Stochastic Gradient Descent. Finite-sum problems

Seminar

Optimization for ML. Faculty of Computer Science. HSE University

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Finite-sum problem

We consider classic finite-sample average minimization:

$$\min_{x \in \mathbb{R}^p} f(x) = \min_{x \in \mathbb{R}^p} \frac{1}{n} \sum_{i=1}^n f_i(x)$$

The gradient descent acts like follows:

$$x_{k+1} = x_k - \frac{\alpha_k}{n} \sum_{i=1}^n \nabla f_i(x)$$
 (GD)

- Iteration cost is linear in n.
- Convergence with constant α or line search.

 $f \to \min_{x,y}$

ecture recap

Finite-sum problem

at each iteration uniformly:

We consider classic finite-sample average minimization:

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The gradient descent acts like follows:

• Iteration cost is linear in
$$n$$
.

 $x_{k+1} = x_k - \frac{\alpha_k}{n} \sum_{i=1}^{n} \nabla f_i(x)$

- Convergence with constant α or line search.
- Let's/ switch from the full gradient calculation to its unbiased estimator, when we randomly choose i_k index of point

$$x_{k+1} = x_k - lpha_k
abla f_{i_k}(x_k)$$

With $p(i_k = i) = \frac{1}{n}$, the stochastic gradient is an unbiased estimate of the gradient, given by:

$$\mathbb{E}[\nabla f_{i_k}(x)] = \sum_{i=1}^n p(i_k = i) \nabla f_i(x) = \sum_{i=1}^n \frac{1}{n} \nabla f_i(x) = \frac{1}{n} \sum_{i=1}^n \nabla f_i(x) = \nabla f(x)$$

This indicates that the expected value of the stochastic gradient is equal to the actual gradient of f(x).

(GD)

(SGD)

Results for Gradient Descent

Stochastic iterations are n times faster, but how many iterations are needed?

If ∇f is Lipschitz continuous then we have:

Assumption	Deterministic Gradient Descent	Stochastic Gradient Descent
PL	$O(\log(1/arepsilon))$	O(1/arepsilon)
Convex	O(1/arepsilon)	$O(1/\varepsilon^2)$
Non-Convex	O(1/arepsilon)	$O(1/arepsilon^2)$

- Stochastic has low iteration cost but slow convergence rate.
 - Sublinear rate even in strongly-convex case.
 - Bounds are unimprovable under standard assumptions.
 - Oracle returns an unbiased gradient approximation with bounded variance.
- Momentum and Quasi-Newton-like methods do not improve rates in stochastic case. Can only improve constant factors (bottleneck is variance, not condition number).

Computational experiments

Visualization of SGD.

Let's look at computational experiments for SGD **.**



