

# Comp380

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## Programming Assignment #5

Due May 17<sup>th</sup> (Wed) 11:59 PM

### <wavefront\_obj.cc>

```
void wavefront_obj_t::draw() {

    int ptr[1] = { -1 }; //edit: numRasterized 를 저장. -1이면 F4 상태가 아닌 것.
    for ( std::size_t f = 0; f < faces.size(); f++ ) {
        face_t &face = faces[f];
        glBegin( GL_PRIMITIVE_MODE );
        for ( std::size_t v = 0; v < face.count; v++ ) {
            int vi = face.idx_begin + v;
            int i;
            if ( is_flat ) {
                if ( v == 0 ) {
                    glNormal3dv( glm::value_ptr( face.normal ) );
                }
            } else if ( ( i = normal_indices[vi] ) >= 0 ) {
                glNormal3dv( glm::value_ptr( normals[i] ) );
            }
            if ( ( i = texcoord_indices[vi] ) >= 0 ) {
                glTexCoord2dv( glm::value_ptr( texcoords[i] ) );
            }
            if ( ( i = vertex_indices[vi] ) >= 0 ) {
                glVertex3dv( glm::value_ptr( vertices[i] ) );
            }
        }

        glEnd(ptr);
    }

    //edit
    if (ptr[0] != -1) {
        printf("numRasterized = %d\n", ptr[0]);
    }
    else { // 기본으로 0을 출력.
        printf("numRasterized = %d\n", 0);
    }

    ptr[0] = -1;
    //end
}
```

## <GLRenderer.h>

```
void End(int * ptr); //edit wavefront_obj.cc 에서 glEnd이 ptr을 argument로 받기위해. processPolygon으로 ptr을
주기 위해.
//-----
void processPolygon( vector<GLVertex> &poly, int * nrPtr ); //edit 내부에서 rasterized된 삼각형의 개수를 센다.
```

## <GLRenderer.cc>

```
void GLRenderer::End(int * ptr) {
//-----
processPolygon( poly, ptr); //edit
//-----
void GLRenderer::processPolygon( vector<GLVertex> &verts, int * nrPtr) {

// rasterization
nrPtr[0] = 0;

for( i = 0; i < ( int )triVerts.size(); i += 3 ) {
    if( !RasterizeTriangle( &triVerts[i] ) ) {
        passVerticesToGL( triVerts, coords, true );
        return;
    }

    //edit
    if ( !glIsEnabled(GL_CULL_FACE)) {
        //edit : 그냥 넘어간다.
    } else {
        double x0, y0, x1, y1, x2, y2;

        x0 = triVerts[i].position[0];
        x1 = triVerts[i+1].position[0];
        x2 = triVerts[i+2].position[0];

        y0 = triVerts[i].position[1];
        y1 = triVerts[i + 1].position[1];
        y2 = triVerts[i + 2].position[1];

        if ( (x0*y1 - y0*x1) + (x1*y2 - y1*x2) + (x2*y0 - y2*x0) < 0) { // edit: whether
back face or front face

            continue; //edit: 즉, 백페이스인 경우는 더하지 않는다.
        }
    }

    if (nrPtr[0] == -1) {
        nrPtr[0] = 1;
    }
    else {
        nrPtr[0] ++;
    }
    //end
}
}
```

## <MyGL.cc>

```
double interpolation(glm::vec4 v1, glm::vec4 v2, double u, double v, double w, double d) { // interpolation
계수(비율)을 계산한다.
    double b = u * v2[0] + v * v2[1] + w * v2[2] + d * v2[3]; // 평면 ux + vy + wz + d 에 대한 상대 거리.
v2[3] != 1 이면 clipping space. 이때는 원점을 지나는 hyperplane이라 생각 가능.
    double a = u * v1[0] + v * v1[1] + w * v1[2] + d * v1[3];
    return -a / (b - a);
}
//-----
void ClipLine( const vector<GLVertex> &vertsIn, vector<GLVertex> &vertsOut, double u, double v, double w,
double d ) {
    // suppose: a line segment vector can be represented by : v1 -> v2
    int size = vertsIn.size();

    if (size == 1) {
        vertsOut = vertsIn;
        return;
    }

    for (int i = 0; i < size; i++) { // Sutherland-Hodgman Algorithm. There are four cases between one
line segment and one clipping plane (or line).
        glm::vec4 v1 = vertsIn[i].position;
        glm::vec4 v2 = vertsIn[(i + 1) % size].position; // % size: for cyclical accessing, and
avoiding [index out of bounds] exception
        bool v1In, v2In;
        v1In = (u*v1[0] + v*v1[1] + w*v1[2] + d*v1[3] >= 0) ? true : false; // inside(or on) or
outside
        v2In = (u*v2[0] + v*v2[1] + w*v2[2] + d*v2[3] >= 0) ? true : false; // inside(or on) or
outside

        if (!v1In && v2In) { //case 1: v1: out, v2: in => output: v1', v2          where v1' is
interpolated vertex from v1 and v2
            double k = interpolation(v1, v2, u, v, w, d); // compute interpolation coefficient k
            GLVertex newVert;
            for (int j = 0; j < 4; j++)          newVert.position[j] = v1[j] + k * (v2[j] - v1[j]);
// linear interpolating for position
            for (int j = 0; j < 4; j++)          newVert.color[j] = vertsIn[i].color[j] + k *
(vertsIn[(i + 1) % size].color[j] - vertsIn[i].color[j]); // linear interpolating for color
            for (int j = 0; j < 3; j++)          newVert.normal[j] = vertsIn[i].normal[j] + k *
(vertsIn[(i + 1) % size].normal[j] - vertsIn[i].normal[j]); // linear interpolating for normal vector
            for (int j = 0; j < 2; j++)          newVert.texCoord[j] = vertsIn[i].texCoord[j] + k *
(vertsIn[(i + 1) % size].texCoord[j] - vertsIn[i].texCoord[j]); // linear interpolating for texture
coordinates
            vertsOut.push_back(newVert);
            vertsOut.push_back(vertsIn[(i + 1) % size]);
        }
        else if (v1In && v2In) { //case 2: v1: in, v2: in -> output: v2
//if (i == 0) vertsOut.push_back(vertsIn[i]); // if v1 is the first vertex of the
polygon, push v1
            vertsOut.push_back(vertsIn[(i + 1) % size]);
        }
        else if (v1In && !v2In) { //case 3: v1: in, v2: out -> output: v1'
            double k = interpolation(v1, v2, u, v, w, d); // compute interpolation coefficient k
            GLVertex newVert;
            for (int j = 0; j < 4; j++)          newVert.position[j] = v1[j] + k * (v2[j] - v1[j]);
            for (int j = 0; j < 4; j++)          newVert.color[j] = vertsIn[i].color[j] + k *
(vertsIn[(i + 1) % size].color[j] - vertsIn[i].color[j]);
            for (int j = 0; j < 3; j++)          newVert.normal[j] = vertsIn[i].normal[j] + k *
(vertsIn[(i + 1) % size].normal[j] - vertsIn[i].normal[j]);
            for (int j = 0; j < 2; j++)          newVert.texCoord[j] = vertsIn[i].texCoord[j] + k *
```

```

(vertsIn[(i + 1) % size].texCoord[j] - vertsIn[i].texCoord[j]);
        //if (i == 0) vertsOut.push_back(vertsIn[i]); // if v1 is the first vertex of the
polygon, push v1
        vertsOut.push_back(newVert);
    } //case 4: v1: out, v2: out -> output: none
}
}

//-----
bool MyGL::ClipPolygon( const vector<GLVertex> &vertsIn, vector<GLVertex> &vertsOut ) {
    if( !_doClipping )
        return false;

    vector<GLVertex> cv1, cv2, cv3; //temporary vector

    ClipLine(vertsIn, cv1, -1, 0, 0, 1); // 여기서 자른 것을
    ClipLine(cv1, cv2, 1, 0, 0, 1); // 여기서 또 자르고, 다시 그걸
    ClipLine(cv2, cv3, 0, -1, 0, 1); // 여기서 또 자르고,...
    ClipLine(cv3, vertsOut, 0, 1, 0, 1);

    //vertsOut = vertsIn;

    return true;
}

//-----
bool MyGL::TriangulatePolygon( const vector<GLVertex> &polygonVerts, vector<GLVertex> &triangleVerts ) {
    if( !_doTriangulate )
        return false;

    if( polygonVerts.size() >= 3 ) {
        int size = polygonVerts.size();
        for (int i = 1; i <= size - 2; i++) { // 그냥 첫 버텍스를 공통 꼭짓점이라 생각하고 차례대로
triangleVerts에 집어넣는다.
            triangleVerts.push_back(polygonVerts[0]);
            triangleVerts.push_back(polygonVerts[i]);
            triangleVerts.push_back(polygonVerts[i + 1]);
        }
        return true;
    } else {
        return false;
    }
}

//-----
bool insideOut(double x, double y, double x0, double y0, double x1, double y1) { // 직선의 내부인지 외부인지
판별한다. 더 정확히 말하면 칠해도 되는지 안되는지.
    double A = y0 - y1;
    double B = x1 - x0;
    double C = x0 * y1 - x1 * y0;

    bool t = (A != 0) ? (A > 0) : (B > 0); // tie-breaker

    return (A*x + B*y + C > 0) || (A*x + B*y + C == 0 && t);
}

//-----
bool insideTriangle(double x, double y, glm::vec4 v0, glm::vec4 v1, glm::vec4 v2) { // 삼각형의 내부인지
외부인지 판별.
    return (insideOut(x, y, v0[0], v0[1], v1[0], v1[1]) &&

```

```

        insideOut(x, y, v1[0], v1[1], v2[0], v2[1]) &&
        insideOut(x, y, v2[0], v2[1], v0[0], v0[1]));
    }

//-----
bool MyGL::RasterizeTriangle( GLVertex verts[3] ) {
    if( !_doRasterize )
        return false;

    glm::vec4 v0 = verts[0].position;
    glm::vec4 v1 = verts[1].position;
    glm::vec4 v2 = verts[2].position;

    double x0 = v0[0], x1 = v1[0], x2 = v2[0],
           y0 = v0[1], y1 = v1[1], y2 = v2[1],
           z0 = v0[2], z1 = v1[2], z2 = v2[2];

    // for Z-buffering, evaluate the coefficients of the linear interpolation w.r.t z (a.k.a plane
    equation)
    double det = (x1 - x0) * (y2 - y0) - (x2 - x0) * (y1 - y0);
    double A = (z1 - z0) * (y2 - y0) - (z2 - z0) * (y1 - y0); A /= det;
    double B = - (z1 - z0) * (x2 - x0) + (z2 - z0) * (x1 - x0); B /= det;
    double z; // z-value

    double x_max = __max(__max(x0, x1), x2); // variables for computing total bounding box vertex.
    이것은 삼각형 v0v1v2와 접하는 직사각형이다.
    double y_max = __max(__max(y0, y1), y2);
    double x_min = __min(__min(x0, x1), x2);
    double y_min = __min(__min(y0, y1), y2);

    // Solving for Linear Interpolation Equations
    // ..... by the Formula on p.22, Lecture08.pdf (slightly modified)
    // [Ar Br Cr 0]      [r0 r1 r2 0]      [(e0)^t 0]
    // [Ag Bg Cg 0]      [g0 g1 g2 0]      [(e1)^t 0]
    // [Ab Bb Cb 0] =    [b0 b1 b2 0] * [(e2)^t 0] / (div)
    // [Aa Ba Ca 0]      [a0 a1 a2 0]      [0 0 0 0]
    // mulOut            =      in1          * in2 라고 쓰자.

    glm_vec4 initial = { 0,0,0,0 };

    glm_vec4 color0 = { verts[0].color[0], verts[0].color[1], verts[0].color[2], verts[0].color[3] };
    glm_vec4 color1 = { verts[1].color[0], verts[1].color[1], verts[1].color[2], verts[1].color[3] };
    glm_vec4 color2 = { verts[2].color[0], verts[2].color[1], verts[2].color[2], verts[2].color[3] };

    glm_vec4 inT[4] = { color0,
                        color1,
                        color2,
                        initial };

    glm_vec4 in1[4];

    glm_mat4_transpose(inT, in1);

    double div = (x1*y2 - x2*y1) - (x0*y2 - x2*y0) + (x0*y1 - x1*y0);

    glm_vec4 in2[4] = { { y1 - y2, x2 - x1, x1*y2 - x2*y1, 0 },
                        { y2 - y0, x0 - x2, x2*y0 - x0*y2, 0 },
                        { y0 - y1, x1 - x0, x0*y1 - x1*y0, 0 },
                        initial,
                    };

    glm_vec4 mulOut[4];

```

```

glm_mat4_mul(in2, in1, mulOut);
glm_vec4 rgba; // glm_vec4 -> glm::vec4로의 변환을 위해 임시저장용.
glm::vec4 color;

for (int x = x_min; x <= x_max; x++) { // total bounding box를 설정.
    for (int y = y_min; y <= y_max; y++) {
        if (insideTriangle(x, y, v0, v1, v2) || insideTriangle(x, y, v0, v2, v1)) { //
삼각형 버텍스들의 orientation에 독립적으로 내.외부 판별.
            glm_vec4 vecMulIn2 = { x, y, 1, 0 };
            rgba = glm_vec4_mul_mat4(vecMulIn2, mulOut);
            color = { rgba.m128_f32[0]/div, rgba.m128_f32[1]/div,
                    rgba.m128_f32[2]/div, rgba.m128_f32[3]/div };

            // interpolating for Z-buffering
            z = z0 + A * (x - x0) + B * (y - y0);

            //z_buffering
            if (depthTestEnabled){
                if (frameBuffer.GetDepth(x, y) > z) {
                    frameBuffer.SetDepth(x, y, z);
                    frameBuffer.SetPixel(x, y, color);
                }
            }
            else if (!depthTestEnabled) {
                frameBuffer.SetPixel(x, y, color);
            }

            /*
            main.cc의
            if( optBackFaceCulling ) {
            glFrontFace( GL_CCW );
            glEnable( GL_CULL_FACE );
            glCullFace( GL_BACK );
            }
            부분 덕분에 따로 여기서 백페이스 컬링을 구현하지 않아도 충분.
            */
        }
    }
}

return true;
}

```