

MATH266: UNSTABLE MOTIVIC HOMOTOPY THEORY

Fall 2024

THOMAS BRAZELTON

ABSTRACT. Notes from MATH266: Motivic homotopy theory, taught at Harvard in Fall 2024.

CONTENTS

0.	Introduction	1
1.	Lecture 1: Torsors	4

0. INTRODUCTION

0.1. Overview. What sorts of things about a ring R are still true when we move to the polynomial ring $R[t]$? In other words, what sorts of things about R can't be varied in a 1-parameter family? Let's give a ton of examples! Don't stress if not all of the words are familiar, we'll break down what's happening here over the course of the semester, this is just motivation.

Example 0.1. Let R be a reduced ring. Then the inclusion $R \rightarrow R[t]$ induces an isomorphism after taking units¹

$$(2) \quad R^\times \xrightarrow{\sim} (R[t])^\times.$$

Recall that the functor sending a commutative ring to its group of units is corepresented by $\mathbb{Z}[u, u^{-1}]$, so Equation 2 is equivalent to saying that the following map is a bijection

$$\mathrm{Hom}_{\mathrm{Ring}}(\mathbb{Z}[u, u^{-1}], R) \rightarrow \mathrm{Hom}_{\mathrm{Ring}}(\mathbb{Z}[u, u^{-1}], R[t]).$$

After taking Spec everywhere, this becomes

$$\mathrm{Hom}_{\mathrm{Sch}}(\mathrm{Spec}(R), \mathbb{G}_m) \rightarrow \mathrm{Hom}_{\mathrm{Sch}}(\mathrm{Spec}(R[t]), \mathbb{G}_m).$$

We therefore might rephrase Equation 2 as saying that $\mathrm{Hom}_{\mathrm{Sch}}(-, \mathbb{G}_m)$ is \mathbb{A}^1 -invariant, at least when we plug in something reduced.

Example 0.3. Let k be a field. Then the functor $k \rightarrow k[t_1, \dots, t_n]$ induces an extension of scalars map

$$\begin{aligned} \mathrm{Mod}_k &\rightarrow \mathrm{Mod}_{k[t_1, \dots, t_n]} \\ M &\mapsto M \otimes_k k[t_1, \dots, t_n]. \end{aligned}$$

Serre's Problem: Is every finitely generated $k[t_1, \dots, t_n]$ -module free?

Recall finitely generated projective R -modules are the same as “algebraic vector bundles” over $\mathrm{Spec}(R)$, so we're asking whether every algebraic vector bundle on \mathbb{A}_k^n is trivial.

Answer: Yes (Quillen–Suslin, 1974). Quillen actually proved more— for R a PID, he proved that the every finitely generated projective $R[t]$ -module is extended from an R -module.² Lindel proved shortly thereafter that every finitely generated projective $A[t]$ -module is extended from an A -algebra,

¹If R is not reduced, say there is some $r \in R$ so that $r^2 = 0$, then $(1 + rt)(1 - rt) = 1$, so $1 + rt \in R[t]^\times$.

²Quillen's proof involves leveraging some previous work of Horrocks, flat descent for vector bundles, and a very clever technique he invented called *patching*. Suslin's proof, which appeared in the same year, is almost completely linear algebraic, leveraging the theory of *unimodular rows*.

where A is a smooth algebra containing a field k . We could read this as saying that the stack of algebraic vector bundles is \mathbb{A}^1 -invariant over the category of smooth affine k -schemes.

More general: (Bass–Quillen conjecture) is it true that for every R regular Noetherian, the map

$$\begin{aligned} \mathrm{Mod}_R^{\mathrm{f.g., proj}} &\rightarrow \mathrm{Mod}_{R[t]}^{\mathrm{f.g., proj}} \\ M &\mapsto M \otimes_R R[t] \end{aligned}$$

is essentially surjective? *Still open.*

Fundamental Theorem of Algebraic K-Theory (Quillen): For R regular Noetherian, we have that $R \rightarrow R[t]$ induces an equivalence³⁴

$$K(R) \xrightarrow{\sim} K(R[t]).$$

In other K -theory is \mathbb{A}^1 -invariant for regular Noetherian rings (regular Noetherian schemes, more generally).

Example 0.4. If $X = \mathrm{Spec}(R)$ or more generally X is a scheme, then the map $\pi: X \times \mathbb{A}^1 \rightarrow X$ induces an isomorphism on Chow groups (see for instance [Ful98, p. 3.3])

$$\pi^*: \mathrm{CH}_*(X) \xrightarrow{\sim} \mathrm{CH}_{*+1}(X \times \mathbb{A}^1).$$

Example 0.5. Let $X = \mathrm{Spec}(R)$ where R is normal and Noetherian.⁵ Then every line bundle on $X \times \mathbb{A}^1$ is extended from a line bundle on X , in other words $X \times \mathbb{A}^1 \rightarrow X$ induces an isomorphism

$$\mathrm{Pic}(X) \xrightarrow{\sim} \mathrm{Pic}(X \times \mathbb{A}^1).$$

Example 0.6. We can also show \mathbb{A}^1 -invariance for the Picard group over a PID. Let R be a PID, then it is a UFD, and we can show that $\mathrm{Pic}(R) = 0$, and therefore $\mathrm{Pic}(R[t_1, \dots, t_n]) = 0$.

Example 0.7. [Aso21, p. 3.7.1.5] Check this doesn't hold for all rings, for example $R = k[x, y]/(y^2 - x^3)$.

Definition 0.8. An *inner product space* over a ring R is a finitely generated projective R -module M and a symmetric bilinear form $\beta: M \times M \rightarrow R$ for which $m \mapsto \beta(-, m)$ defines an isomorphism $M \cong M^*$.

Theorem 0.9. (Harder's Theorem, VII.3.13 in Lam's book on Serre's problem) Let k be a field. Then every inner product space over $k[t]$ is extended from an inner product space over k .

Remark 0.10. The stable analogue of this has to do with \mathbb{A}^1 -invariance of Hermitian K -theory [reference needed].

Algebraic vector bundles are GL_n -torsors (we will talk about torsors in more detail next week), so the Bass–Quillen conjecture is really asking about \mathbb{A}^1 -invariance of torsors over affine schemes. We could ask an analogous question about G -torsors for any G . Here's an example result in this direction that we'll see later in the semester:

Theorem 0.11. [AHW20, p. 1.3] If k is a field, and G is an isotropic reductive group scheme, then G -torsors in the Nisnevich site are \mathbb{A}^1 -invariant over any smooth affine k -scheme.

³So Bass–Quillen is really a question about *unstable* modules.

⁴The statement for K_0 is originally due to Grothendieck [Aso21, p. 5.6.1.3]. The statement for K_1 is due to Bass–Heller–Swan [Aso21, p. 5.8.2.1].

⁵We can get away with weaker assumptions on this. In Aravind's notes 3.7.1.3 he assumes R is a locally factorial Noetherian normal domain.

0.2. \mathbb{A}^1 -homotopy theory. Recall from algebraic topology that $X \times [0, 1] \rightarrow X$ is a weak homotopy equivalence, which implies that any cohomology theory is insensitive to taking a product with an interval, e.g. for $H^*(-, \mathbb{Z})$ integral cohomology we get

$$H^*(X, \mathbb{Z}) \xrightarrow{\sim} H^*(X \times [0, 1], \mathbb{Z}).$$

In fact this type of homotopy invariance is an axiom of generalized Eilenberg–Steenrod cohomology theories.

Example 0.12. Let $k \subseteq \mathbb{C}$ be a subfield of the complex numbers. Then there is a *Betti realization* functor

$$\begin{aligned} \mathrm{Var}_k &\rightarrow \mathrm{Top} \\ X &\mapsto X(\mathbb{C}) \end{aligned}$$

sending a variety to its underlying analytic space. Note that

$$X \times \mathbb{A}_k^1 \mapsto (X \times \mathbb{A}_k^1)(\mathbb{C}) = X(\mathbb{C}) \times \mathbb{C}.$$

Therefore any homotopy invariant functor out of spaces provides another example of an \mathbb{A}^1 -invariant functor out of k -varieties, for example

$$\begin{aligned} X &\mapsto H^*(X(\mathbb{C}); \mathbb{Z}) \\ X &\mapsto \pi_*(X(\mathbb{C})). \end{aligned}$$

Q: Can we build a homotopy theory of algebraic varieties in which the affine line \mathbb{A}^1 plays the role that the interval $[0, 1]$ plays in classical topology?

A: Yes! This is what’s known as \mathbb{A}^1 -homotopy theory or *motivic homotopy theory*. This dates back to Morel and Voevodsky’s seminal work in 1999, but many ideas date back to work of Karoubi–Villamayor, Jardine, Weibel in the 1980’s, work of Brown, Gersten, Illusie and Joyal in the 1970’s, and of Quillen and Grothendieck in the 1960’s.

Q: What can we do with motivic homotopy theory?

A: Motivic homotopy theory blends algebraic geometry and topology in a beautiful way, allowing us to do many things. A short list is:

- ▷ we obtain a natural home for these kinds of \mathbb{A}^1 -invariant cohomology theories of varieties, and can study them in a method analogous to algebraic topology (e.g. we can classify cohomology operations, use fiber sequences to carry out computations, unify various spectral sequences, etc.)
- ▷ we have access to obstruction theory for classifying torsors over affine varieties — recent success in this direction is Asok–Bachmann–Hopkins’ resolution of Murthy’s conjecture
- ▷ we can eliminate differentials in the Adams spectral sequence via looking at their motivic depth (citation needed)

Q: What techniques will we learn in this class?

A: We should be able to do the following things:

- ▷ learn descent and torsors more thoroughly, and unify perspectives on sheaves and stacks using higher categorical language
- ▷ work with infinity-categories at a very basic level
- ▷ learn how to work with motivic spaces and do computations
- ▷ learn motivic obstruction theory and its applications

0.3. A bit more about these notes.

Remark 0.13. (*Transparency about pedagogy*) We’re going to place affine representability on the horizon and keep our eyes fixed on it while motivate building the category of motivic spaces. This is of course ahistorical— although affine representability was one of the key early results explored by Morel, motivic spaces and spectra were developed in order to house theories such as algebraic

K -theory, Bloch's higher Chow groups, and to grow new theories such as algebraic cobordism. We chose this route for a few reasons:

- (1) The Fall 2024 Thursday seminar is on the motivic Steenrod algebra, so we're hoping this class will contrast nicely and provide some foundational background in techniques in motivic obstruction theory.
- (2) In order to tailor the course to a broader audience, we'd like to unify the class around a key question which has general appeal, so we've picked the classification of torsors over affine varieties using motivic methods as such a question. This has certain advantages, for instance we can pause in the sheaf topos and discuss classifying torsors there before building motivic spaces — this vista is useful to people across many fields.
- (3) This forces us to spend a bit longer on descent and torsors, two words which strike fear in the heart of many, and are worth investing some more time in.

Remark 0.14. (*On background*) We're assuming a strong handle of algebraic geometry and category theory, and a fair bit of familiarity with commutative algebra and homotopy theory. We'll see very quickly that ∞ -categories (and/or model categories) are needed in order to develop the setting in which we wish to work. We've elected to take the ∞ -categorical approach, since it streamlines many of the constructions and key ideas, at the cost of being a high technical investment; for this reason we've done our best to make the ∞ -categorical machinery easy to black box. The reader should be aware that while the categorical language will be heavy in the first half of these notes, it will quickly fade into the background as we become familiar with the ambient setting we're working in and can set our focus towards computations.

1. LECTURE 1: TORSORS

Assumption 1.1. For this lecture, every time we say “cover” you can assume we are working with Zariski covers, or even open covers of topological spaces, since the intuition will be the same and the results here will be mostly identical. If you know about other topologies, the statements here work for any site. We will go into sheaves and sites more next week, when we will remark that everything here works for other nice sites (étale, Nisnevich, flat, etc.).

Definition 1.2. Let G be a group. Then a G -set X is called a *torsor* if its G -action is simple and transitive. Equivalently, the map

$$\begin{aligned} G \times X &\rightarrow X \times X \\ (g, x) &\mapsto (x, gx) \end{aligned}$$

is a bijection.

Note there are two types of G -torsors — sets of the form G/e , and the empty set. Depending on the convention, we might want to exclude the case of the empty set by including $X \neq \emptyset$ in the definition.

Intuition 1.3. A G -torsor is like a group G which has remembered its multiplication but forgotten its identity. Any choice of basepoint $x \in X$ yields a canonical bijection $G \xrightarrow{\sim} X$ by sending $g \mapsto g \cdot x$.

Example 1.4. In a locally small category \mathcal{C} , given two objects $x, y \in \mathcal{C}$, the set of isomorphisms $\text{Isom}_{\mathcal{C}}(x, y)$ is a left $\text{Aut}_{\mathcal{C}}(x)$ -torsor and a right $\text{Aut}_{\mathcal{C}}(y)$ -torsor.

Let's try to extend this definition to the setting where G isn't a single group, but a *sheaf of groups* \mathcal{G} on a site. What is the appropriate analogue of a torsor in this setting? By abuse of notation we will also call this a *torsor*.

Definition 1.5. [Stacks, 03AH] Let \mathcal{G} be a sheaf of groups on X , and let $\text{Shv}_{\mathcal{G}}(X)$ denote the category of \mathcal{G} -sheaves, meaning sheaves of sets equipped with a \mathcal{G} -action, and equivariant morphisms between them. We define the category of \mathcal{G} -torsors $\text{Tors}_{\mathcal{G}}(X) \subseteq \text{Shv}_{\mathcal{G}}(X)$ to be the full subcategory on those \mathcal{F} so that

- (1) if $\mathcal{F}(U)$ is non-empty then the action

$$\mathcal{G}(U) \times \mathcal{F}(U) \rightarrow \mathcal{F}(U)$$

is simply transitive⁶

- (2) there exists a covering $\{U_i \rightarrow X\}$ over which $\mathcal{F}(U_i) \neq \emptyset$.⁷

Terminology 1.6. The choice of topology comes into play in that second point. If $\mathcal{F} \in \text{Shv}_{\mathcal{G}}(X)$, we say it is τ -locally trivial if \mathcal{G} is a τ -sheaf of groups, \mathcal{F} is a τ -sheaf of sets, and point (2) holds for any τ -cover.

Example 1.7. The sheaf \mathcal{G} , acting on itself by scaling, is called the *trivial* \mathcal{G} -torsor.

Example 1.8. For any group scheme G , we will refer to G -torsors, mean torsors the representable functor $\text{Hom}(-, G)$.

Proposition 1.9. A \mathcal{G} -torsor \mathcal{F} on X is trivial if and only if $\mathcal{F}(X) \neq \emptyset$, i.e. if it admits a global section.

Theorem 1.10. Every morphism in $\text{Tors}_G(X)$ is an isomorphism.

So what are some examples of torsors, and why might we care to classify them?

Example 1.11. If L/k is a Galois field extension then $\text{Spec}(L) \rightarrow \text{Spec}(k)$ is a $\text{Gal}(L/k)$ -torsor in any topology.

▷ *the inverse Galois problem*: which groups G occur as Galois groups of number fields? This is asking to scratch the surface of understanding G -torsors over $\text{Spec}(\mathbb{Q})$ for all finite groups G .

Example 1.12. A GL_n -torsor (say in the Zariski topology) is an algebraic vector bundle.

Proof. Since GL_n is affine, every torsor is representable, hence GL_n -torsors are just principal GL_n -bundles, which are precisely algebraic vector bundles. \square

▷ *Bass–Quillen conjecture*: this can be reframed as asking whether each GL_n -torsor over a regular Noetherian ring is trivial

▷ *Hartshorne’s conjecture* concerns GL_2 -torsors over \mathbb{A}^n for $n \geq 7$

Example 1.13. A PGL_n -torsor is a Brauer–Severi variety (or a central simple algebra).

▷ the *period-index conjecture* then concerns the complexity of PGL_n -torsors.

Goal 1.14. Develop methods to classify torsors.

Let’s do this, by first considering an alternative perspective on what a torsor is. We learned this from Alex Youcis’ excellent note on torsors [You].

1.1. Sheaves and stacks. Recall if \mathcal{F} is a sheaf of sets, this means for every cover $\{U_i \rightarrow U\}$, we have that the diagram is an equalizer

$$\mathcal{F}(U) \rightarrow \prod_{i,j} \mathcal{F}(U_i) \rightrightarrows \prod_{i,j} \mathcal{F}(U_i \times_U U_j).$$

This first map is a monomorphism (injection) because it is an equalizer. This means that if $x, y \in \mathcal{F}(U)$ are equal in $\mathcal{F}(U_i)$ for each i , then they are equal in $\mathcal{F}(U)$. In other words, the map “reflects equality” — this is literally just what it means for something to be an injection.

⁶This means that in the category of $\mathcal{G}(U)$ -sets, we have that $\mathcal{F}(U) \cong \mathcal{G}(U)$, but $\mathcal{F}(U)$ doesn’t have a group structure — we might imagine that it has forgotten its identity element. Picking a basepoint $e \in \mathcal{F}(U)$ defines a group structure on $\mathcal{F}(U)$.

⁷In other words, we can find a cover in which to visualize $\mathcal{F}(U_i)$ as a group for each i .

Let's suppose now that $\mathcal{F}(U)$ is a *category* for every U . We'll define this concretely soon once we have more machinery, but for now let's just pretend that we know what this means — it means we can glue objects and morphisms along covers. Consider the analogous restriction functor:

$$\begin{aligned}\mathcal{F}(U) &\rightarrow \prod \mathcal{F}(U_i) \\ x &\mapsto (x|_{U_i})_i.\end{aligned}$$

Q: Does this map need to reflect isomorphisms?⁸

Example 1.15. Let \mathcal{F} be the functor sending U to the category of line bundles over U . If the cover is picked appropriately small, then all line bundles are isomorphic to the trivial line bundle over U_i , but they need not be isomorphic globally as line bundles over U .

A: No, by the example above. This means that we can have $x, y \in \mathcal{F}(U)$ so that $x|_{U_i} \cong y|_{U_i}$ for each i , but we *do not have* that x and y are isomorphic in the category $\mathcal{F}(U)$. In other words, the two notions are *different*:

- ▷ x and y agree *globally*, meaning x and y are isomorphic in $\mathcal{F}(U)$
- ▷ x and y agree *locally*, meaning there exists an open cover $\{U_i \rightarrow U\}$ for which we have isomorphisms $x|_{U_i} \xrightarrow{\sim} y|_{U_i}$ in $\mathcal{F}(U_i)$.⁹

Remark 1.16. This is a big difference between sheaves of sets (or 1-categories in general) and sheaves of categories (also called *stacks*). Equality is reflected along a cover for sheaves of sets, but isomorphism is not necessarily reflected along a cover.

Question 1.17. How many isomorphism classes of objects $y \in \mathcal{F}(U)$ are *locally isomorphic* to x along a cover, but not globally isomorphic?

We're going to build a sheaf that measures this! We'll call this sheaf $\text{Aut}_{\mathcal{F}}(x)$, and it is defined by

$$U_i \mapsto \text{Aut}_{\mathcal{F}(U_i)}(x)$$

Exercise 1.19. This is a priori just a presheaf of groups. Check it is actually a sheaf of groups.

Recall: If \mathcal{G} is a sheaf of groups over U , and $\mathcal{U} = \{U_i \rightarrow U\}$ is a cover.

- (1) We define a *Čech 1-cocycle* to be a collection of elements $g_{ij} \in \mathcal{G}(U_i \times_U U_j)$ for each i, j so that

$$g_{jk}g_{ij} = g_{ik}$$

on triple overlaps.

- (2) We say two 1-cocycles (g_{ij}) and (γ_{ij}) are cohomologous if there are $\alpha_i \in \mathcal{G}(U_i)$ for each i so that

$$\alpha_j g_{ij} = \gamma_{ij} \alpha_i.$$

- (3) We define the *Čech cohomology* $\check{H}^1(U, \mathcal{G})$ to be the colimit of the Čech cohomology over covers, filtered with respect to refinement.

Theorem 1.20. There is a bijection between $H^1(U, \text{Aut}_{\mathcal{F}}(x))$ and isomorphism classes of objects $y \in \mathcal{F}(U)$ which are locally isomorphic to x .

Proof. Let's first define a map. If y is locally isomorphic to x , then there is a cover $\{U_i\}$ of U and isomorphisms $\phi_i: x|_{U_i} \xrightarrow{\sim} y|_{U_i}$ for each i . If the ϕ_i 's agreed on overlaps then they would glue to a global isomorphism $\phi: x \xrightarrow{\sim} y$ because $\text{Aut}(x)$ is a sheaf of groups, so it makes sense to look on

⁸A functor which reflects isomorphisms is called *conservative*.

⁹The notation $x|_{U_i}$ is shorthand for the image of x under the restriction functor $\mathcal{F}(U) \rightarrow \mathcal{F}(U_i)$

overlaps to see what happens. Note that $\phi_i|_{U_{ij}}$ and $\phi_j|_{U_{ij}}$ will differ by an automorphism of $x|_{U_{ij}}$, call this g_{ij} :

$$g_{ij} := \left(\phi_j|_{U_{ij}} \right)^{-1} \left(\phi_i|_{U_{ij}} \right) : x|_{U_{ij}} \xrightarrow{\sim} x|_{U_{ij}}.$$

On triple overlaps, these satisfy the relations (check)

$$g_{jk}g_{ij} = g_{ik}.$$

In other words we get a 1-cocycle! There was ambiguity here, since we *picked* isomorphisms $x|_{U_i} \xrightarrow{\sim} y|_{U_i}$ as our starting data. The remaining thing to prove is that any other choice of local isomorphisms gives rise to a cohomologous 1-cocycle.

Suppose we instead picked some $\psi_i : x|_{U_i} \xrightarrow{\sim} y|_{U_i}$ for each i , yielding $\gamma_{ij} = \psi_j^{-1}\psi_i$. Then ψ_i and ϕ_i differ by an automorphism of y which we call α_i :

$$\begin{array}{ccc} x|_{U_i} & \xrightarrow{\phi_i} & y|_{U_i} \\ & \searrow \alpha_i & \nearrow \psi_i \\ & x|_{U_i} & \end{array}$$

Then on U_{ij} we have

$$g_{ij} = \phi_j^{-1}\phi_i = (\psi_j\alpha_j)^{-1}\psi_i\alpha_i = \alpha_j^{-1}\gamma_{ij}\alpha_i.$$

Rescaling on the left by α_j we get

$$\alpha_j g_{ij} = \gamma_{ij} \alpha_i,$$

so (g_{ij}) and (γ_{ij}) give cohomologous 1-cocycles. \square

Theorem 1.21. There is a bijection between isomorphism classes of \mathcal{G} -torsors and $\check{H}^1(U, \mathcal{G})$.

Sketch. Let \mathcal{F} be a \mathcal{G} -torsor, and pick $s_i \in \mathcal{F}(U_i)$ for each i . Then on the overlap $U_i \times_U U_j$, we have that s_i and s_j differ by a unique element $g_{ij} \in \mathcal{G}(U_i \times_U U_j)$. We run basically an identical argument. \square

So if $\mathcal{G} = \text{Aut}_{\mathcal{F}}(x)$ then we have a bijection

$$\left\{ \begin{array}{l} \text{iso classes of } y \in \mathcal{F}(U) \\ \text{locally isomorphic to } x \end{array} \right\} \leftrightarrow \check{H}^1(U, \text{Aut}_{\mathcal{F}}(x)) \leftrightarrow \{\text{Aut}_{\mathcal{F}}(x)\text{-torsors}\}.$$

These sorts of arguments are compatible with refinement of the cover, and since Čech and sheaf cohomology agree we see that G -torsors are in bijection with the first sheaf cohomology $H^1(U, G)$.

Exercise 1.22. (Fun/hard) Show that every sheaf of groups \mathcal{G} is of the form $\text{Aut}_{\mathcal{F}}(x)$ for some sheaf of categories \mathcal{F} .

Intuition 1.23. A \mathcal{G} -torsor is an object whose automorphisms locally look like $\mathcal{G}(U_i)$.

1.2. Interlude: representable G -torsors. When both the presheaf \mathcal{G} and the sheaf of sets \mathcal{F} are representable, we get a slightly different characterization.

Proposition 1.24. Let X be a scheme, let Y be a group scheme, and let

$$f : Y \rightarrow X$$

be a G -equivariant map. Suppose there exists a cover $\{U_i \rightarrow X\}$ for which

$$U_i \times_X Y \rightarrow Y$$

is isomorphic to the trivial cover $G \times_X U_i \rightarrow U_i$. Then $Y \rightarrow X$ is a representable G -torsor, sometimes called a *principal G -bundle*.

Often it's just enough to assume the sheaf of groups is representable to get all torsors are representable.

Proposition 1.25. Let G be an affine group scheme over X , and let $\tau \leq \text{fppf}$. Then every G -torsor is representable. (see [Stacks, p. 0497], [You, p. 3.25])

Sketch. Every G -torsor is an algebraic space, and algebraic spaces which are locally affine are schemes. Since a G -torsor is locally isomorphic to G , which was assumed to be affine, then we conclude every torsor is actually a scheme. \square

Terminology 1.26. A representable fpqc-torsor for G is called a *principal homogeneous space*.

Remark 1.27. If $t \leq \tau$, then every t -cover is a τ -cover, hence if we can find a t -cover trivializing a G -torsor, then it also trivializes it in the τ -topology. hence

$$t \leq \tau \Rightarrow \{t\text{-torsors}\} \subseteq \{\tau\text{-torsors}\}.$$

So a very natural question is *how do we tell when a τ -torsor is also a t -torsor?* We'll discuss this next week.

1.3. Interlude: representability of torsors in topology. So it's a very reasonable goal to ask for any tools that could help us try to classify torsors. A natural idea, by analogy, is to look to homotopy theory, where we have a suite of tools for studying torsors.

Definition 1.28. Let X be a compact Hausdorff topological space and G a group. Then a *principal G -bundle* (or we might just say a G -torsor) is a fiber bundle $\pi: Y \rightarrow X$ so that G acts freely and transitively on the fibers.

In topology there is a *universal G -torsor*, which is denoted $EG \rightarrow BG$. This is universal in the sense that, given any map $f: X \rightarrow BG$, we can consider the fiber product

$$\begin{array}{ccc} f^*EG & \longrightarrow & EG \\ \downarrow & \lrcorner & \downarrow \\ X & \xrightarrow{f} & BG. \end{array}$$

Then $f^*EG \rightarrow X$ is a principal G -bundle, and all principal G -bundles are obtained in this way. Not only that, but isomorphic principal G -bundles are given by homotopic classifying maps. In other words we have a bijection

$$\text{Prin}_G(X) \leftrightarrow [X, BG].$$

So the data of a principal G -bundle is the data of a map $X \rightarrow BG$, and an isomorphism of principal G -bundles is equivalent to a homotopy between two maps $f, g: X \rightarrow BG$.

Example 1.29. We have that $B(\mathbb{Z}/2) = \mathbb{RP}^\infty$ and $E\mathbb{Z}/2 = S^\infty$, so that $\mathbb{Z}/2$ -torsors are real line bundles. Similarly $BC^\times = \mathbb{CP}^\infty$.

A big example comes from quotienting out by a compact subgroup:

Theorem 1.30. (Samelson, 1941) If $H \leq G$ is a compact subgroup of a Lie group, then $G \rightarrow G/H$ is a Serre fibration and principal H -bundle.

Corollary 1.31. We have fiber sequences

$$\begin{aligned} H &\rightarrow G \rightarrow G/H \\ G/H &\rightarrow BH \rightarrow BG. \end{aligned}$$

Example 1.32. For the inclusions $O(n) \subseteq O(n+1)$ and $U(n) \subseteq U(n+1)$ we get fiber sequences

$$\begin{aligned} S^{2n+1} &\rightarrow \text{BU}(n) \rightarrow \text{BU}(n+1) \\ S^n &\rightarrow \text{BO}(n) \rightarrow \text{BO}(n+1). \end{aligned}$$

This is how Bott periodicity is proved.

1.4. Why we like representability of torsors. This has a number of huge applications:

- ▷ Given any cohomology theory E^* and any class $c \in E^*(BG)$, if $f^*(c) \neq g^*(c)$ in $E^*(X)$, this means that f and g correspond to non-isomorphic torsors. This is the basic idea of characteristic classes.

Example 1.33. If $G = \mathrm{GL}_n(\mathbb{C})$, then $\mathrm{BGL}_n(\mathbb{C}) = \mathrm{BU}(n) = \mathrm{Gr}_{\mathbb{C}}(n, \infty)$ is a Grassmannian of n -planes in \mathbb{C}^∞ . A map $f: X \rightarrow \mathrm{Gr}_{\mathbb{C}}(n, \infty)$ gives a complex n -dimensional vector space by pullback.

Theorem 1.34. (Pontryagin–Steenrod) There is a bijection

$$\mathrm{Vect}_{\mathbb{C}}^n(X) \cong [X, \mathrm{BU}(n)].$$

Since $H^*(\mathrm{BU}(n); \mathbb{Z}) = \mathbb{Z}[c_1, \dots, c_n]$, if $E \rightarrow X$ is any rank n vector bundle classified by a map $f: X \rightarrow \mathrm{BU}(n)$, then its Chern classes are by definition $c_i(E) = f^*c_i$.

- ▷ We have access to *obstruction theory* – this lets us break down lifting problems into smaller manageable stages.

Example 1.35. If X is a complex n -dimensional manifold, and $E \rightarrow X$ is a rank n complex vector bundle, then it splits off a free summand if and only if $c_n(E) = 0$.

Example 1.36. If we fix $c_1, \dots, c_n \in H^*(X; \mathbb{Z})$, we can ask how many isomorphism classes of complex rank n vector bundles on X have these given Chern classes. Since $c_i \in H^{2i}(X; \mathbb{Z}) = [X, K(\mathbb{Z}, 2i)]$ this is equivalent to asking how many lifts there are for

$$\begin{array}{ccc} & & \mathrm{BU}(n) \\ & \nearrow & \downarrow \\ X & \xrightarrow{c_1, \dots, c_n} & \prod_i K(\mathbb{Z}, 2i). \end{array}$$

If X is a finite CW complex, there are only finitely many such lifts by basic obstruction theory.

- ▷ Suppose we have two groups G and K , and we want to study natural ways to create K -torsors out of G -torsors over any space. Then representability, combined with the Yoneda lemma, allows us to completely classify all the ways to do this.

Example 1.37. There is one and only one natural non-trivial function

$$\{\mathrm{GL}_n(\mathbb{R})\text{-torsors}\} \rightarrow \{(\mathbb{Z}/2)\text{-torsors}\},$$

given by the nonzero class in $[\mathrm{BGL}_n(\mathbb{R}), B\mathbb{Z}/2] = \mathbb{Z}/2$. This is called the *determinant bundle* or the *first Stiefel–Whitney class*.

1.5. Motivation of what’s to come.

Question 1.38. By analogy to homotopy theory, we might ask, for a group scheme G , the following questions:

- (1) Is there an analogous universal space BG in algebraic geometry which classifies G -torsors?
- (2) If so, can we classify G -torsors over X via some “homotopy classes” of maps from X to BG ?

The answer to both will be yes, but *not in the category of varieties*. We need more machinery than is available to us there.

REFERENCES

- [AHW20] Aravind Asok, Marc Hoyois, and Matthias Wendt. “Affine representability results in \mathbb{A}^1 -homotopy theory III: finite fields and complements”. In: *Algebr. Geom.* 7.5 (2020), pp. 634–644.
- [Aso21] Aravind Asok. *Algebraic geometry from an \mathbb{A}^1 -homotopic viewpoint*. 2021.

-
- [Ful98] William Fulton. *Intersection theory*. Second. Vol. 2. Ergebnisse der Mathematik und ihrer Grenzgebiete. 3. Folge. A Series of Modern Surveys in Mathematics [Results in Mathematics and Related Areas. 3rd Series. A Series of Modern Surveys in Mathematics]. Springer-Verlag, Berlin, 1998, pp. xiv+470.
- [Stacks] The Stacks Project Authors. *Stacks Project*. <https://stacks.math.columbia.edu>. 2018.
- [You] Alex Youcis. “A brief discussion of torsors”.