#### Matrix calculus. Line search.

#### Seminar

Optimization for ML. Faculty of Computer Science. HSE University

എ റ ഉ

### Theory recap. Differential

• Differential  $df(x)[\cdot]:U\to V$  in point  $x\in U$  for  $f(\cdot):U\to V$ :

$$f(x+h) - f(x) = \underbrace{d\!f(x)[h]}_{\text{differential}} + \overline{o}(||h||)$$

$U \to V$	$\mathbb{R}$	$\mathbb{R}^n$	$\mathbb{R}^{n \times m}$
$\mathbb{R}$	f'(x)dx	$\nabla f(x)dx$	$\nabla f(x)dx$
$\mathbb{R}^n$	$\nabla f(x)^T dx$ $tr(\nabla f(X)^T dX)$	J(x)dx	_
$\mathbb{R}^{n  imes m}$	$tr(\nabla f(X)^T dX)$	_	_

### Theory recap. Differential

• Differential  $df(x)[\cdot]:U\to V$  in point  $x\in U$  for  $f(\cdot):U\to V$ :

$$f(x+h) - f(x) = \underbrace{df(x)[h]}_{\text{differential}} + \overline{o}(||h||)$$

Canonical form of the differential:

U  o V	$\mathbb{R}$	$\mathbb{R}^n$	$\mathbb{R}^{n  imes m}$
$\mathbb{R}$	f'(x)dx	$\nabla f(x)dx$	$\nabla f(x)dx$
$\mathbb{R}^n$	$\nabla f(x)^T dx$	J(x)dx	_
$\mathbb{R}^{n  imes m}$	$tr(\nabla f(X)^T dX)$	_	_

# Theory recap. Differentiation Rules

• Useful differentiation rules and standard derivatives:

Differentiation Rules	Standard Derivatives
dA = 0	$d(\langle A, X \rangle) = \langle A, dX \rangle$
$d(\alpha X) = \alpha(dX)$	$d(\langle Ax, x \rangle) = \langle (A + A^T)x, dx \rangle$
d(AXB) = A(dX)B	$d(Det(X)) = Det(X)\langle X^{-T}, dX \rangle$
d(X+Y) = dX + dY	$d(X^{-1}) = -X^{-1}(dX)X^{-1}$
$d(X^T) = (dX)^T$	
d(XY) = (dX)Y + X(dY)	
$d(\langle X, Y \rangle) = \langle dX, Y \rangle + \langle X, dY \rangle$	
$d\left(\frac{X}{\phi}\right) = \frac{\phi dX - (d\phi)X}{\phi^2}$	

Lecture reminder

# Theory recap. Differential and Gradient / Hessian

We can retrieve the gradient using the following formula:

$$df(x) = \langle \nabla f(x), dx \rangle$$

**೧** ∅

# Theory recap. Differential and Gradient / Hessian

We can retrieve the gradient using the following formula:

$$df(x) = \langle \nabla f(x), dx \rangle$$

Then, if we have a differential of the above form and we need to calculate the second derivative of the matrix/vector function, we treat "old" dx as the constant  $dx_1$ , then calculate  $d(df) = d^2 f(x)$ 

Lecture reminder

# Theory recap. Differential and Gradient / Hessian

We can retrieve the gradient using the following formula:

$$df(x) = \langle \nabla f(x), dx \rangle$$

Then, if we have a differential of the above form and we need to calculate the second derivative of the matrix/vector function, we treat "old" dx as the constant  $dx_1$ , then calculate  $d(df) = d^2 f(x)$ 

$$d^2 f(x) = \langle \nabla^2 f(x) dx_1, dx \rangle = \langle H_f(x) dx_1, dx \rangle$$

 $f \to \min_{x,y,z}$ 

Lecture reminder

• Solution localization methods:

- Solution localization methods:
  - Dichotomy search method

େ ଚେଡ

- Solution localization methods:
  - Dichotomy search method
  - Golden selection search method

େ ଚେଡ

- Solution localization methods:
  - Dichotomy search method
  - Golden selection search method
- Inexact line search:

- Solution localization methods:
  - Dichotomy search method
  - Golden selection search method
- Inexact line search:
  - Sufficient decrease

େ ଚେ 🗢

- Solution localization methods:
  - Dichotomy search method
  - Golden selection search method
- Inexact line search:
  - Sufficient decrease
  - Goldstein conditions

େ ପ୍ର

- Solution localization methods:
  - Dichotomy search method
  - Golden selection search method
- Inexact line search:
  - Sufficient decrease
  - Goldstein conditions
  - Curvature conditions

എ റ ഉ

- Solution localization methods:
  - Dichotomy search method
  - Golden selection search method
- Inexact line search:
  - Sufficient decrease
  - Goldstein conditions
  - Curvature conditions
  - The idea behind backtracking line search

େ ଚେ ଚ

#### Matrix Calculus. Problem 1

Find  $\nabla f(x)$ , if  $f(x) = \frac{1}{2}x^TAx + b^Tx + c$ .

### Matrix Calculus. Problem 2

Find  $\nabla f(X)$ , if  $f(X) = tr(AX^{-1}B)$ 

#### Matrix Calculus. Problem 3

Find the gradient  $\nabla f(x)$  and hessian  $\nabla^2 f(x)$ , if  $f(x) = \frac{1}{3} ||x||_2^3$ 

# Line Search. Example 1: Comparison of Methods (Colab 4)

$$f_1(x) = x(x-2)(x+2)^2$$
  
[a, b] = [-3, 2]

Random search: 72 function calls. 36 iterations.  $f_1^* = 0.09$ Binary search: 23 function calls. 13 iterations.  $f_1^* = 10.00$ Golden search: 19 function calls. 18 iterations.  $f_1^* = 10.00$ Parabolic search: 20 function calls. 17 iterations.  $f_1^* = 10.00$ 

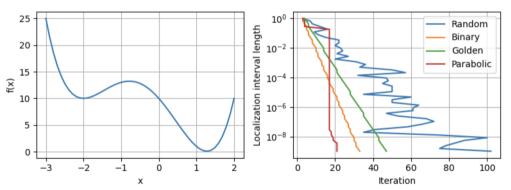


Figure 1: Comparison of different line search algorithms with  $f_1$ 

**⊕ ೧ 0** 

# Line Search. Example 1: Comparison of Methods (Colab ♣)

$$f_2(x) = -\sqrt{\frac{2}{\pi}} \frac{x^2 e^{-\frac{x^2}{8}}}{8}$$
$$[a, b] = [0, 6]$$

Random search: 68 function calls. 34 iterations.  $f_2^*=0.71$  Binary search: 23 function calls. 13 iterations.  $f_2^*=0.71$  Golden search: 20 function calls. 19 iterations.  $f_2^*=0.71$  Parabolic search: 17 function calls. 14 iterations.  $f_2^*=0.71$ 

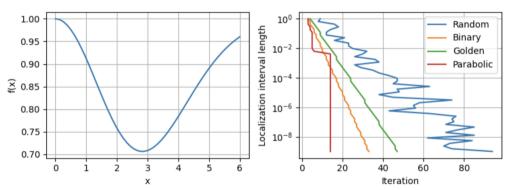


Figure 2: Comparison of different line search algorithms with  $f_2$ 

**♥೧**0

# Line Search. Example 1: Comparison of Methods (Colab ♣)

$$f_3(x) = \sin\left(\sin\left(\sin\left(\sqrt{\frac{x}{2}}\right)\right)\right)$$
  
 $[a, b] = [5, 70]$ 

Random search: 66 function calls. 33 iterations.  $f_3^*=0.25$  Binary search: 32 function calls. 17 iterations.  $f_3^*=0.25$  Golden search: 25 function calls. 24 iterations.  $f_3^*=0.25$  Parabolic search: 103 function calls. 100 iterations.  $f_3^*=0.25$ 

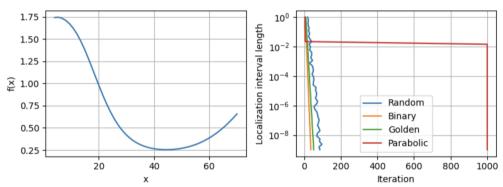


Figure 3: Comparison of different line search algorithms with  $f_3$ 

⊕ n ø

• Parabolic Interpolation + Golden Search = Brent Method

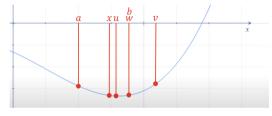


Figure 4: Idea of Brent Method

- Parabolic Interpolation + Golden Search = Brent Method
- The key idea of the method is to track the value of the optimized scalar function at six points a, b, x, w, v, u

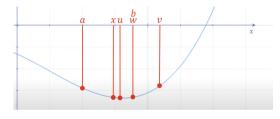


Figure 4: Idea of Brent Method

- Parabolic Interpolation + Golden Search = Brent Method
- The key idea of the method is to track the value of the optimized scalar function at six points a, b, x, w, v, u
- [a, b] localization interval in the current iteration

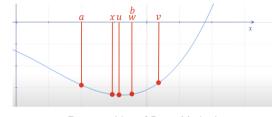


Figure 4: Idea of Brent Method

- Parabolic Interpolation + Golden Search = Brent Method
- The key idea of the method is to track the value of the optimized scalar function at six points a, b, x, w, v, u
- [a,b] localization interval in the current iteration
- The pounts x, w and v such that the inequality  $f(x) \leq f(w) \leq f(v)$  is valid

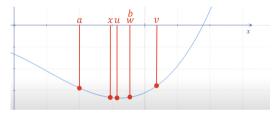


Figure 4: Idea of Brent Method

- Parabolic Interpolation + Golden Search = Brent Method
- The kev idea of the method is to track the value of the optimized scalar function at six points a, b, x, w, v, u
- [a,b] localization interval in the current iteration
- The pounts x, w and v such that the inequality  $f(x) \leq f(w) \leq f(v)$  is valid
- u minimum of a parabola built on points x, w and v or the point of the golden section of the largest of the intervals [a, x] [x, b].

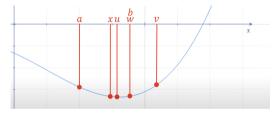


Figure 4: Idea of Brent Method



A parabola is constructed only if the points x, w and v are different, and its vertex  $u^*$  is taken as the point u only if  $u^* \in [a,b]$ 

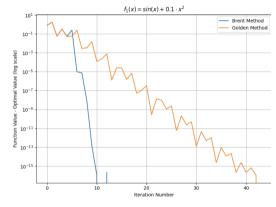


Figure 5: An example of how the Brent Method works

A parabola is constructed only if the points x, w and v are different, and its vertex  $u^{\ast}$  is taken as the point u only if

- $u^* \in [a, b]$
- $u^*$  is no more than half the length of the step that was before the previous one, from the point x

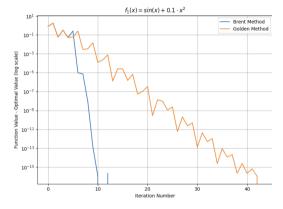


Figure 5: An example of how the Brent Method works

₹ n ø

A parabola is constructed only if the points x, w and v are different, and its vertex  $u^*$  is taken as the point u only if

- $u^* \in [a, b]$
- $u^*$  is no more than half the length of the step that was before the previous one, from the point x
- If the conditions above are not met, then point  $\boldsymbol{u}$  is located from the golden search

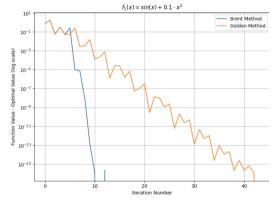


Figure 5: An example of how the Brent Method works



A parabola is constructed only if the points x, w and v are different, and its vertex  $u^*$  is taken as the point u only if

- $u^* \in [a, b]$
- $u^*$  is no more than half the length of the step that was before the previous one, from the point x
- If the conditions above are not met, then point  $\boldsymbol{u}$  is located from the golden search
- Example In Colab ♣

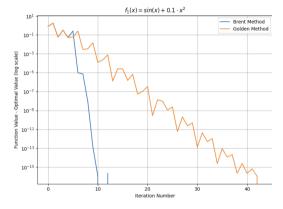


Figure 5: An example of how the Brent Method works

