Compiling from F_i^+ to JavaScript

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Syntax of F_i^+

Types
$$A,B,C ::= \top \ | \ \bot \ | \ \mathbb{B} \ | \ X \ | \ A \to B \ | \ \forall X*A. \ B \ | \ \{\ell:A\} \ | \ A \ \& \ B$$

Type indices
$$\tau ::= \mathbb{B} \mid \overrightarrow{\tau} \mid \tau^{\forall} \mid \{\ell : \tau\} \mid \tau_1 \& \tau_2$$

Expressions
$$e := \{\} \mid b \mid x \mid \mathbf{fix} \ x : A. \ e \mid \lambda x : A. \ e : B \mid e_1 \ e_2 \mid \Lambda X * A. \ e : B \mid e \ A \mid \{\ell = e\} \mid e.\ell\}$$

$$| e_1,, e_2 | e : A$$

Values
$$v := \{\} \mid b \mid \lambda x : A.\ e : B \mid \Lambda X * A.\ e : B \mid \{\ell = v\} \mid v_1,, v_2\}$$

$$|A| = \tau$$
 (Type translation)

$$|\mathbb{B}| = \mathbb{B} \qquad |X| = X \qquad |\forall X*A. \ B| = |B|^\forall \qquad |A \rightarrow B| = |\overrightarrow{B}| \qquad |\{\ell:A\}| = \{\ell:|A|\} \qquad |A \ \& \ B| = |A| \ \& \ |B|$$

$$\rceil A \lceil$$
 (Top-like types)

$$\frac{\text{TL-TOP}}{|\top|} \qquad \frac{\text{TL-AND}}{|A| |B|} \qquad \frac{\text{TL-ARROW}}{|B|} \qquad \frac{\text{TL-ALL}}{|B|} \qquad \frac{\text{TL-RCD}}{|A|}$$

$$A^{\circ}$$
 (Ordinary types)

O-Top O-Bot O-Base O-Var
$$B^{\circ}$$
 O-Arrow B° O-All B° A°

$$\overline{T^{\circ}}$$
 $\overline{L^{\circ}}$ $\overline{B^{\circ}}$ $\overline{X^{\circ}}$ $\overline{(A \to B)^{\circ}}$ $\overline{(\forall X*A. B)^{\circ}}$ $\overline{\{\ell: A\}^{\circ}}$

```
\Gamma \vdash e \Leftrightarrow A \leadsto z \text{ in } J
                                                                                                                                                               (Type-directed compilation)
                                                                     J-TopAbs
                                                                                                                                                               \operatorname{J-Base}
       Ј-Тор
                                                                                                       ]B[
                                                                                                                                                                            	au = |\mathbb{B}|
       \Gamma \vdash \{\} \Rightarrow \top \leadsto z \text{ in } S_1
                                                                                                                                                               \Gamma \vdash b \Rightarrow \mathbb{B} \rightsquigarrow z \text{ in } S_2
                                                                     \Gamma \vdash \lambda x : A. \ e : B \Rightarrow A \rightarrow B \implies z \text{ in } S_1
                                                                                                                                     J-ABS
 J-Var
                                                                                                                                        \Gamma, x : A \vdash e \Leftarrow B \rightsquigarrow y \text{ in } J
                                                             \Gamma, x: A \vdash e \Leftarrow A | \leadsto y \text{ in } J |
              x:A\in\Gamma
                                                          \Gamma \vdash \mathbf{fix} \ x : A. \ e \Rightarrow A \leadsto x \ \mathbf{in} \ S_3
                                                                                                                                     \Gamma \vdash \lambda x : A. \ e : B \Rightarrow A \rightarrow B \rightsquigarrow z \text{ in } S_4
  \Gamma \vdash x \Rightarrow A \rightsquigarrow x \text{ in } \varnothing
                        J-APP
                             \Gamma \vdash e_1 \Rightarrow A \rightsquigarrow x \text{ in } J_1
                                       A \triangleright B \rightarrow C
                                                                                                       J-TABS
                             \Gamma \vdash e_2 \Leftarrow B \leadsto y \text{ in } J_2
                                                                                                                                     \tau = |B|^{\forall}
                          A \vartriangleright x \bullet y \hookrightarrow z \text{ with } J_3
                                                                                                             \Gamma, X * A \vdash e \Leftarrow B \leadsto y \text{ in } J
                          \Gamma \vdash e_1 \ e_2 \Rightarrow C | \leadsto z \ \mathbf{in} \ S_5
                                                                                                      \Gamma \vdash \Lambda X * A. \ e : B \Rightarrow \forall X * A. \ B \rightsquigarrow z \ \mathbf{in} \ S_6
J-TAPP
           \Gamma \vdash e \Rightarrow B \rightsquigarrow y \text{ in } J_1
                                                                                                                                                            J-Proj
                  B \rhd \forall X * C_1. C_2
                                                                                                                                                                 \Gamma \vdash e \Rightarrow A \rightsquigarrow x \text{ in } J_1
                                                                              J-Rcd
                                                                              \tau = \{\ell : |A|\}
\Gamma \vdash e \Rightarrow A \leadsto x \text{ in } J
\Gamma \vdash \{\ell = e\} \Rightarrow \{\ell : A\} \leadsto z \text{ in } S_8
                    \Gamma \vdash A * C_1
                                                                                                                                                                  A \rhd \{\overline{\ell} : B\}
                                                                                                                                                            A \vartriangleright x \bullet \ell \hookrightarrow z \text{ with } J_2
        B \vartriangleright y \bullet A \hookrightarrow z \text{ with } J_2
\Gamma \vdash e A \Rightarrow C_2[X \mapsto A] \rightsquigarrow z \text{ in } S_7
                                                                                                                                                         \Gamma \vdash e.\ell \Rightarrow B \rightsquigarrow z \text{ in } S_9
     J-Merge
               \Gamma \vdash e_1 \Rightarrow A \bowtie x \text{ in } J_1
                                                                                                                                                          \Gamma \vdash e \Rightarrow A \rightsquigarrow x \text{ in } J_1
               \Gamma \vdash e_2 \Rightarrow B \bowtie y \text{ in } J_2
                                                                                     J-Anno
                                                                                                                                                       \frac{A <: B \bowtie x \mapsto y \text{ with } J_2}{\Gamma \vdash e \Leftarrow B \bowtie y \text{ in } S_{11}}
                        \Gamma \vdash A * B
                                                                                      \Gamma \vdash e \Leftarrow A \leadsto x \text{ in } J
                                                                                     \overline{\Gamma \vdash e : A \Rightarrow A} \rightsquigarrow x \text{ in } J
      \Gamma \vdash e_1,, e_2 \Rightarrow A \& B \rightsquigarrow z \text{ in } S_{10}
/* S1 */
                                                                        };
                                                                                                                                                /* S8 */
var z = {};
                                                                                                                                                 J;
                                                                        /* S5 */
                                                                                                                                                var z = {};
/* S2 */
                                                                                                                                                z.\langle t \rangle = x;
                                                                        J1;
var z = {};
                                                                        J2;
z.<t> = b;
                                                                        J3;
                                                                                                                                                /* S9 */
                                                                                                                                                 J1;
                                                                        /* S6 */
/* S3 */
                                                                                                                                                J2;
var x = (() \Rightarrow \{
                                                                        var z = {};
                                                                        z.<t> = X => {
                                                                                                                                                /* S10 */
    J;
    return y;
                                                                            J;
                                                                                                                                                 J1;
})();
                                                                            return y;
                                                                                                                                                var z = \{...x, ...y\};
/* S4 */
var z = {};
                                                                        /* S7 */
                                                                                                                                                /* S11 */
z.<t> = x => {
                                                                        J1;
                                                                                                                                                J1;
                                                                        J2;
                                                                                                                                                var y = {};
    J;
    return y;
                                                                                                                                                 J2;
```

```
A \vartriangleright x \bullet arg \hookrightarrow z \text{ with } J
```

(Distributive application)

$$\begin{array}{c} A\text{-Top} \\ \hline A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{12} \\ \hline A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{12} \\ \hline \\ A\text{-All} \\ \hline \forall X*A. \ B \rhd x \bullet C \hookrightarrow z \text{ with } S_{14} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z_1 \text{ with } J_1 \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z_2 \text{ with } J_2 \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z_2 \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \bullet arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ arg \hookrightarrow z \text{ with } S_{16} \\ \hline \\ A \rhd x \circ z \rightarrow z \text{ w$$

```
A <: B \rightsquigarrow x \mapsto y \text{ with } J
```

(Coercive subtyping)

$$\frac{B^{\circ} \quad \exists B \lceil}{A <: B \mid \leadsto x \mapsto y \text{ with } \varnothing}$$

S-BASE
$$\tau = |\mathbb{B}|$$

$$\mathbb{B} <: \mathbb{B} \leadsto x \mapsto y \text{ with } S_{17}$$

S-Arrow
$$\begin{aligned}
\tau_1 &= |\overrightarrow{A_2}| & \tau_2 &= |\overrightarrow{B_2}| & B_2^{\circ} \\
B_1 &<: A_1 & \leadsto x_1 \mapsto y_1 \text{ with } J_1 \\
A_2 &<: B_2 & \leadsto x_2 \mapsto y_2 \text{ with } J_2
\end{aligned}$$

$$A_1 \rightarrow A_2 <: B_1 \rightarrow B_2 & \leadsto x \mapsto y \text{ with } S_{18}$$

S-All
$$\begin{aligned} \tau_1 &= |A_2|^\forall \\ \tau_2 &= |B_2|^\forall \quad B_2^\circ \\ B_1 &<: A_1 \quad \leadsto x_1 \mapsto y_1 \text{ with } J_1 \\ A_2 &<: B_2 \quad \leadsto x_2 \mapsto y_2 \text{ with } J_2 \end{aligned}$$

$$\forall X*A_1. \ A_2 <: \forall X*B_1. \ B_2 \quad \leadsto x \mapsto y \text{ with } S_{19}$$

S-RCD
$$\tau_1 = \{\ell : |A|\}$$

$$\tau_2 = \{\ell : |B|\} \quad B^{\circ}$$

$$\begin{array}{c|c}
 7_2 = \{\ell : |B|\} & B \\
 A <: B & \leadsto x_0 \mapsto y_0 \text{ with } J \\
\hline
 \{\ell : A\} <: \{\ell : B\} & \leadsto x \mapsto y \text{ with } S_{20}
\end{array}$$

S-Andl
$$C^{\circ}$$

$$A <: C \leadsto x \mapsto y \text{ with } J$$

$$A \& B <: C \leadsto x \mapsto y \text{ with } J$$

S-Andr C° $B <: C \leadsto x \mapsto y \text{ with } J$ $A \& B <: C \leadsto x \mapsto y \text{ with } J$

S-Split
$$B_1 \lhd B \rhd B_2$$

$$A \lessdot: B_1 \Leftrightarrow x \mapsto y_1 \text{ with } J_1$$

$$A \lessdot: B_2 \Leftrightarrow x \mapsto y_2 \text{ with } J_2$$

$$y_1 : B_1 \rhd z : B \vartriangleleft y_2 : B_2 \text{ with } J_3$$

$$A \lessdot: B \Leftrightarrow x \mapsto z \text{ with } S_{21}$$

```
/* S17 */
                                /* S19 */
                                                                J;
                                y.<t2> = X => {
                                                               y.<t2> = y0;
y.<t> = x.<t>;
                                  var x2 = x.<t1>(X);
/* S18 */
                                  var y2 = {};
                                                                /* S21 */
y.<t2> = p => {
                                                               var y1 = {};
                                  J2;
  var x2 = x.<t1>(p);
                                 return y2;
                                                                J1;
                                                               var y2 = {};
  var y2 = {};
                                };
  J2;
                                                                J2;
                                /* S20 */
  return y2;
                                                                J3;
                                var x0 = x.<t1>;
};
                                var y0 = {};
```

```
x:A \vartriangleright z:C \vartriangleleft y:B  with J
```

};

(Coercive merging)

```
M-Arrow
                                                                                                   \tau_1 = |\overrightarrow{B_1}| \qquad \tau_2 = |\overrightarrow{B_2}|
       M-And
                                                                                           y_1: B_1 \triangleright y: B \triangleleft y_2: B_2 \text{ with } J
                   \tau_1 = |A| \qquad \tau_2 = |B|
                                                                            \frac{g_1 \cdot B_1 \lor g \cdot B}{x_1 : A \to B_1 \rhd z : A \to B} \vartriangleleft x_2 : A \to B_2 \text{ with } S_{23}
       \overline{x:A \vartriangleright z:A \& B \vartriangleleft y:B \text{ with } S_{22}}
                                    M\text{-}All
                                                              \tau = |B|^{\forall}
\tau_1 = |B_1|^{\forall} \quad \tau_2 = |B_2|^{\forall}
                                                        y_1: B_1 > y: B \vartriangleleft y_2: B_2 with J
                                     \overline{x_1: \forall X*A.\ B_1 \ \triangleright \ z: \forall X*A.\ B \ \triangleleft \ x_2: \forall X*A.\ B_2 \text{ with } S_{24}}
                                          M-RCD
                                                                        \tau = \{\ell : |A|\}
                                                                       \tau_1 = \{\ell : |A_1|\}
                                                                       \tau_2 = \{\ell: |A_2|\}
                                                       y_1:A_1 \vartriangleright y:A \vartriangleleft y_2:A_2 with J
                                          \overline{x_1 : \{\ell : A_1\} \, \triangleright \, z : \{\ell : A\} \, \triangleleft \, x_2 : \{\ell : A_2\} \text{ with } S_{25}}
/* S22 */
z = {\ldots x, \ldots y};
                                                        /* S24 */
                                                                                                                 /* S25 */
                                                        z.\langle t \rangle = X \Rightarrow \{
                                                                                                                 var y1 = x1.<t1>;
/* S23 */
                                                           var y1 = x1.<t1>(X);
                                                                                                                 var y2 = x2.<t2>;
z.<t> = p => {
                                                          var y2 = x2.<t2>(X);
                                                                                                                 var y = {};
  var y1 = x1.<t1>(p);
                                                          var y = {};
                                                                                                                 J;
   var y2 = x2.<t2>(p);
                                                                                                                 z.<t> = y;
                                                            J;
   var y = {};
                                                            return y;
   J;
                                                         };
   return y;
```