ADMM

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Optimization methods. MIPT





Dual (sub)gradient method

Even if we can't derive dual (conjugate) in closed form, we can still use dual-based gradient or subgradient methods.

Consider the problem:

$$\min_{x} \quad f(x)$$
 subject to
$$Ax = b$$

Dual gradient ascent

$$x_k \in \arg\min_{x} \left[f(x) + (u_{k-1})^T A x \right]$$

$$u_k = u_{k-1} + \alpha_k (A x_k - b)$$

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- Good: x update decomposes when f does.
- Bad: require stringent assumptions (strong convexity of f) to ensure convergence

Augmented Lagrangian method transforms the primal problem to:

$$\min_{x} f(x) + \frac{\rho}{2} \|Ax - b\|^{2}$$
 s.t. $Ax = b$

 $f \to \min_{x,y,z}$ Reminder: dual methods

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- Good: better convergence properties.
- Bad: lose decomposability

Alternating direction method of multipliers or ADMM aims for the best of both worlds. Consider the following optimization problem:

Minimize the function:

$$\min_{x,z} f(x) + g(z)$$

$$\text{s.t. } Ax + Bz = c$$

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where $\rho > 0$ is a parameter. The augmented Lagrangian for this problem is defined as:

$$L_{\rho}(x, z, u) = f(x) + g(z) + u^{T}(Ax + Bz - c) + \frac{\rho}{2} ||Ax + Bz - c||^{2}$$



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Note: The usual method of multipliers would replace the first two steps by a joint minimization:

$$(x^{(k)}, z^{(k)}) = \arg\min_{x, z} L_{\rho}(x, z, u^{(k-1)})$$

Assume (very little!)

then ADMM converges:

- ullet f,g convex, closed, proper
 - If the functions f and g are convex and computationally friendly for $\arg \min$, then ADMM has the following convergence bound for any $x \in \mathbb{R}^{d_x}$, $y \in \mathbb{R}^{d_y}$, $\lambda \in \mathbb{R}^n$:

$$L_0\left(\frac{1}{k}\sum_{i=1}^k x_i, \frac{1}{k}\sum_{i=1}^K y_i, \lambda\right) - L_0(x, y, \frac{1}{k}\sum_{i=1}^k \lambda_k) \le \frac{1}{2k} \|z_0 - z\|_P^2,$$

where L_0 is the Lagrangian without augmentation, P and the initial value of z^0 are defined as :

$$P = \begin{pmatrix} \rho A^T A & 0 & -A^T \\ 0 & 0 & 0 \\ -A & 0 & \frac{1}{2}I \end{pmatrix} \quad z^0 = \begin{pmatrix} x^0 \\ y^0 \\ \lambda^0 \end{pmatrix}.$$

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- iterates approach feasibility: $Ax_k + Bz_k c \rightarrow 0$
- objective approaches optimal value: $f(x_k) + g(z_k) \rightarrow p^*$
- If the functions f and g are convex and computationally friendly for $\arg \min$, then ADMM has the following convergence bound for any $x \in \mathbb{R}^{d_x}$, $y \in \mathbb{R}^{d_y}$, $\lambda \in \mathbb{R}^n$:

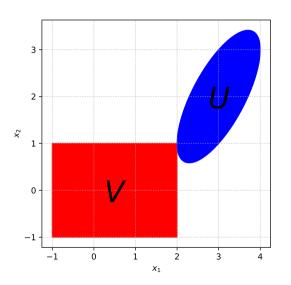
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Example:

Example: Alternating Projections



Consider finding a point in the intersection of convex sets $U, V \subseteq \mathbb{R}^n$:

$$\min_{x} I_{U}(x) + I_{V}(x)$$

To transform this problem into ADMM form, we express it as:

$$\min_{x,z} I_U(x) + I_V(z)$$
 subject to $x-z=0$

Each ADMM cycle involves two projections:

$$x_k = \arg\min_{x} P_U (z_{k-1} - w_{k-1})$$

$$z_k = \arg\min_{z} P_V (x_k + w_{k-1})$$

$$w_k = w_{k-1} + x_k - z_k$$

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Examples



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- The non-standard formulation of the problem itself, for which ADMM is invented, turns out to include many important special cases. "Unusual" variable y often plays the role of an auxiliary variable.
- Here the penalty is an additional modification to stabilize and accelerate convergence. It is not necessary to make ρ very large.



Examples

Sources

• Alternating Direction Method of Multipliers by S.Boyd





Sources

- Alternating Direction Method of Multipliers by S.Boyd
- Ryan Tibshirani. ConvAlternating Direction Method of Multipliers by S.Boydex Optimization 10-725



Examples

