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Web Processing - Standardized GIS Analyses for Cable Route Planning

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Topic and Motivation

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- route planning, e.g. connection of offshore wind farms to the power grid
- conflicts with land usage, land coverage, regulation
- routing cables from landing point to final position
- offer a standard web service for the routing

Motivation

- ► Energy Security
- ► Contribution to important real world problems



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Start Date	End Date	
09/23/2022		Project Start
09/23/2022	10/10/2022	Initial Literature Study
10/01/2022	10/23/2022	Initial Data Search
10/14/2022		Kick-Off Presentation
10/16/2022	10/28/2022	Data Conversion/Costs/test execution
10/28/2022	12/31/2022	provide WPS/implement LCP
12/02/2022		Midterm Presentation
12/14/2022	02/01/2022	Optimization/Research Issue
02/01/2022		Feature Freeze
02/01/2022	02/28/2023	Finalizing Report
02/28/2023		Submission
03/15/2023		Final Presentation

Get Land coverage/ usage planning

Datatype	Sources	
Protected Areas	German Environment Agency ¹	
land usage	Federal Agency for Cartography and Geodesy ²	
planning land usage	'Metropolplaner' (Planing data Lower Saxony	
	& Bremen) ³	
Houses (Level of Detail 1)	State Office for Geoinformation and	
	Land Surveying of Lower Saxony ⁴	
transformers, power lines	OpenStreetMap	

¹https://geodienste.bfn.de/schutzgebiete?lang=de

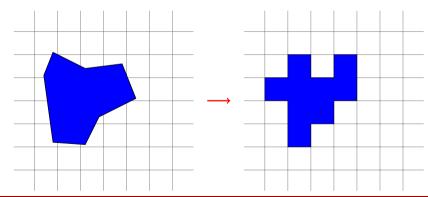
²https://gdz.bkg.bund.de/index.php/default/open-data.html

³https://metropolplaner.de/metropolplaner/

⁴https://opengeodata.lgln.niedersachsen.de/

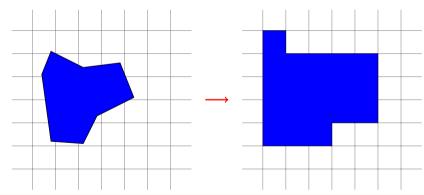
Rasterization

- vector (point, line, polygon) -> raster
- ▶ all touched <- false



Rasterization

- vector (point, line, polygon) -> raster
- ▶ all touched <- true



Costs and Configuration

Configuration

- resolution, all touched
- calculate by layer:
 - filtering by attribute values
 - buffering by value or/and attribute value
- cost calculation: maximum of al layers

Cost Level	Cost (numeric)	Example
Prohibited	500	National Parks, Buildings
strongly Restricted	10	Bird Sanctuary
Restricted	5	industrial areas
No Restriction	0.5	default
Preferential	0.1	power grid, motorways buffers

Cost Raster



Figure: 100 m Resolution with all touched false.

Cost Raster



Figure: 100 m Resolution with all touched false.



Figure: 100 m Resolution with all touched true.

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- goal: calculate path from cost with web service
- current:
 - testing pywps⁵
 - ▶ cost path (open Dijkstra implementation QGIS-plugin)⁶

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 $^{^5} https://pywps.readthedocs.io/en/latest/index.html\\$

⁶https://github.com/Gooong/LeastCostPath