Proximal Gradient Method. Proximal operator

Seminar

Optimization for ML. Faculty of Computer Science. HSE University



Regularized / Composite Objectives

Many nonsmooth problems take the form

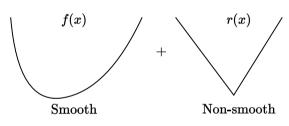
$$\min_{x \in \mathbb{R}^n} \varphi(x) = f(x) + r(x)$$

• Lasso, L1-LS, compressed sensing

$$f(x) = \frac{1}{2} ||Ax - b||_2^2, r(x) = \lambda ||x||_1$$

• L1-Logistic regression, sparse LR

$$f(x) = -y \log h(x) - (1-y) \log(1-h(x)), r(x) = \lambda ||x||_1$$



Non-smooth convex optimization lower bounds

convex (non-smooth)	strongly convex (non-smooth)
$f(x_k) - f^* \sim \mathcal{O}\left(\frac{1}{\sqrt{k}}\right)$	$f(x_k) - f^* \sim \mathcal{O}\left(\frac{1}{k}\right)$
$k_arepsilon \sim \mathcal{O}\left(rac{1}{arepsilon^2} ight)$	$k_arepsilon \sim \mathcal{O}\left(rac{1}{arepsilon} ight)$

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- Subgradient method is optimal for the problems above.
- One can use Mirror Descent (a generalization of the subgradient method to a possiby non-Euclidian distance) with the same convergence rate to better fit the geometry of the problem.
- However, we can achieve standard gradient descent rate $\mathcal{O}\left(\frac{1}{k}\right)$ (and even accelerated version $\mathcal{O}\left(\frac{1}{k^2}\right)$) if we will exploit the structure of the problem.



Proximal operator

i Proximal operator

For a convex set $E \in \mathbb{R}^n$ and a convex function $f: E \to \mathbb{R}$ operator $\operatorname{prox}_f(x)$ s.t.

$$\operatorname{prox}_f(x) = \operatorname*{argmin}_{y \in E} \left[f(y) + \frac{1}{2} ||y - x||_2^2 \right]$$

is called $\operatorname{\mathbf{proximal}}$ $\operatorname{\mathbf{operator}}$ for function f at point x

Let \mathbb{I}_S be the indicator function for closed, convex S. Recall orthogonal projection $\pi_S(y)$

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With the following notation of indicator function

$$\mathbb{I}_S(x) = \begin{cases} 0, & x \in S, \\ \infty, & x \notin S, \end{cases}$$

Rewrite orthogonal projection $\pi_S(y)$ as

$$\pi_S(y) := \arg\min_{x \in \mathbb{R}^n} \frac{1}{2} ||x - y||^2 + \mathbb{I}_S(x).$$

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Proximity: Replace \mathbb{I}_S by some convex function!

$$\mathsf{prox}_r(y) = \mathsf{prox}_{r,1}(y) := \arg\min \frac{1}{2} \|x - y\|^2 + r(x)$$

Proximal Gradient Method



Proximal Gradient Method Theorem

Consider the proximal gradient method

$$x_{k+1} = \operatorname{prox}_{\alpha r} (x_k - \alpha \nabla f(x_k))$$

for the criterion $\phi(x) = f(x) + r(x)$ s.t.: 1. f is convex, differentiable with Lipschitz gradients; 1. r is convex and prox-friendly. Then Proximal Gradient Method with fixed step size $\alpha = \frac{1}{L}$ converges with rate $O(\frac{1}{L})$



ISTA and FISTA

Methods for solving problems involving L1 regularization (e.g. Lasso).

ISTA (Iterative Shrinkage-Thresholding Algorithm) Step:

$$x_{k+1} = \operatorname{prox}_{\alpha\lambda||\cdot||_1} (x_k - \alpha \nabla f(x_k))$$

• Convergence: $O(\frac{1}{h})$

0.500

0.200

0.020 0.050

0.005 000



FISTA (Fast Iterative Shrinkage-Thresholding

Algorithm) Step:

$$x_{k+1} = \operatorname{prox}_{\alpha\lambda||\cdot||_1} (y_k - \alpha \nabla f(y_k)),$$

$$t_{k+1} = \frac{1 + \sqrt{1 + 4t_k^2}}{2},$$

$$y_{k+1}=x_{x+1}+\frac{t_k-1}{t_{k+1}}(x_{k+1}-x_k)$$
 • Convergence: $O(\frac{1}{t^2})$

Convergence.
$$O(k^2)$$

Problem 1. ReLU in prox

Question

Find the $\operatorname{prox}_f(x)$ for $f(x) = \lambda \max(0, x)$:

$$\operatorname{prox}_{\lambda \max(0,\cdot)}(x) = \operatorname*{argmin}_{y \in \mathbb{R}} \left[\frac{1}{2} ||y-x||^2 + \lambda \max(0,y) \right]$$



Problem 2. Grouped l_1 -regularizer

Question

Find the $\operatorname{prox}_f(x)$ for $f(x) = ||x||_{1/2} = \sum_{g=0}^G ||x_g||_2$ where $x \in \mathbb{R}^n = [\underbrace{x_1, x_2, \dots, \underbrace{x_{n-2}, x_{n-1}, x_n}}]$:

$$\operatorname{prox}_{||x||_{1/2}}(x) = \operatorname*{argmin}_{y \in \mathbb{R}} \left[\frac{1}{2} ||y - x||_2^2 + \sum_{g = 0}^G ||y_g||_2 \right]$$

Linear Least Squares with L_1 -regularizer

Proximal Methods Comparison for Linear Least Squares with L_1 -regularizer \clubsuit Open in Colab.

