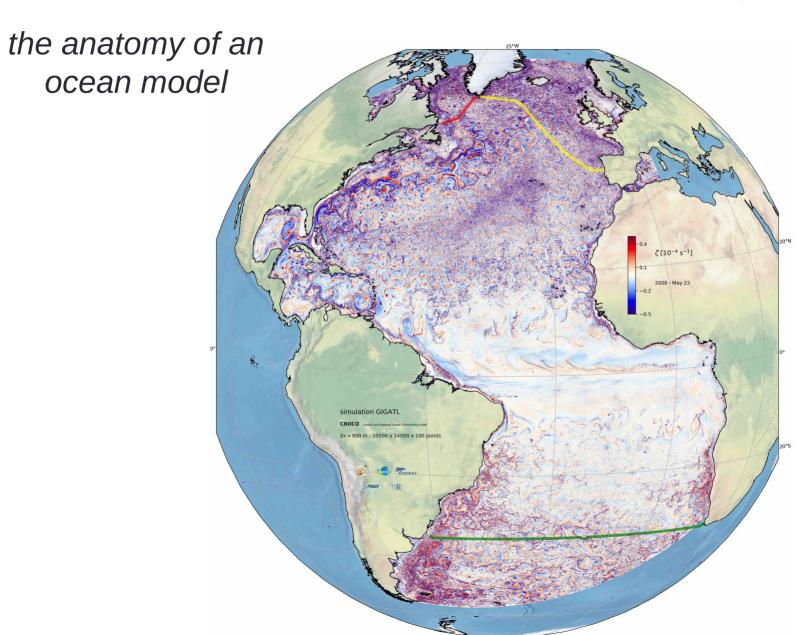
Numerical Modelling

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- Lesson 1 : [D109]
 - Introduction
 - Equations of motions
 - Activity 1 [run an ocean model]
- Lesson 2 : [B012]
 - Horizontal Discretization
 - Activity 2 [Dynamics of an ocean gyre]
- Lesson 3 : [B012]
 - Presentation of the model CROCO
 - Dynamics of the ocean gyre
 - Activity 2 [Dynamics of an ocean gyre]
- Lesson 4: [D109]
 - Numerical schemes
 - Activity 3 [Impacts of numerics]
- Lesson 5 : [D109]

- Vertical coordinates
- Activity 3 [Impact of topography]
- Lesson 6 : [D109]
 - Boundary Forcings
 - Activity 4 [Design a realistic simulation]
- Lesson 7: [D109]
 - Diagnostics and validation
 - Activity 5 [Analyze a realistic simulation]
- Lesson 8 : [D109]
 - Work on your projet

Presentations and material will be available at:

jgula.fr/ModNum/

https://github.com/quentinjamet/

Useful references

Extensive courses:

- MIT: https://ocw.mit.edu/courses/earth-atmospheric-and-planetary-sciences/12-950-atmospheric-and-oceanic-modeling-spring-2004/lecture-notes/
- Princeton: https://stephengriffies.github.io/assets/pdfs/GFM_lectures.pdf

Overview on ocean modelling and current challenges:

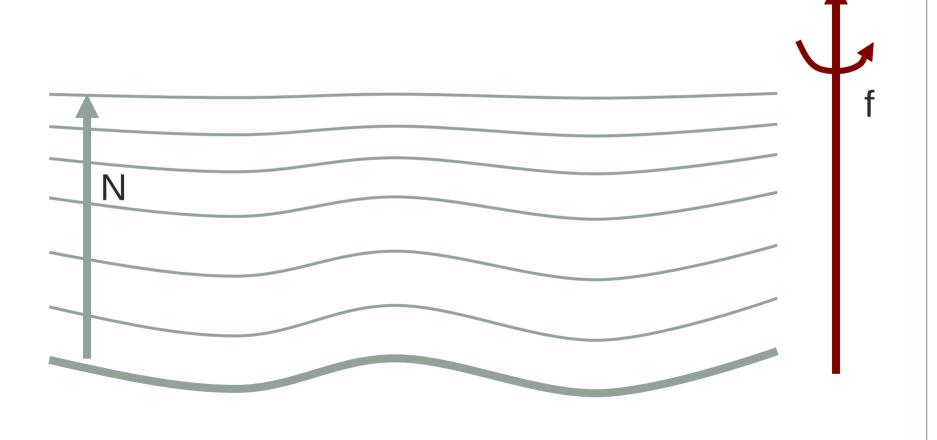
- Griffies et al., 2000, Developments in ocean climate modelling, Ocean Modelling. http://jgula.fr/ModNum/Griffiesetal00.pdf
- Griffies, 2006, "Some Ocean Model Fundamentals", In "Ocean Weather Forecasting: An Integrated View of Oceanography", 2006, Springer Netherlands. http://jgula.fr/ModNum/Griffies_Chapter.pdf
- Fox-Kemper et al, 19, "Challenges and Prospects in Ocean Circulation Models" http://jgula.fr/ModNum/FoxKemperetal19.pdf

ROMS/CROCO:

- https://www.myroms.org/wiki/
- Shchepetkin, A., and J. McWilliams, 2005: The Regional Oceanic Modeling System (ROMS): A splitexplicit, free-surface, topography-following- coordinate ocean model. Ocean Modell. http://jgula.fr/ModNum/ShchepetkinMcWilliams05.pdf

(See chapter 3 of Cushman-Roisin and Beckers)

Ingredients: rotation + stratification



(See chapter 3 of Cushman-Roisin and Beckers)

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[XX equations for the XX variables: ...]

(See chapter 3 of Cushman-Roisin and Beckers)

- Momentum equations (3d)
- Conservation of mass

$$\frac{D\vec{u}}{Dt} = \dots$$

$$\partial_t \rho + \nabla \cdot (\rho \vec{u}) = 0$$

- Conservation of heat
- Conservation of salinity
- Equation of state :

$$\frac{DT}{Dt} = \mathcal{S}_T$$

$$\frac{DS}{Dt} = \mathcal{S}_S$$

$$\rho = \rho(T, S, p)$$

[7 equations for the 7 variables: u,v,w,p,T,S,ρ]

(See chapter 3 of Cushman-Roisin and Beckers)

Momentum equations (3d)

$$\frac{D\vec{u}}{Dt} = \dots$$

Conservation of mass

$$\partial_t \rho + \nabla \cdot (\rho \vec{u}) = 0$$

Conservation of heat

$$\frac{DT}{Dt} = \mathcal{S}_T$$

Conservation of salinity

$$\frac{DS}{Dt} = \mathcal{S}_S$$

Equation of state :

$$\rho = \rho(T, S, p)$$

[**7** equations for the **7** variables: u,v,w,p,T,S,ρ]

→ Cannot be integrated forward in time consistently
 We need further approximations

(See chapter 3 of Cushman-Roisin and Beckers)

- The different approximations to obtain HPE:
 - Adiabatic motion

$$\partial_{\theta}\rho|_{S,P} = \partial_{S}\rho|_{\theta,P} = 0$$

- Boussinesq approximation (Incompressible flow) $\rho(x,y,z,t) = \rho_0 + \rho'(x,y,z,t)$
- Hydrostatic approximation

$$\delta = \frac{H}{L} = \frac{W}{U} \ll 1$$

 Traditional approximation (Horizontal Coriolis)

$$(\widetilde{f} w, \widetilde{f} u) \ll (fu, fv)$$

- Navier-Stokes Equations (NS)
- Non-hydrostatic Primitive Equations (NH)
- Hydrostatic Primitive Equations (PE)
- Shallow-water (SW)
- Quasi-geostrophic (QG)
- 2D Euler equations
- Etc.

Type of models

Navier Stokes • DNS = Direct Numerical Simulation

LES = Large Eddy Simulation

PF

SW

SQG

QG

PE = Primitive Equations models

SW = Shallow-Water models

• SQG = Surface Quasi-Geostrophic models

QG = Quasi-Geostrophic models

Etc.

CFD

Process studies

Ocean
Circulation
Models

Idealized models

Navier-Stokes Equations:

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + g\vec{k} = -\frac{\vec{\nabla} P}{\rho} + \vec{\mathcal{F}}$$

Momentum equations

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$

Mass conservation (no source/sink)

Navier-Stokes Equations:

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + g\vec{k} = -\frac{\vec{\nabla} P}{\rho} + \vec{\mathcal{F}}$$
 Time Advection (inertia) Rotation Gravity Pressure gradient + Dissipation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$

Mass conservation (no source/sink)

Navier-Stokes Equations:

Linearized momentum equations

- + continuity equation
- + adiabatic motion:
- = Acoustic modes (sound waves)

$$\rho_0 \frac{\partial \vec{u}}{\partial t} = -\vec{\nabla}P$$

$$\frac{\partial P}{\partial t} = -\rho_0 c_s^2 \vec{\nabla}P \cdot \vec{u}$$

$$\partial_{tt}P = c_s^2 \nabla^2 P$$

With $c_s \approx 1500\,\mathrm{m\,s}^{-1}$ in water, a model requires a very small time-step to solve these equations.

→ Ex: sound waves would take about 1/30 sec to cross a 50-m long swimming pool

Boussinesq Approximation:

Density perturbations small compared to mean background value:

$$\rho = \rho_0 + \rho' \qquad \qquad \rho' << \rho_0$$

$$\rho' << \rho_0$$

Linearize all terms involving a product with density, except the gravity term which is already linear:

$$\rho \vec{u} \rightarrow \rho_0 \vec{u}$$

$$\rho g \rightarrow \rho g$$

Boussinesq Approximation:

[+ incompressibility or adiabatic]

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$



$$\begin{array}{rcl} \partial_t \rho + \nabla \, . \rho \vec{u} &=& \partial_t \rho + \rho \nabla \, . \vec{u} + \vec{u} \, \nabla \rho \\ &=& (\rho_0 + \rho') \, \nabla \, . \vec{u} + D_t \rho' \\ \sim & \rho_0 \, \nabla \, . \vec{u} \end{array}$$

$$\vec{\nabla} \cdot \vec{u} = 0$$

Mass conservation → Volume conservation

Non hydrostatic boussinesq (NH):

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + \frac{\rho}{\rho_0} g \vec{k} = -\frac{\vec{\nabla} P}{\rho_0} + \frac{\vec{\mathcal{F}}}{\rho_0} + \frac{\vec{\mathcal{D}}}{\rho_0}$$

$$\vec{\nabla} \cdot \vec{u} = 0$$

Easier to solve than Navier-Stokes, but still requires to invert a 3d elliptic equation for P (computationally expansive)

Hydrostatic balance:

The vertical component of the Boussinesq momentum equations is

$$\partial_t w + \vec{u} \cdot \vec{\nabla} w + 2\Omega \cos \phi u + \frac{\rho}{\rho_0} g = \frac{1}{\rho_0} \partial_z P + F_w + D_w$$

For long horizontal motions (L >> H) the dominant balance is

H ~3000 m L ~3000 km

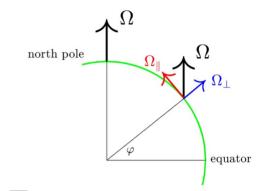
$$\frac{\partial P}{\partial z} = -\rho g$$

Such that pressure is just a vertical integral:

$$P = \int_{z}^{\eta} g\rho dz$$

Traditional approximation

= neglect horizontal Coriolis term



$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + \frac{\rho}{\rho_0} g \vec{k} = -\frac{\vec{\nabla} P}{\rho_0} + \vec{\mathcal{F}} + \vec{\mathcal{D}}$$

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + f \vec{k} \times \vec{u} + \frac{\rho}{\rho_0} g \vec{k} = -\frac{\vec{\nabla} P}{\rho_0} + \vec{\mathcal{F}} + \vec{\mathcal{D}}$$

Hydrostatic Primitive Equations (PE)

2d momentum with Boussinesq approximation:

$$\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - fv = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$$

$$\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + fu = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$$
Hydrostatic:
$$\frac{\partial P}{\partial t} = -\rho q$$

ullet Continuity equation for an incompressible fluid: abla

$$\vec{\nabla} \cdot \vec{u} = 0$$

Hydrostatic Primitive Equations (PE)

2d momentum with Boussinesq approximation:

$$\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - fv = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$$

$$\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + fu = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$$

$$\frac{\partial P}{\partial z} = -\rho g$$

Hydrostatic:

Continuity equation for an incompressible fluid:

$$\vec{\nabla} \cdot \vec{u} = 0$$

• Conservation of heat and salinity $\frac{DT}{Dt} = \mathcal{S}_T$ $\frac{DS}{Dt} = \mathcal{S}_S$

• Equation of state : $\rho = \rho(T, S, z)$

Hydrostatic Primitive Equations (PE)

- 4 prognostics equations for u, v, T, S
- 3 diagnostics equations for w, p, P

Hydrostatic Primitive Equations (PE)

2d momentum with Boussinesq approximation:

$$\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - fv = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$$

$$\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + fu = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$$

$$\frac{\partial P}{\partial z} = -\rho g$$

Hydrostatic:

$$\vec{\nabla} \cdot \vec{u} = 0$$

• Conservation of heat and salinity $\frac{DT}{Dt} = S_T$ $\frac{DS}{Dt} = S_S$

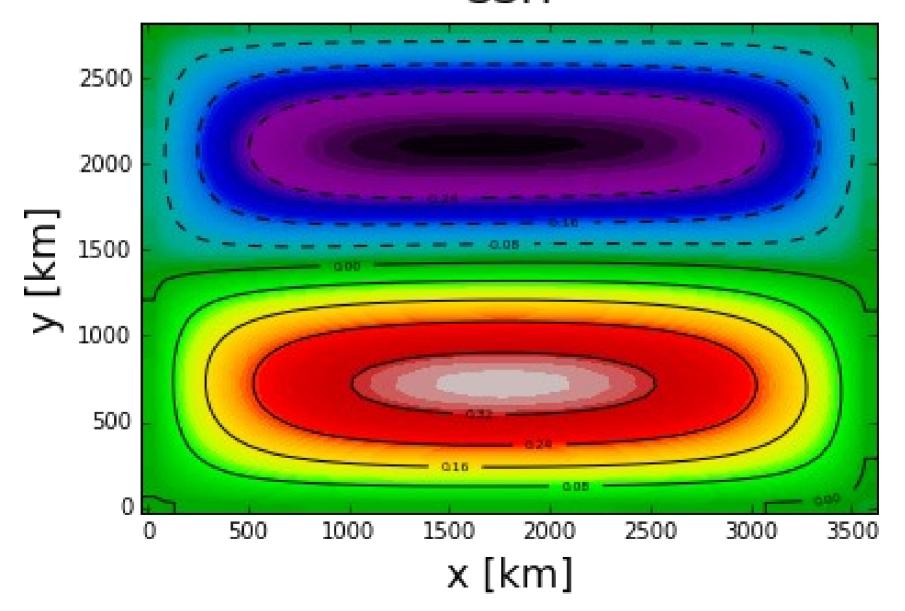
• Equation of state :
$$\rho = \rho(T, S, z)$$

Hydrostatic Primitive Equations (PE)

- 4 prognostics equations for u, v, T, S
- 3 diagnostics equations for w, p, P

- + Forcings (wind, heat flux)
- + sub-grid scale parameterizations (bottom drag, mixing, etc.)

Activity 1 – Run an idealized ocean basin **SSH**



Activity 1 - Run an idealized ocean basin

- Jobcomp (compilation)
- cppdefs.h (Numerical/physical options)
- param.h (gris size/ parallelisation)
- croco.in (choice of variables, parameter values, etc.)

Activity 1 - Run an idealized ocean basin

https://github.com/quentinjamet/Tuto

1) Preparing and compiling the model

For that use the the jobcomp bash file ./jobcomp

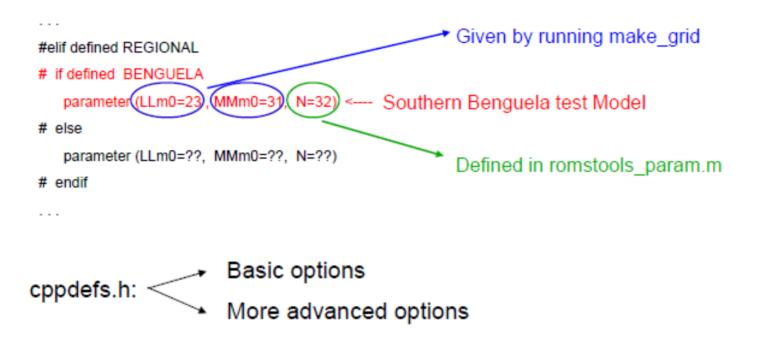
- Set library path
- 2. Automatic selection of option accordingly the platform used
- 3. Use of makefile
 - C-preprocessing step: .F _ .f using the CPP keys definitions (in cppdefs.h file, customization of the code)
 - Compilation step : .f _ .o (object) using Fortran compiler
 - Linking step: link all the .o file and the librairy (Netcdf, MPI, AGRIF)

--> produce the executable roms

1) Preparing and compiling the model

Edit the param.h and cppdefs.h file to set-up the model

param.h defines the size of the arrays in ROMS:



- Define CPP keys used by the C-preprocessor when compiling the model.
- Reduce the code to its minimal size: fast compilation.
- Avoid FORTRAN logical statements: efficient coding.

1) Preparing and compiling the model

View cppdef.h file



```
BASIC OPTIONS
                Configuration Name */
# define BENGUELA
                Parallelization */
#undef OPFNMP
# undef MPI
                Embedding */
# undef AGRIF
                Open Boundary Conditions */
# undef TIDES
# define OBC EAST
# undef OBC WEST
# define OBC NORTH
# define OBC SOUTH
                 Embedding conditions */
# ifdef AGRIF
# undef AGRIF_OBC_EAST
# define AGRIF_OBC_WEST
# define AGRIF OBC NORTH
# define AGRIF OBC SOUTH
# endif
               Applications */
# undef BIOLOGY
#undef FLOATS
# undef STATIONS
#undef PASSIVE TRACER
#undef SEDIMENTS
#undef BBL
```

```
MORE ADVANCED OPTIONS
                 Model dynamics */
# define SOLVE3D
# define UV COR
# define UV ADV
# ifdef TIDES
# define SSH TIDES
# define UV TIDES
# define TIDERAMP
# endif
                Grid configuration */
# define CURVGRID
# define SPHERICAL
# define MASKING
                      Input/Output & Diagnostics */
# define AVERAGES
# define AVERAGES K
# define DIAGNOSTICS TS
# define DIAGNOSTICS UV
                       Equation of State */ ...
                      Surface Forcing */ ...
                      Lateral Forcing */ ...
                      Input/Output & Diagnostics */ ...
                      Bottom Forcing */ ...
                      Point Sources - Rivers */ ...
                      Lateral Mixing */ ...
                      Vertical Mixing */ ...
                      Open Boundary Conditions */ ...
/*
                      Embedding conditions */ ...
/*
```

2) Running the model

The namelist roms.in

roms.in provides the run time parameters for ROMS:

```
title:
    Southern Benguela
time stepping: NTIMES dt[sec] NDTFAST NINFO
              5400 60
        480
S-coord: THETA S, THETA B, Hc (m)
      6.0d0
             0.0d0
                    10.0d0
grid: filename
                                          Warning! These
              ROMS FILES/roms grd.nc
                                        should be identical to
forcing: filename
                                             the ones in
              ROMS FILES/roms frc.nc
bulk forcing: filename
                                        romstools_param.m
             ROMS FILES/roms blk.nc
climatology: filename
             ROMS_FILES/roms_clm.nc
boundary: filename
             ROMS FILES/roms bry.nc
initial NRRFC filename
             ROMS FILES/roms ini.nc
           NRST, NRPFRST / filename
restart:
         480 -1
             ROMS FILES/roms rst.nc
```

```
history: LDEFHIS, NWRT, NRPFHIS / filename
      T 480 0
             ROMS FILES/roms his.nc
averages: NTSAVG, NAVG, NRPFAVG / filename
         48 0
             ROMS FILES/roms avg.nc
primary history fields: zeta UBAR VBAR U V wrtT(1:NT)
             T F F F F 10*F
auxiliary history fields: rho Omega W Akv Akt Aks HBL Bostr
              FFFFFFF
primary averages: zeta UBAR VBAR U V wrtT(1:NT)
         T T T T T 10*T
auxiliary averages: rho Omega W Akv Akt Aks HBL Bostr
          FTTFTFTT
rho0:
   1025.d0
lateral_visc: VISC2, VISC4 [m^2/sec for all]
        0.
             0.
tracer diff2: TNU2(1:NT)
                         [m^2/sec for all]
       10*0.d0
bottom drag: RDRG [m/s], RDRG2, Zob [m], Cdb min, Cdb max
        0.0d-04  0.d-3  1.d-2  1.d-4  1.d-1
gamma2:
        1.d0
           X SPONGE [m], V SPONGE [m^2/sec]
sponge:
                     800
         100.e3
nudg_cof: TauT_in, TauT_out, TauM_in, TauM_out [days for all]
             360
                    10.
                         360
```

Activity 1 - Run an idealized ocean basin

· param.h

```
parameter (LLm0=60, MMm0=50, N=10
```

· cppdefs.h

```
# define UV_COR
# define UV_VIS2
# define TS_DIF2

# define ANA_GRID
# define ANA_INITIAL
```

· ana_grid.F

```
f0=1.E-4
beta=0.
```

· croco.in

Homework

- For next time:
 - Read https://www.jgula.fr/ModNum/Stommel48.pdf
 - Read https://www.jgula.fr/ModNum/Munk50.pdf