s)!}$  **Number of ways to choose detectable faults**

Ways of obtaining sample coverage  $x = \binom{CN_p}{xN_s} \cdot \binom{(1-C)N_p}{(1-x)N_s}$  **Number of ways to choose undetectable faults**

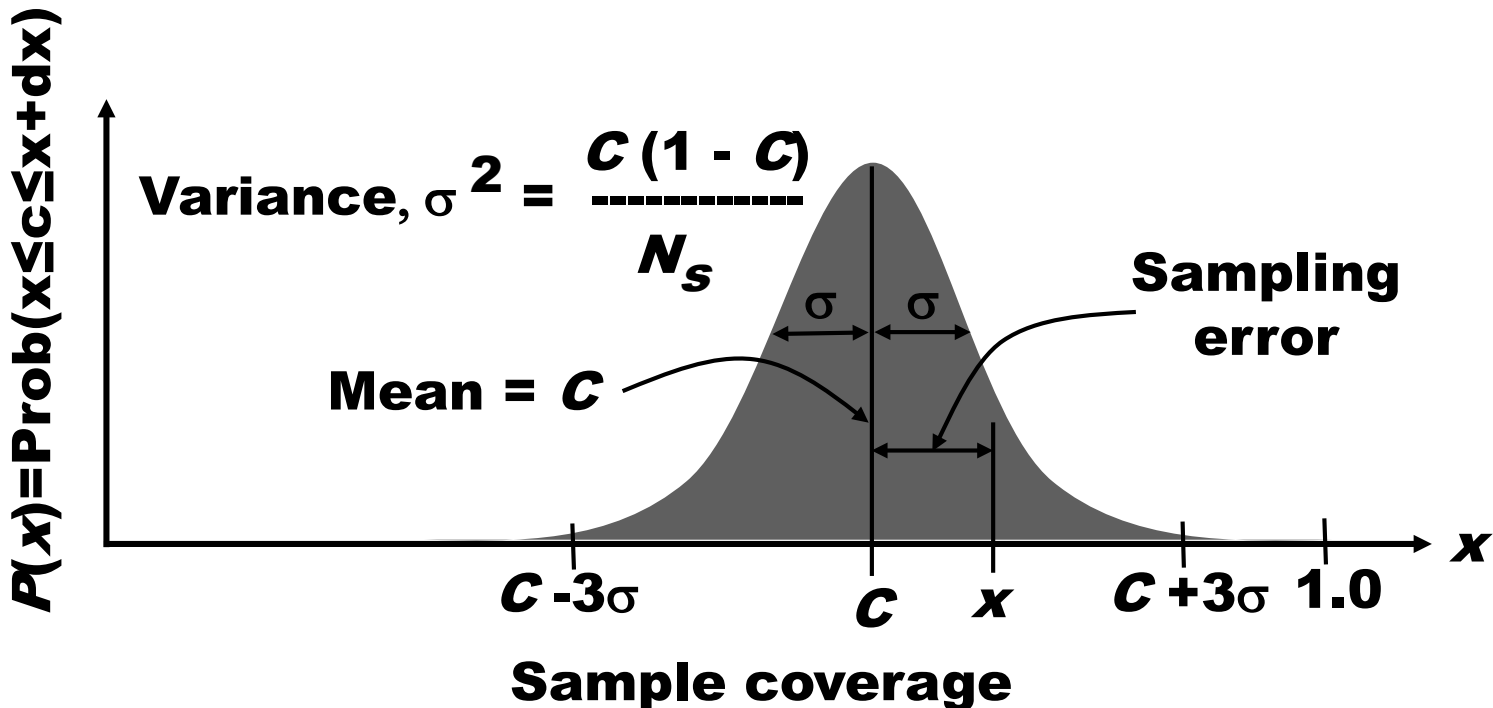
$$p(x) = \text{Prob}(\text{sample coverage, } c = x) = \frac{\binom{CN_p}{xN_s} \cdot \binom{(1-C)N_p}{(1-x)N_s}}{\binom{N_p}{N_s}}$$

- This is known as the **hypergeometric** probability density function of a discrete-valued random variable. The random variable  $c$  can take discrete values  $0, 1/N_s, 2/N_s, \dots, 1$ . When  $N_s$  is large,  $c$  can be treated as a continuous variable and the above  $p(x)$  can be approximated by a **Gaussian (normal)** probability density function with mean  $E(c) = C$  and variance  $\sigma^2$ :

$$p(x) = \text{Prob}(x \leq c \leq x + dx) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-C)^2}{2\sigma^2}}$$

# Probability Density of Sample Coverage

$$p(x) = \text{Prob}(x \leq c \leq x + dx) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-C)^2}{2\sigma^2}}$$



Probability that the sampled fault coverage stays within a limit

# Sampling Error

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- The variance of  $c$  can be determined as:

$$\sigma^2 = \frac{C(1-C)}{N_s} \left(1 - \frac{N_s}{N_p}\right) \approx \frac{C(1-C)}{N_s}$$

- The sampling error is defined as  $|x-C|$  and its high confidence (0.997 probability) can be determined by limiting it to  $3\sigma$ .

$$\begin{aligned} |x - C| &= 3\sigma \\ &= 3 \sqrt{\frac{C(1-C)}{N_s}} \end{aligned}$$

- For sampling error  $\lambda\sigma$  in general (instead of  $3\sigma$ ) solve this quadratic equation for  $C$ :

$$(x - C)^2 = \lambda^2 \frac{C(1-C)}{N_s}$$

- When  $\lambda=3$ , using approximation of  $N_s \geq 1000$

$$3\sigma \text{ coverage estimate} = C_{3\sigma} = x \pm \frac{4.5}{N_s} \sqrt{1 + 0.44 N_s x(1-x)}$$

## Example I

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- A circuit with 39,096 faults has an actual fault coverage of  $C=87.1\%$ . This is found by an accurate fault simulation in 94sec CPU time.
- The measured coverage in a random sample of  $N_s=1,000$  faults is  $x=88.7\%$ .
- CPU time for sample simulation was 11sec, i.e. about 10% of that for all faults.
- The  $C_{3\sigma}$  formula gives an estimate of   
—  $88.7\% \pm 3\%$ .

## Example II

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- For the same circuit with 39,096 faults, suppose we want the  $3\sigma$  sampling error not to exceed  $\pm\Delta$

$$\Delta^2 = \frac{4.5^2}{N_s^2} (1 + 0.44N_s x(1-x)) \approx \frac{4.5^2}{N_s} 0.44x(1-x)$$

- The sample size is assumed to be large. Since maximum value of  $x(1-x)$  is 0.25 which occurs at  $x=0.5$ , we get:

$$N_s = \frac{4.5^2 \times 0.44 \times 0.25}{\Delta^2} = \frac{2.2275}{\Delta^2}$$

- For  $\Delta=0.02$ , we obtain  $N_s=5,569$ , that is the sample size for the worst case. If  $x=0.90$ , then  $C_\Delta = C_{0.02} = 0.90 \pm 0.02$ .
- If  $x=0.90$ , the  $3\sigma$  range will be  $C_{3\sigma} = 0.90 \pm 0.012$ .