



HACETTEPE UNIVERSITY  
COMPUTER ENGINEERING DEPARTMENT

BM233 LOGIC DESIGN LAB - 2021 FALL

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## Final Project

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December 29, 2021

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# 1 Problem Definition

A finite-state machine (FSM) or simply a state machine is used to design both computer programs and sequential logic circuits. It is conceived as an abstract machine that can be in one of a finite number of user-defined states. The machine is in only one state at a time; the state it is in at any given time is called the current state. It can change from one state to another when initiated by a triggering event or condition; this is called a transition. A particular FSM is defined by a list of its states, and the triggering condition for each transition. The behavior of state machines can be observed in many devices in modern society performing a predetermined sequence of actions depending on a sequence of events with which they are presented. Simple examples are vending machines which dispense products when the proper combination of coins are deposited, elevators which drop riders off at upper floors before going down, traffic lights which change sequence when cars are waiting, and combination locks which require the input of combination numbers in the proper order. The state machines are modeled using two basic types of sequential networks- Mealy and Moore. In a Mealy machine, the output depends on both the present (current) state and the present (current) inputs. In Moore machine, the output depends only on the present state. A general model of a Mealy sequential machine consists of a combinatorial network, which generates the outputs and the next state, and a state register which holds the present state as shown below. The state register is normally modeled as D flip-flops. The state register must be sensitive to a clock edge. The other block(s) can be modeled either using the always procedural block or a mixture of the always procedural block and dataflow modeling statements; the always procedural block will have to be sensitive to all inputs being read into the block and must have all output defined for every branch in order to model it as a combinatorial block. In this final project, we should design a mealy machine as follows:

Inputs:

- **SYCLK:** This input is the system clock signal provided to the chip from the armor system. The clock cycle is set to 10 ms.
- **REBOOT:** This input provides a reset signal (on HIGH) which resets the system to its default settings (idle state, full ammo).
- **target\_locked:** This input is supplied to the chip from the helmet's target acquisition system. Once the gun has been locked on the target, this signal becomes HIGH. As soon as the target lock has been lost, the signal immediately becomes LOW.
- **is\_enemy:** This is yet another input signal supplied from the helmet's target acquisition system. Since the helmet has a connection to KAM AI, an ultra-fast recognition of the targets is performed in real-time. This signal is HIGH when the target is recognized as a threat, and LOW otherwise.
- **firing\_mode:** This signal is supplied from the combatant's neural-link. When the combatant wishes to shoot in the automatic firing mode, this signal becomes HIGH. Otherwise it is LOW by default, and in that case, the firing mode of the machine gun is set to firing a single shot.

- `fire_command`: This is yet another input signal supplied from the combatant's neural-link. When the combatant wishes to fire the gun (equivalent of pulling the trigger in traditional guns) this signal becomes HIGH. Otherwise, it is LOW by default.
- `overheat_sensor`: The gun is equipped with a high-tech cooling system which is triggered when the gun overheats. This overheating is detected by a temperature sensor mounted on the gun. When the gun overheats, the signal becomes HIGH. Otherwise, it is LOW by default.

#### Outputs:

- 2:0 `current_state`: A 3-bit wide output that shows the current state of the gun. It is supplied to the helmet's display system so that the combatant can be aware of the gun's status.
- `fire_trigger`: A 1-bit output signal which triggers the machine gun. Whenever it goes HIGH, a bullet is fired. For automatic firing mode, it should be set to HIGH then LOW in a cyclic manner to achieve automatic shooting.
- `criticality_alert`: Also a 1-bit output signal which goes HIGH when the last magazine has been loaded into the gun. This signal is also supplied to the helmet's display system so that the combatant can be aware that the ammo is about to become completely depleted.

#### States:

- `idle` (binary code 000): This is the start state. In this state, the machine gun is at rest. No shots are being fired.
- `shoot_single` (binary code 001): In this state, only a single shot is fired from the machine gun.
- `shoot_auto` (binary code 010): While in this state, the machine gun is in the automatic firing mode. In this state, the machine gun keeps firing at the rate of 6000 rpm until it has exhausted its ammunition supply or it has overheated.
- `reload` (binary code 011): When the machine gun depletes the ammunition from the magazine it enters this state in which it loads a new magazine. Reloading takes 50 ms.
- `overheat` (binary code 100): When the machine gun overheats from shooting, it has to be cooled down, otherwise it cannot resume shooting. The machine gun stays in this state until it is cooled down. This process takes 100 ms.
- `downfall` (binary code 101): When all of the magazines and ammo have been exhausted, the machine gun goes into this state, at which point it cannot shoot anymore until the system has been rebooted by technical service which replenishes the ammunition.

#### System Behavior — State Transitions

The `SIGANFU_MACHINE_GUN` has a capacity of carrying 4 magazines, each of which has a capacity of 25 .50 caliber rounds (a total of 100 bullets). After depleting a magazine, the machine gun should reload immediately until there are no spare magazines left. The reloading process takes

50 milliseconds. The user is notified that they are on their last magazine by setting the output signal `criticality_alert` to HIGH.

The shooting process is triggered by the `fire_command` input signal and is controlled by setting the output signal `fire_trigger` to HIGH, which operates as an electronic trigger to fire bullets towards the target.

The weapon has two firing modes defined as "Single Shooting" and "Auto Shooting". The firing mode of the weapon is specified using the `firing_mode` input signal. There is no direct transition between firing modes. The system must go into the IDLE state before switching between the firing modes for at least one clock cycle.

In automatic firing mode, the weapon fires a bullet every 10 milliseconds as long as the `fire_command` signal is HIGH (remember that the shooting rate of the SIGANFU\_MACHINE\_GUN is 6000 rpm). Firing a bullet is achieved by setting the `fire_trigger` output signal to HIGH for 5 ms and then to LOW for another 5 ms to achieve the specified firing rate.

In single firing mode, the weapon fires a single bullet using the same trigger delay. In this mode, the weapon cannot fire more than one round before going back to the IDLE state, and this is true even if the `fire_command` signal remains HIGH after the bullet has been fired. After the `fire_command` signal has become LOW, the weapon can return to the IDLE state. This mode is useful for precise shooting tasks such as sniper functionality.

The weapon has two fail-safe mechanisms which prevent its extremely destructive power to be used against allies or innocent civilians. Both mechanisms work by receiving input signals from the helmet's Target-Acquiring-System (TAS). By its specifications, the weapon cannot fire until a proper target is acquired (i.e., there is a precise lock on the target), which is specified by the input signal `target_locked` being HIGH, in order to prevent bystander casualties. The weapon also cannot fire upon allies or non-enemy parties, which is specified by the input signal `is_enemy`.

It also has an internal temperature sensor that prevents the weapon from overheating and eliminates the possibility of any malfunction caused by overheating. The sensor makes the `overheat_sensor` input signal HIGH when it detects temperatures above the operating range. When this signal is HIGH, the machine gun should stop firing immediately and wait for 100 milliseconds to cool itself down in the OVERHEAT state.

#### Idle

The initial state of the SIGANFU\_MACHINE\_GUN finite state machine (as well as the state when the system is rebooted) is the IDLE state. When in this state, the SIGANFU\_MACHINE\_GUN can transition into one of the shooting states (SHOOT\_SINGLE or SHOOT\_AUTO) only if all three of the following conditions are satisfied: The target is an enemy (if `is_enemy` is HIGH) TAS is locked on the target (if `target_locked` is HIGH) the user wants to fire the gun (if `fire_command` is HIGH). If all of the conditions for firing the gun are satisfied, the SIGANFU\_MACHINE\_GUN can proceed into one of two possible shooting states: either SHOOT\_AUTO or SHOOT\_SINGLE, based on the `firing_mode` input signal (LOW for SHOOT\_SINGLE and HIGH for SHOOT\_AUTO). If any one of the necessary conditions for shooting is not satisfied, then the SIGANFU\_MACHINE\_GUN should stay in the IDLE state.

#### SHOOT\_AUTO

When in the SHOOT\_AUTO state, the SIGANFU\_MACHINE\_GUN should first check if the gun

has overheated (if `overheat_sensor` is `HIGH`). If this is the case, the `SIGANFU_MACHINE_GUN` should transition to the `OVERHEAT` state where it must stay for 100 milliseconds for the cooling to be completed.

Secondly, the `SIGANFU_MACHINE_GUN` should check if there are any bullets left in the currently used magazine. If there are not any bullets left, then the `SIGANFU_MACHINE_GUN` has two options based on the number of spare magazines left. If there aren't any magazines left to reload, the `SIGANFU_MACHINE_GUN` should proceed to the `DOWNFALL` state. If there are enough spare magazines to reload, the `SIGANFU_MACHINE_GUN` should proceed to the `RELOAD` state where it must stay for 50 milliseconds, the time it takes for reloading to complete.

Finally, the `SIGANFU_MACHINE_GUN` should check if the shooting is still the intended behavior in the same way as in the `IDLE` state (check all the conditions that must be satisfied for shooting). If not, the `SIGANFU_MACHINE_GUN` should transition to the `IDLE` state.

After making sure the `SIGANFU_MACHINE_GUN` can and should continue to fire (to stay in `SHOOT_AUTO`), the necessary steps for firing should be taken (continue firing, updating ammo, etc.).

#### SHOOT\_SINGLE

Similarly to the `SHOOT_AUTO` state, the `SIGANFU_MACHINE_GUN` should make sure if it can and should fire in this state before taking any action and transition to the appropriate states accordingly.

The main difference of this state from the `SHOOT_AUTO` state is that the `SIGANFU_MACHINE_GUN` should only fire `ONCE` when in this state, and then transition to the `IDLE` state once the `fire_command` becomes `LOW`. Until `fire_command` becomes `LOW`, the `SIGANFU_MACHINE_GUN` should wait in this state without firing any more bullets.

#### RELOAD

In this state, the `SIGANFU_MACHINE_GUN` should change the current depleted magazine with one of the spare magazines. To do this, it should replenish the number of bullets in the current magazine (to 25) while decreasing the number of the available spare magazines. Before this operation, the `SIGANFU_MACHINE_GUN` should check if the reloading is actually possible by making sure it has a positive number of the remaining spare magazines. Once reloading is successfully performed, if the user is on their last magazine (no more spare magazines left), then the `SIGANFU_MACHINE_GUN` should warn the user about this critical situation by making the output signal `criticality_alert` `HIGH`. The reloading process takes 50 milliseconds, so the `SIGANFU_MACHINE_GUN` must wait for this exact amount of time in this state.

After the reload operation is complete, the `SIGANFU_MACHINE_GUN` should check if it should go back to shooting or not, and transition to the appropriate state by checking the `firing_mode` input signal if all the shooting conditions are satisfied. If it is decided that the `SIGANFU_MACHINE_GUN` should not fire, it should then transition to the `IDLE` state.

#### OVERHEAT

In this state, the `SIGANFU_MACHINE_GUN` must wait for 100 milliseconds for the cooling process to complete. When the time has come for the `SIGANFU_MACHINE_GUN` to continue operating, the `SIGANFU_MACHINE_GUN` should make sure if it can and should transition back to the shooting state or not, and then proceed to the appropriate state accordingly (back to shooting if possible

and wanted, to the DOWNFALL state if completely out of ammo, to the RELOAD state if needs to reload, or the IDLE state otherwise).

If it can and should fire, then it should transition to the appropriate state by checking the firing\_mode input signal.

#### DOWNFALL

This is the failure state of the SIGANFU\_MACHINE\_GUN in which it cannot shoot anymore no matter what the inputs are, until it has been rebooted (ammo replenished and system reset via technical service). When this occurs, the user is out of bullets and should find other ways to fight vicious enemies. Only when the system gets rebooted (REBOOT signal becomes HIGH), the SIGANFU\_MACHINE\_GUN can exit this state and transition back to the IDLE state, but this time all ammo stats will also be reset (the current magazine will have 25 bullets, there will be 3 more full spare magazines available).

## 2 State Transition Diagram

- 1.

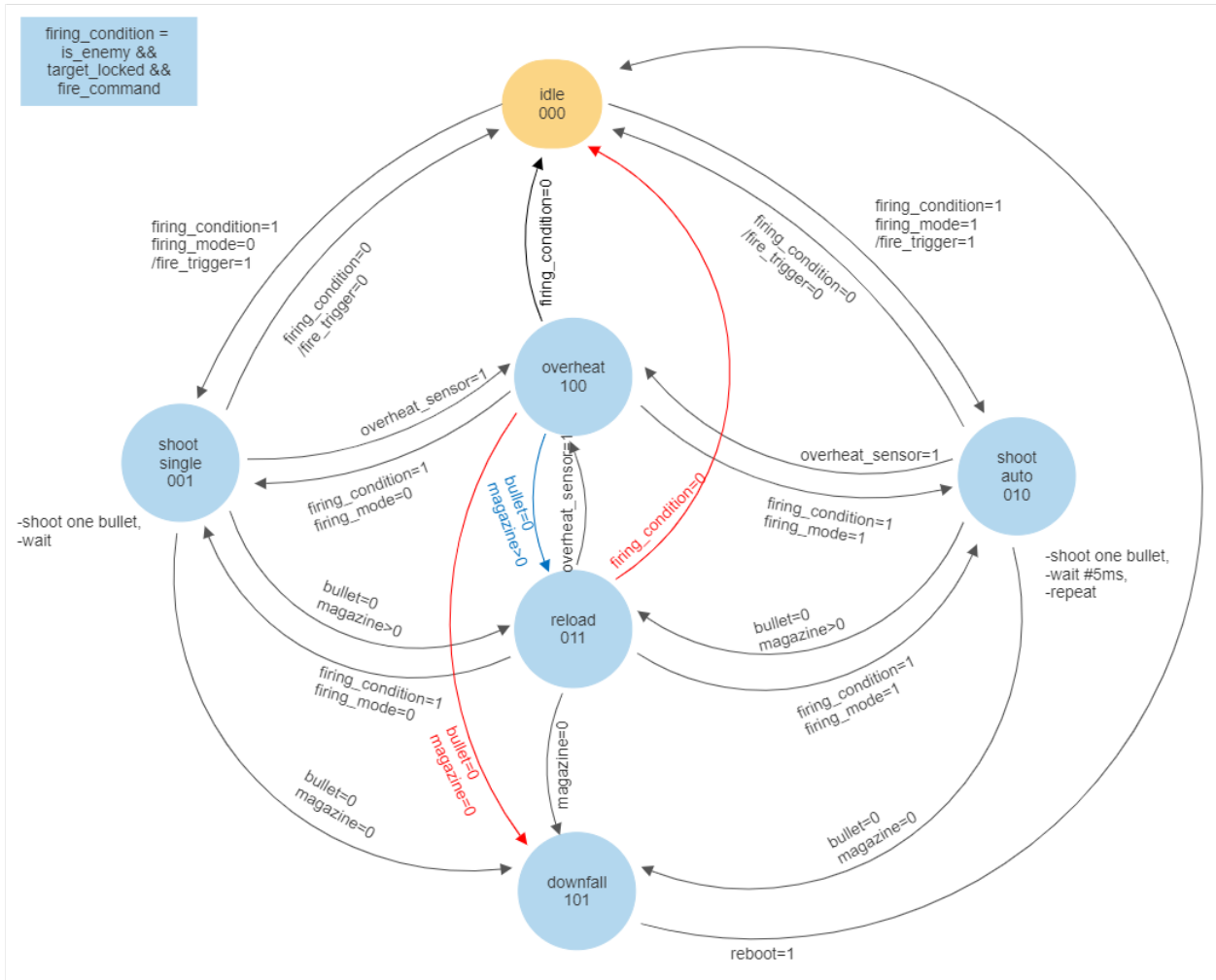


Figure 1: State Transition Diagram

### 3 Solution Code

```
1  `timescale 1ms / 100ns
2
3  module siganfu_machine_gun (
4      input sysclk,
5      input reboot,
6      input target_locked,
7      input is_enemy,
8      input fire_command,
9      input firing_mode, // 0 single, 1 auto
10     input overheat_sensor,
11     output reg[2:0] current_state,
12     output reg criticality_alert,
13     output reg fire_trigger
14 );
15 reg[2:0] nextstate;
16 parameter idle=3'b000;
17 parameter shoot_single=3'b001;
18 parameter shoot_auto=3'b010;
19 parameter reload=3'b011;
20 parameter overheat=3'b100;
21 parameter downfall=3'b101;
22
23 assign firing_condition = is_enemy && target_locked && fire_command; //all of them mu
24
25 integer bullet = 25;
26 integer magazine = 3;
27 integer shot = 0; //checks if shoot_single has already been shot
28
29 always @(posedge sysclk or posedge reboot) // always block to update state
30 if (reboot)
31     current_state <= idle;
32 else
33     current_state <= nextstate;
34
35
36 always @(current_state or firing_condition or reboot or firing_mode or overheat_sens
37 begin
38     case(current_state)
39         idle:
40             begin
41                 if(firing_condition && firing_mode == 0)
42                     begin
43                         fire_trigger = 0;
44                         nextstate = shoot_single;
45                     end
46                 else if(firing_condition && firing_mode == 1)
```



```

47         begin
48             fire_trigger = 0;
49             nextstate = shoot_auto;
50         end
51     else
52     begin
53         fire_trigger=0;
54         nextstate = idle;
55     end
56 end
57 shoot_single:
58     if(overheat_sensor)
59     begin
60         shot = 0;
61         nextstate = overheat;
62     end
63     else if(bullet > 0)
64     begin
65         if(shot == 0)
66         begin
67             fire_trigger = 1;
68             #5;
69             fire_trigger = 0;
70             bullet = bullet - 1;
71             shot = 1;
72         end
73         if(fire_command == 0)
74         begin
75             shot = 0;
76             nextstate=idle;
77         end
78     else if(bullet == 0 && magazine > 0)
79     begin
80         shot = 0;
81         nextstate=reload;
82     end
83     else if(bullet == 0 && magazine == 0)
84     begin
85         shot = 0;
86         nextstate = downfall;
87     end
88     end
89 shoot_auto:
90     begin
91         while((fire_command == 1) && (bullet>0) && (overheat_sensor == 0) && (firi
92         begin
93             fire_trigger = 1;
94             bullet = bullet - 1;

```

```

95         #5;
96         fire_trigger = 0;
97         #5;
98     end
99     if(overheat_sensor)
100         nextstate = overheat;
101     else if(firing_condition == 0)
102         nextstate=idle;
103     else if(bullet == 0)
104     begin
105         if(magazine > 0)
106             nextstate=reload;
107         else
108             nextstate=downfall;
109         end
110     end
111 reload:
112 begin
113     if(magazine > 0)
114     begin
115         magazine = magazine - 1;
116         bullet = 25;
117         #50;
118     end
119     else if(magazine < 0)
120         nextstate = downfall;
121     if(firing_condition)
122     begin
123         if(firing_mode == 1)
124             nextstate = shoot_auto;
125         else
126             nextstate = shoot_single;
127         end
128     else
129         nextstate = idle;
130     end
131 overheat:
132 begin
133     #100;
134     if(firing_condition)
135     begin
136         if(bullet == 0 && magazine < 0)
137             nextstate = downfall;
138         else if(bullet == 0 && magazine >= 0)
139             nextstate = reload;
140         else if(firing_mode == 0)
141             nextstate=shoot_single;
142         else

```

```

143             nextstate = shoot_auto;
144         end
145         else if(bullet == 0 && magazine < 0)
146             nextstate = downfall;
147         else if(bullet == 0 && magazine >= 0)
148             nextstate = reload;
149         else
150             nextstate=idle;
151         end
152     downfall:
153     begin
154         if(reboot == 1)
155             begin
156                 bullet = 25;
157                 magazine = 3;
158                 nextstate = idle;
159             end
160         end
161     endcase
162 end
163
164 always @(magazine) //always block to check the criticality alert
165 begin
166     if(magazine == 0)
167         criticality_alert = 1;
168     else
169         criticality_alert = 0;
170     end
171
172 endmodule

```

## 4 Results

### TEST 1: Safety Test

Fig. 2.

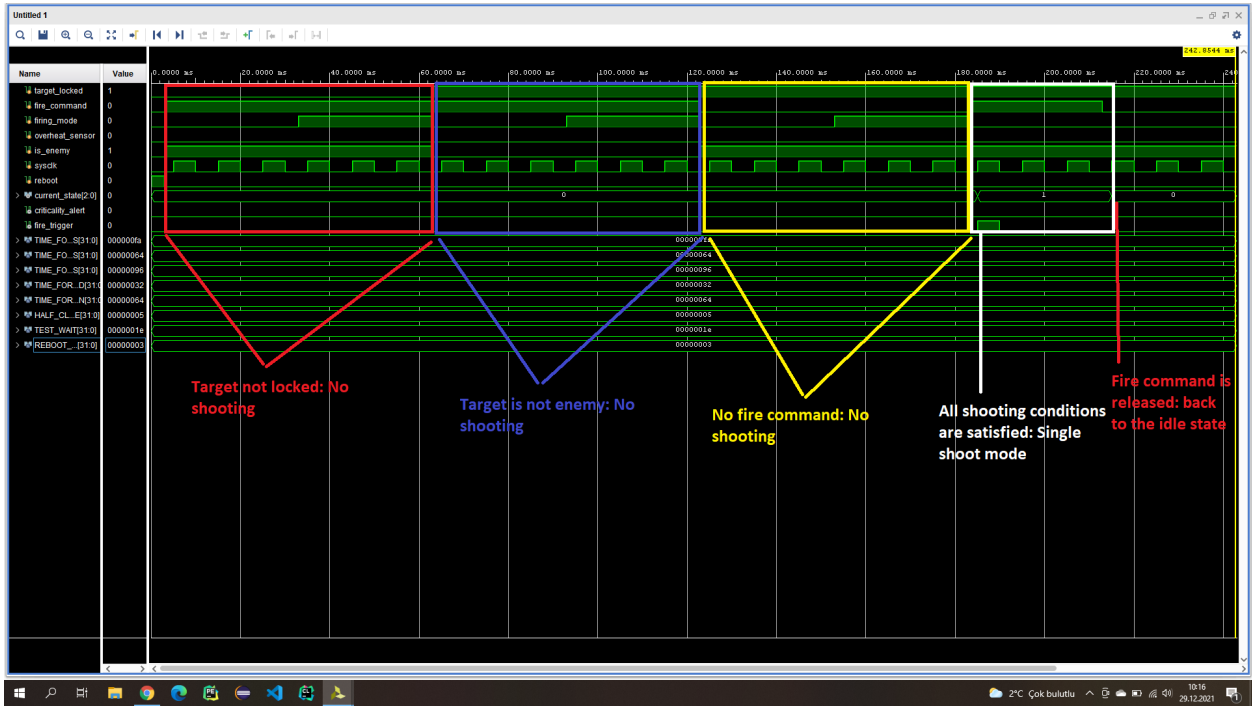


Figure 2: Safety Test

TEST 2: Single Shooting Test  
Fig. 3.

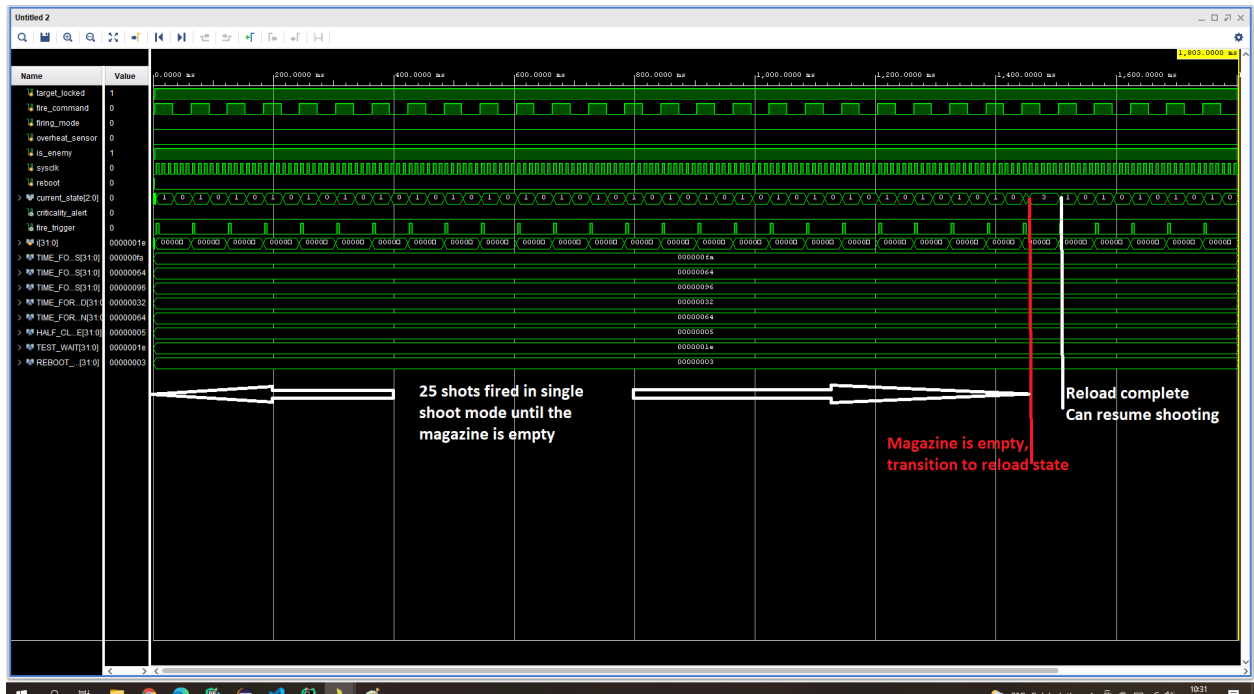


Figure 3: Single Shooting Test

TEST 3: Automatic Shooting Test  
Fig. 4.

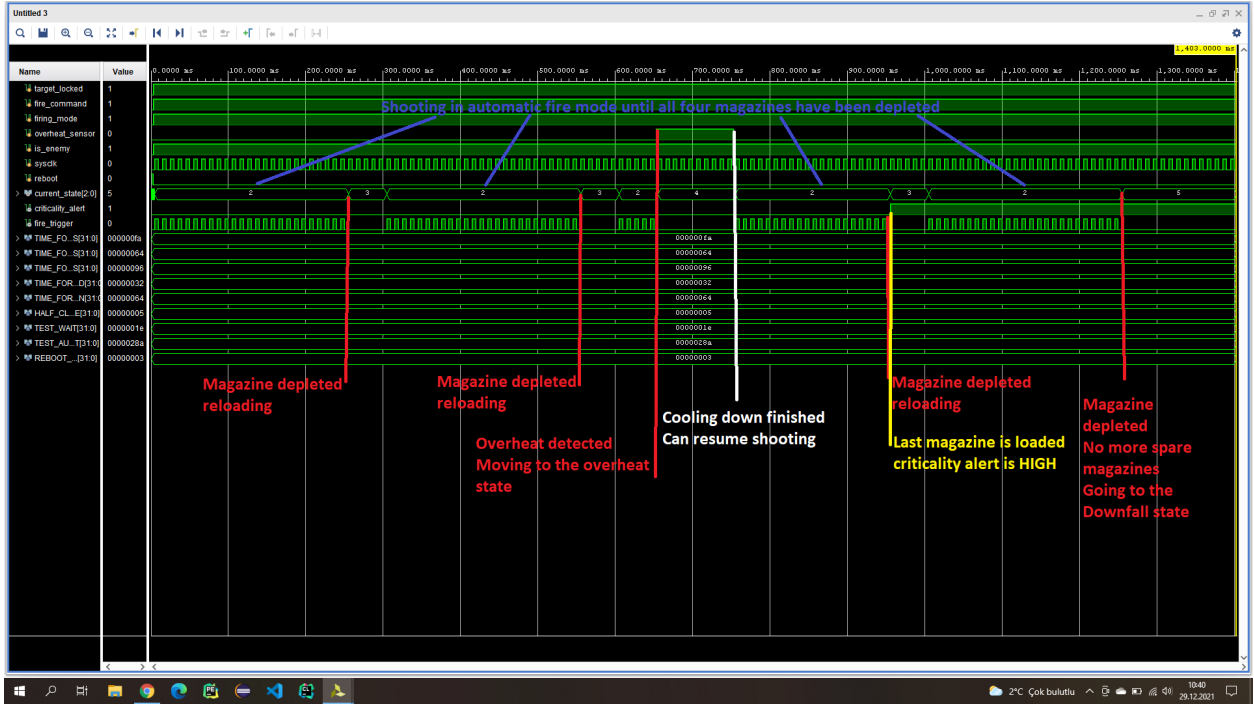


Figure 4: Automatic Shooting Test

TEST 4: Returning from RELOAD and OVERHEAT Test  
Fig. 5.

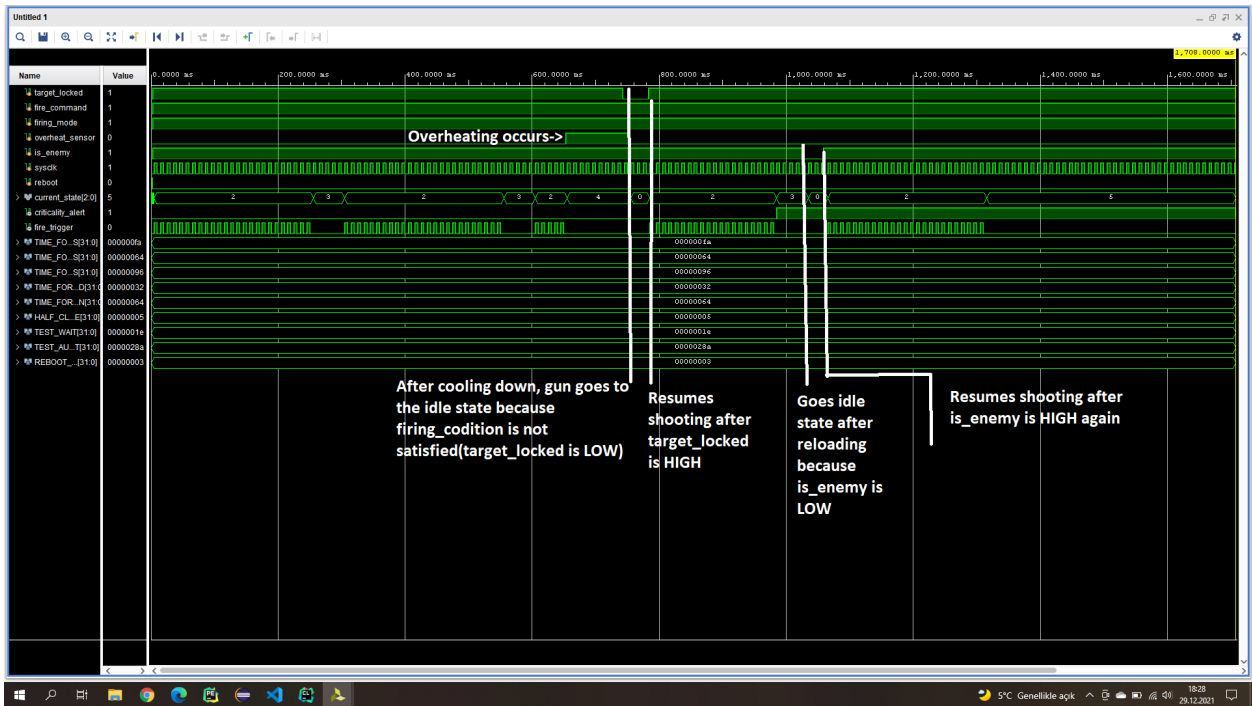


Figure 5: Returning from RELOAD and OVERHEAT Test

TEST 5: RELOAD after OVERHEAT Test  
Fig. 6.

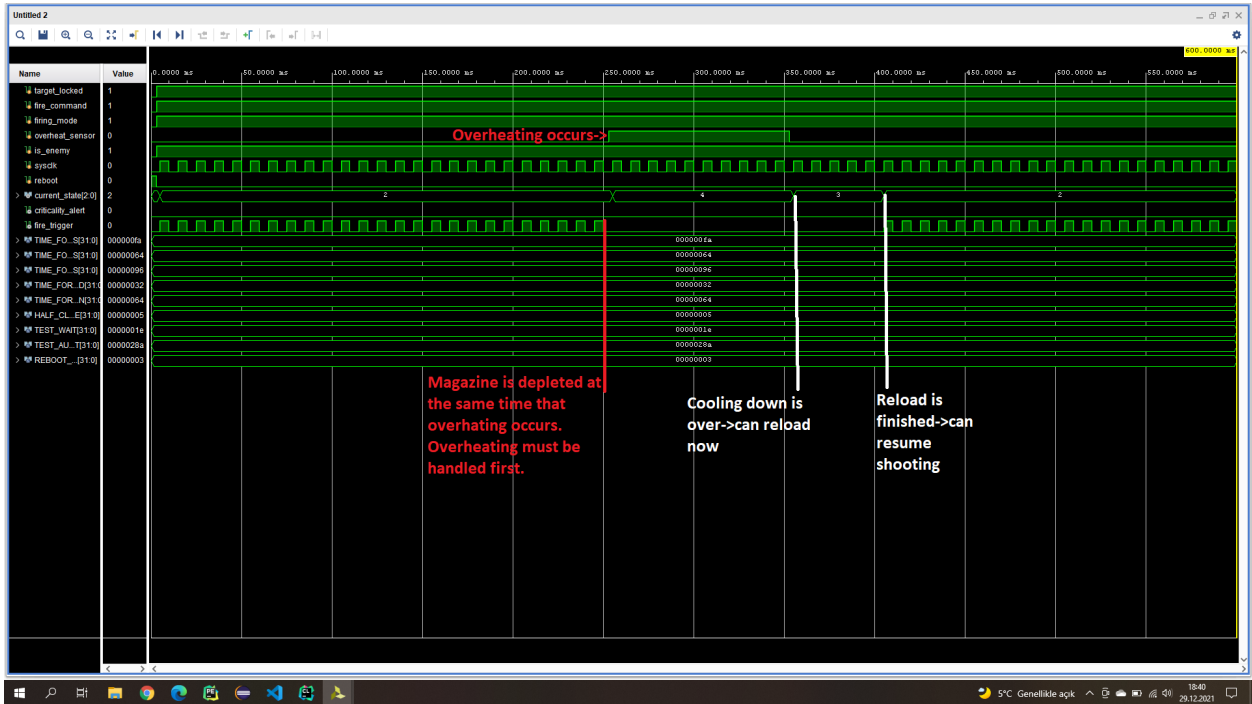


Figure 6: RELOAD after OVERHEAT Test



TEST 6: REBOOT Test  
Fig. 7.

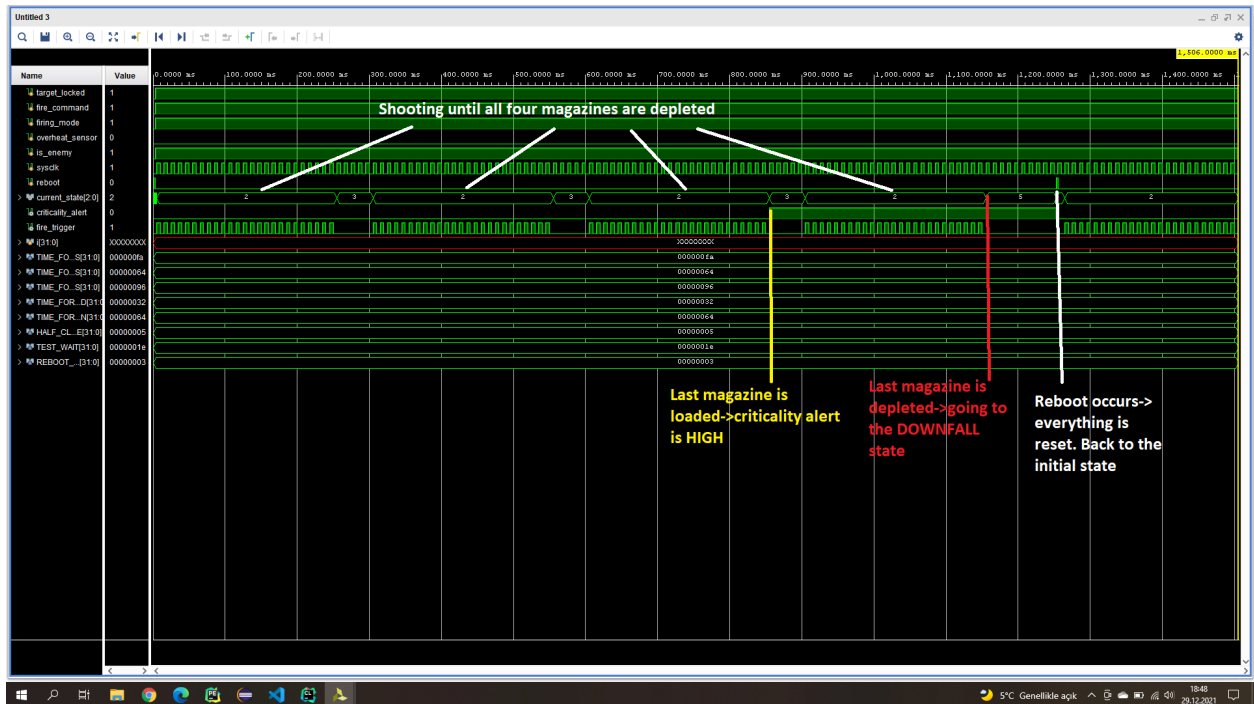


Figure 7: Reboot test

Fig. 8.

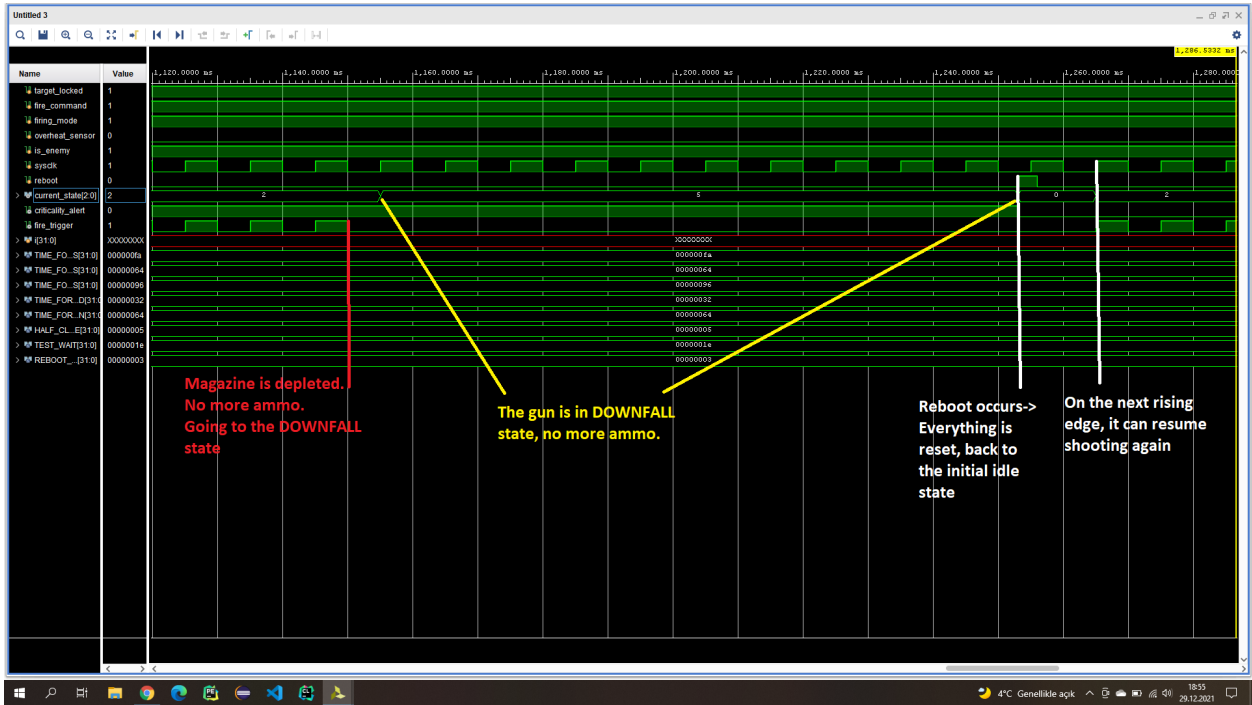


Figure 8: Reboot test(zoomed in downfall state)

## References

- BBM231 Lecture Notes
- BBM233 Lecture Notes
- <https://www.xilinx.com/support/documentation/university/ISE-Teaching/HDL-Design/14x/Nexys3/Verilog/docs-pdf/lab10.pdf>
- [https://www.smartdraw.com/software/drawing-software.htm?id=361780&gclid=CjwKCAiAiKu0BhBQsK8SnD1V\\_1AnNXwQ1hbEYASKw2LNZy7AAkNqZWeZdYgCWAPeeST4sxRoCq4QQA\\_vD\\_BwE](https://www.smartdraw.com/software/drawing-software.htm?id=361780&gclid=CjwKCAiAiKu0BhBQsK8SnD1V_1AnNXwQ1hbEYASKw2LNZy7AAkNqZWeZdYgCWAPeeST4sxRoCq4QQA_vD_BwE)