

Section 1

Question 1:

$$\begin{bmatrix} 1 & 0 & -T_x \\ 0 & 1 & -T_y \\ 0 & 0 & 1 \end{bmatrix}$$

Inverse of the translation transform matrix:

$$\begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

If the original transform matrix of a rotation transform is:

$$\begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

the matrix is: All the inverse is doing is rotating the matrix by $-\theta$ instead of θ . Notably the inverse of the rotation matrix is also the transpose of the original matrix.

Question 3:

$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

The inverse of the x-axis reflection matrix is: This is the same as the original reflection matrix. This is intuitive, because if you are trying to undo a reflection all you need to do is reflect the image once more.

Question 4:

Using the inversion formula for a 2×2 matrix you can calculate the inverse of the shear transform matrix. These calculations can be found below (for a shear in the x-axis):

$$\begin{bmatrix} 1 & r_x \\ 0 & 1 \end{bmatrix}^{-1} = \frac{1}{1-0} \begin{bmatrix} 1 & -r_x \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -r_x \\ 0 & 1 \end{bmatrix}$$

This inverse makes sense, because you need to subtract the sheared value added to the x coordinate. If $x' = x + r_x y$ then $x = x' - r_x y$. Following this sense for the y-axis yields the

following inverse matrix: $\begin{bmatrix} 1 & 0 \\ -r_y & 1 \end{bmatrix}$.

Section 2

Results:

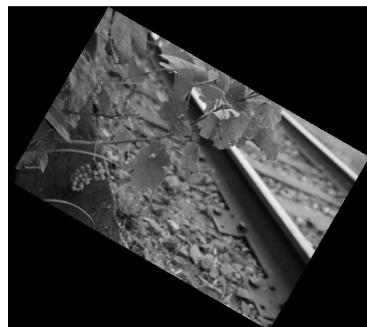
Image 1



1



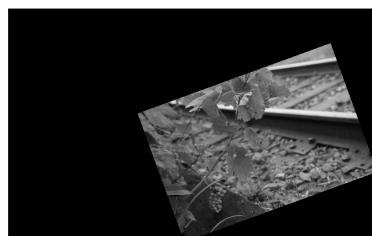
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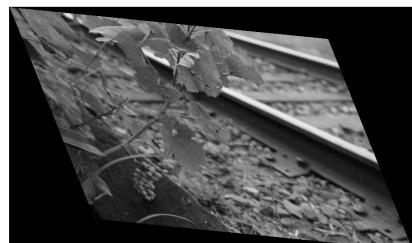
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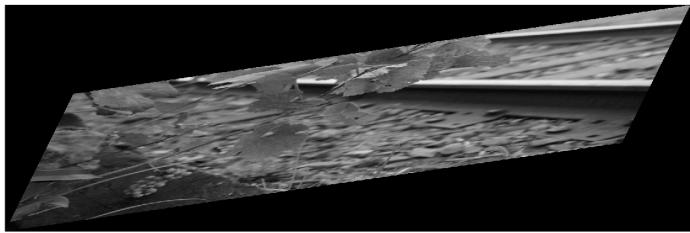
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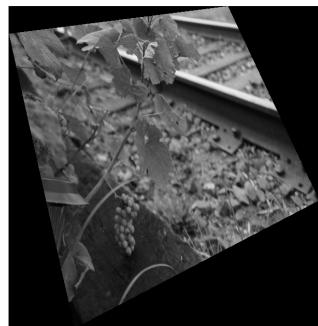
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Image 2



1



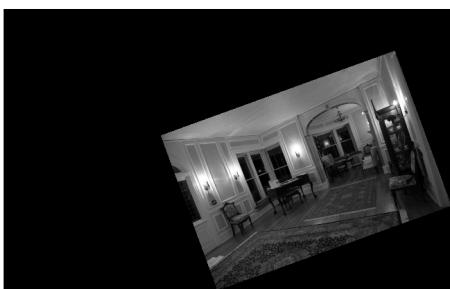
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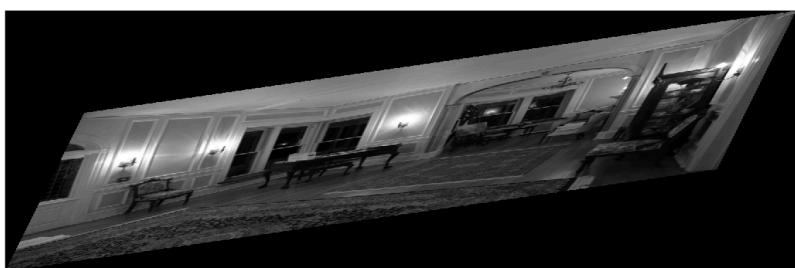
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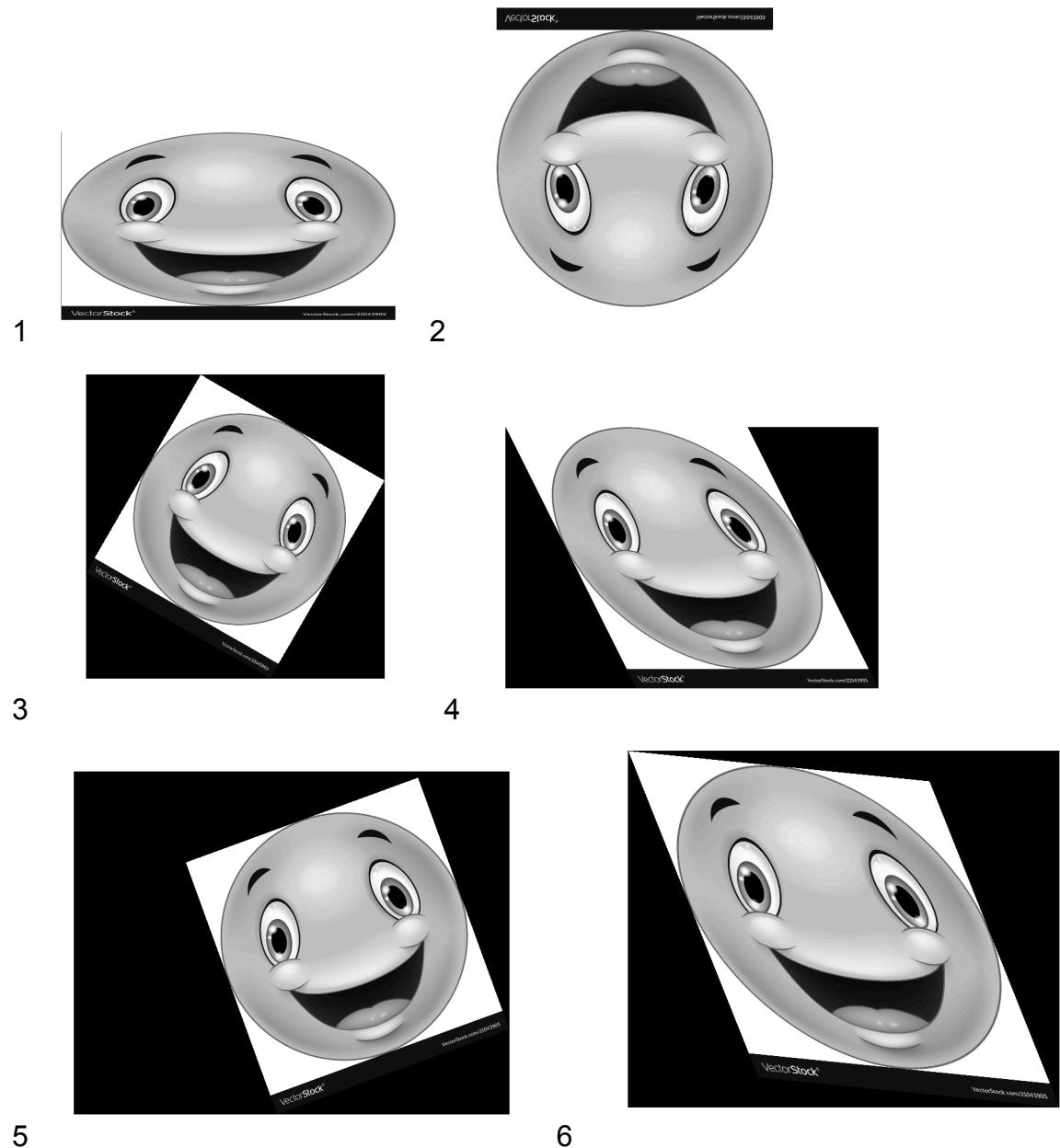


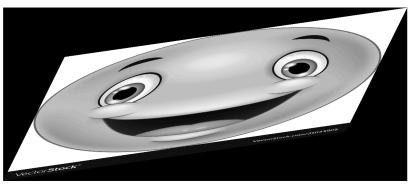
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Image 3

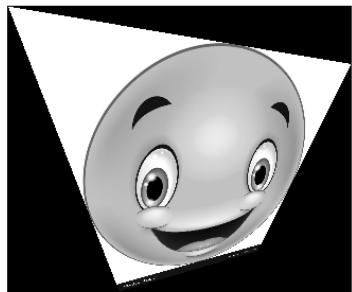




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