

Stochastic Gradient Descent. Finite-sum problems

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Optimization methods. MIPT

Finite-sum problem

We consider classic finite-sample average minimization:

$$\min_{x \in \mathbb{R}^p} f(x) = \min_{x \in \mathbb{R}^p} \frac{1}{n} \sum_{i=1}^n f_i(x)$$

ImageNet $\sim 10^7$ images

WikiText $\sim 10^{10}$ tokens

The gradient descent acts like follows:

$$x_{k+1} = x_k - \frac{\alpha_k}{n} \sum_{i=1}^n \nabla f_i(x)$$

~~LOSS_i(w, x)~~
 $f_i = f(x, z_i)$ (GD)

- Iteration cost is linear in n .

$$\text{LOSS}(w) = \frac{1}{n} \sum_{i=1}^n \text{LOSS}_i(w, x_i)$$

↑
one per
one per
one per

↑
note per iteration
gathered

Finite-sum problem

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МАТ. ОХУГАҮЛЕЛІК РАСТАРЫНЫҢ

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=
негізгі
рекуренция.

The gradient descent acts like follows:

$$x_{k+1} = x_k - \frac{\alpha_k}{n} \sum_{i=1}^n \nabla f_i(x) = x_k - \alpha_k \cdot \frac{1}{n} (\nabla f_1 + \nabla f_2 + \dots + \nabla f_n) \quad (\text{GD})$$

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СТОХАСТИЧКИЙ
ГРАДИЕНТ

Let's/ switch from the full gradient calculation to its unbiased estimator, when we randomly choose i_k index of point at each iteration uniformly:

$$x_{k+1} = x_k - \alpha_k \nabla f_{i_k}(x_k) \quad (\text{SGD})$$

With $p(i_k = i) = \frac{1}{n}$, the stochastic gradient is an unbiased estimate of the gradient, given by:

$$\mathbb{E}[\nabla f_{i_k}(x)] = \sum_{i=1}^n p(i_k = i) \nabla f_i(x) = \sum_{i=1}^n \frac{1}{n} \nabla f_i(x) = \frac{1}{n} \sum_{i=1}^n \nabla f_i(x) = \nabla f(x)$$

This indicates that the expected value of the stochastic gradient is equal to the actual gradient of $f(x)$.

Results for Gradient Descent

Stochastic iterations are n times faster, but how many iterations are needed?

If ∇f is Lipschitz continuous then we have:

Assumption	Deterministic Gradient Descent	Stochastic Gradient Descent
PL	$O(\log(1/\varepsilon))$	$O(1/\varepsilon)$
Convex	$O(1/\varepsilon)$	$O(1/\varepsilon^2)$
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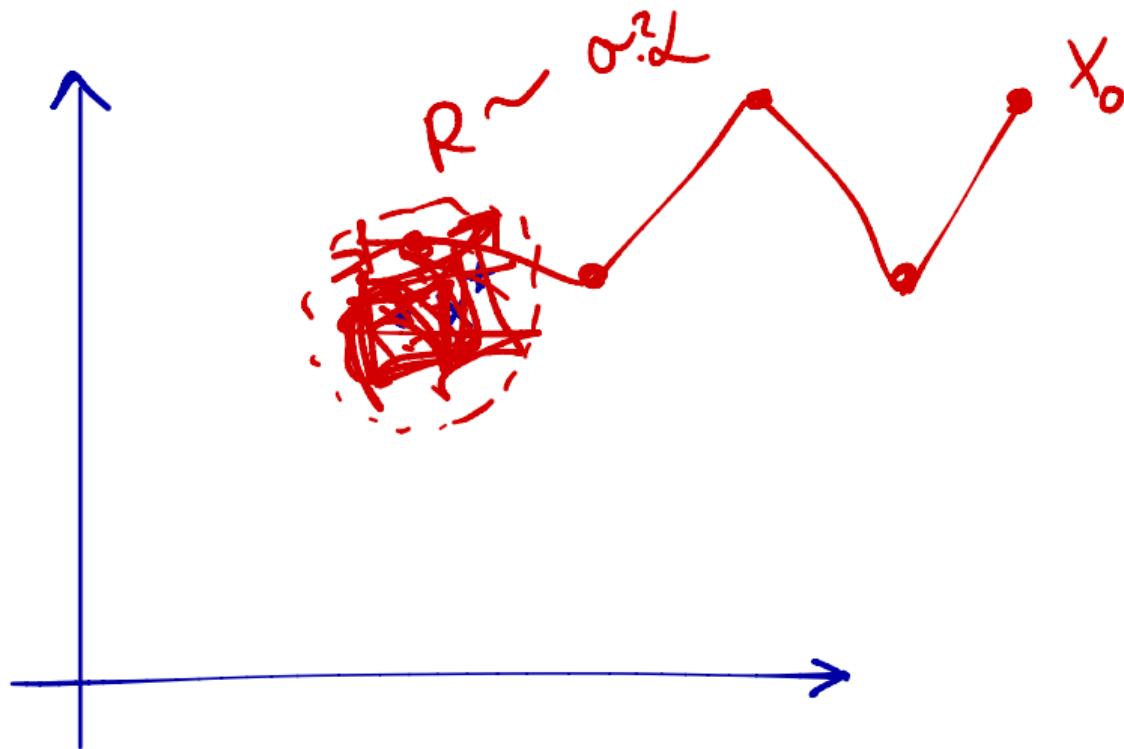
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 - Bounds are unimprovable under standard assumptions.
 - Oracle returns an unbiased gradient approximation with bounded variance.
- Momentum and Quasi-Newton-like methods do not improve rates in stochastic case. Can only improve constant factors (bottleneck is variance, not condition number).

Typical behaviour



Convergence

$$x_{k+1} - x_k = -\alpha_k \nabla f_{i_k}(x_k)$$

Lipschitz continuity implies:

$$f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} \|x_{k+1} - x_k\|^2$$

using (SGD):

$$f(x_{k+1}) \leq f(x_k) - \alpha_k \langle \nabla f(x_k), \nabla f_{i_k}(x_k) \rangle + \alpha_k^2 \frac{L}{2} \|\nabla f_{i_k}(x_k)\|^2$$

Now let's take expectation with respect to i_k :

$$\mathbb{E}[f(x_{k+1})] \leq \mathbb{E}[f(x_k) - \alpha_k \langle \nabla f(x_k), \nabla f_{i_k}(x_k) \rangle + \alpha_k^2 \frac{L}{2} \|\nabla f_{i_k}(x_k)\|^2]$$

Using linearity of expectation:

$$\mathbb{E}[f(x_{k+1})] \leq f(x_k) - \alpha_k \langle \nabla f(x_k), \mathbb{E}[\nabla f_{i_k}(x_k)] \rangle + \alpha_k^2 \frac{L}{2} \mathbb{E}[\|\nabla f_{i_k}(x_k)\|^2]$$

Since uniform sampling implies unbiased estimate of gradient: $\mathbb{E}[\nabla f_{i_k}(x_k)] = \nabla f(x_k)$:

$$\mathbb{E}[f(x_{k+1})] \leq f(x_k) - \alpha_k \|\nabla f(x_k)\|^2 + \alpha_k^2 \frac{L}{2} \mathbb{E}[\|\nabla f_{i_k}(x_k)\|^2]$$

Convergence. Smooth PL case.

$$\text{Var} X = \mathbb{E} X^2 - (\mathbb{E} X)^2$$

$$-\|\nabla f(x_k)\|_2^2 \leq -2\mu(f(x_k) - f^*)$$

$$\frac{1}{2}\|\nabla f(x)\|_2^2 \geq \mu(f(x) - f^*), \forall x \in \mathbb{R}^p \quad (\text{PL})$$

This inequality simply requires that the gradient grows faster than a quadratic function as we move away from the optimal function value. Note, that strong convexity implies PL, but not vice versa. Using PL we can write:

$$\mathbb{E}[f(x_{k+1})] - f^* \leq (1 - 2\alpha_k \mu)[f(x_k) - f^*] + \alpha_k^2 \frac{L}{2} \mathbb{E}[\|\nabla f_i(x_k)\|^2]$$

This bound already indicates, that we have something like linear convergence if far from solution and gradients are similar, but no progress if close to solution or have high variance in gradients at the same time. Now we assume, that the variance of the stochastic gradients is bounded:

$$\mathbb{E}[\|\nabla f_i(x_k)\|^2] \leq \sigma^2$$

Thus, we have

$$\mathbb{E}[f(x_{k+1}) - f^*] \leq (1 - 2\alpha_k \mu)[f(x_k) - f^*] + \frac{L\sigma^2 \alpha_k^2}{2}.$$

Convergence. Smooth PL case.

$\sim \frac{1}{K}$

1. Consider **decreasing stepsize** strategy with $\alpha_k = \frac{2k+1}{2\mu(k+1)^2}$ we obtain

$$\mathbb{E}[f(x_{k+1}) - f^*] \leq \frac{k^2}{(k+1)^2} [f(x_k) - f^*] + \frac{L\sigma^2(2k+1)^2}{8\mu^2(k+1)^4}$$

$$1 - 2d_x\mu = 1 - \frac{(2k+1)}{(k+1)^2} + \dots$$

$$\frac{(k+1)^2 - 2k-1}{(k+1)^2} = \frac{2}{(k+1)^2}$$

Convergence. Smooth PL case.

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$(k+1)^2$

- Multiplying both sides by $(k+1)^2$ and letting $\delta_f(k) \equiv k^2 \mathbb{E}[f(x_k) - f^*]$ we get

$$\delta_f(k+1) \leq \delta_f(k) + \frac{L\sigma^2(2k+1)^2}{8\mu^2(k+1)^2}$$

$$\leq \delta_f(k) + \frac{L\sigma^2}{2\mu^2},$$

$$\delta_f(k+1) - \delta_f(k) \leq \frac{L\sigma^2}{2\mu^2}$$

where the second line follows from $\frac{2k+1}{k+1} < 2$. Summing up this inequality from $k=0$ to k and using the fact that $\delta_f(0) = 0$ we get

$$\delta_f(k+1) \leq \delta_f(0) + \frac{L\sigma^2}{2\mu^2} \sum_{i=0}^k 1 \leq \frac{L\sigma^2(k+1)}{2\mu^2} \Rightarrow$$

$$(k+1)^2 \mathbb{E}[f(x_{k+1}) - f^*] \leq \frac{L\sigma^2(k+1)}{2\mu^2}$$

which gives the stated rate.

$$\mathbb{E}[f(x_{k+1}) - f^*] \leq \frac{L\sigma^2}{2\mu^2(k+1)}$$

Convergence. Smooth PL case.

$$\frac{2}{\mu + L}$$

3. **Constant step size:** Choosing $\alpha_k = \alpha$ for any $\alpha < 1/2\mu$ yields

$$\mathbb{E}[f(x_{k+1}) - f^*] \leq (1 - 2\alpha\mu)^k [f(x_0) - f^*] + \frac{L\sigma^2\alpha^2}{2} \sum_{i=0}^k (1 - 2\alpha\mu)^i$$

$$\leq (1 - 2\alpha\mu)^k [f(x_0) - f^*] + \frac{L\sigma^2\alpha^2}{2} \sum_{i=0}^{\infty} (1 - 2\alpha\mu)^i$$

$$= (1 - 2\alpha\mu)^k [f(x_0) - f^*] + \frac{L\sigma^2\alpha}{4\mu},$$

where the last line uses that $\alpha < 1/2\mu$ and the limit of the geometric series.

Convergence. Smooth non-convex case.

Convergence. Convex case.

Мини-батч SGD Myul b SGD: gap или прокладка?

