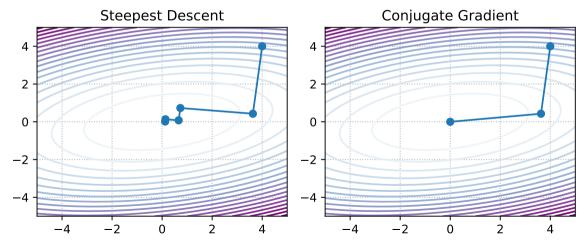


Strongly convex quadraticsConsider the following quadratic optimization problem:

Optimality conditions

$$\min_{x \in \mathbb{R}^n} f(x) = \min_{x \in \mathbb{R}^n} \frac{1}{2} x^\top A x - b^\top x + c, \text{ where } A \in \mathbb{S}^n_{++}. \tag{1}$$



Exact line search aka steepest descent

$$\alpha_k = \arg\min_{\alpha \in \mathbb{R}^+} f(x_{k+1}) = \arg\min_{\alpha \in \mathbb{R}^+} f(x_k - \alpha \nabla f(x_k))$$

More theoretical than practical approach. It also allows you to analyze the convergence, but often exact line search can be difficult if the function calculation takes too long or costs a lot. An interesting theoretical property of this method is that each following iteration is orthogonal to the previous one:

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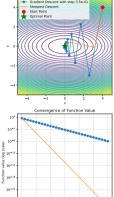
$$\alpha_k = \arg\min_{\alpha \in \mathbb{R}^+} f(x_k - \alpha \nabla f(x_k))$$

Optimality conditions:

$$\nabla f(x_k)^T \nabla f(x_{k+1}) = 0$$

Optimal value for quadratics

$$\nabla f(x_k)^{\top} A(x_k - \alpha \nabla f(x_k)) - \nabla f(x_k)^{\top} b = 0 \qquad \alpha_k = \frac{\nabla f(x_k)^T \nabla f(x_k)}{\nabla f(x_k)^T A \nabla f(x_k)}$$



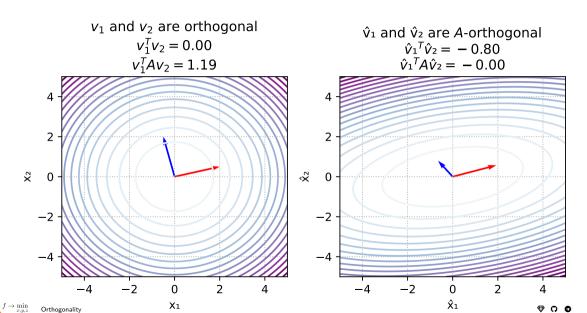
Trajectories with Contour Plot

Figure 1: Steepest Descent

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 $f \to \min_{x,y,z}$

Quadratic optimization problem



Suppose, we have two coordinate systems and some quadratic function $f(x) = \frac{1}{2}x^TIx$ looks just like on the left part of Figure 2, while in other coordinates it looks like $f(\hat{x}) = \frac{1}{2}\hat{x}^TA\hat{x}$, where $A \in \mathbb{S}^n_{++}$.

$$\frac{1}{2}x^T I x \qquad \qquad \frac{1}{2}\hat{x}^T A \hat{x}$$

Since $A = Q\Lambda Q^T$:

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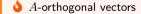


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Vectors $x \in \mathbb{R}^n$ and $y \in \mathbb{R}^n$ are called A-orthogonal (or A-conjugate) if

$$x^T A y = 0 \qquad \Leftrightarrow \qquad x \perp_A y$$

When A = I, A-orthogonality becomes orthogonality.

Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

Output: n linearly independent vectors, which are pairwise orthogonal d_0,\ldots,d_{n-1} .

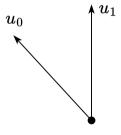


Figure 3: Illustration of Gram-Schmidt orthogonalization process

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Output: n linearly independent vectors, which are pairwise orthogonal $d_0,\ldots,d_{n-1}.$

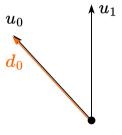


Figure 4: Illustration of Gram-Schmidt orthogonalization process

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Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

Output: n linearly independent vectors, which are pairwise orthogonal d_0,\ldots,d_{n-1} .

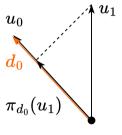


Figure 5: Illustration of Gram-Schmidt orthogonalization process

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Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

Output: n linearly independent vectors, which are pairwise orthogonal d_0, \ldots, d_{n-1} .

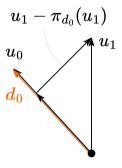


Figure 6: Illustration of Gram-Schmidt orthogonalization process

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Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

Output: n linearly independent vectors, which are pairwise orthogonal $d_0,\ldots,d_{n-1}.$

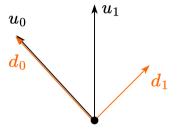
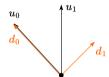
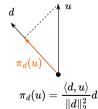
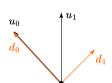


Figure 7: Illustration of Gram-Schmidt orthogonalization process

Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

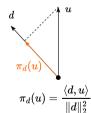




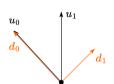


Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

$$d_0 = u_0$$

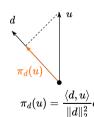




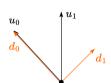


Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

$$d_0 = u_0 d_1 = u_1 - \pi_{d_0}(u_1)$$





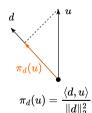


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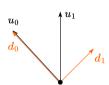
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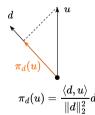
$$d_1 = u_1 - \pi_{d_0}(u_1)$$

$$d_2 = u_2 - \pi_{d_0}(u_2) - \pi_{d_1}(u_2)$$









Input: n linearly independent vectors u_0, \ldots, u_{n-1} .

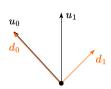
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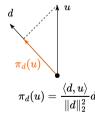
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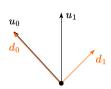
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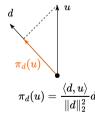
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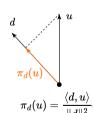
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$$d_k = u_k + \sum_{i=1}^{k-1} \beta_{ik} d_i \qquad \beta_{ik} = -\frac{\langle d_i, u_k \rangle}{\langle d_i, d_i \rangle}$$

 $f \to \min_{x,y,z}$ Orthogonality

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$$x^* = x_0 + \sum_{i=0}^{n-1} \alpha_i d_i$$
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• We will prove, that α_i and d_i could be selected in a very efficient way (Conjugate Gradient method).



Thus, we formulate an algorithm:

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5. Repeat steps 2-4 until n directions are built, where n is the dimension of space (dimension of x).

1 Lemma 1. Linear independence of A-conjugate vectors.

If a set of vectors d_1, \ldots, d_n - are A-conjugate (each pair of vectors is A-conjugate), these vectors are linearly independent. $A \in \mathbb{S}^n_{++}$.



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Lemma 1. Linear independence of A-conjugate vectors.

If a set of vectors d_1, \ldots, d_n - are A-conjugate (each pair of vectors is A-conjugate), these vectors are linearly independent. $A \in \mathbb{S}^n_{++}$.

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Thus, $\alpha_j=0$, for all other indices one has to perform the same process

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• Note also, that since $x_{k+1} = x_0 + \sum_{i=1}^k \alpha_i d_i$, we have

⊕ ∩ **a**

(4)

(5)

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Suppose, we solve n-dimensional quadratic convex optimization problem (1). The conjugate directions method

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with $\alpha_i = \frac{\langle d_i, r_i \rangle}{\langle d_i, Ad_i \rangle}$ taken from the line search, converges for at most n steps of the algorithm.



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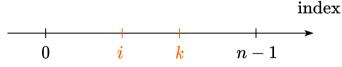
Proof

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$$e_k = \sum_{j=k}^{n-1} -\alpha_j d_j$$

Multiply both sides by $-d_i^T A$.

$$-d_i^T A e_k = \sum_{i=1}^{n-1} \alpha_j d_i^T A d_j = 0$$



Thus, $d_i^T r_k = 0$ and residual r_k is orthogonal to all previous directions d_i for the CD method.

 $t \to \min_{x,y,z}$ Conjugate Directions (CD) method

(7)

The idea of the Conjugate Gradients (CG) method

• It is literally the Conjugate Direction method, where we have a special (effective) choice of d_0, \ldots, d_{n-1} .





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- The main idea is that for an arbitrary CD method, the Gramm-Schmidt process is quite computationally expensive and requires a quadratic number of vector addition and scalar product operations $\mathcal{O}\left(n^2\right)$, while in the case of CG, we will show that the complexity of this procedure can be reduced to linear $\mathcal{O}\left(n\right)$.



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 $\mathsf{CG} = \mathsf{CD} + r_0, \dots, r_{n-1}$ as starting vectors for $\mathsf{Gram} ext{-}\mathsf{Schmidt} + A ext{-}\mathsf{orthogonality}.$





Conjugate gradients (CG) method

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All residuals are pairwise orthogonal to each other in the CG method:

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$$d_i = u_i + \sum_{i=0}^{k-1} \beta_{ji} d_j \ \beta_{ji} = -\frac{\langle d_j, u_i \rangle_A}{\langle d_j, d_j \rangle_A}$$
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Then, we use residuals as starting vectors for the process and $u_i = r_i$.



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If j < i < k, we have the lemma 4 with $d_i^T r_k = 0$ and $d_i^T r_k = 0$. We $d_i = r_i + \sum_{j=0}^{k-1} eta_{ji} d_j \;\; eta_{ji} = -rac{\langle d_j, r_i
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angle_A} \;\; ext{(10)} \;\; ext{have:}$ $r_k^T u_i = 0$ for CD $r_k^T r_i = 0$ for CG

Moreover, if k = i:

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$$r_{k+1} = -Ae_{k+1} = -A(e_k + \alpha_k d_k) = -Ae_k - \alpha_k A d_k = r_k - \alpha_k A d_k$$

Finally, all these above lemmas are enough to prove, that $\beta_{ji}=0$ for all i,j, except the neighboring ones.

 $r_{k+1} = r_k - \alpha_k A d_k$

(11)

(12)

Consider the Gram-Schmidt process in the CG method

$$\beta_{ji} = -\frac{\langle d_j, u_i \rangle_A}{\langle d_j, d_j \rangle_A}$$



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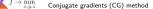
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 $f \to \min_{x,y,z}$ Conjugate gradients (CG) method

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⊕ n ø

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Finally, we have a formula for i = j + 1:

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And for the direction

$$d_{k+1} = r_{k+1} + \beta_{k,k+1} d_k, \qquad \beta_{k,k+1} = \beta_k = \frac{\langle r_{k+1}, r_{k+1} \rangle}{\langle r_{k+1}, r_{k+1} \rangle}.$$



Conjugate gradients method

$$\begin{split} \mathbf{r}_0 &:= \mathbf{b} - \mathbf{A} \mathbf{x}_0 \\ \text{if } \mathbf{r}_0 \text{ is sufficiently small, then return } \mathbf{x}_0 \text{ as the result} \\ \mathbf{d}_0 &:= \mathbf{r}_0 \\ k &:= 0 \\ \text{repeat} \\ & \alpha_k := \frac{\mathbf{r}_k^\mathsf{T} \mathbf{r}_k}{\mathbf{d}_k^\mathsf{T} \mathbf{A} \mathbf{d}_k} \\ & \mathbf{x}_{k+1} := \mathbf{x}_k + \alpha_k \mathbf{d}_k \\ & \mathbf{r}_{k+1} := \mathbf{r}_k - \alpha_k \mathbf{A} \mathbf{d}_k \\ & \text{if } \mathbf{r}_{k+1} \text{ is sufficiently small, then exit loop} \\ & \beta_k := \frac{\mathbf{r}_{k+1}^\mathsf{T} \mathbf{r}_{k+1}}{\mathbf{r}_k^\mathsf{T} \mathbf{r}_k} \\ & \mathbf{d}_{k+1} := \mathbf{r}_{k+1} + \beta_k \mathbf{d}_k \\ & k := k+1 \\ \text{end repeat} \end{split}$$



Convergence

Theorem 1. If matrix A has only r different eigenvalues, then the conjugate gradient method converges in riterations.

Theorem 2. The following convergence bound holds

$$||x_k - x^*||_A \le 2 \left(\frac{\sqrt{\kappa(A)} - 1}{\sqrt{\kappa(A)} + 1}\right)^k ||x_0 - x^*||_A,$$

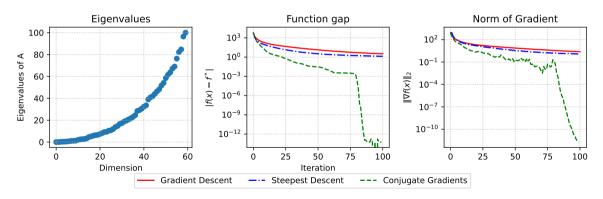
where $||x||_A^2 = x^\top Ax$ and $\kappa(A) = \frac{\lambda_1(A)}{\lambda_n(A)}$ is the conditioning number of matrix $A, \lambda_1(A) \geq ... \geq \lambda_n(A)$ are the eigenvalues of matrix A

Note: Compare the coefficient of the geometric progression with its analog in gradient descent.



$$f(x) = \frac{1}{2}x^{T}Ax - b^{T}x \to \min_{x \in \mathbb{R}^{n}}$$

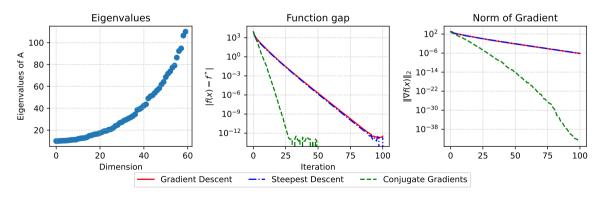
Convex quadratics. n=60, random matrix.





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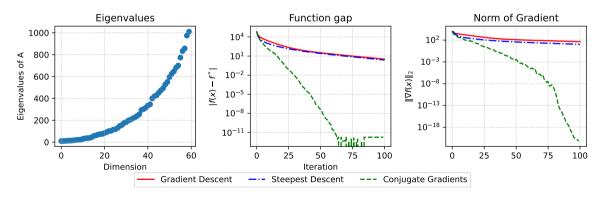
Strongly convex quadratics. n=60, random matrix.





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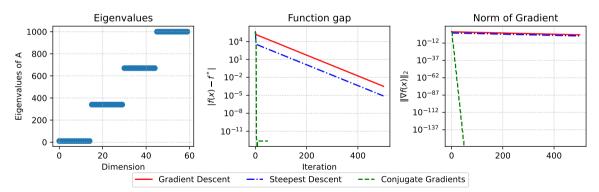
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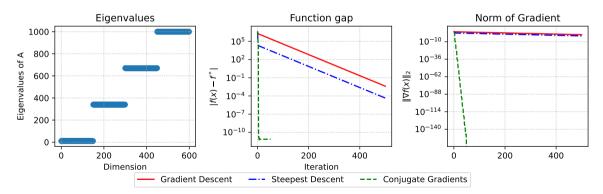
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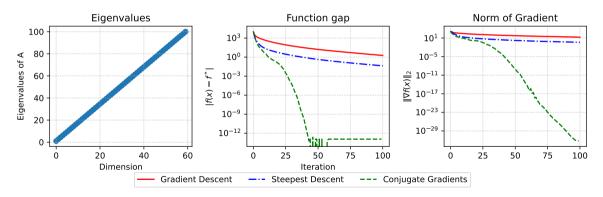
Strongly convex quadratics. n=600, clustered matrix.





$$f(x) = \frac{1}{2}x^{T}Ax - b^{T}x \to \min_{x \in \mathbb{R}^{n}}$$

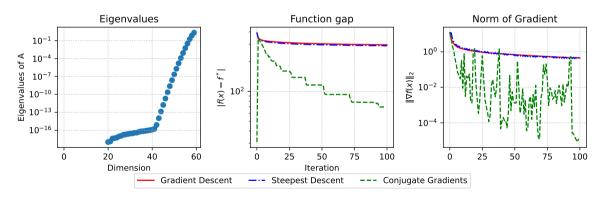
Strongly convex quadratics. n=60, uniform spectrum matrix.





$$f(x) = \frac{1}{2}x^{T}Ax - b^{T}x \to \min_{x \in \mathbb{R}^{n}}$$

Strongly convex quadratics. n=60, Hilbert matrix.







Non-linear conjugate gradient method

In case we do not have an analytic expression for a function or its gradient, we will most likely not be able to solve the one-dimensional minimization problem analytically. Therefore, step 2 of the algorithm is replaced by the usual line search procedure. But there is the following mathematical trick for the fourth point:

For two iterations, it is fair:

$$x_{k+1} - x_k = cd_k,$$

where c is some kind of constant. Then for the quadratic case, we have:

$$\nabla f(x_{k+1}) - \nabla f(x_k) = (Ax_{k+1} - b) - (Ax_k - b) = A(x_{k+1} - x_k) = cAd_k$$

Expressing from this equation the work $Ad_k = \frac{1}{c} \left(\nabla f(x_{k+1}) - \nabla f(x_k) \right)$, we get rid of the "knowledge" of the function in step definition β_k , then point 4 will be rewritten as:

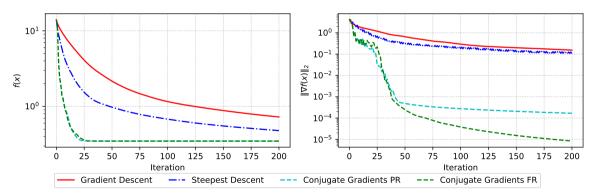
$$\beta_k = \frac{\nabla f(x_{k+1})^\top (\nabla f(x_{k+1}) - \nabla f(x_k))}{d_k^\top (\nabla f(x_{k+1}) - \nabla f(x_k))}.$$

This method is called the Polack-Ribier method.

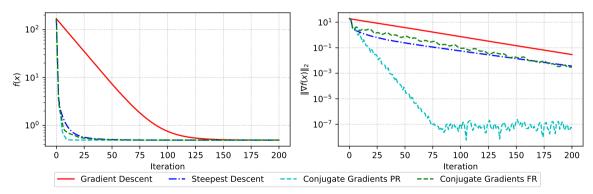




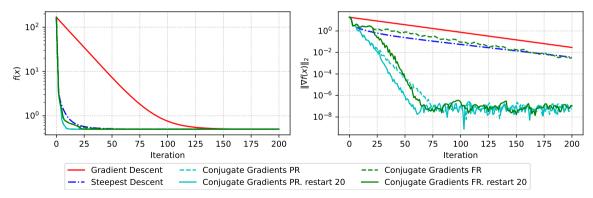
$$f(x) = \frac{\mu}{2} ||x||_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$



$$f(x) = \frac{\mu}{2} ||x||_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$

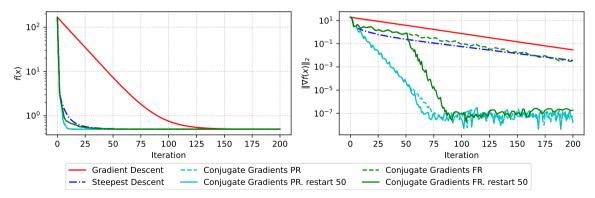


$$f(x) = \frac{\mu}{2} ||x||_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$



$$f(x) = \frac{\mu}{2} ||x||_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$

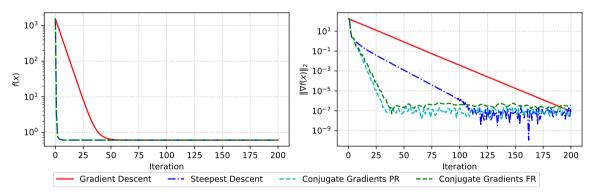
Regularized binary logistic regression. n=300. m=1000. μ =1



 $J \to \min_{x,y,z}$ Non-linear CG



$$f(x) = \frac{\mu}{2} ||x||_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$



$$f(x) = \frac{\mu}{2} ||x||_2^2 + \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \langle a_i, x \rangle)) \to \min_{x \in \mathbb{R}^n}$$

