

Team Contest Reference

Universität zu Lübeck

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1 Mathematische Algorithmen

1.1 Primzahlen

1.1.1 Sieb des Eratosthenes

```
1 static boolean[] sieve(int until) {
2     boolean[] a = new boolean[until + 1];
3     Arrays.fill(a, true);
4     for (int i = 2; i < Math.sqrt(a.length); i++) {
5         if (a[i]) {
6             for (int j = i * i; j < a.length; j += i) a[j] = false;
7         }
8     }
9     return a; // a[i] == true, iff. i is prime. a[0] is ignored
10 }
```

2 Datenstrukturen

2.1 Fenwick Tree (Binary Indexed Tree)

```
1 class FenwickTree {
2     private int[] values;
3     private int n;
4     public FenwickTree(int n) {
5         this.n = n;
6         values = new int[n];
7     }
8     public int get(int i) { //get value of i
9         int x = values[0];
10        while (i > 0) {
11            x += values[i];
12            i -= i & -i; }
13        return x;
14    }
15    public void add(int i, int x) { // add x to interval [i,n]
16        if (i == 0) values[0] += x;
17        else {
18            while (i < n) {
19                values[i] += x;
20                i += i & -i; }
21        }
22    }
23 }
```

3 Graphenalgorithmen

3.1 Topologische Sortierung

```
1 static List<Integer> topoSort(Map<Integer, List<Integer>> edges,
2   Map<Integer, List<Integer>> revedges) {
3   Queue<Integer> q = new LinkedList<Integer>();
4   List<Integer> ret = new LinkedList<Integer>();
5   Map<Integer, Integer> indeg = new HashMap<Integer, Integer>();
6   for (int v : revedges.keySet()) {
7     indeg.put(v, revedges.get(v).size());
8     if (revedges.get(v).size() == 0)
9       q.add(v);
10  }
11  while (!q.isEmpty()) {
12    int tmp = q.poll();
13    ret.add(tmp);
14    for (int dest : edges.get(tmp)) {
15      indeg.put(dest, indeg.get(dest) - 1);
16      if (indeg.get(dest) == 0)
17        q.add(dest);
18    }
19  }
20  return ret;
21 }
```

3.2 Prim (Minimum Spanning Tree)

```
1 #define WHITE 0
2 #define BLACK 1
3 #define INF INT_MAX
4
5 int baum( int **matrix, int N){
6   int i, sum = 0;
7
8   int color[N];
9   int dist[N];
10
11   // markiere alle Knoten ausser 0 als unbesucht
12   color[0] = BLACK;
13   for( i=1; i<N; i++){
14     color[i] = WHITE;
15     dist[i] = INF;
16   }
17
18   // berechne den Rand
19   for( i=1; i<N; i++){
20     if( dist[i] > matrix[i][nextIndex]){
21       dist[i] = matrix[i][nextIndex];
22     }
23   }
24
25   while( 1){
26     int nextDist = INF, nextIndex = -1;
27
28     /* Den naechsten Knoten waehlen */
29     for(i=0; i<N; i++){
30       if( color[i] != WHITE) continue;
31
32       if( dist[i] < nextDist){
33         nextDist = dist[i];
```

```

34         nextIndex = i;
35     }
36 }
37
38 /* Abbruchbedingung */
39 if( nextIndex == -1) break;
40
41 /* Knoten in MST aufnehmen */
42 color[nextIndex] = RED;
43 sum += nextDist;
44
45 /* naechste kuerzeste Distanzen berechnen */
46 for( i=0; i<N; i++){
47     if( i == nextIndex || color[i] == BLACK ) continue;
48
49     if( dist[i] > matrix[i][nextIndex]){
50         dist[i] = matrix[i][nextIndex];
51     }
52 }
53 }
54
55 return sum;
56 }

```

4 Geometrische Algorithmen

4.1 Graham Scan (Convex Hull)

```

1 static List<P> graham(List<P> l) {
2     if (l.size() < 3)
3         return l;
4     P temp = l.get(0);
5     for (P p : l)
6         if (temp.y > p.y || temp.y == p.y && temp.x > p.x)
7             temp = p;
8     final P start = temp; // min y (then leftmost)
9
10    Collections.sort(l, new Comparator<P>() {
11        public int compare(P o1, P o2) {
12            if (new Double(Math.atan2(o1.y - start.y, o1.x - start.x)) // same angle
13                .compareTo(Math.atan2(o2.y - start.y, o2.x - start.x)) == 0)
14                return new Double(Math.sqrt((o1.x - start.x)
15                    * (o1.x - start.x) + (o1.y - start.y)
16                    * (o1.y - start.y))).compareTo((o2.x - start.x)
17                    * (o2.x - start.x) + (o2.y - start.y)
18                    * (o2.y - start.y)); // use distance
19            return new Double(Math.atan2(o1.y - start.y, o1.x - start.x))
20                .compareTo(Math.atan2(o2.y - start.y, o2.x - start.x));
21        }
22    });
23    Stack<P> s = new Stack<P>();
24    s.add(start);
25    s.add(l.get(1));
26    for (int i = 2; i < l.size(); i++) {
27        while (s.size() >= 2
28            && ccw(s.get(s.size() - 2), s.get(s.size() - 1), l.get(i)) <= 0)
29            s.pop();
30        s.push(l.get(i));
31    }
32    return s;
33 }

```

```

34
35 // turn is counter-clockwise if > 0; collinear if = 0; clockwise else
36 static double ccw(P p1, P p2, P p3) {
37     return (p2.x - p1.x) * (p3.y - p1.y) - (p2.y - p1.y) * (p3.x - p1.x);
38 }
39
40 public static class P {
41     double x, y;
42
43     P(double x, double y) {
44         this.x = x;
45         this.y = y;
46     }
47     // polar coordinates (not used)
48     // double r() { return Math.sqrt(x * x + y * y); }
49     // double d() { return Math.atan2(y, x); }
50 }

```

5 Verschiedenes

5.1 Potenzmenge

```

1 static <T> Iterator<List<T>> powerSet(final List<T> l) {
2     return new Iterator<List<T>>() {
3         int i; // careful: i becomes 2^l.size()
4         public boolean hasNext() {
5             return i < (1 << l.size());
6         }
7         public List<T> next() {
8             Vector<T> temp = new Vector<T>();
9             for (int j = 0; j < l.size(); j++)
10                 if (((i >>> j) & 1) == 1)
11                     temp.add(l.get(j));
12             i++;
13             return temp;
14         }
15         public void remove() {}
16     };
17 }

```