

## Syntax of $\lambda_i^+$

Types	$A, B, C ::= \top \mid \mathbb{B} \mid A \rightarrow B \mid \{\ell : A\} \mid A \& B$
Type indices	$\tau ::= \mathbb{B} \mid \overrightarrow{\tau} \mid \{\ell : \tau\} \mid \tau_1 \& \tau_2$
Expressions	$e ::= \{\} \mid b \mid x \mid \mathbf{fix} \ x : A. e \mid \lambda x : A. e : B \mid e_1 e_2 \mid \{\ell = e\} \mid e.\ell \mid e_1 ,, e_2 \mid e : A$
Values	$v ::= \{\} \mid b \mid \lambda x : A. e : B \mid \{\ell = v\} \mid v_1 ,, v_2$

$$\boxed{|A| = \tau}$$

(Type translation)

$$|\mathbb{B}| = \mathbb{B} \quad |A \rightarrow B| = \overrightarrow{|B|} \quad |\{\ell : A\}| = \{\ell : |A|\} \quad |A \& B| = |A| \& |B|$$

## Compiling from $\lambda_i^+$ to JavaScript

$$\boxed{\Gamma \vdash e \Leftrightarrow A \rightsquigarrow z \text{ in } J}$$

(Type-directed compilation)

<b>J-TOP</b> $\frac{}{\Gamma \vdash \{\} \Rightarrow \top \rightsquigarrow z \text{ in } S_1}$	<b>J-TOPABS</b> $\frac{}{\Gamma \vdash \lambda x : A. e : B \Rightarrow A \rightarrow B \rightsquigarrow z \text{ in } S_1}$	<b>J-BASE</b> $\frac{\tau =  \mathbb{B} }{\Gamma \vdash b \Rightarrow \mathbb{B} \rightsquigarrow z \text{ in } S_2}$
<b>J-VAR</b> $\frac{x : A \in \Gamma}{\Gamma \vdash x \Rightarrow A \rightsquigarrow x \text{ in } \emptyset}$	<b>J-FIX</b> $\frac{\Gamma, x : A \vdash e \Leftarrow A \rightsquigarrow y \text{ in } J}{\Gamma \vdash \mathbf{fix} \ x : A. e \Rightarrow A \rightsquigarrow x \text{ in } S_3}$	<b>J-ABS</b> $\frac{\tau = \overrightarrow{ B }}{\Gamma, x : A \vdash e \Leftarrow B \rightsquigarrow y \text{ in } J} \quad \Gamma \vdash \lambda x : A. e : B \Rightarrow A \rightarrow B \rightsquigarrow z \text{ in } S_4$
<b>J-APP</b> $\frac{\Gamma \vdash e_1 \Rightarrow A \rightsquigarrow x \text{ in } J_1 \quad A \triangleright B \rightarrow C \quad \Gamma \vdash e_2 \Leftarrow B \rightsquigarrow y \text{ in } J_2}{\Gamma \vdash e_1 e_2 \Rightarrow C \rightsquigarrow z \text{ in } S_5}$	<b>J-RCD</b> $\frac{\tau = \{\ell :  A \} \quad \Gamma \vdash e \Rightarrow A \rightsquigarrow x \text{ in } J}{\Gamma \vdash \{\ell = e\} \Rightarrow \{\ell : A\} \rightsquigarrow z \text{ in } S_6}$	<b>J-PROJ</b> $\frac{\Gamma \vdash e \Rightarrow A \rightsquigarrow x \text{ in } J_1 \quad A \triangleright \{\ell : B\}}{\Gamma \vdash e.\ell \Rightarrow B \rightsquigarrow z \text{ in } S_7}$
<b>J-MERGE</b> $\frac{\Gamma \vdash e_1 \Rightarrow A \rightsquigarrow x \text{ in } J_1 \quad \Gamma \vdash e_2 \Rightarrow B \rightsquigarrow y \text{ in } J_2 \quad A * B}{\Gamma \vdash e_1 ,, e_2 \Rightarrow A \& B \rightsquigarrow z \text{ in } S_8}$	<b>J-ANNO</b> $\frac{\Gamma \vdash e \Leftarrow A \rightsquigarrow x \text{ in } J}{\Gamma \vdash e : A \Rightarrow A \rightsquigarrow x \text{ in } J}$	<b>J-SUB</b> $\frac{\Gamma \vdash e \Rightarrow A \rightsquigarrow x \text{ in } J_1 \quad A <: B \rightsquigarrow x \mapsto y \text{ with } J_2}{\Gamma \vdash e \Leftarrow B \rightsquigarrow y \text{ in } S_9}$

```
/* S1 */
var z = {};

/* S2 */
var z = {};
z.<t> = b;

/* S3 */
var x = (() => {
  J;
```

```
    return y;
  })();

/* S4 */
var z = {};
z.<t> = x => {
  J;
  return y;
};
```

```
/* S5 */
J1;
J2;
J3;

/* S6 */
J;
var z = {};
z.<t> = x;
```

```
/* S7 */
J1;
J2;
```

```
/* S8 */
J1;
J2;
var z = {...x, ...y};
```

```
/* S9 */
J1;
var y = {};
J2;
```

$A \triangleright x \bullet \text{arg} \hookrightarrow z \text{ with } J$

(Distributive application)

A-TOP

$$\frac{\lceil A \rceil}{A \triangleright x \bullet \text{arg} \hookrightarrow z \text{ with } S_{10}}$$

A-ARROW

$$\frac{\tau = \overrightarrow{|B|}}{A \rightarrow B \triangleright x \bullet y \hookrightarrow z \text{ with } S_{11}}$$

A-RCD

$$\frac{\tau = \{\ell : |A|\}}{\{\ell : A\} \triangleright x \bullet \ell \hookrightarrow z \text{ with } S_{12}}$$

A-AND

$$\frac{\begin{array}{l} A \triangleright x \bullet \text{arg} \hookrightarrow z_1 \text{ with } J_1 \\ B \triangleright x \bullet \text{arg} \hookrightarrow z_2 \text{ with } J_2 \end{array}}{A \& B \triangleright x \bullet \text{arg} \hookrightarrow z \text{ with } S_{13}}$$

```
/* S10 */
var z = {};

/* S11 */
var z = x.<t>(y);
```

```
/* S12 */
var z = x.<t>;
```

```
/* S13 */
J1;
J2;
var z = {...z1, ...z2};
```

$A <: B \rightsquigarrow x \mapsto y \text{ with } J$

(Coercive subtyping)

S-TOP

$$\frac{B^\circ \quad \lceil B \rceil}{A <: B \rightsquigarrow x \mapsto y \text{ with } \emptyset}$$

S-BASE

$$\frac{\tau = |\mathbb{B}|}{\mathbb{B} <: \mathbb{B} \rightsquigarrow x \mapsto y \text{ with } S_{14}}$$

S-ARROW

$$\frac{\begin{array}{l} \tau_1 = \overrightarrow{|A_2|} \quad \tau_2 = \overrightarrow{|B_2|} \quad B_2^\circ \\ B_1 <: A_1 \rightsquigarrow x_1 \mapsto y_1 \text{ with } J_1 \\ A_2 <: B_2 \rightsquigarrow x_2 \mapsto y_2 \text{ with } J_2 \end{array}}{A_1 \rightarrow A_2 <: B_1 \rightarrow B_2 \rightsquigarrow x \mapsto y \text{ with } S_{15}}$$

S-RCD

$$\frac{\begin{array}{l} \tau_1 = \{\ell : |A|\} \\ \tau_2 = \{\ell : |B|\} \quad B^\circ \\ A <: B \rightsquigarrow x_0 \mapsto y_0 \text{ with } J \end{array}}{\{\ell : A\} <: \{\ell : B\} \rightsquigarrow x \mapsto y \text{ with } S_{16}}$$

S-ANDL

$$\frac{A <: C \rightsquigarrow x \mapsto y \text{ with } J}{A \& B <: C \rightsquigarrow x \mapsto y \text{ with } J}$$

S-ANDR

$$\frac{B <: C \rightsquigarrow x \mapsto y \text{ with } J}{A \& B <: C \rightsquigarrow x \mapsto y \text{ with } J}$$

S-SPLIT

$$\frac{\begin{array}{l} B_1 \triangleleft B \triangleright B_2 \\ A <: B_1 \rightsquigarrow x \mapsto y_1 \text{ with } J_1 \\ A <: B_2 \rightsquigarrow x \mapsto y_2 \text{ with } J_2 \\ y_1 : B_1 \triangleright z : B \triangleleft y_2 : B_2 \text{ with } J_3 \end{array}}{A <: B \rightsquigarrow x \mapsto z \text{ with } S_{17}}$$

```

/* S14 */          return y2;
y.<t> = x.<t>;        };
/* S15 */          /* S16 */          /* S17 */
y.<t2> = p => {       var x0 = x.<t1>;      var y1 = {};
  var x2 = x.<t1>(p); var y0 = {};      J1;
  var y2 = {};      J2;
  J2;               y.<t2> = y0;          var y2 = {};
                                   J2;
                                   J3;

```

$x : A \triangleright z : C \triangleleft y : B \textbf{ with } J$

(Coercive merging)

M-ARROW

$$\begin{array}{c}
\text{M-AND} \\
\frac{\tau_1 = |A| \quad \tau_2 = |B|}{x : A \triangleright z : A \& B \triangleleft y : B \textbf{ with } S_{17}}
\end{array}
\quad
\begin{array}{c}
\text{M-ARROW} \\
\frac{\tau_1 = \overrightarrow{|B_1|} \quad \tau_2 = \overrightarrow{|B_2|} \quad y_1 : B_1 \triangleright y : B \triangleleft y_2 : B_2 \textbf{ with } J}{x_1 : A \rightarrow B_1 \triangleright z : A \rightarrow B \triangleleft x_2 : A \rightarrow B_2 \textbf{ with } S_{18}}
\end{array}$$

M-RCD

$$\frac{\tau = \{\ell : |A|\} \quad \tau_1 = \{\ell : |A_1|\} \quad \tau_2 = \{\ell : |A_2|\} \quad y_1 : A_1 \triangleright y : A \triangleleft y_2 : A_2 \textbf{ with } J}{x_1 : \{\ell : A_1\} \triangleright z : \{\ell : A\} \triangleleft x_2 : \{\ell : A_2\} \textbf{ with } S_{19}}$$

```

/* S17 */          /* S18 */          /* S19 */
z = {...x, ...y};  z.<t> = p => {      var y1 = x1.<t1>(p);
                                   var y2 = x2.<t2>(p);
                                   var y = {};
                                   J;
                                   return y;
                                   };
                                   /* S19 */
                                   var y1 = x1.<t1>;
                                   var y2 = x2.<t2>;
                                   var y = {};
                                   J;
                                   z.<t> = y;

```