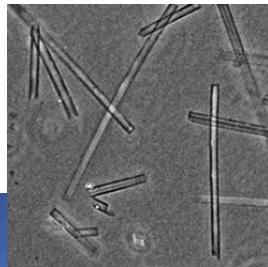


Initiation au Traitement des Images



Organisation

- ▶ Cours (8h)
 - Evaluation : examen écrit sans documents
 - Intervenant : Y. Berthoumieu
- ▶ Enseignement intégré (8h)
 - Cours et mise en oeuvre dans l'environnement Matlab
 - Intervenants : G. Bourmaud/J. Daniel/M. Donias (en 1/4 de promo)
- ▶ (TP, 8h, UV Optionnelle TSI)
 - Chroma-Keying, Détramage, Contours/Rehaussement
 - Evaluation : rapport (par binôme)
 - Intervenant : M. Donias

Sources d'images numériques

Acquisition analogique



Acquisition numérique

Domaine du non visible



Simulation/infographie



Définition (1 / 3)

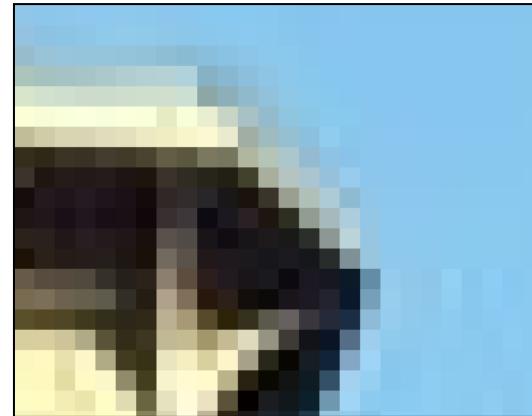
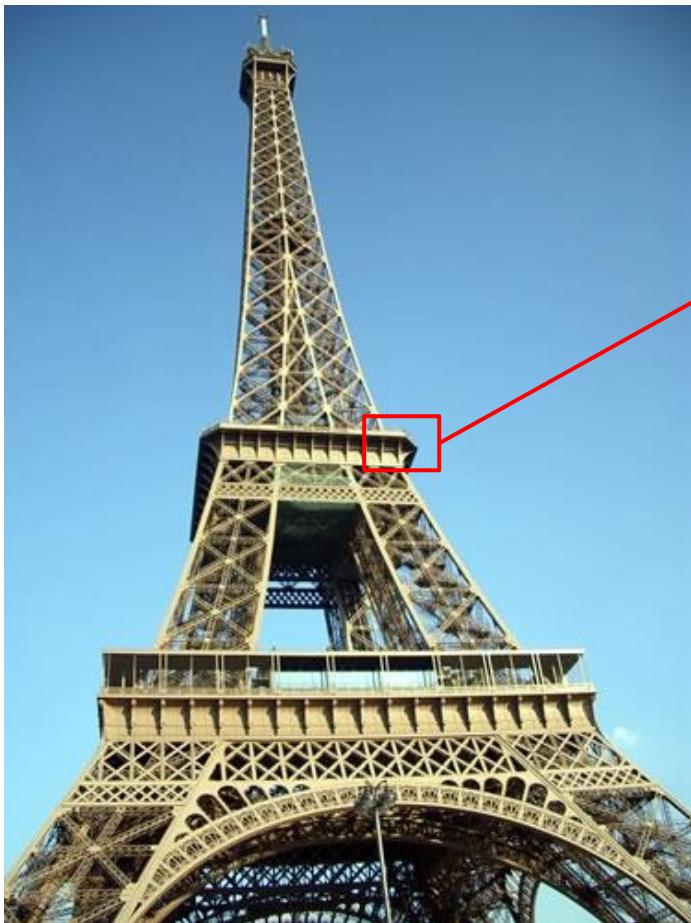


Image numérique
=

Matrice de pixels « colorés »

- Dimensions (nombre de pixels)
- Coordonnées (position du pixel)
- Valeur (couleur du pixel)

Définition (2 / 3)



R=212 G=16 B=40	R=205 G=65 B=112	R=103 G=120 B=176	R=62 G=127 B=193
R=201 G=26 B=43	R=197 G=69 B=94	R=154 G=106 B=148	R=98 G=117 B=186
R=192 G=101 B=106	R=138 G=59 B=80	R=127 G=96 B=137	R=97 G=129 B=188
R=255 G=250 B=250	R=230 G=192 B=213	R=140 G=118 B=156	R=73 G=97 B=145
R=250 G=248 B=251	R=255 G=248 B=255	R=255 G=246 B=255	R=182 G=176 B=210

Intensité vectorielle

« Vraies » couleurs

- Composante rouge (R)
- Composante verte (V)
- Composante bleue (B)

212	205	103	62
201	197	154	98
192	138	127	97
255	230	140	73
250	255	255	182

Matrice R

40	112	176	193
43	94	148	186
106	80	137	188
250	213	156	145
251	255	255	210

Matrice B



16	65	120	127
26	69	106	117
101	59	96	129
250	192	118	97
248	248	246	176

Matrice V

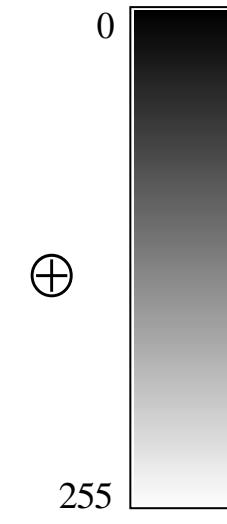
Format usuel : entiers 0 à 255

Définition (3 / 3)



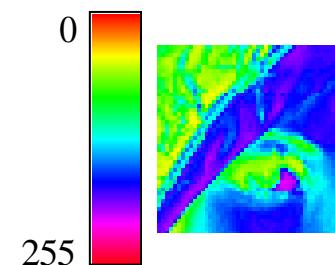
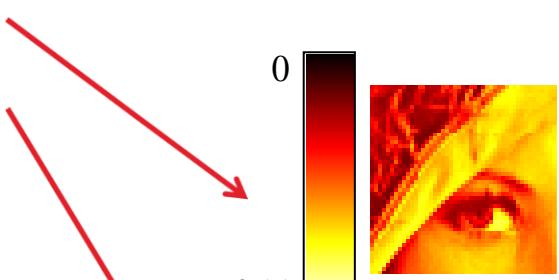
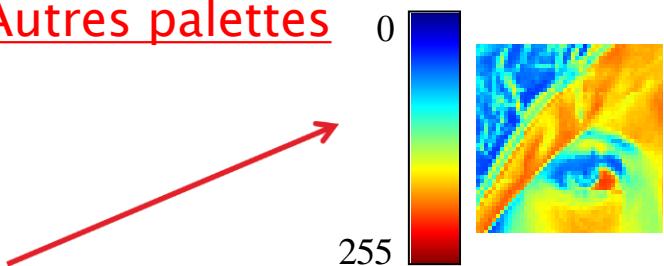
60	64	62	62	55	51
59	73	98	90	66	54
72	105	167	170	120	74
88	91	188	202	184	150
103	77	191	205	203	190
75	131	208	209	207	202

Intensité scalaire



Palette
(niveaux de gris)

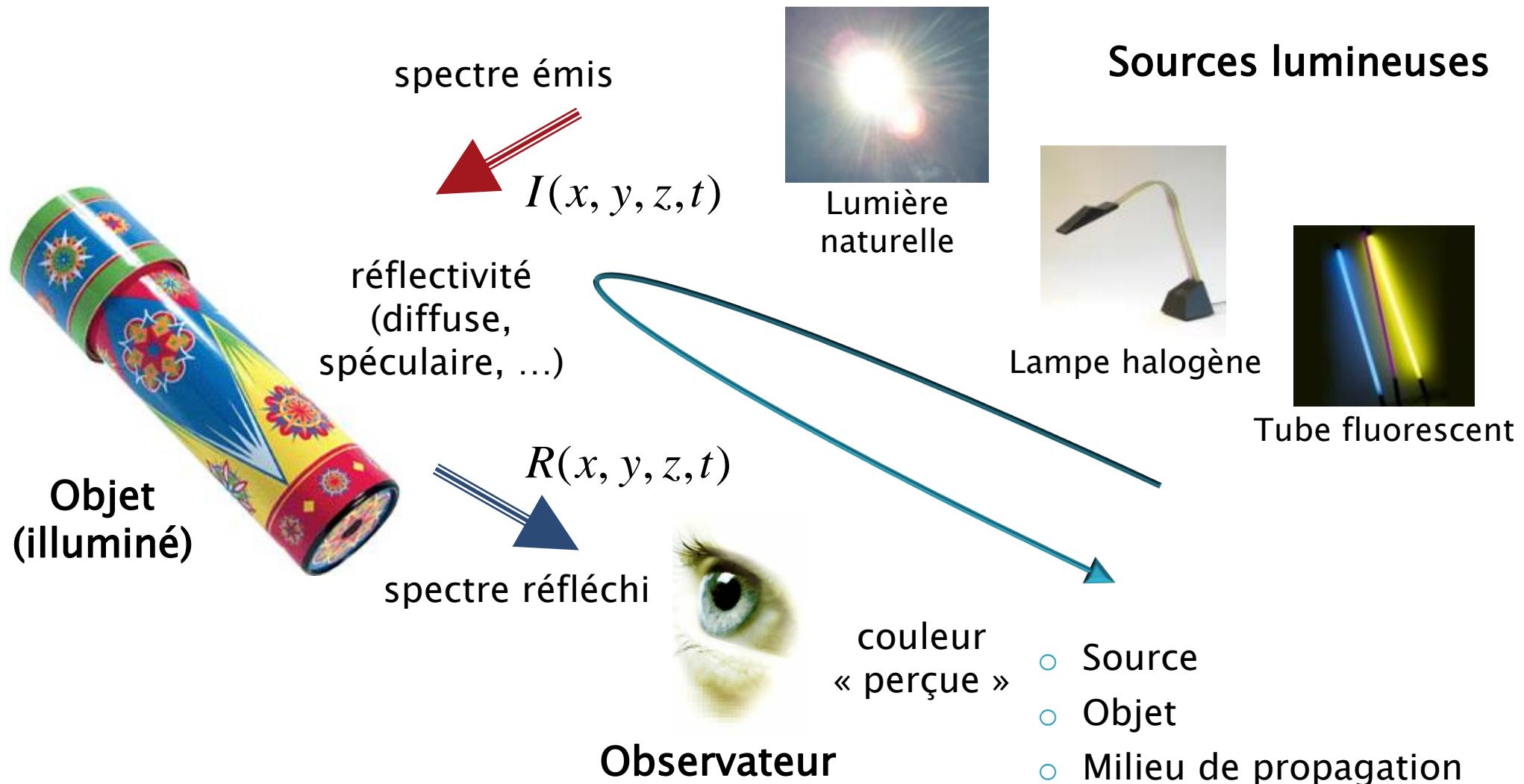
Autres palettes



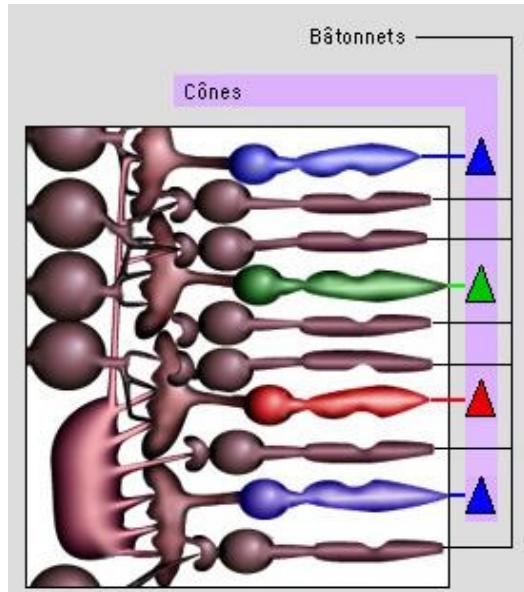
Couleurs indexées ou « fausses » couleurs

- Scalaire (\rightarrow index de table)
- Palette (table de correspondance couleur)

Modélisation



Système visuel humain (SVH)

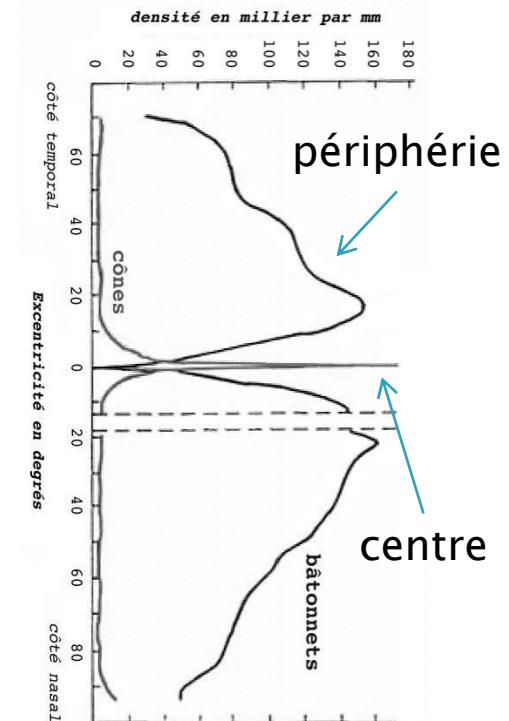
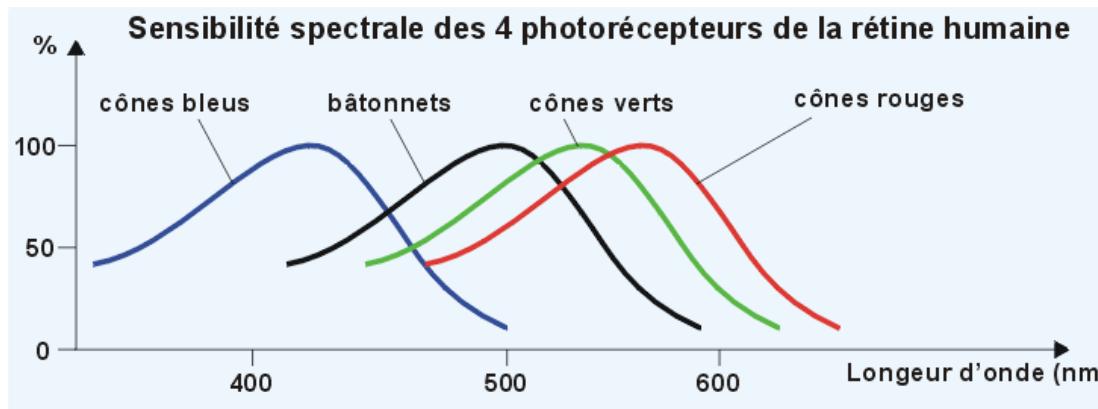


○ Bâtonnets

- ✓ ~ 120 millions, forme allongée
- ✓ En périphérie de la rétine
- ✓ Vision nocturne (regroupés, très sensibles à la luminosité mais pas aux détails)

○ Cônes

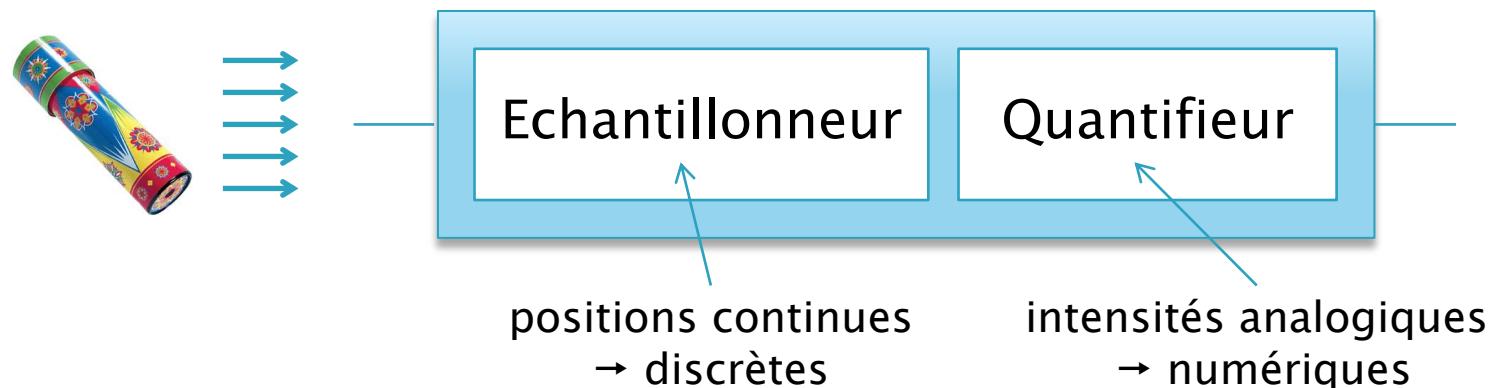
- ✓ ~ 6 millions, 3 sous-familles (S, M, L)
- ✓ Au centre de la rétine (fovéa)
- ✓ Vision diurne (densité élevée)



Distribution angulaire

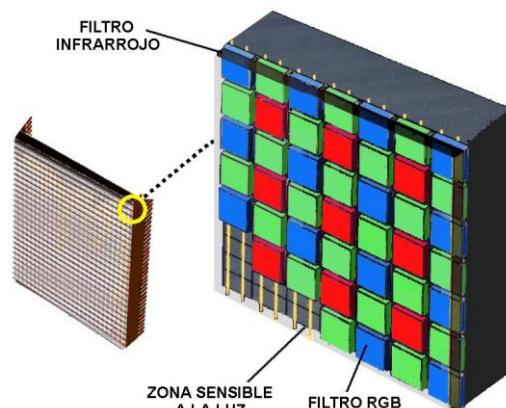
Système Visuel Humain (SVH)
=
Système trichromate

Systèmes d'acquisition des couleurs

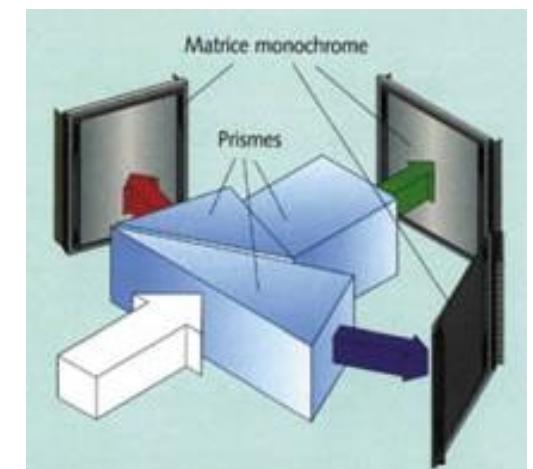


Capteur CMOS

Éléments
photosensibles



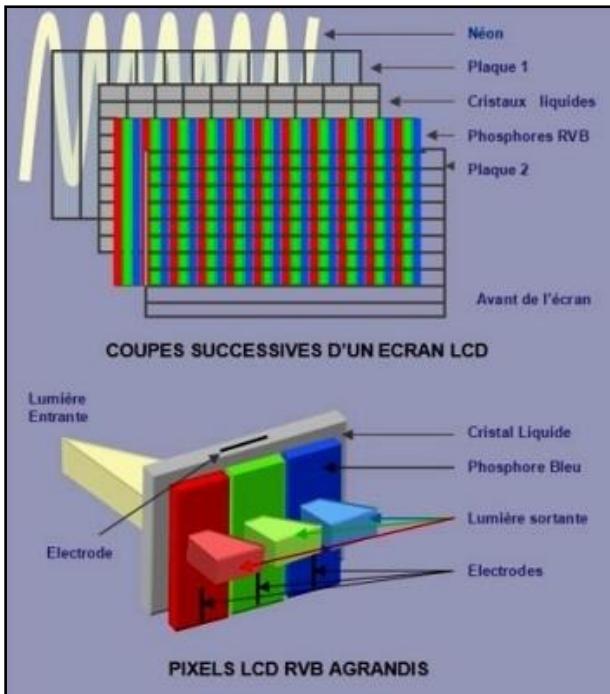
Capteur Fovéon



Capteur (Mono)CCD

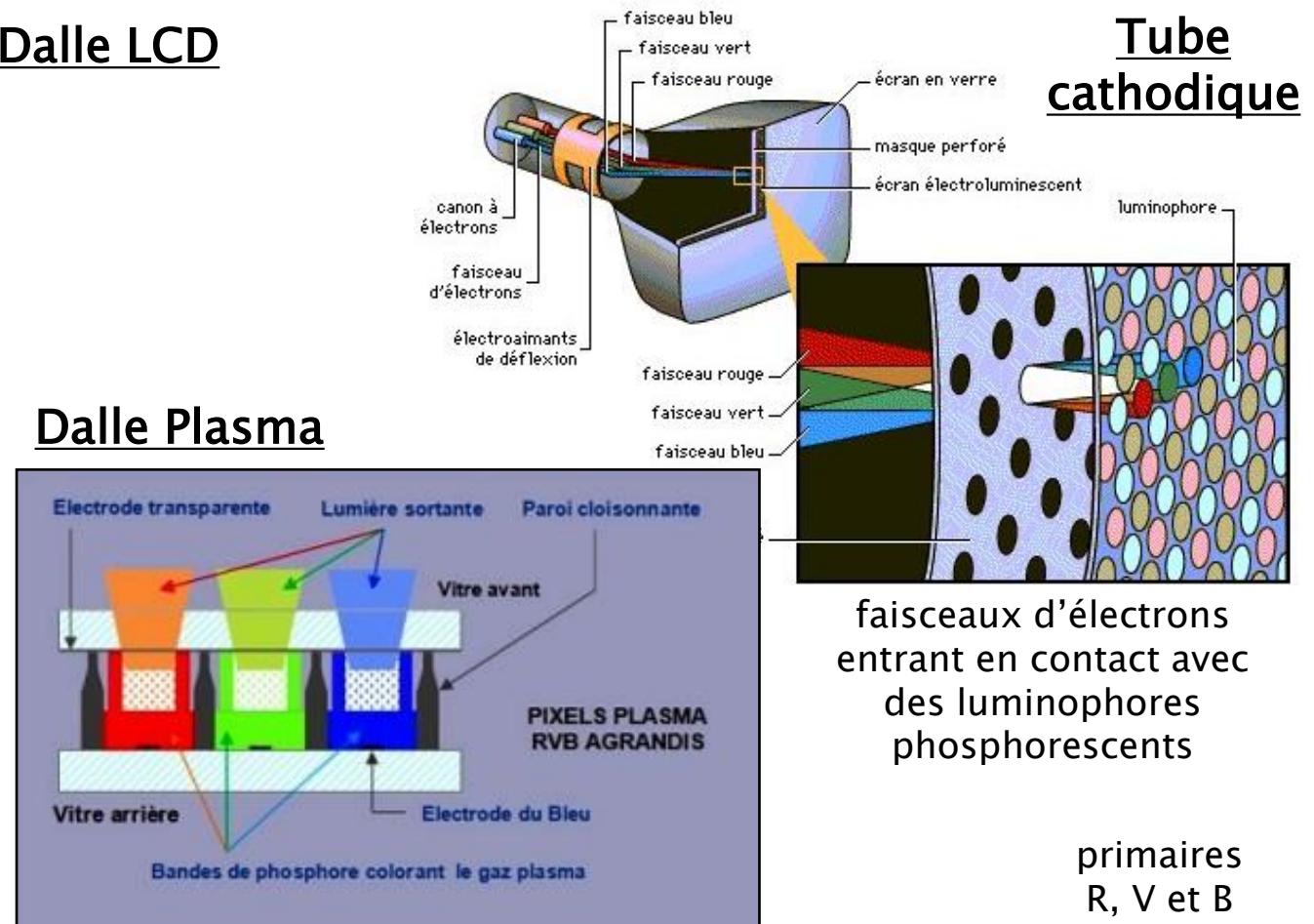
Capteur Tri-CCD

Systèmes de restitution des couleurs



tensions électriques contrôlant l'orientation de cristaux liquides et modulant le passage d'une lumière fluorescente à travers des filtres

Dalle LCD



mélanges de gaz inerte excités par des décharges électriques et transformés en plasma produisant une lumière initialement ultra-violette

Tube cathodique

primaires
R, V et B
dépendantes
de la
technologie

Plan

- ▶ Images couleur
 - Lecture
 - Visualisation
 - Synthèse
- ▶ Espaces caractéristiques
 - Couleur/Amplitude
 - Spatial
 - Fréquentiel
- ▶ Traitements
 - Filtrage linéaire
 - Filtrage non-linéaire

Un exemple en « vraies » couleurs

```
>> A=imread('pool.tif');  
>> whos
```

Name	Size
------	------

A	383x510x3
---	-----------

Grand total is 585990 elements using 585990 bytes

```
>> figure, image(A)  
>> A(:,:,1)  
>> A(:,:,2)  
>> A(:,:,3)
```

hauteur

largeur

Bytes	Class
-------	-------

585990	uint8 array
--------	-------------

« vraies »
couleurs

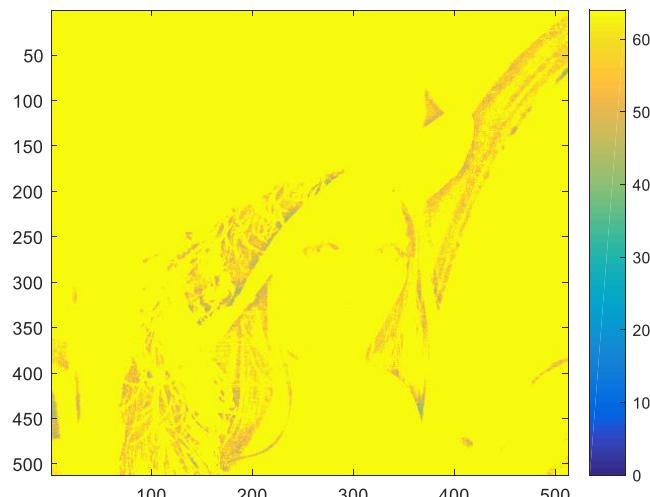


Un exemple en couleurs indexées

```
>> A=imread('lena.bmp');  
>> whos  
 Name      Size            Bytes  Class  
 A         512x512        262144  uint8 array
```

Grand total is 262144 elements using 262144 bytes

```
>> figure, image(A), colorbar  
>> A  
>> figure, image(A), colormap(gray(256)), colorbar
```



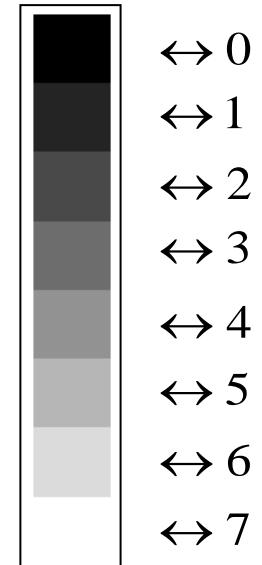
Palette ?

```
>> gray(8)
```

```
ans =
```

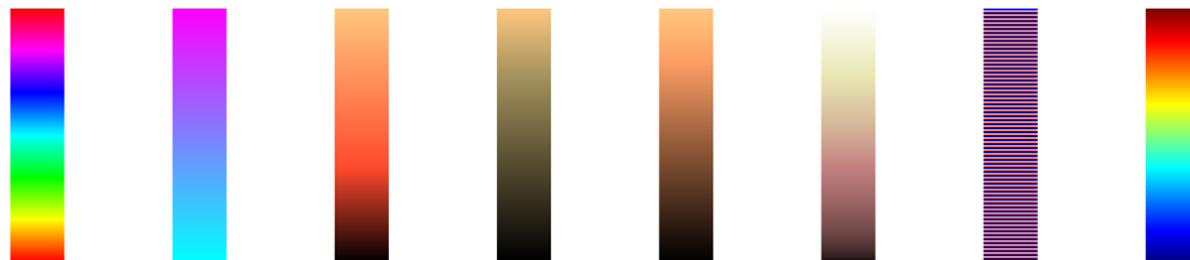
0	0	0
0.1429	0.1429	0.1429
0.2857	0.2857	0.2857
0.4286	0.4286	0.4286
0.5714	0.5714	0.5714
0.7143	0.7143	0.7143
0.8571	0.8571	0.8571
1.0000	1.0000	1.0000

R, G, B



Autres palettes : hsv, cool, hot, bone, copper, pink, flag, jet, ...

64 niveaux par défaut



Fichier et palette

```
>> [A,map]=imread('lena.bmp');  
>> figure, image(A), colormap(map), colorbar
```



Fonctions Matlab de visualisation

	image	imagesc	imshow
Formats	uint8, uint16, double		uint8, uint16, single, double, ...
Palette initiale	parula (64 niveaux)		gray (256 niveaux)
Intervalles (couleurs indexées)	[0,N-1] uint8, uint16 [1,N] double (sur N couleurs)		[0,255] uint8 [0,65535] uint16 [0,1] single/double
Intervalles (« vraies » couleurs)	[0,255] uint8, uint16 [0,1] double		[0,255] uint8 [0,65535] uint16 [0,1] single, double
Grossissement initial	variable		1
Ratio L/H initial	variable		1 (pixels carrés)
Divers		Mise à l'échelle des intensités (auto. par défaut/contrôlée [.])	Toolbox « Image Processing »

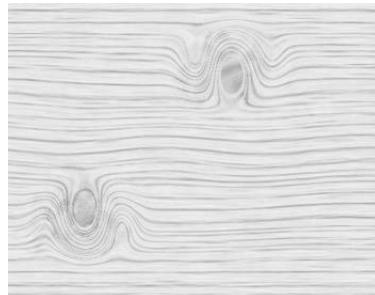
Méthodologie (1 / 4)

- ▶ Bilan des caractéristiques de l'image
 - Dimensions spatiales
 - Format numérique
 - Intervalles d'intensité
 - Codage
 - ✓ « vraies » couleurs
 - ✓ couleurs indexées
- ▶ Identification de la fonction d'affichage
 - Contexte
 - ✓ de « fidélité »
 - ✓ « informationnel »
 - ✓ de comparaison
 - Choix : palette, ratio L/H, intervalles d'intensité, etc.

Méthodologie (2/4)

Contexte « de fidélité »

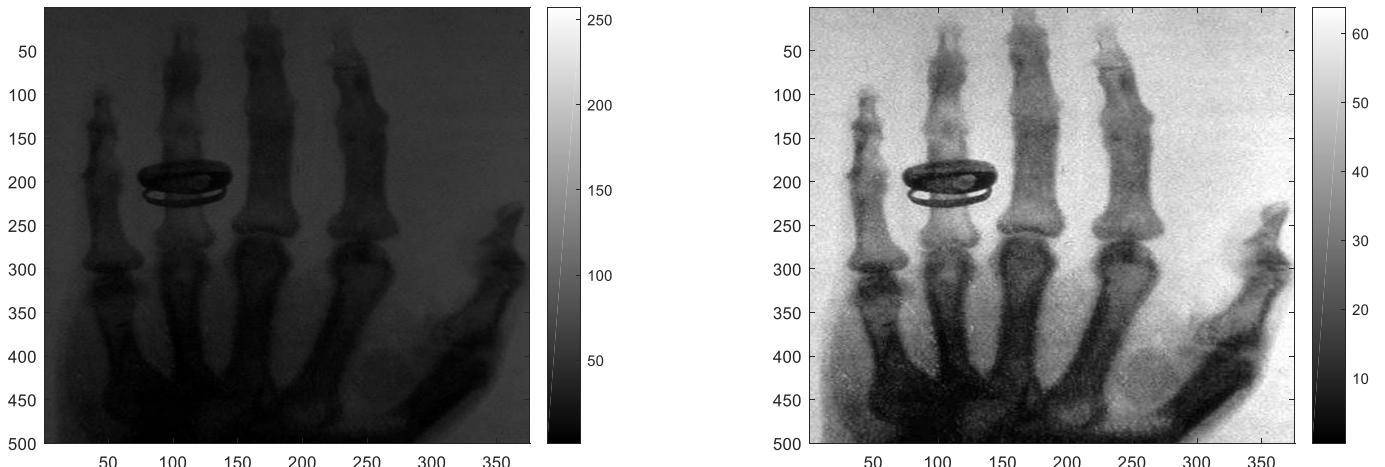
- Respect des intensités initiales
- imshow/image



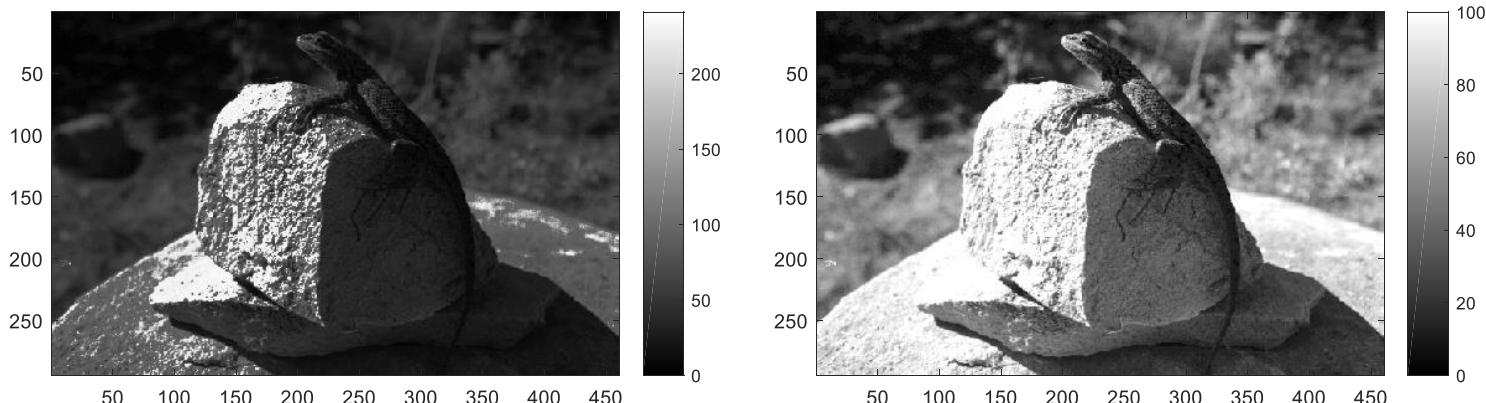
Méthodologie (3 / 4)

Contexte « informationnel » (couleurs indexées uniquement)

- Etalement automatique des intensités (`imagedc`)



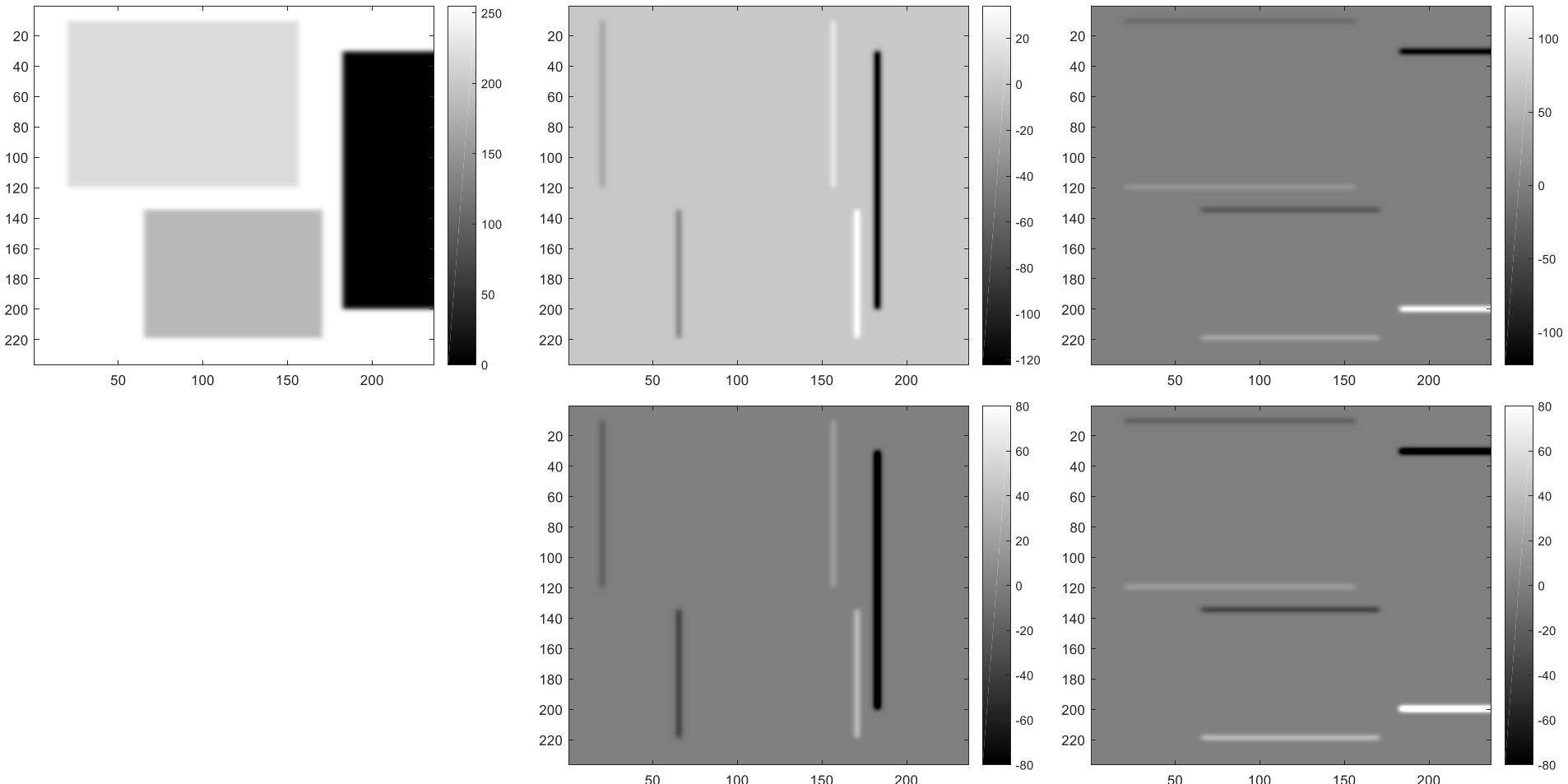
- Etalement contrôlé des intensités (`imagedc/imshow(...,[])`)



Méthodologie (4 / 4)

Contexte de comparaison (couleurs indexées uniquement)

- Etalement contrôlé et identique des intensités



Formats et opérations

```
clear  
close all  
  
A=imread('lena.bmp');  
figure, image(A)  
colormap(gray(256))  
  
B=zeros(512);  
B(250:370,240:350)=300;  
  
A=double(A);  
C=A+B;  
figure, image(C)  
colormap(gray(256))
```



Challenge 1 : format numérique

```
clear  
close all  
  
s=load('challenge.mat');  
I=s.A;
```

Challenge 2 : ratio L/H

```
clear
close all

s=load('challenge.mat');
I=s.B;
```

Challenge 3 : intervalles d'intensité

```
clear  
close all  
  
s=load('challenge.mat');  
I=s.C;
```

Challenge 4 : palette continue

```
clear  
close all  
  
s=load('challenge.mat');  
I=s.D;
```

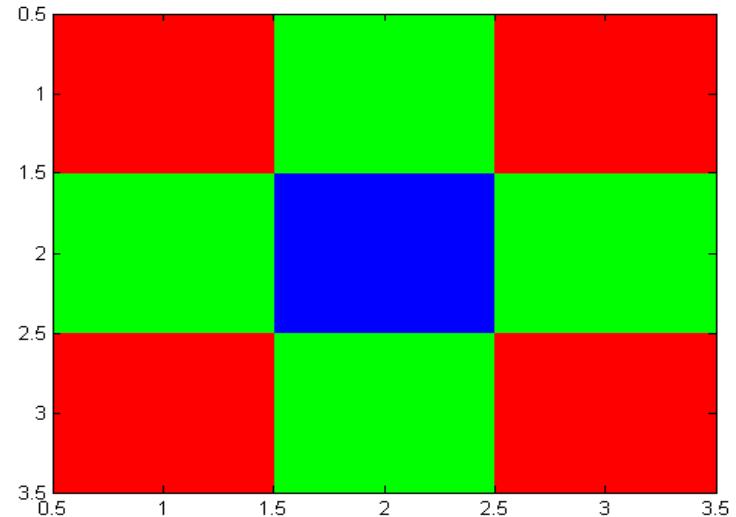
Challenge 5 : palette « discrète »

```
clear
close all

s=load('challenge.mat');
I=s.E;
```

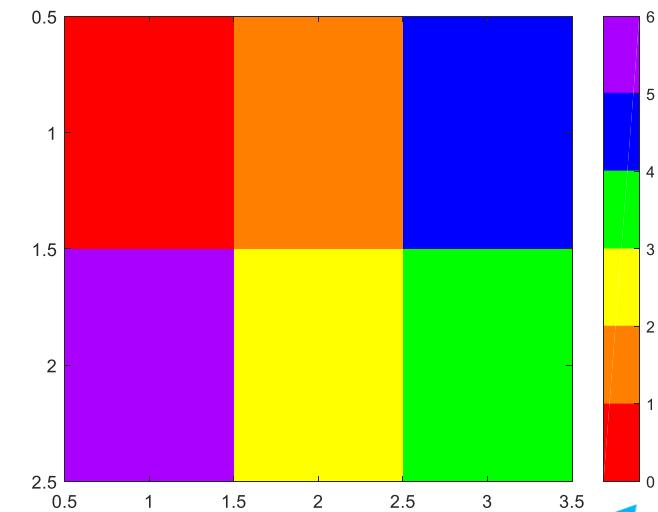
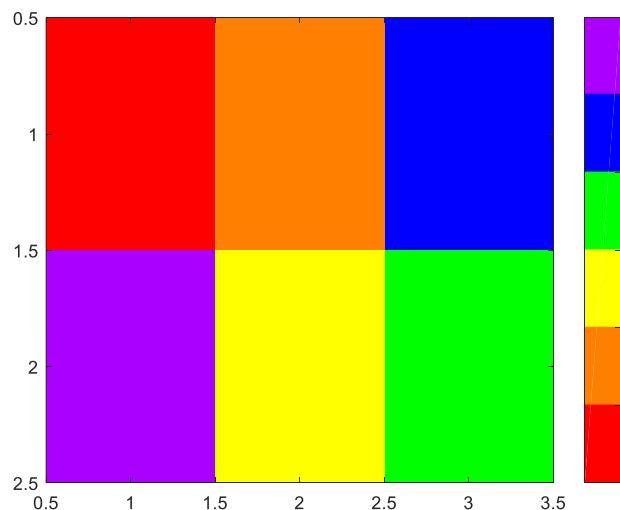
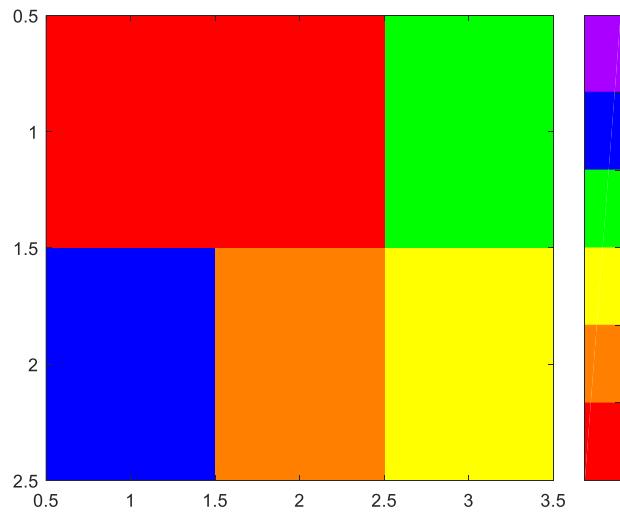
Synthèse en « vraies couleurs »

```
clear  
close all  
  
r=[1 0 1;0 0 0;1 0 1];  
g=[0 1 0;1 0 1;0 1 0];  
b=[0 0 0;0 1 0;0 0 0];  
  
img=cat(3,r,g,b);  
figure, image(img)
```



Synthèse en couleurs indexées

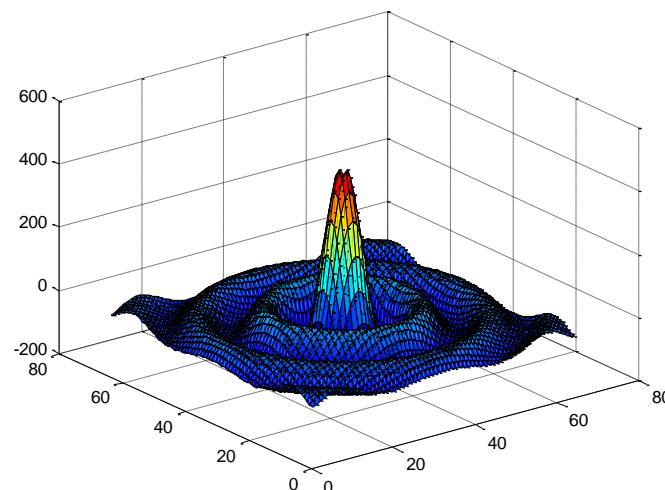
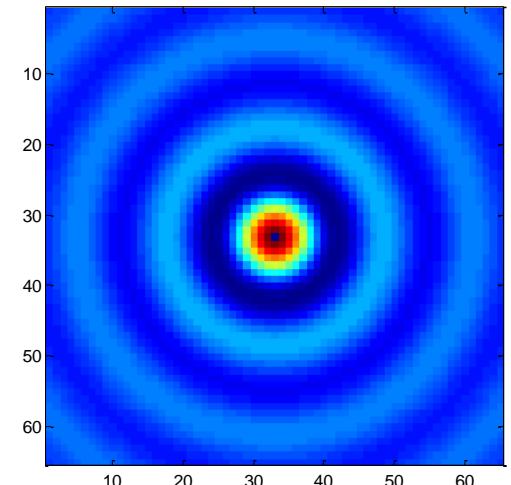
```
clear, close all  
  
img=[0 1 4;5 2 3];  
figure  
image(img)  
colormap(prism(6))  
colorbar  
figure  
image(uint8(img))  
colormap(prism(6))  
colorbar  
figure,  
image(img+1)  
colormap(prism(6))  
colorbar
```



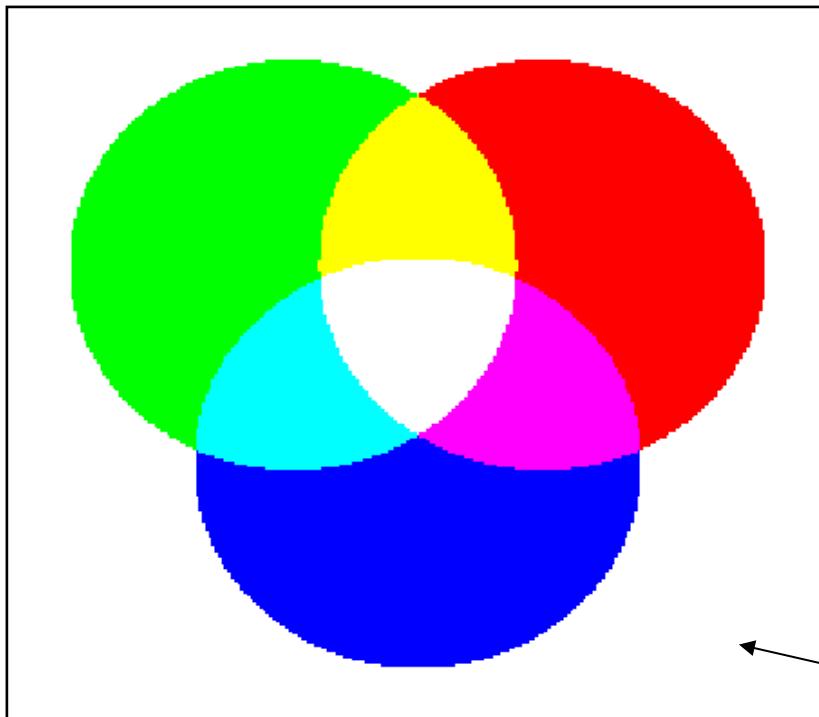
0 ou 1 !!!

Synthèse analytique : meshgrid

```
clear  
close all  
  
[X, Y]=meshgrid(-32:32,-32:32);  
R=(X.^2+Y.^2).^0.5;  
  
img=1000*sin(R/2)./R;  
figure, imagesc(img), axis square  
figure, surf(img)
```



Exercice : synthèse additive



- ▶ « Vraies » couleurs
 - ▶ Couleurs indexées
- noir !

« Vraies » couleurs

```
clear
close all

size=255;
radius=70;
dist=45;
[R,G,B]=disks(size, radius, dist);
img=cat(3,R,G,B);
figure, imshow(img)
```

Couleurs indexées

```
clear
close all

size=255;
radius=70;
dist=45;
[R,G,B]=disks(size, radius, dist);
img=uint8(R+2*G+4*B);
map=[0 0 0;1 0 0;0 1 0;1 1 0;0 0 1;1 0 1;0 1 1;1 1 1];
figure, imshow(img, map)
```

Synthèse additive dynamique

```
clear, close all

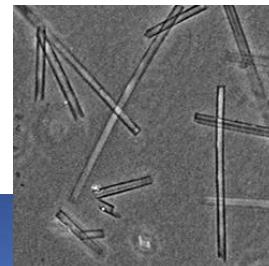
size=255; radius=70; dist=45;
[R,G,B]=disks(size, radius, dist);
R=uint8(R*255);
G=uint8(G*255);
B=uint8(B*255);
v=VideoWriter('video.avi', 'Uncompressed AVI');
v.FrameRate=5;
open(v)
for n=1:100
    q=mod(n, 3);
    if q == 0
        img=cat(3, R, G, B);
    elseif q == 1
        img=cat(3, B, R, G);
    else
        img=cat(3, G, B, R);
    end
    writeVideo(v, img);
end
close(v)
```

- ▶ Couleurs circulantes
- ▶ Vidéo
 - 100 images
 - 5 images/seconde
 - sans compression

Exercice : interaction

- ▶ Affichage d'une image
- ▶ Capture d'un segment (`ginput`), de gauche à droite et de haut en bas
- ▶ Extraction du profil (signal horizontal ou vertical le plus « proche ») correspondant
- ▶ Affichage du profil

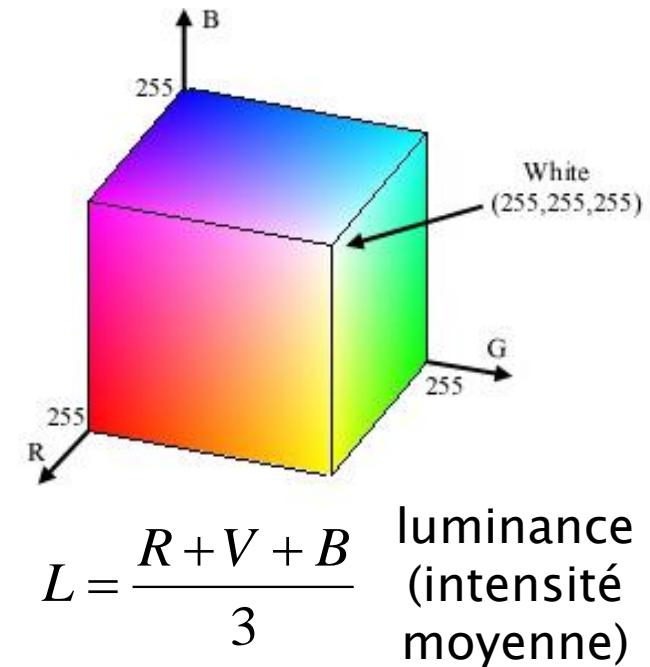
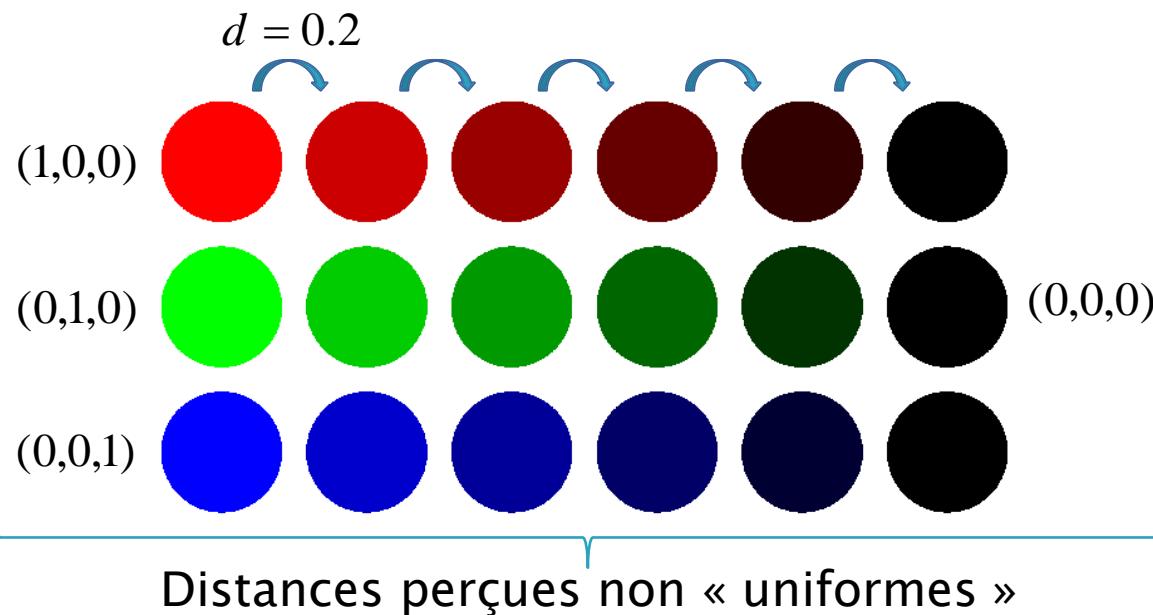
Initiation au Traitement des Images



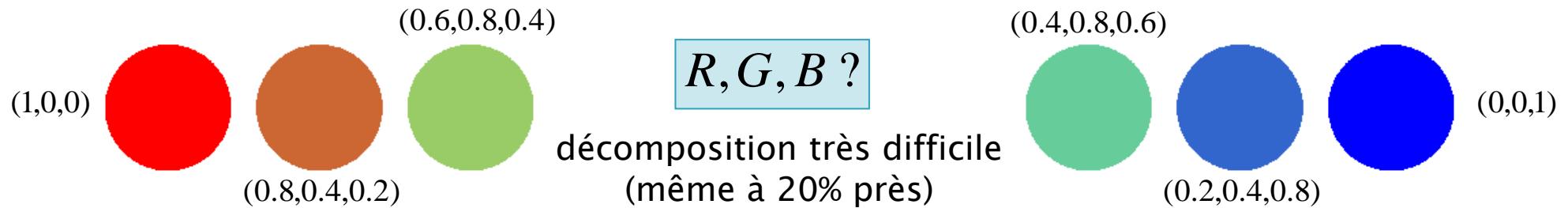
- ▶ Couleur/Amplitude
- ▶ Spatial
- ▶ Fréquentiel

Espaces caractéristiques

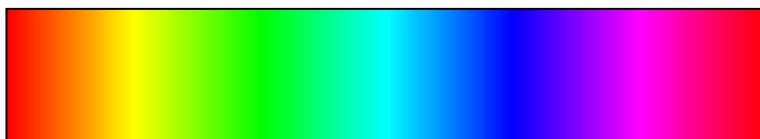
Espace chromatique RVB(RGB)



Espace d'acquisition du système visuel humain



Espace chromatique TSL (HSL)



Teinte



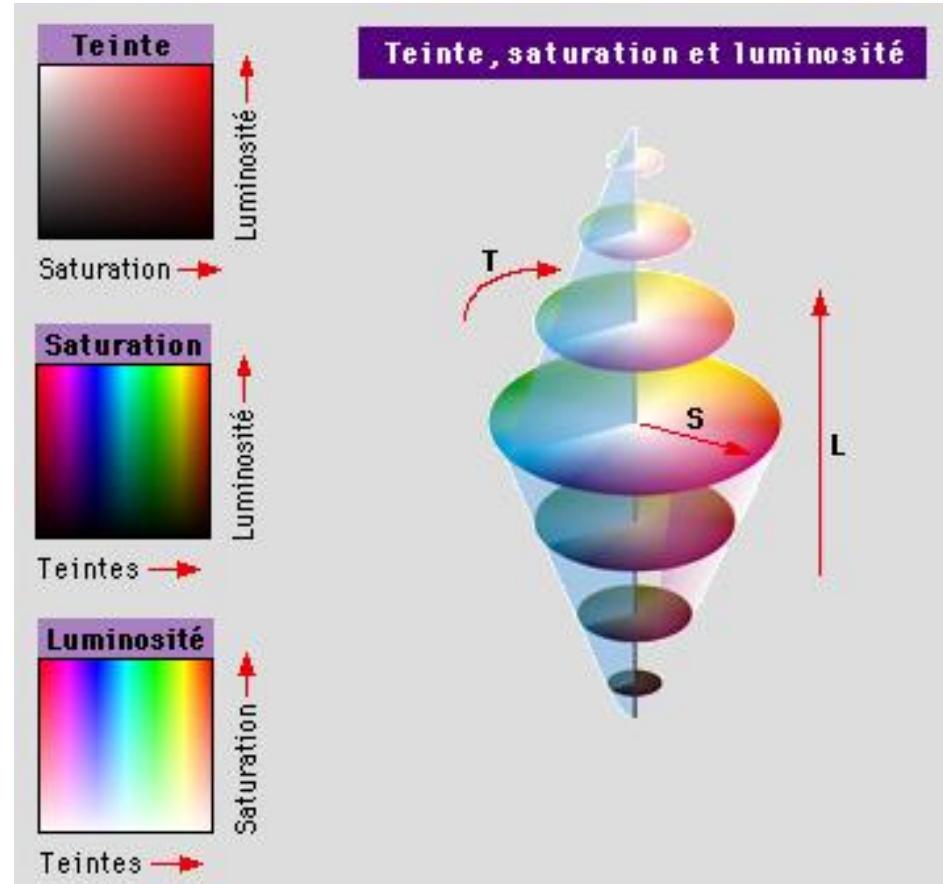
Saturation

« mélange »
avec le gris



Luminosité

« mélange »
avec le noir



Espace de description naturelle

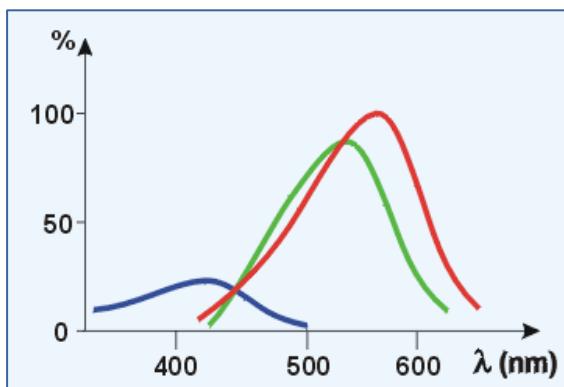
Luminance vs Chrominance



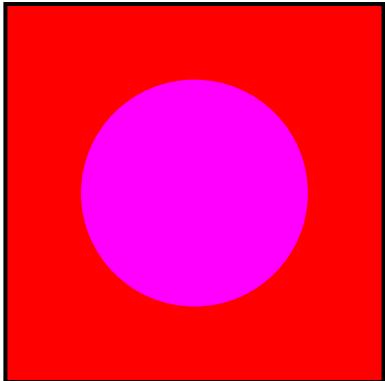
luminosité plus forte



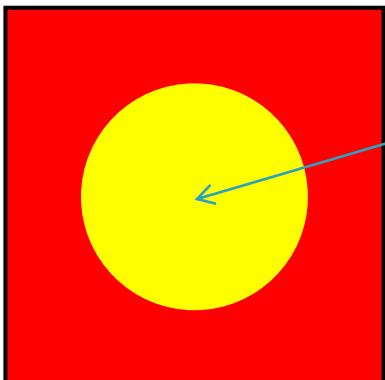
contrastes plus faibles



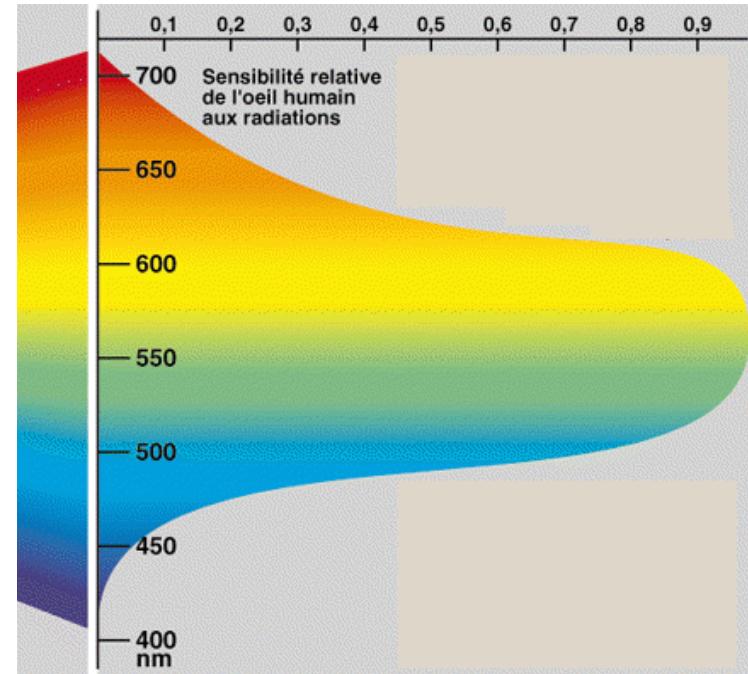
Luminance « perceptuelle »



Rouge/Bleu



Rouge/Vert



$$Y = 0.299 R + 0.587 V + 0.114 B$$

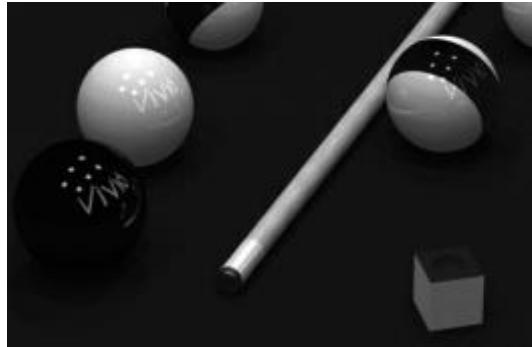
pondération plus faible

Espace colorimétrique YCbCr

```
clear  
close all  
  
A=double(imread('pool.tif'));  
R=A(:,:,1);  
G=A(:,:,2);  
B=A(:,:,3);  
  
Y=0.299*R+0.587*G+0.114*B;  
Cb=0.564*(B-Y)+128;  
Cr=0.713*(R-Y)+128;  
L=(R+G+B)/3;  
  
figure, imshow(uint8(A))  
figure, imshow(uint8(L))  
figure, imshow(uint8(Y))
```

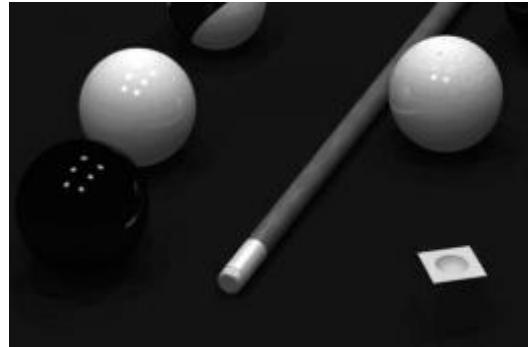
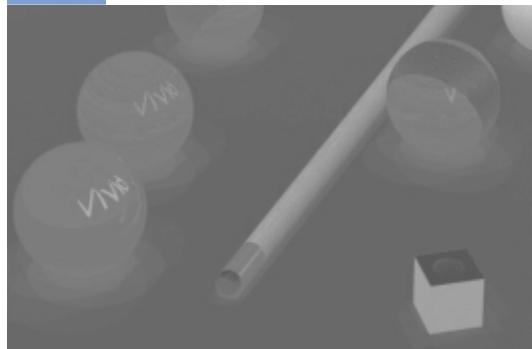
```
tx=90:350;  
ty=160:330;  
  
figure,  
subplot(2,3,1)  
imshow(uint8(R(ty,tx)))  
subplot(2,3,2)  
imshow(uint8(B(ty,tx)))  
subplot(2,3,3)  
imshow(uint8(G(ty,tx)))  
subplot(2,3,4)  
imshow(uint8(Cr(ty,tx)))  
subplot(2,3,5)  
imshow(uint8(Cb(ty,tx)))  
subplot(2,3,6)  
imshow(uint8(A(ty,tx,:)))
```





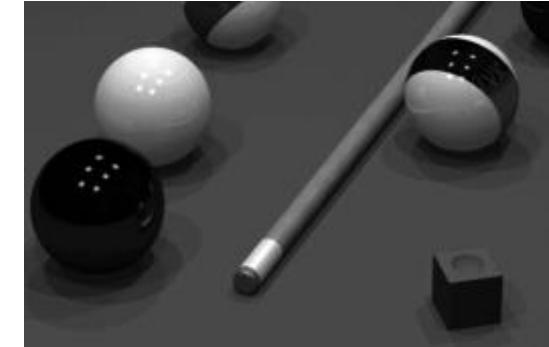
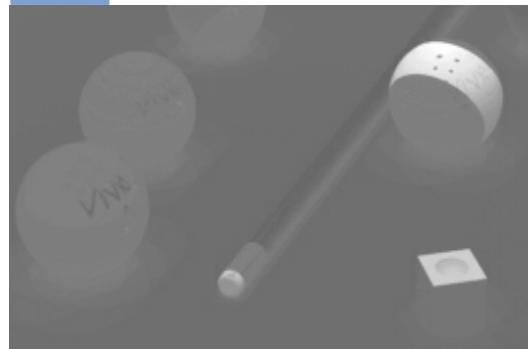
R

C_r



B

C_b



G



Résolution spatiale



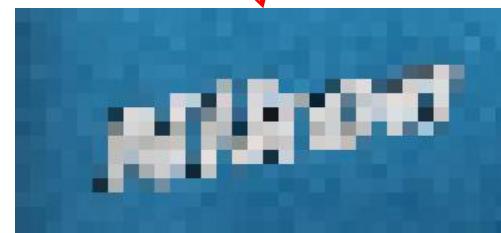
1500×1500



300×300



Nikon



150×150

```

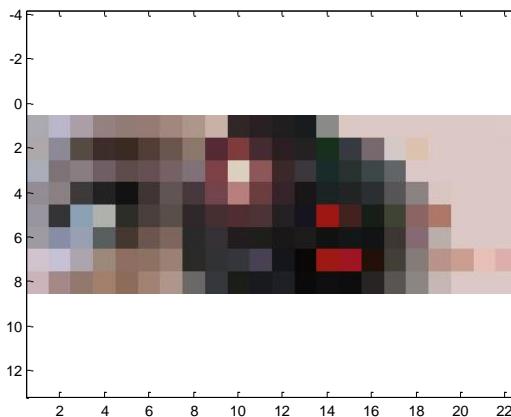
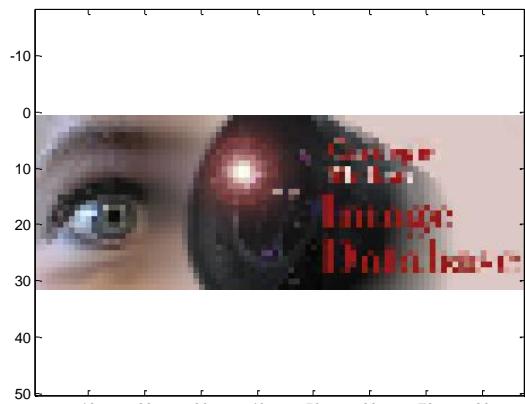
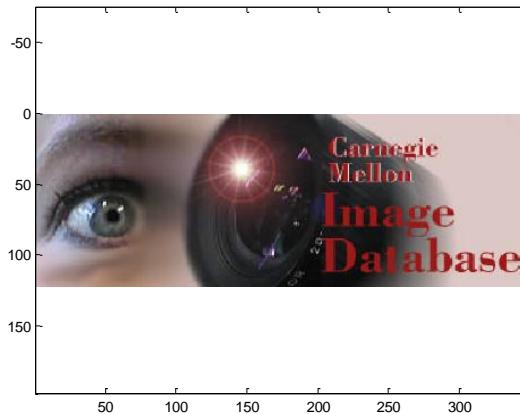
clear
close all

A=imread('title.jpg');
figure
image(A)
axis('equal')
[Ny,Nx,Nz]=size(A);

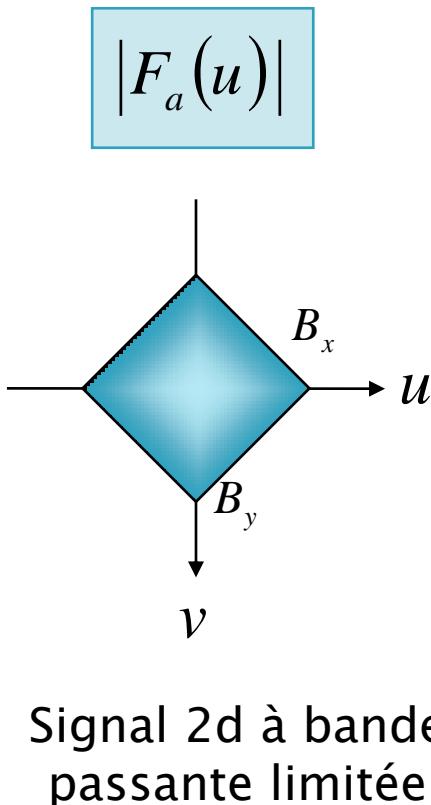
figure
image(A(1:4:Ny,1:4:Nx,:))
axis('equal')

figure
image(A(1:16:Ny,1:16:Nx,:))
axis('equal')

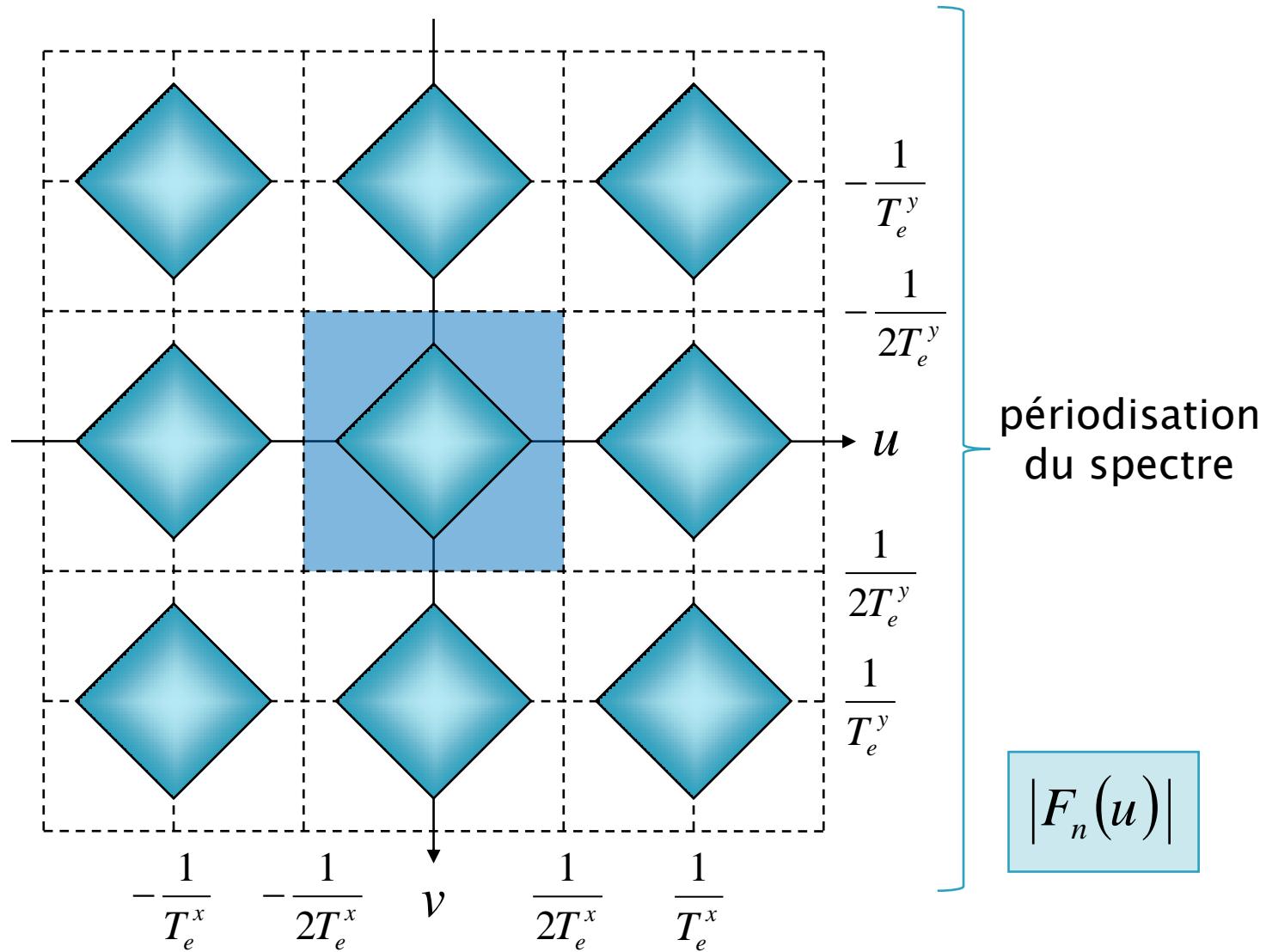
```



Spectre d'une séquence discrète 2d

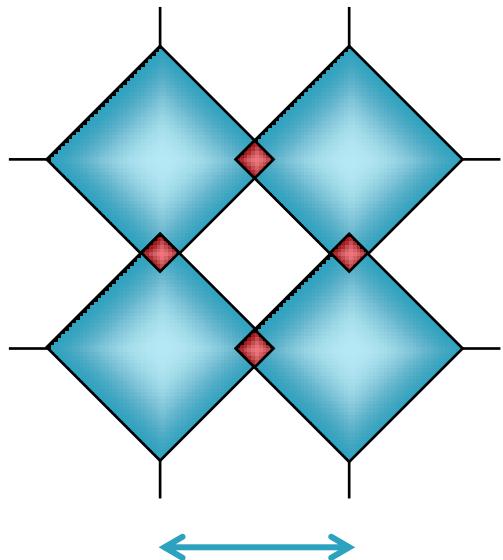


Signal 2d à bande
passante limitée

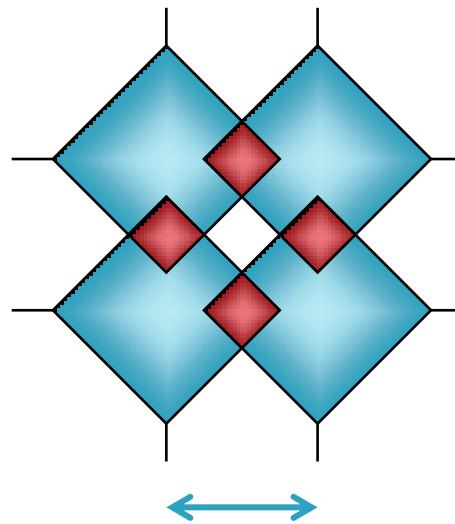


$$|F_n(u)|$$

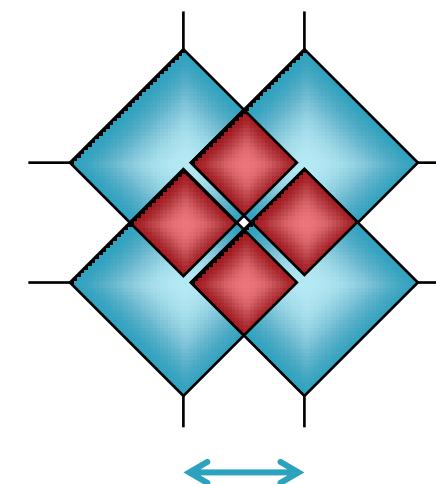
Recouvrement fréquentiel



$$\frac{1}{T_e^x}$$



$$\frac{1}{T_e^x}$$

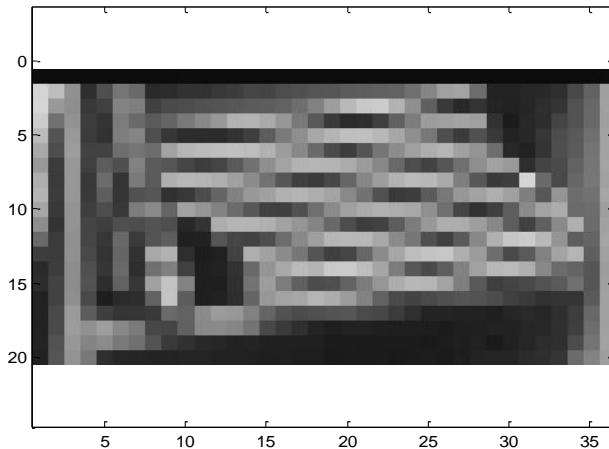
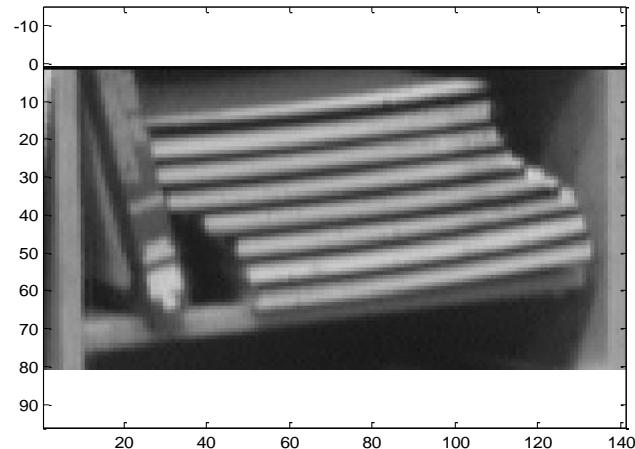


$$\frac{1}{T_e^x}$$

Des hautes fréquences ... aux basses fréquences

```
clear  
close all  
  
A=imread('barbara.bmp');  
figure  
image(A)  
colormap(gray(256))  
axis('equal')  
figure  
image(A(1:80,140:280))  
colormap(gray(256))  
axis('equal')
```

```
[Ny,Nx]=size(A);  
  
B=A(1:4:Ny,1:4:Nx);  
figure  
image(B)  
colormap(gray(256))  
axis('equal')  
figure  
image(B(1:20,35:70))  
colormap(gray(256))  
axis('equal')
```



Transformée de Fourier

Transformée directe

$$F(u, v) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy = TF(f(x, y))$$

variables
fréquentielles

variables
spatiales

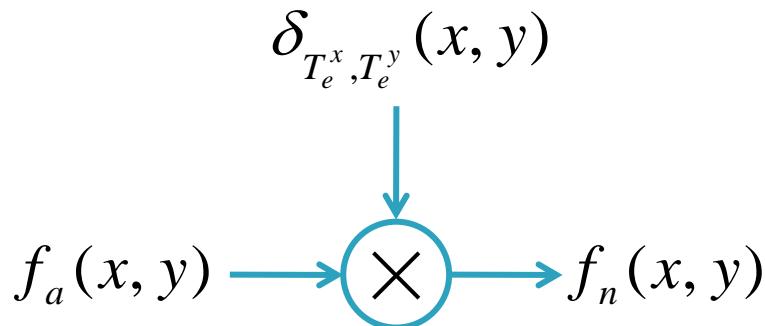
**Extension au cas des
signaux bidimensionnels
(images)**

Transformée inverse

$$f(x, y) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} F(u, v) e^{j2\pi(ux+vy)} du dv = TF^{-1}(F(u, v))$$

Echantillonnage régulier 2d

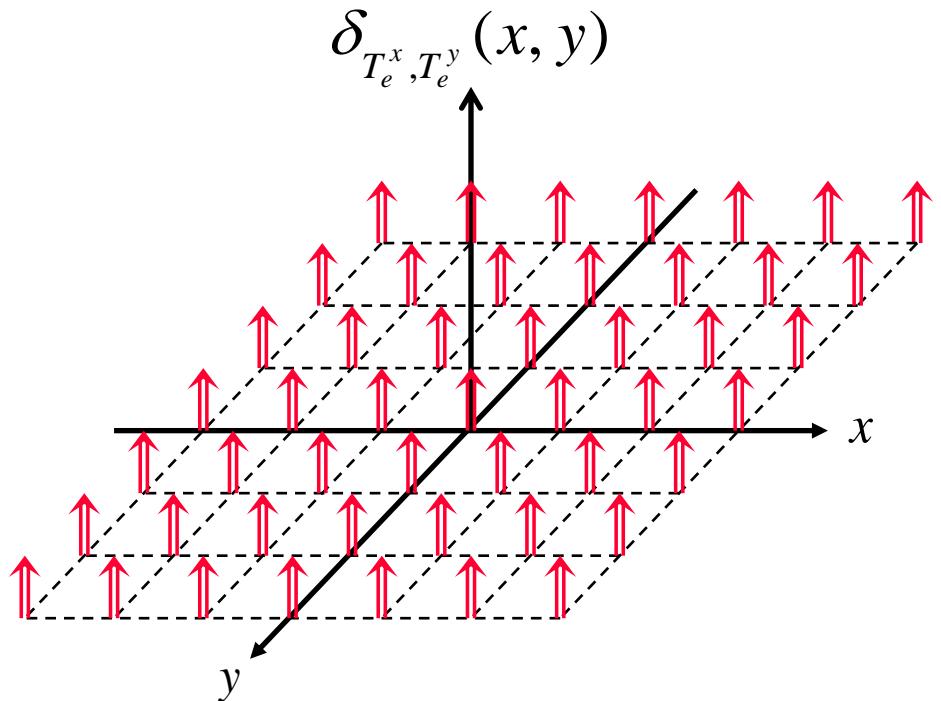
$$f_n(x, y) = \begin{cases} f_a(x, y) & \text{pour } \begin{cases} x = mT_e^x \\ y = nT_e^y \end{cases} \\ 0 & \text{sinon} \end{cases}$$



$$f_n(x, y) = f_a(x, y) \delta_{T_e^x, T_e^y}(x, y)$$

séquence discrète

notée $f(mT_e^x, nT_e^y)$ ou $f(m, n)$



Peigne de Dirac 2d

$$\delta_{T_e^x, T_e^y}(x, y) = \sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} \delta(x - mT_e^x, y - nT_e^y)$$

Transformée de Fourier discrète 2d

$$F(u, v) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy = TF(f(x, y))$$

Transformée (continue)
de Fourier (TF)

échantillonnage spatial

$$F_n(u, v) = \sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} f(mT_e^x, nT_e^y) e^{-j2\pi(umT_e^x + vnT_e^y)}$$

Transformée (continue)
de Fourier d'une
séquence discrète (TFCD)

périodes
d'échantillonnage

transformée
 (f_e^x, f_e^y) -périodique

Transformée de Fourier
discrète (d'une séquence
discrète) (TFD)

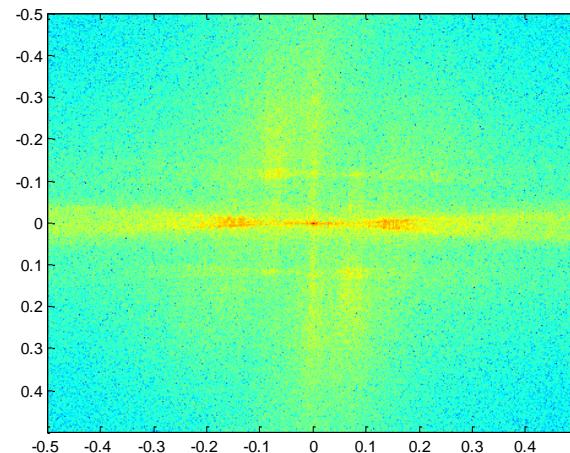
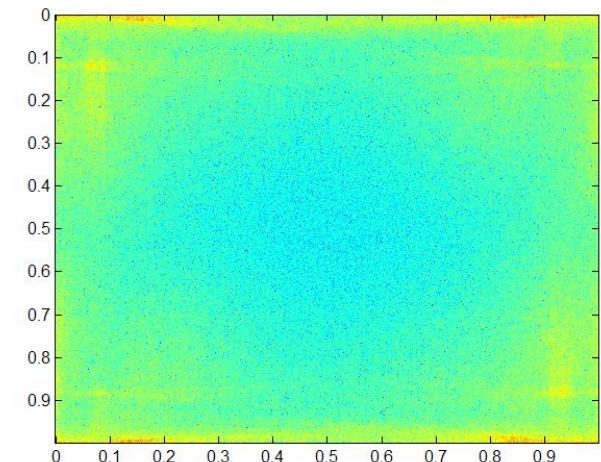
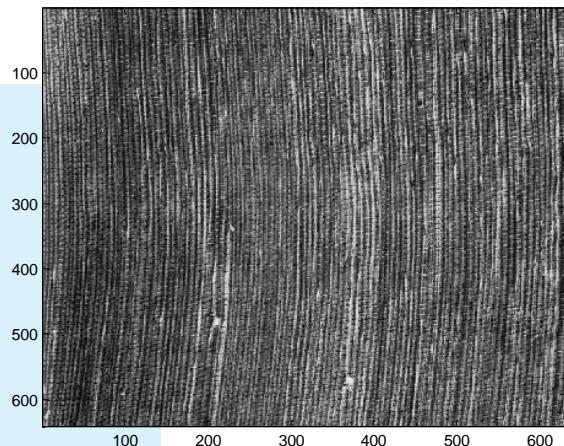
fenêtrage et
échantillonnage des fréquences

$$F(k, l) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} f(m, n) e^{-j2\pi\left(k \frac{m}{M} + l \frac{n}{N}\right)}$$

variables discrètes $\begin{cases} k \in [0, M-1] \\ l \in [0, N-1] \end{cases}$

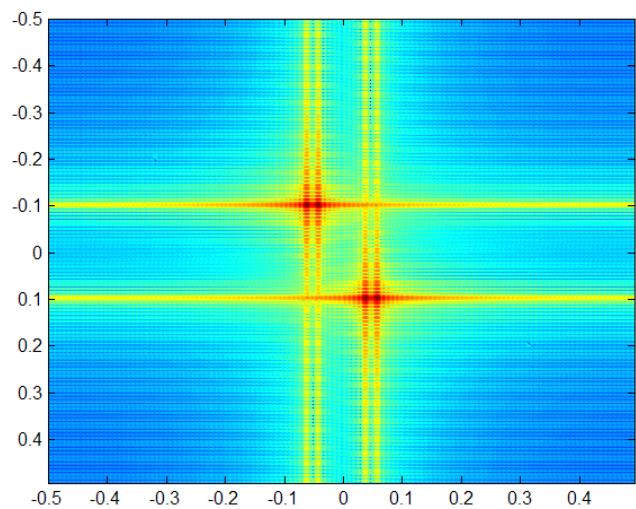
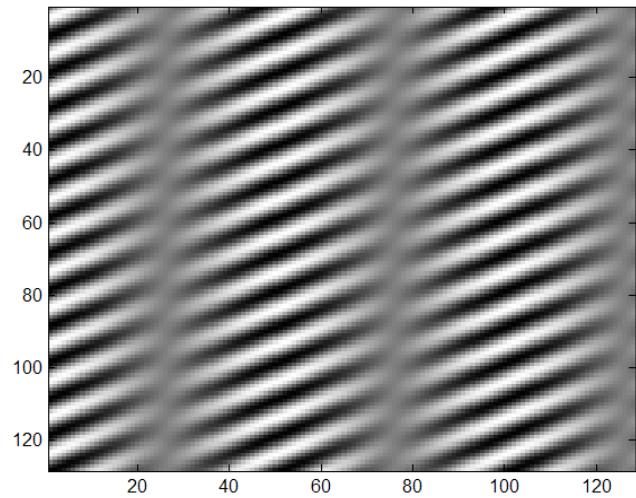
TFD

```
clear  
close all  
  
A=imread('trame.bmp');  
figure, image(A)  
colormap(gray(256))  
[h,w]=size(A);  
B=log10(abs(fft2(A)));  
fx=linspace(0,1-1/w,w);  
fy=linspace(0,1-1/h,h);  
figure, imagesc(fx,fy,B);  
% w et h pairs  
fx=linspace(-0.5,0.5-1/w,w);  
fy=linspace(-0.5,0.5-1/h,h);  
figure  
imagesc(fx,fy,fftshift(B));
```



TFD et fenêtrage

```
clear  
close all  
  
N=128;  
t=0:N-1;  
[X,Y]=meshgrid(t);  
I=50*sin(2*pi*0.04*X+2*pi*0.1*Y)+...  
    50*sin(2*pi*0.06*X+2*pi*0.1*Y)+...  
    0.01*sin(2*pi*0.32*X+2*pi*0.2*Y);  
figure, imagesc(I), colormap(gray(256))  
If=fftshift(log10(abs(fft2(I,512,512))));  
f=linspace(-0.5,0.5-1/N,N);  
figure, imagesc(f,f,If)
```

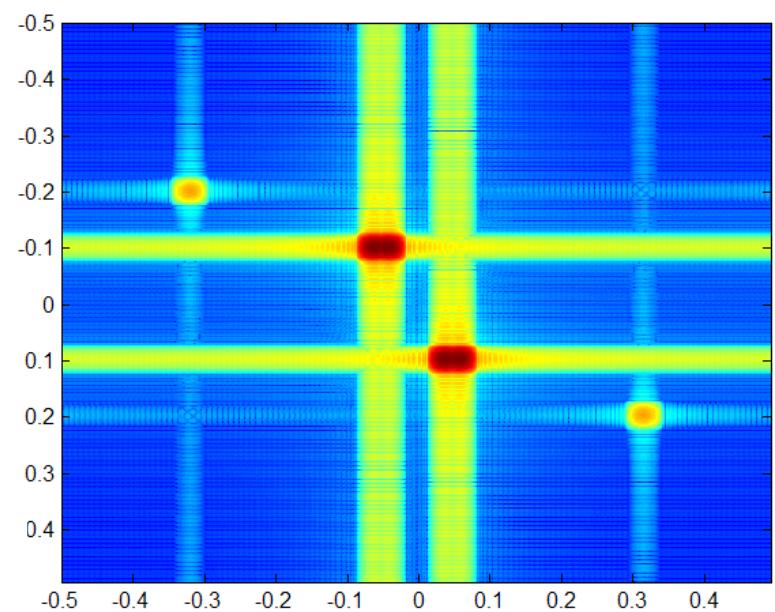
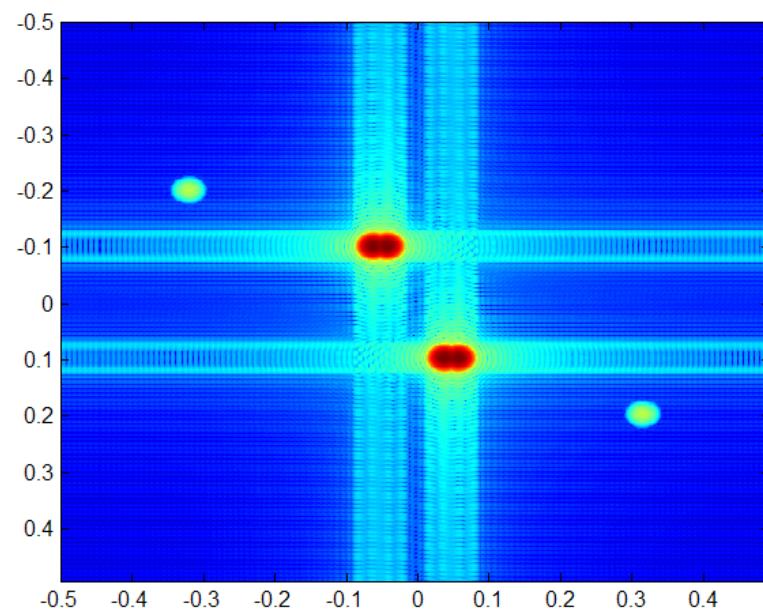
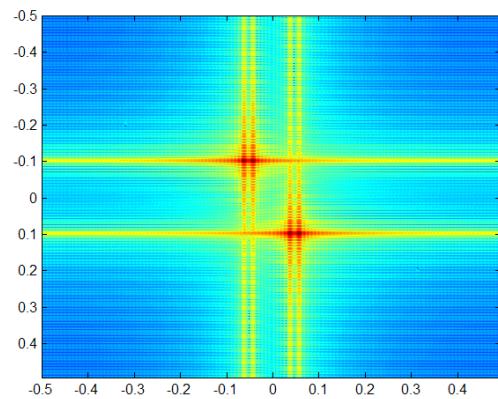


Kaiser séparable

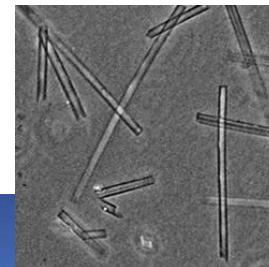
```
W=kaiser(128,10)*kaiser(128,10)';
Iw=I.*W;
If2=fftshift(log10(abs(fft2(Iw,512,512))));  
figure, imagesc(f,f,If2)
```

```
M=-64:63;
[X,Y]=meshgrid(M);
R=(X.^2+Y.^2);
Rf=64^2;
a=10;
Wc=besselj(0,a*sqrt(1-R/Rf))/besselj(0,a);
Iw2=I.*Wc;
If3=fftshift(log10(abs(fft2(Iw2,512,512))));  
figure, imagesc(f,f,If3)
```

Kaiser à symétrie circulaire



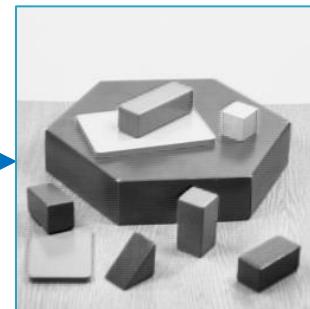
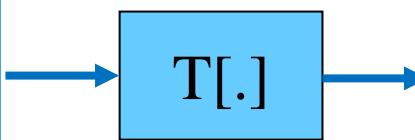
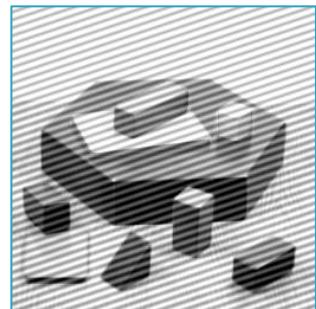
Initiation au Traitement des Images



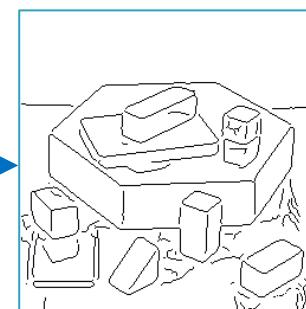
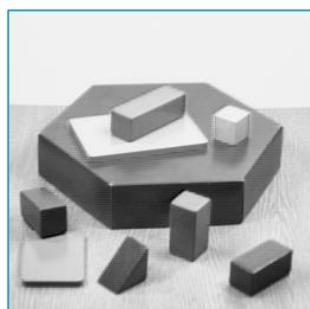
- ▶ **Filtrage linéaire**
 - Filtres RIF
 - Détection de contours
- ▶ **Filtrage non linéaire**

Traitements

Filtres RIF



Filtrage fréquentiel

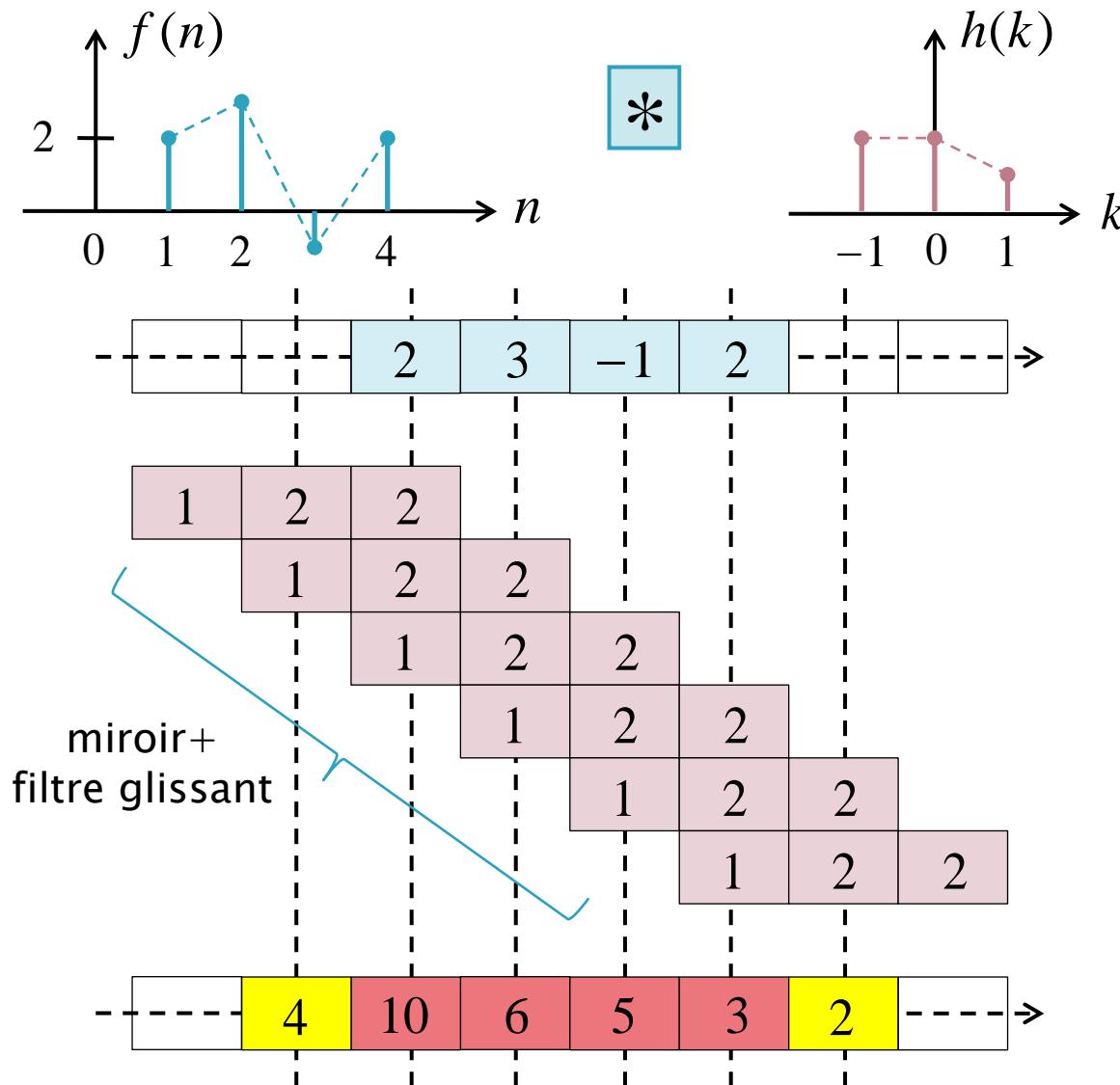


Détection de contours

$$g(m, n) = \sum_{k=-K}^K \sum_{l=-L}^L f(m-k, n-l) h(k, l)$$

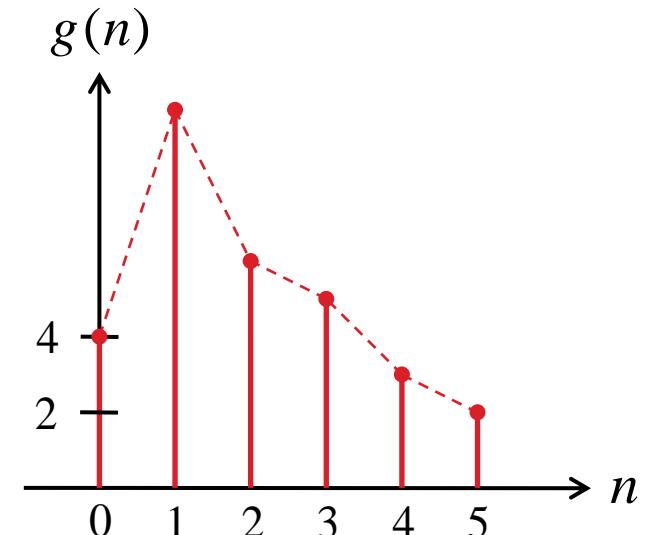
Convolution 2D

Convolution discrète 1d

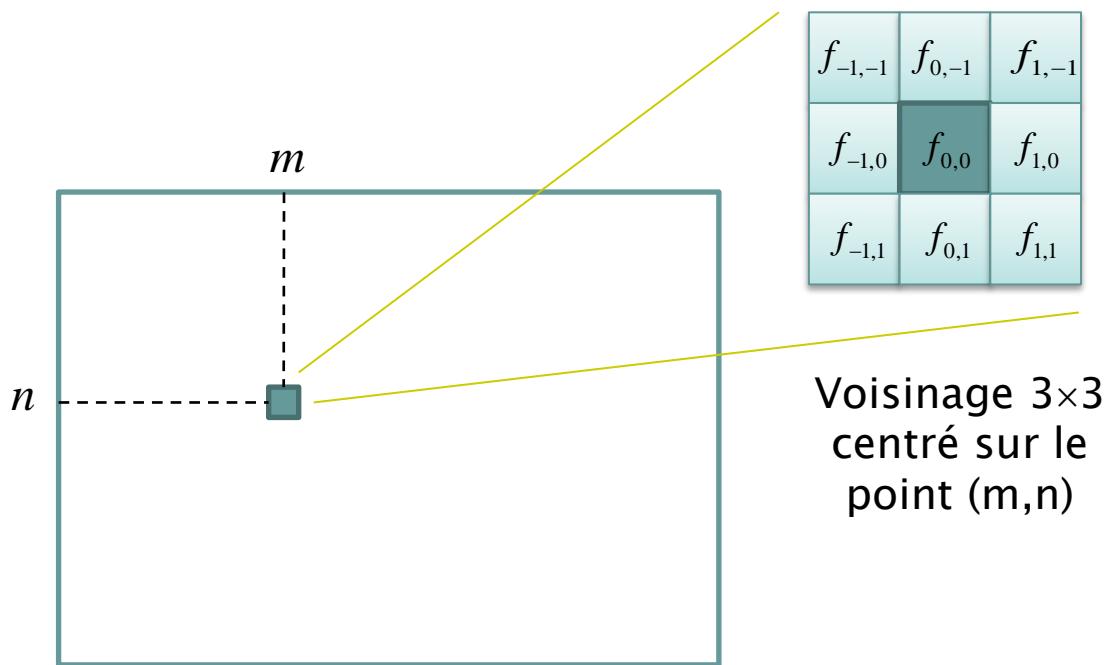


$$\begin{aligned}
 g(n) &= \sum_{k=-K}^K f(n-k)h(k) \\
 &= \sum_{k=-K}^K f(n+k)h(-k)
 \end{aligned}$$

miroir



Convolution discrète 2d



$*$

$h_{-1,-1}$	$h_{0,-1}$	$h_{1,-1}$
$h_{-1,0}$	$h_{0,0}$	$h_{1,0}$
$h_{-1,1}$	$h_{0,1}$	$h_{1,1}$

filtre 3×3

symétrie
centrale

$h_{1,1}$	$h_{0,1}$	$h_{-1,1}$
$h_{1,0}$	$h_{0,0}$	$h_{-1,0}$
$h_{1,-1}$	$h_{0,-1}$	$h_{-1,-1}$

$$\begin{aligned}
 g(m, n) &= \sum_{k=-K}^K \sum_{l=-L}^L f(m-k, n-l) h(k, l) \\
 &= \sum_{k=-K}^K \sum_{l=-L}^L f(m+k, n+l) h(-k, -l)
 \end{aligned}$$

Exemple : convolution 3x3

```
clear
close all

I=[3 1 1 1 1 1; ...
    1 1 1 1 1 1; ...
    1 1 1 1 1 1; ...
    1 1 1 1 1 1]
H=ones(3)/9
Ic1=conv2(I,H)
Ic2=conv2(I,H, 'same')
```

```
I =
```

3	1	1	1	1	1
1	1	1	1	1	1
1	1	1	1	1	1
1	1	1	1	1	1

```
H =
```

0.1111	0.1111	0.1111
0.1111	0.1111	0.1111
0.1111	0.1111	0.1111

```
Ic1 =
```

0.3333	0.4444	0.5556	0.3333	0.3333	0.3333	0.2222	0.1111
0.4444	0.6667	0.8889	0.6667	0.6667	0.6667	0.4444	0.2222
0.5556	0.8889	1.2222	1.0000	1.0000	1.0000	0.6667	0.3333
0.3333	0.6667	1.0000	1.0000	1.0000	1.0000	0.6667	0.3333
0.2222	0.4444	0.6667	0.6667	0.6667	0.6667	0.4444	0.2222
0.1111	0.2222	0.3333	0.3333	0.3333	0.3333	0.2222	0.1111

```
Ic2 =
```

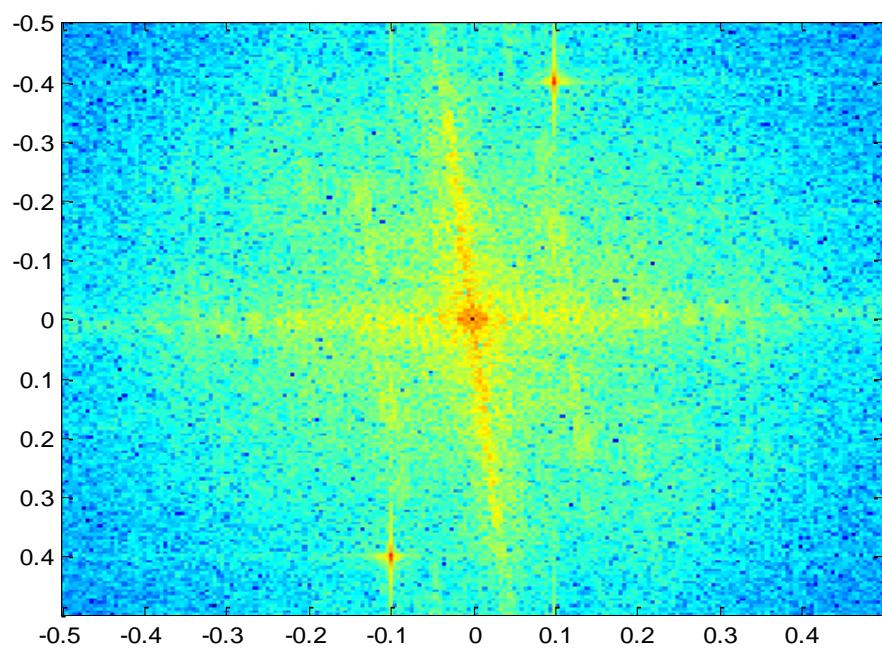
0.6667	0.8889	0.6667	0.6667	0.6667	0.4444
0.8889	1.2222	1.0000	1.0000	1.0000	0.6667
0.6667	1.0000	1.0000	1.0000	1.0000	0.6667
0.4444	0.6667	0.6667	0.6667	0.6667	0.4444

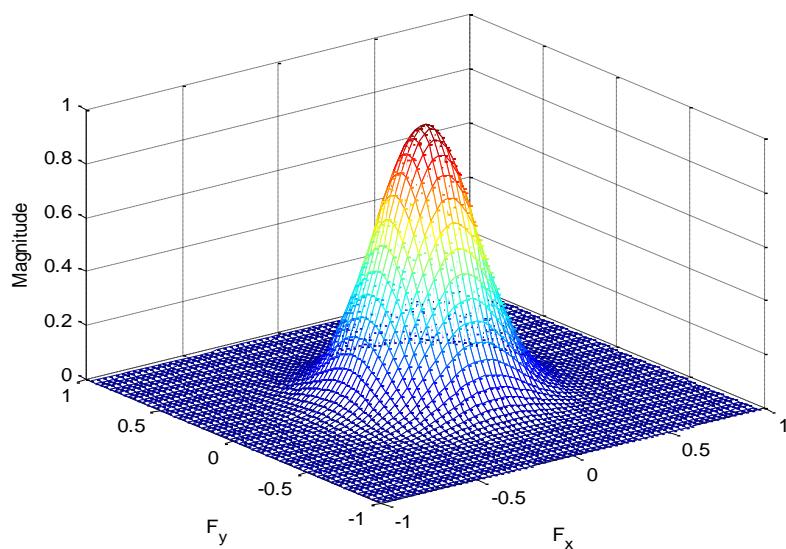
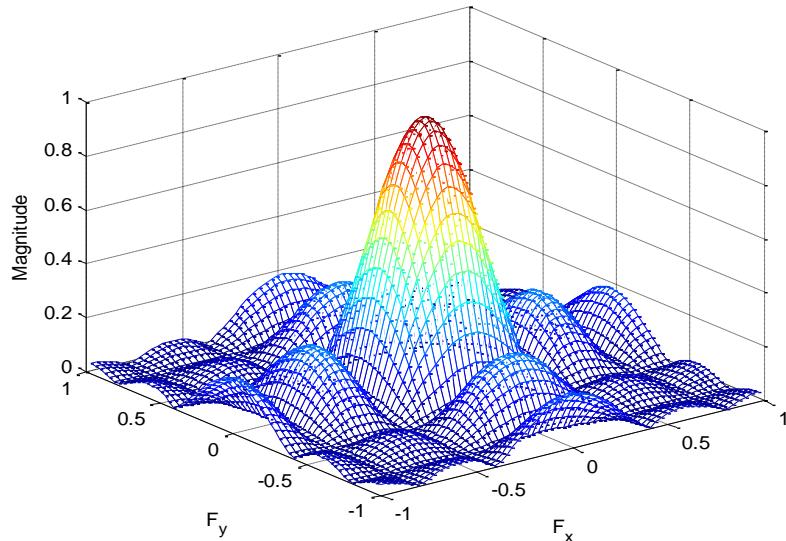
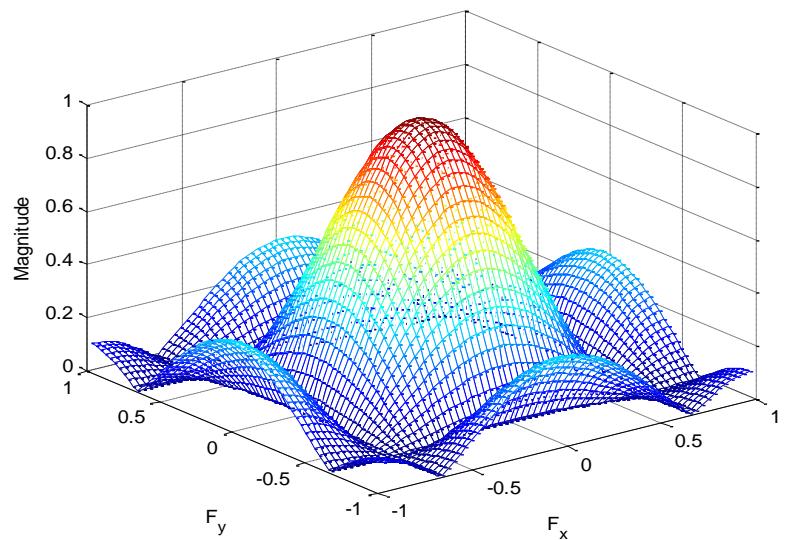
Exercice

- ▶ Affichage de l'image ‘monument_ext.bmp’
- ▶ Filtrage passe-bas pour éliminer/réduire le bruit
 - Justification du choix (visualisation de la TFD)
 - Vérification de l'adéquation des filtres (freqz2)
- ▶ Affichage des images filtrées et de leur spectre
- ▶ Calcul et affichage du « bruit » (différence entre l'image initiale et les images filtrées)

```
clear, close all

A=double(imread('monument_ext.bmp')) ;
figure, imshow(uint8(A))
[h,w]=size(A);
fx=linspace(-0.5,0.5-1/w,w);
fy=linspace(-0.5,0.5-1/h,h);
IfA=fftshift(log10(abs(fft2(A))) );
figure, imagesc(fx,fy,IfA)
H1=ones(3)/9;
H2=ones(5)/25;
[X,Y]=meshgrid(-5:5);
sigma=1.5;
H3=exp(-(X.^2+Y.^2)/(2*sigma^2))/(2*pi*sigma*sigma);
figure, freqz2(H1)
figure, freqz2(H2)
figure, freqz2(H3)
```

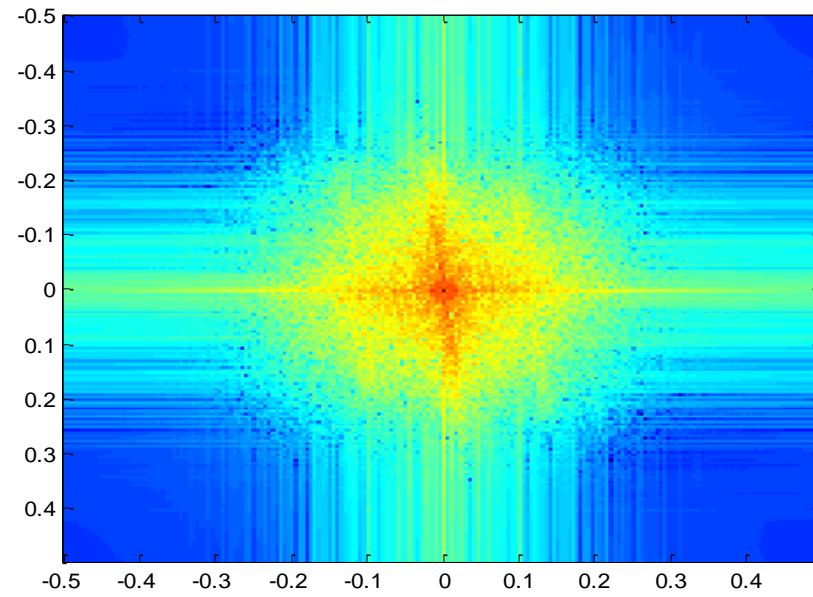
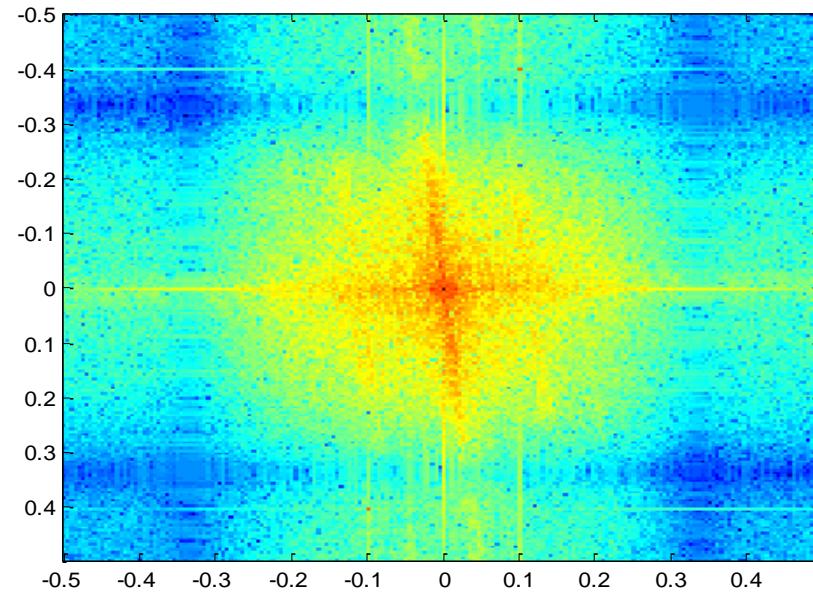
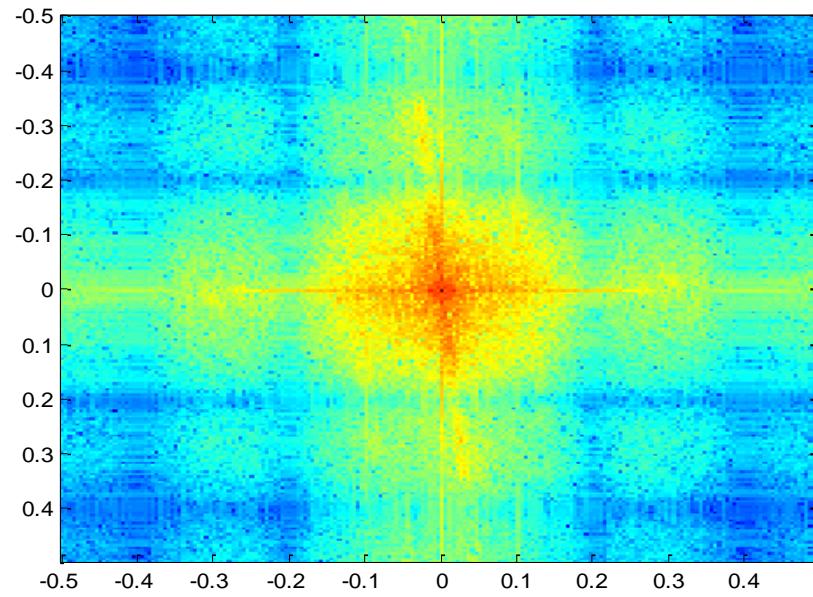
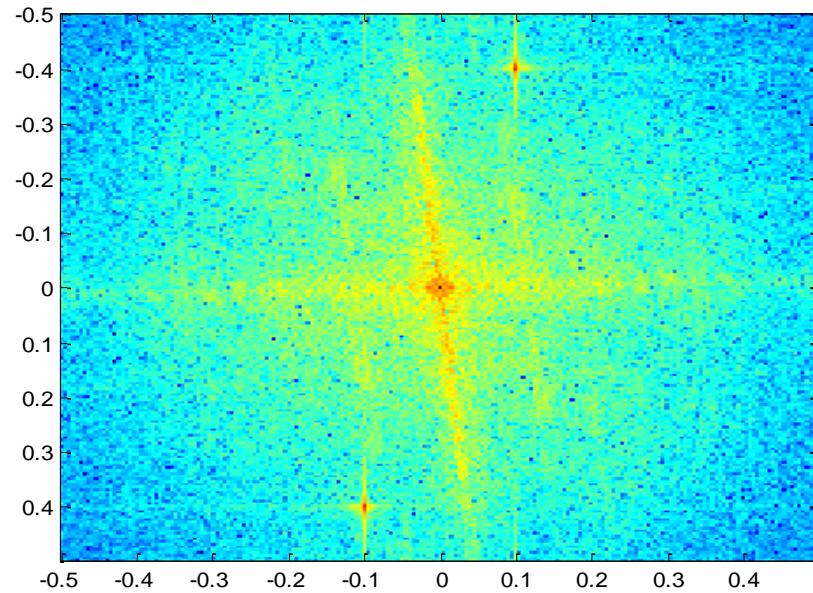




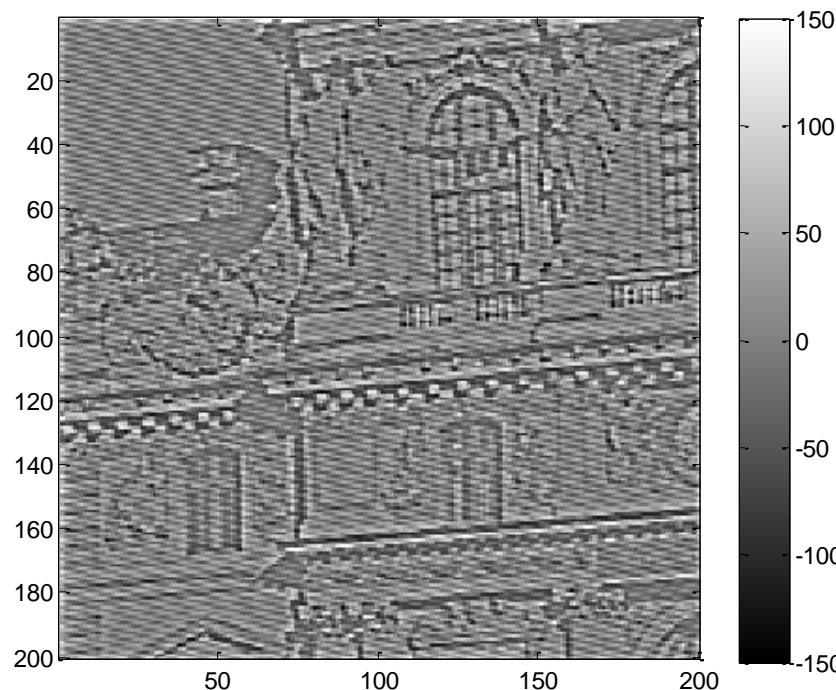
```
B=conv2(A,H1,'same');
figure, imshow(uint8(B));
C=conv2(A,H2,'same');
figure, imshow(uint8(C));
D=conv2(A,H3,'same');
figure, imshow(uint8(D));

IfB=fftshift(log10(abs(fft2(B)) ));
figure, imagesc(fx,fy,IfB)
IfC=fftshift(log10(abs(fft2(C)) ));
figure, imagesc(fx,fy,IfC)
IfD=fftshift(log10(abs(fft2(D)) ));
figure, imagesc(fx,fy,IfD)
```





```
figure, imagesc(A-B, [-150 150]),  
colormap(gray(256)), colorbar, axis square  
figure, imagesc(A-C, [-150 150]),  
colormap(gray(256)), colorbar, axis square  
figure, imagesc(A-D, [-150 150]),  
colormap(gray(256)), colorbar, axis square
```



Détection de contours

```
clear
close all

A=double(imread('cameraman.tif'));
figure, imshow(uint8(A))
[X,Y]=meshgrid(-5:5);
sigma=1.5;
Hx=-X.*exp(-(X.^2+Y.^2)/(2*sigma^2))/(2*pi*sigma^4);
Hy=-Y.*exp(-(X.^2+Y.^2)/(2*sigma^2))/(2*pi*sigma^4);
Gx=conv2(A,Hx,'same');
Gy=conv2(A,Hy,'same');
G=(Gx.*Gx+Gy.*Gy).^0.5;
figure
imshow(G, [0 50])
colormap(flipud(gray(256)))
```



$\sigma = 0,75$



$\sigma = 2,5$



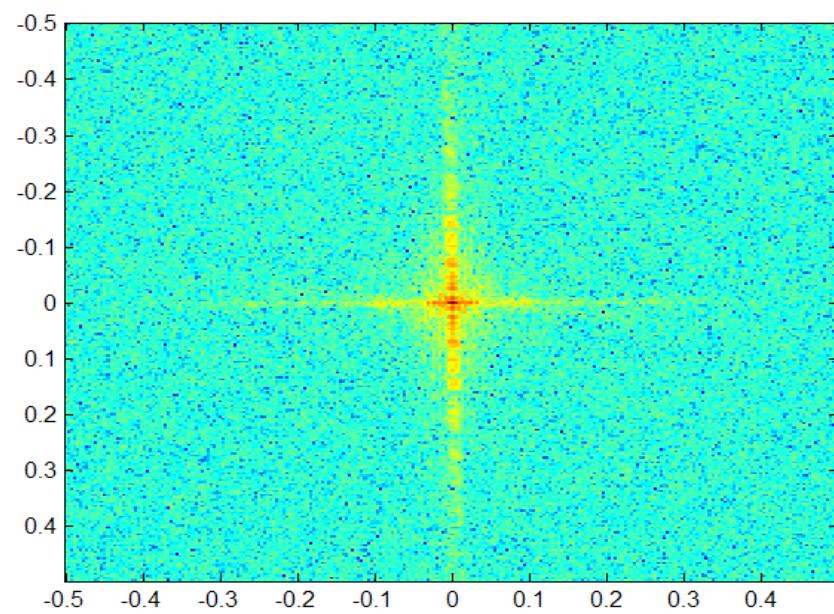
$\sigma = 1,5$

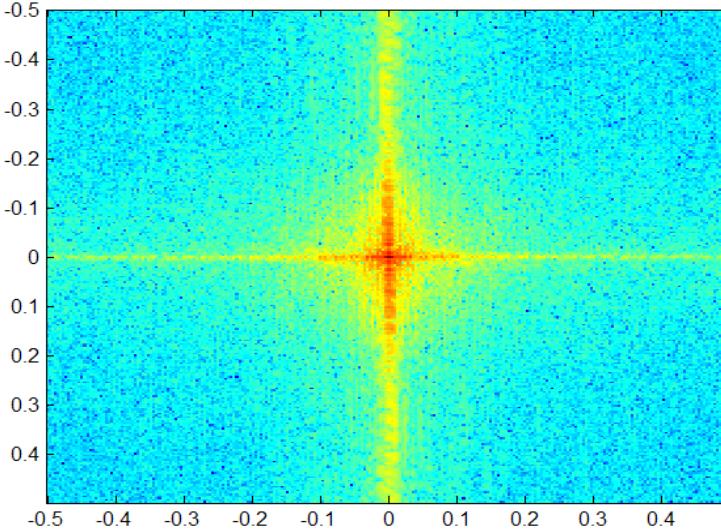
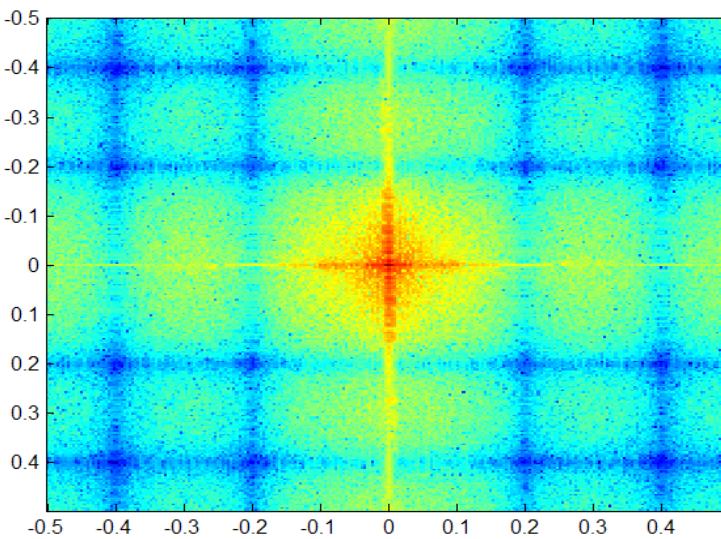
Exercice

- ▶ Affichage de l'image 'couloir.tif'
- ▶ Application d'un filtre RIF passe-bas
- ▶ Comparaison avec un filtre non linéaire (médian)

```
clear, close all

A=double(imread('couloir.tif')) ;
figure, imshow(uint8(A))
[h,w]=size(A) ;
fx=linspace(-0.5,0.5-1/w,w) ;
fy=linspace(-0.5,0.5-1/h,h) ;
IfA=fftshift(log10(abs(fft2(A)))) ;
figure, imagesc(fx,fy,IfA)
H1=ones(5)/25;
B=conv2(A,H1,'same') ;
figure, imshow(uint8(B)) ;
IfB=fftshift(log10(abs(fft2(B)))) ;
figure, imagesc(fx,fy,IfB)
C=medfilt2(A, [5 5]) ;
figure, imshow(uint8(C)) ;
IfC=fftshift(log10(abs(fft2(C)))) ;
figure, imagesc(fx,fy,IfC)
```





Syntaxes et fonctions utiles

```
x=2 ;  
  
u=[ 5 -3 2 4 ] ;  
v=u+x;  
w=v>1 ;  
  
A=u' *u ;  
y=u*u' ;  
B=A+x;  
C=A+B;  
D=A.*B;  
E=D>2 ;  
F=E (2:end,1:2) ;  
  
t=A( : ) ;  
A=reshape(t, [4 4]) ;
```

size, whos
zeros, ones, double, uint8
imread, imwrite
figure, subplot, image, imagesc, imshow
colorbar, colormap, axis
load
cat
ginput, plot, line, hold, surf
min, max, abs, log10, sqrt, mod
fix
meshgrid
linspace, fft2, fftshift
conv2, freqz2
medfilt2
flipud
videoWriter, writeVideo, open