



# Applications of deep learning to subgrid eddy parameterization in high- and low-resolution ocean model

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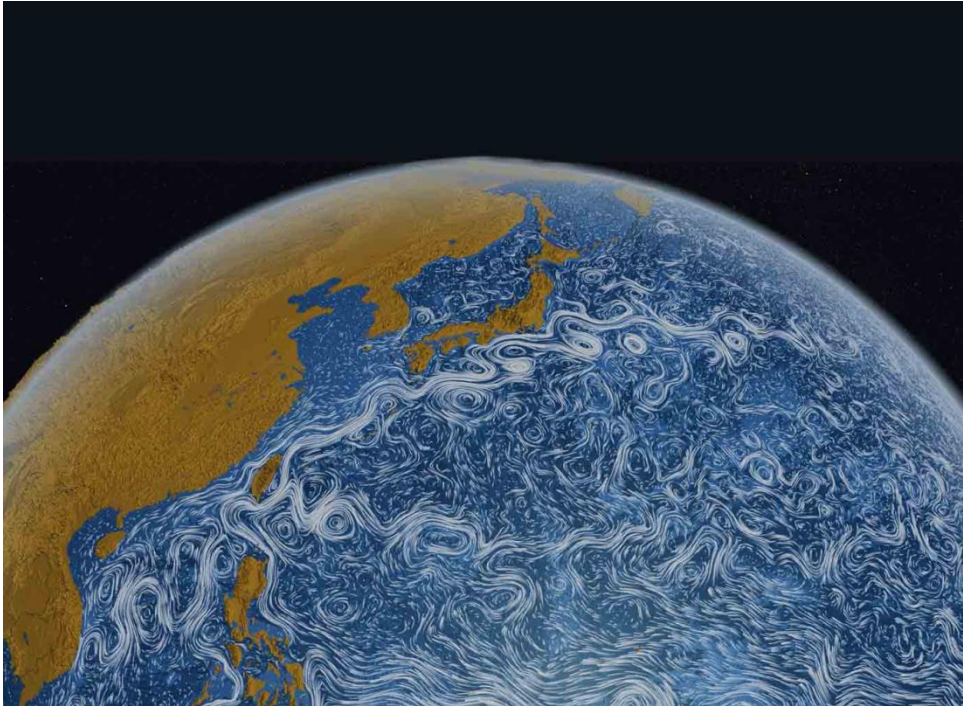
September 6<sup>th</sup> 2019



PART ONE  
Introduction

# 1.1 Introduction

## Background



Interaction with  
large-scale flow

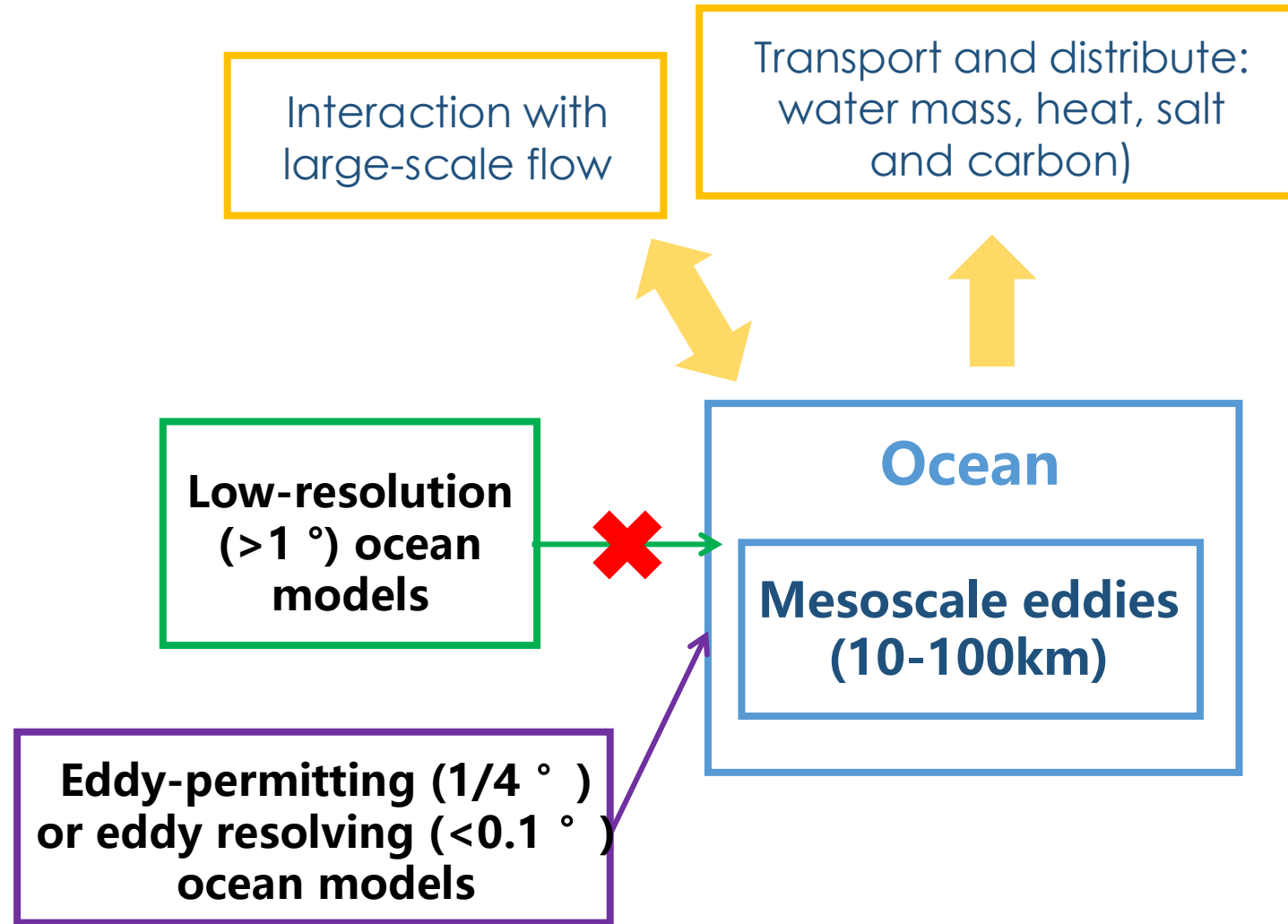
Transport and distribute:  
water mass, heat, salt  
and carbon)

**Ocean**

**Mesoscale eddies  
(10-100km)**

# 1.1 Introduction

## Background



# 1.1 Introduction

## Background

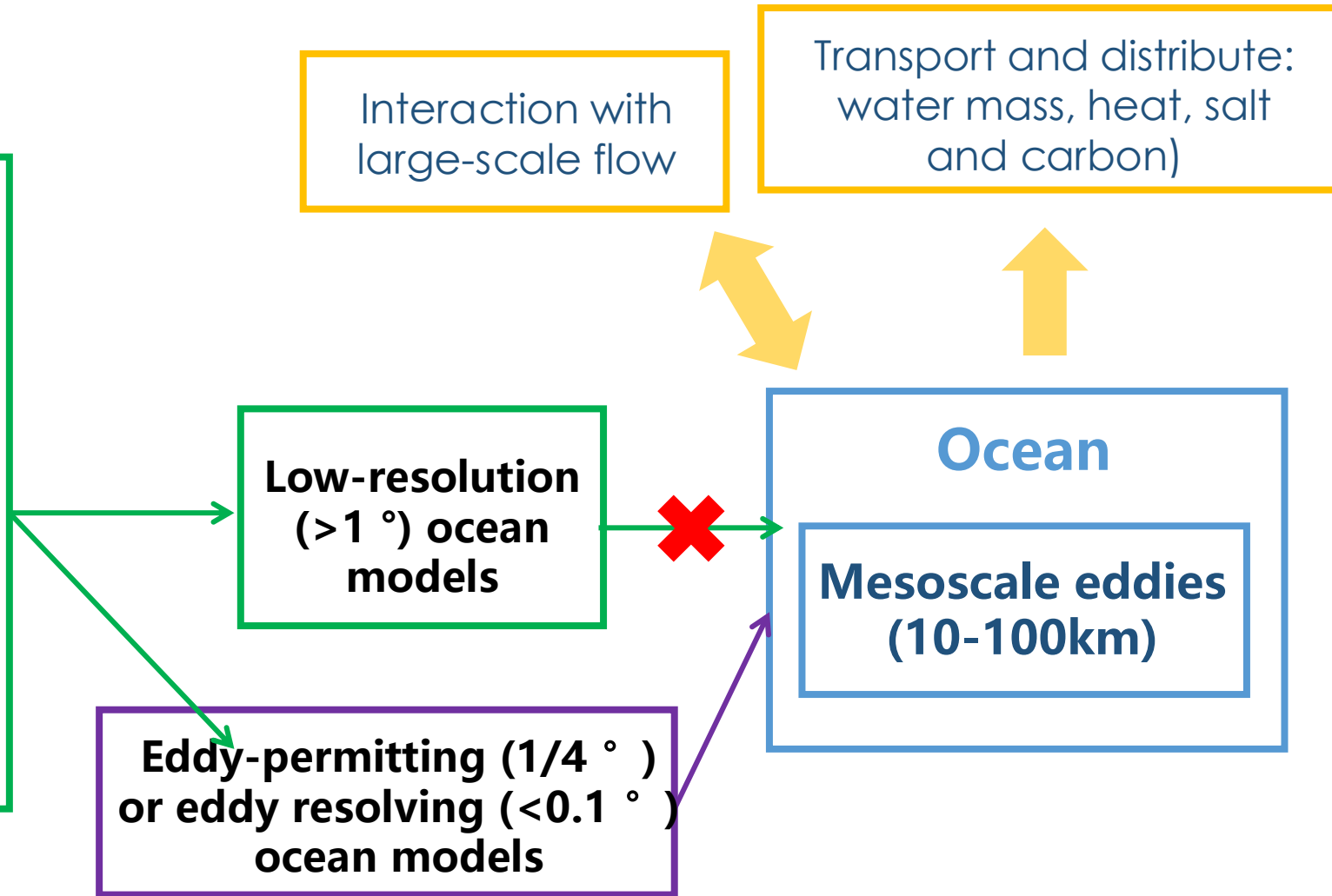
### Eddy parameterization:

#### ➤ **Deterministic:**

- Gent-McWilliams (GM)  
[Gent and McWilliams, 1990]
- Resolution function  
[Hallberg, 2013]

#### ➤ **Stochastic :**

- Probability distribution function  
[Zanna et al., 2017]



## Machine Learning

### Deep Learning :

- Popular in the field : image processing, language, etc.
- Extract information from data
- Data-driven approach, to approximate nonlinear relationship, without obey physical principles and conservation laws.

### Applications:

- Climate models:
  - Typhoon Forecast [Jiang et al., 2018],
  - representing unresolved moist convection [Gentine et al., 2018].
- Turbulence modeling ( e.g [Ling et al., 2016])

# 1.2 Introduction

## Machine Learning

### Deep Learning :

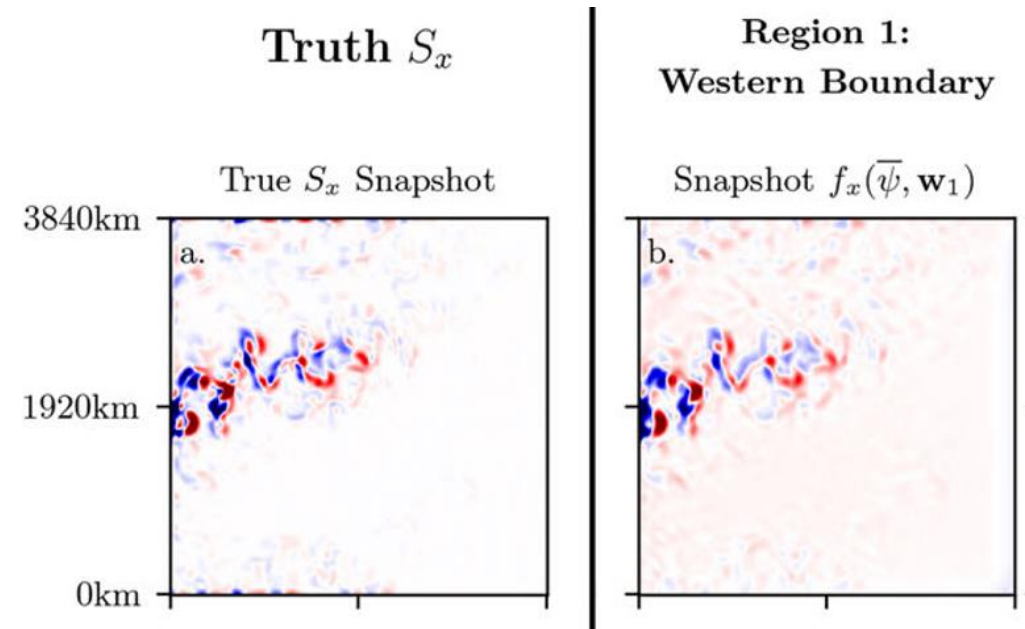
- Popular in the field : image processing, language, etc.
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- Data-driven approach, to approximate nonlinear relationship, without obey physical principles and conservation laws.

### Applications:

- Climate models:
  - Typhoon Forecast [Jiang et al., 2018],
  - representing unresolved moist convection [Gentine et al., 2018].
- Turbulence modeling ( e.g [Ling et al., 2016])

### Bolton et al.,2019 (BM18):

- An idealized high-resolution ocean model,
- Deep learning : Convolutional neural networks (CNNs)
- Represent both the spatial and temporal variability of the eddy momentum forcing



### Objectives

1. Apply the CNNs in a **realistic simulation**
2. Test the sensitivity of the neural networks
3. The main goal : Using sub-sample data from an eddy-resolving model, to represent unresolved eddies in low-resolution model as a **subgrid-scale parametrization**



# contents



2 Methodology

3 Main Results

*3.1 Gyre Case*

*3.2 Realistic Case*

*3.3 Implementation in Low-resolution*

4 Conclusion



PART TWO  
**Methodology**

## 2.2 Methodology

### Subgrid eddy momentum forcing

The horizontal momentum equation :

$$\frac{\partial u}{\partial t} + (u \cdot \nabla) u = F + D$$

Large-Eddy Simulation :

Large scale and eddy components

$$u = \bar{u} + u'$$

*Gaussian  
Filter*

## 2.2 Methodology

### Subgrid eddy momentum forcing

The horizontal momentum equation :

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = \mathbf{F} + \mathbf{D}$$

$$\frac{\partial \bar{\mathbf{u}}}{\partial t} + (\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} = \bar{\mathbf{F}} + \bar{\mathbf{D}} + (\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} - \overline{(\mathbf{u} \cdot \nabla) \mathbf{u}}$$

Large-Eddy Simulation :

Large scale and eddy components

$$\mathbf{u} = \bar{\mathbf{u}} + \mathbf{u}'$$

*Gaussian  
Filter*

## 2.2 Methodology

### Subgrid eddy momentum forcing

The horizontal momentum equation :

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = \mathbf{F} + \mathbf{D}$$

$$\frac{\partial \bar{\mathbf{u}}}{\partial t} + (\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} = \bar{\mathbf{F}} + \bar{\mathbf{D}} +$$

$$(\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} - \overline{(\mathbf{u} \cdot \nabla) \mathbf{u}}$$

$$\frac{\partial \bar{\mathbf{u}}}{\partial t} + (\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} = \bar{\mathbf{F}} + \bar{\mathbf{D}} + \mathbf{S}$$

Filtered  
momentum forcing

Filtered  
Dissipation

Subgrid eddy momentum  
forcing

Large-Eddy Simulation :

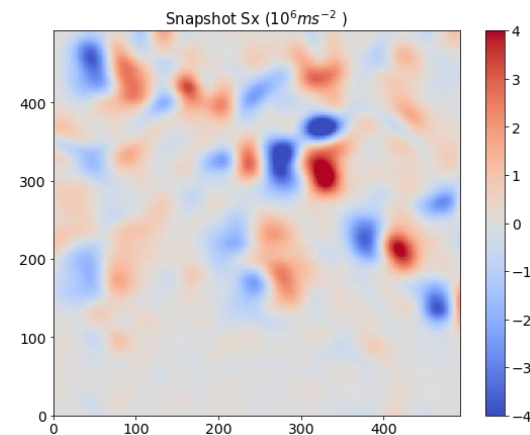
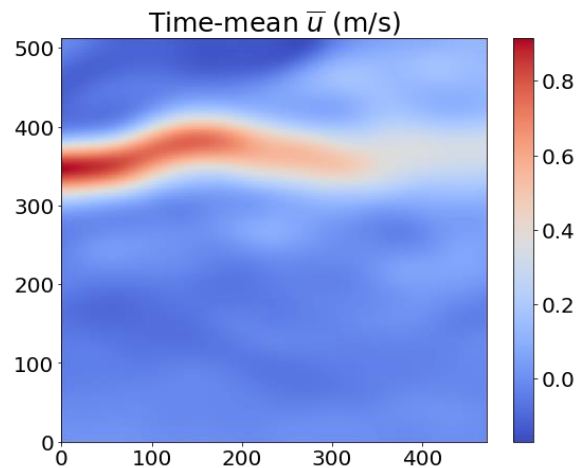
Large scale and eddy components

$$\mathbf{u} = \bar{\mathbf{u}} + \mathbf{u}'$$

*Gaussian  
Filter*

## 2.2 Methodology

### Subgrid eddy momentum forcing



$$(\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} - \overline{(\mathbf{u} \cdot \nabla) \mathbf{u}}$$

$$\frac{\partial \bar{\mathbf{u}}}{\partial t} + (\bar{\mathbf{u}} \cdot \nabla) \bar{\mathbf{u}} = \bar{\mathbf{F}} + \bar{\mathbf{D}} + \mathbf{S} = (S_x, S_y)$$

Filtered  
momentum forcing

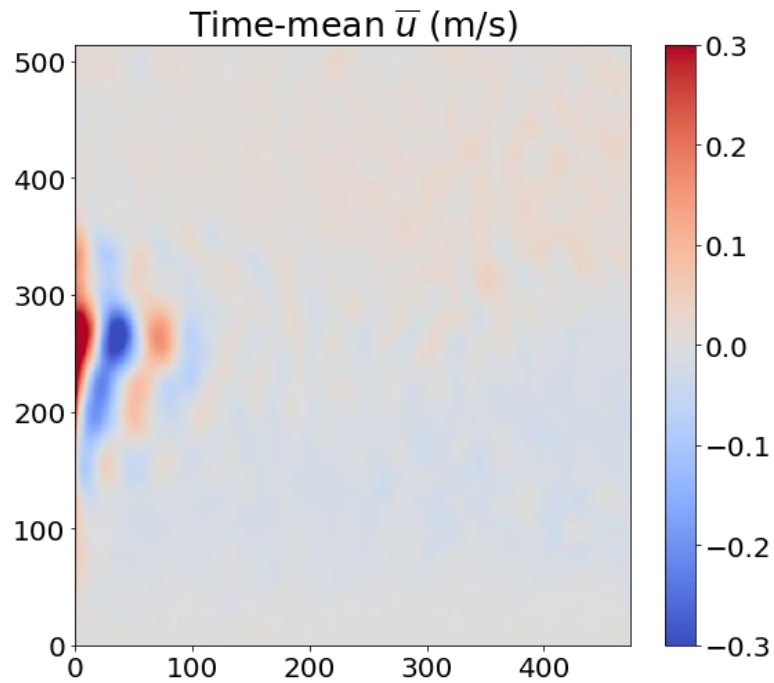
Filtered  
Dissipation

**Subgrid eddy momentum  
forcing**

## 2.1 Methodology

### The Ocean model and data

#### 1. Gyre case: Coastal and Regional Ocean COmmunity (CROCO)



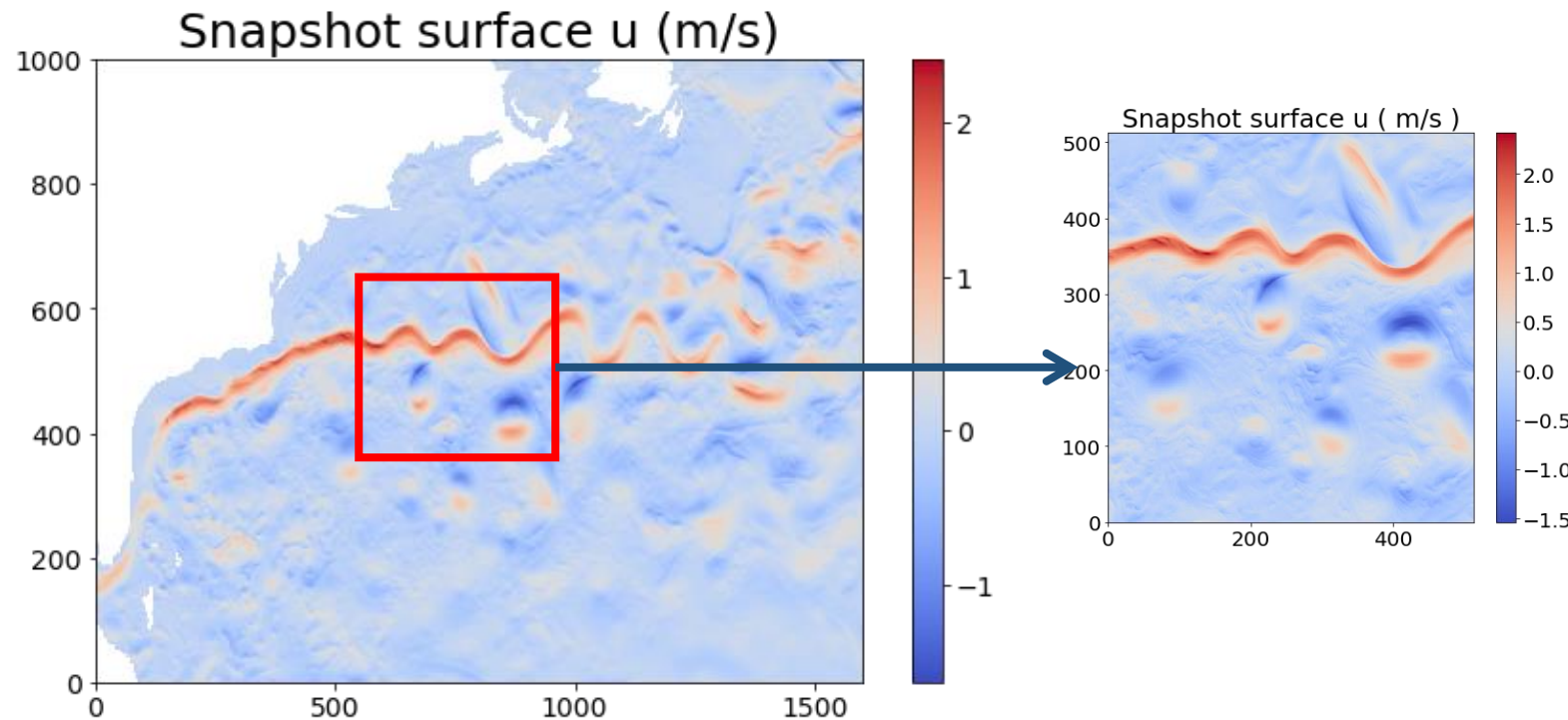
#### Study Region:

- Bounded-square basin
- Length  $L=3600\text{km}$
- Flat bottom
- High-resolution  $512 \times 512$ ,  $dx=7.0 \text{ km}$
- Constant wind stress forcing applied on surface
- 1000 daily data of velocity stored

## 2.1 Methodology

### The Ocean model and data

#### 2. Realistic simulation in the Gulf Stream: Regional Ocean Modeling System (ROMS)



#### Study Region:

- Realistic simulation  
512 x 512,  $dx=2.5$  km
- In the Gulf Stream
- Length  $L=1280$ km
- The effect of the topography is considered
- 5-day intervals , 1000 snapshots of velocity stored

From Gula et al. [2015]



## 2.3 Methodology

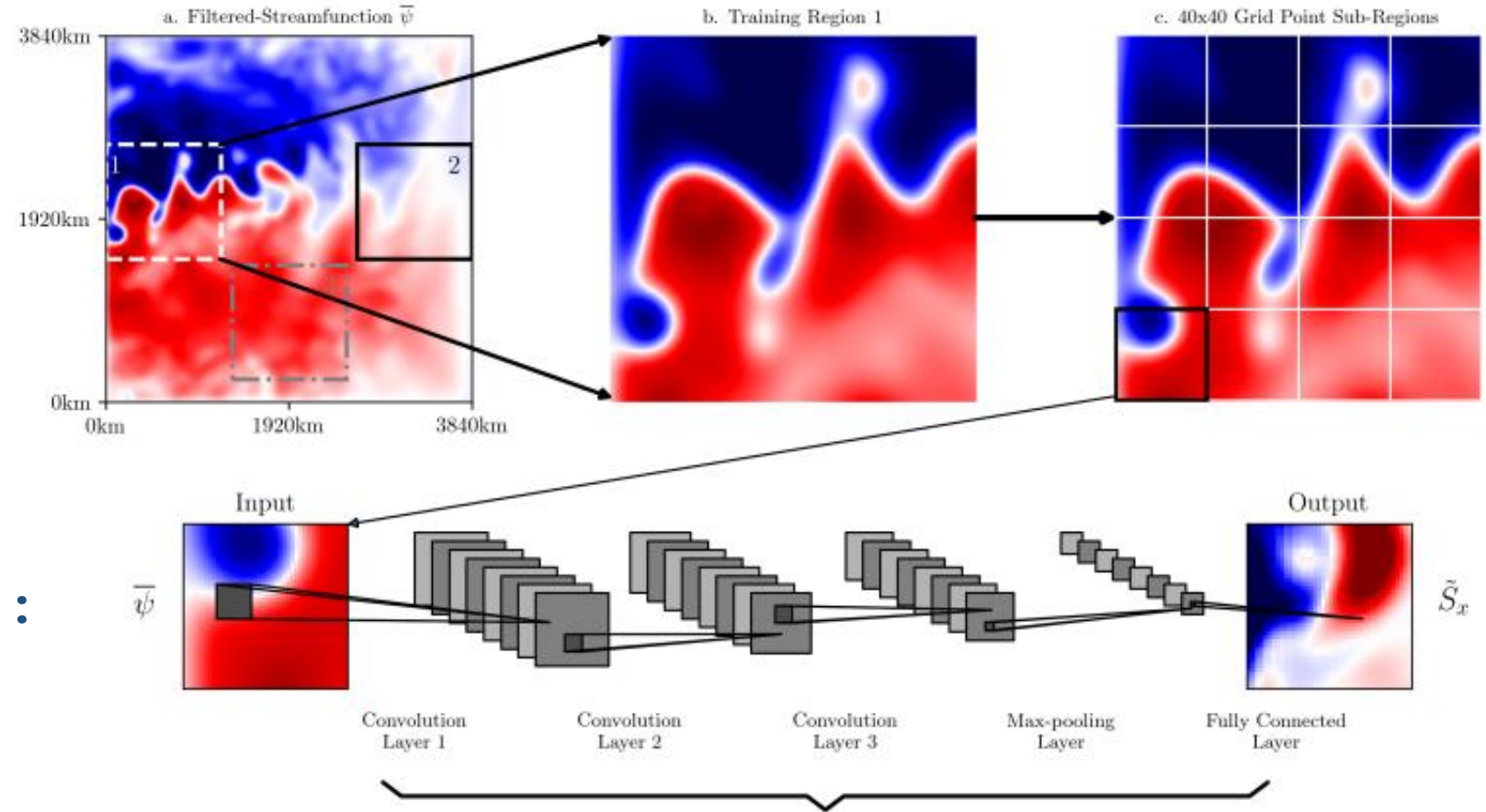
### Deep Learning with the CNNs

#### Training Strategy: in BM18

The full domain  
(512 x 512)

Study Region  
(160 x 160)

Training Sub-region  
16 x (40 x 40)



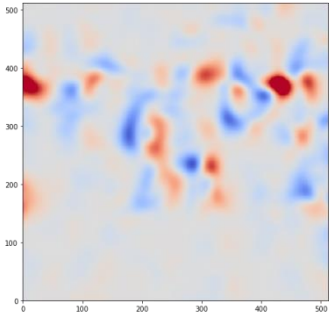
The architecture of CNNs :

## 2.3 Methodology

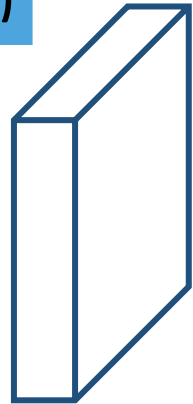
### Deep Learning with the CNNs

### Another architecture of CNNs

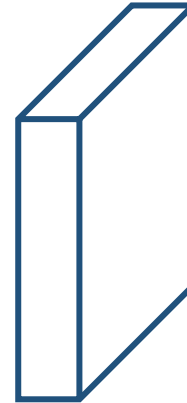
Training data  
(40 x 40)



Conv  
(9 x 9, 32)



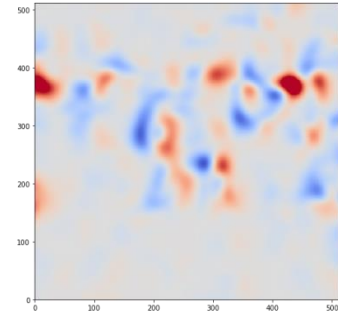
Conv  
(1 x 1, 16)



DeConv  
(9 x 9, 1)



Prediction  
(40 x 40)



Feature  
extraction

Non-linear  
Mapping

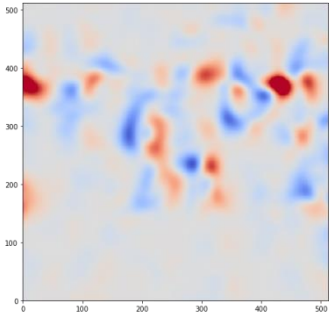
Reconstruction  
and  
Deconvolution

## 2.3 Methodology

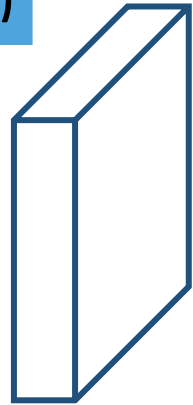
### Deep Learning with the CNNs

### Another architecture of CNNs

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Conv  
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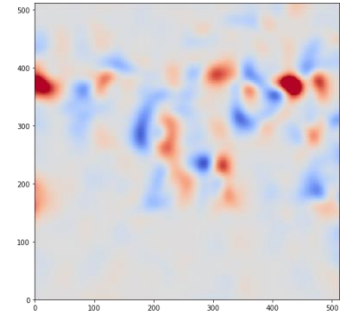
Conv  
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DeConv  
(9 x 9, 1)



Prediction  
(40 x 40)



Feature  
extraction

Non-linear  
Mapping

Reconstruction  
and  
Deconvolution

Total training parameters: 4 449  
In BM18 : 325 728

Fast speed to learn , maintain good performance

## 2.3 Methodology

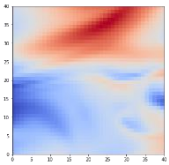
### Training Strategy

**Total Dataset :**

Training dataset  
(80%)

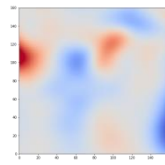
Validation dataset  
(20%)

Training data  
(40 x 40)

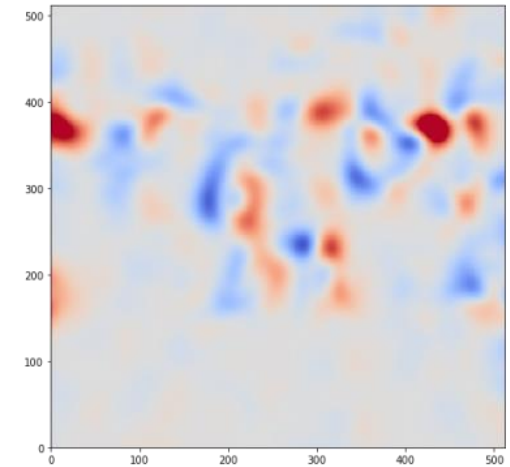


**CNNs**

Prediction  
(40 x 40)

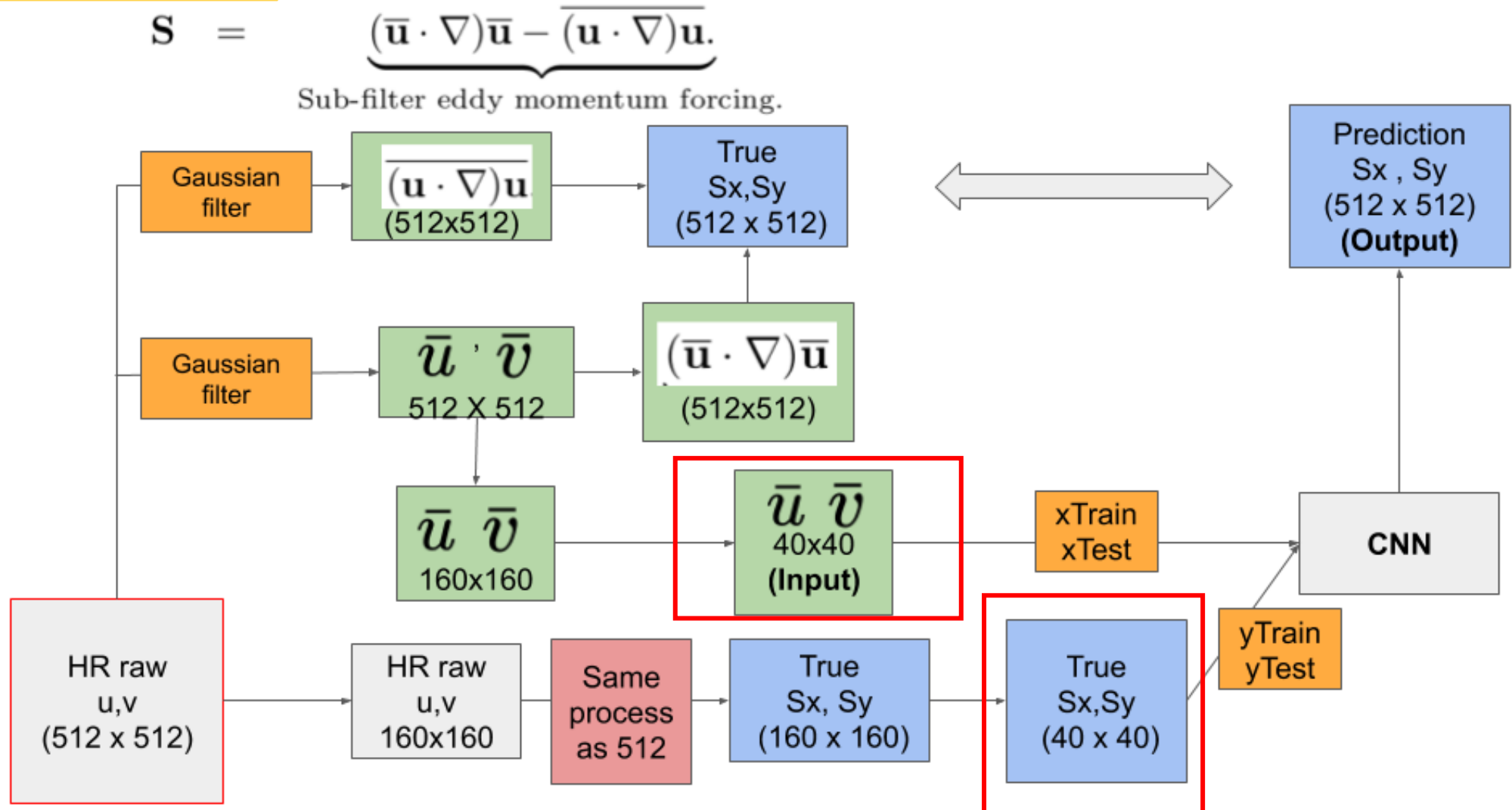


Prediction  
(512 x 512)



## 2.3 Methodology

### Implementation details



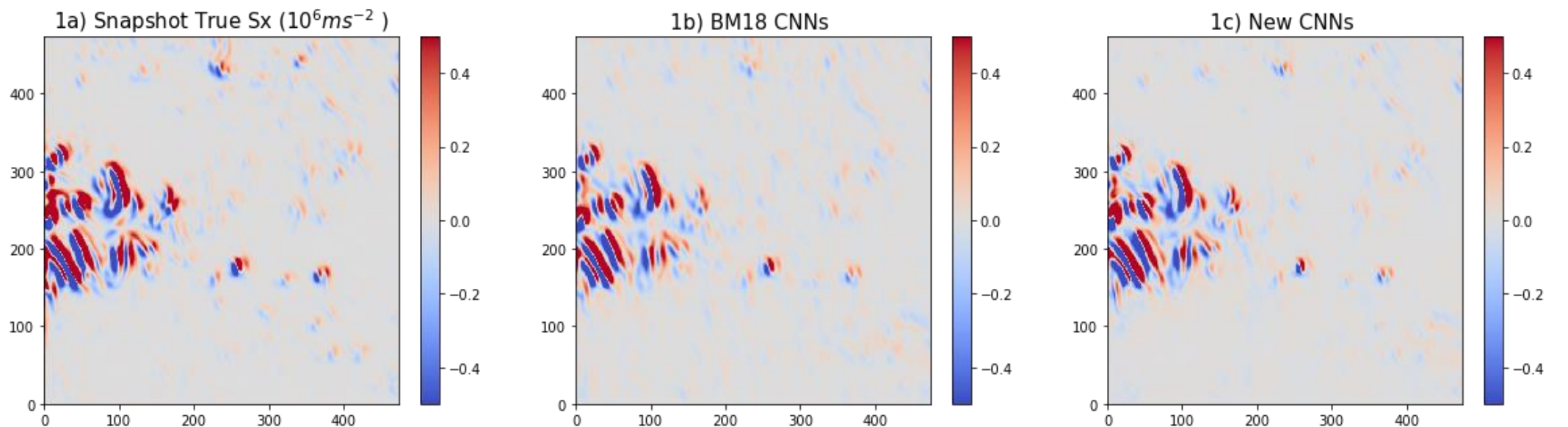


PART THREE

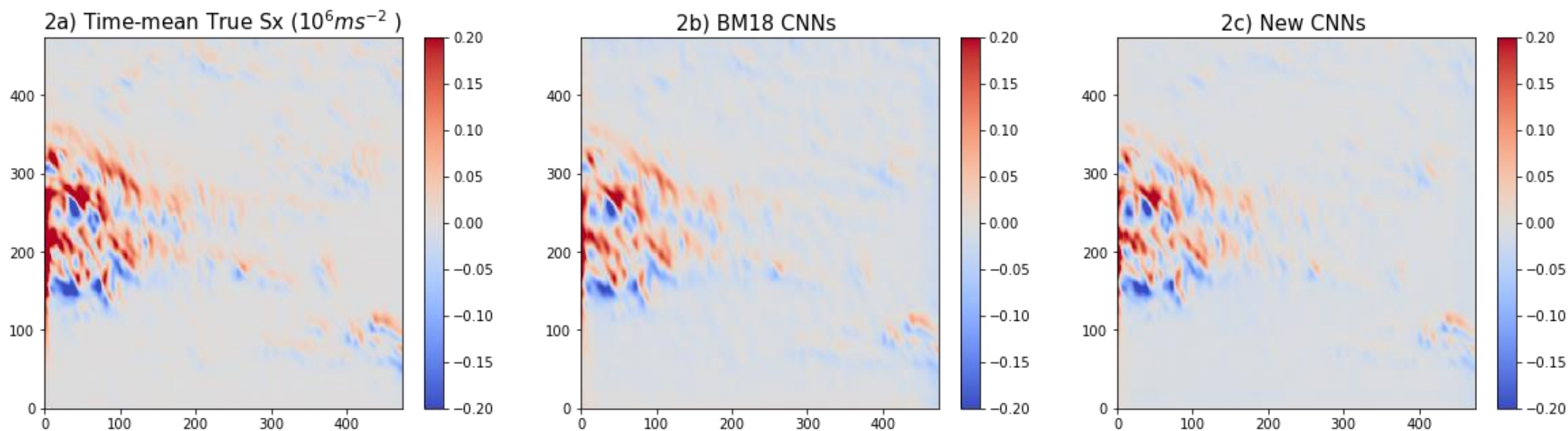
**Main Results**

## 3.1 Gyre case : comparison with BM18

Snapshot  
of  $S_x$



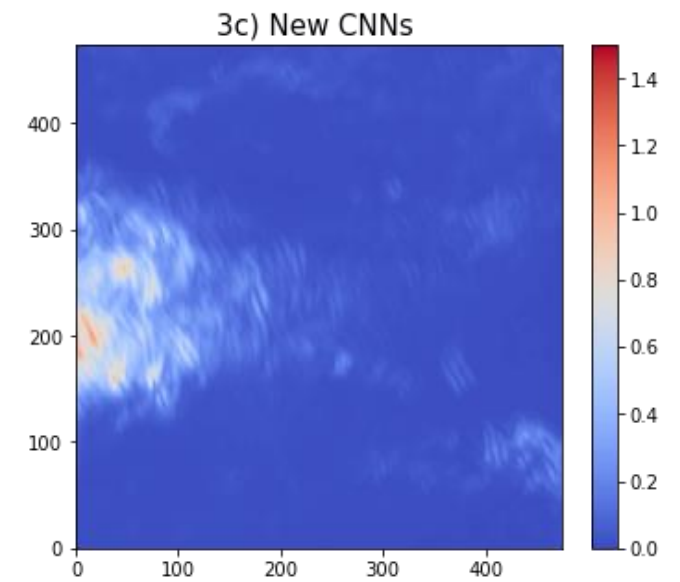
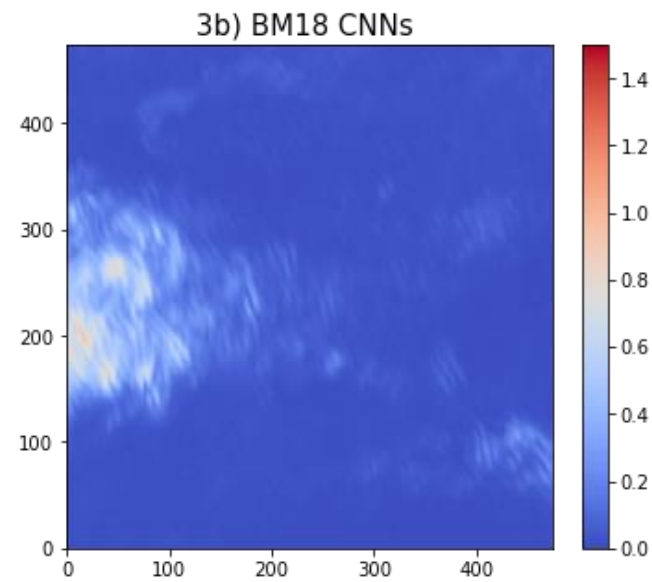
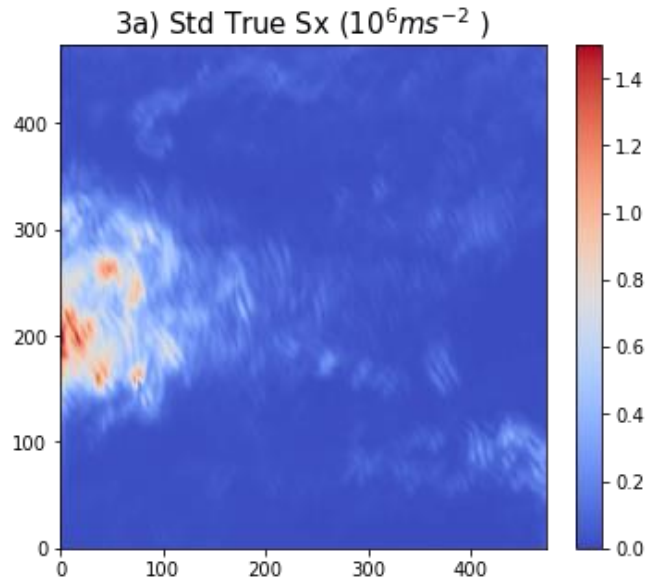
Time-mean  
 $S_x$



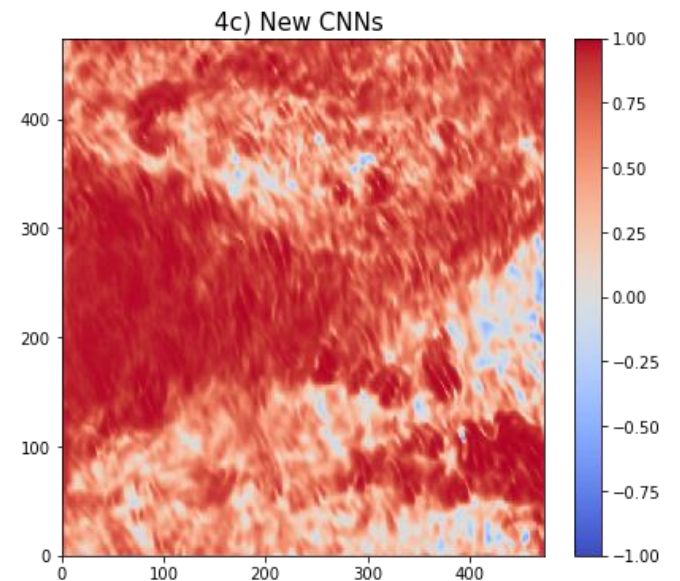
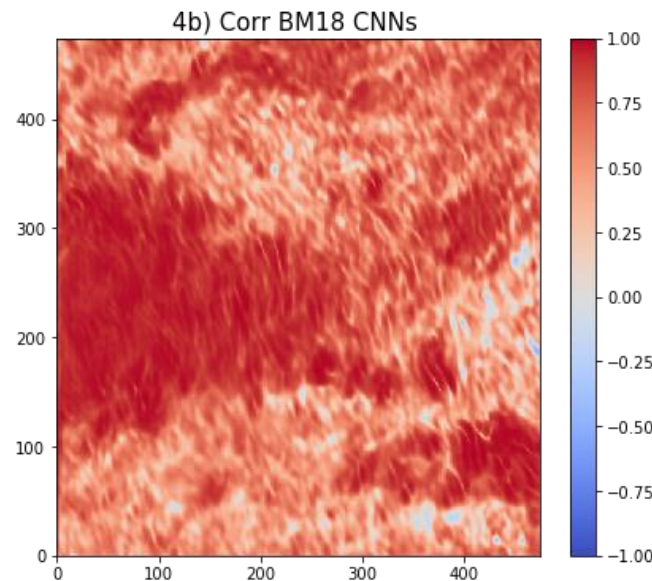


## 3.1 Gyre case : comparison with BM18

Standard  
deviation  
of  $S_x$

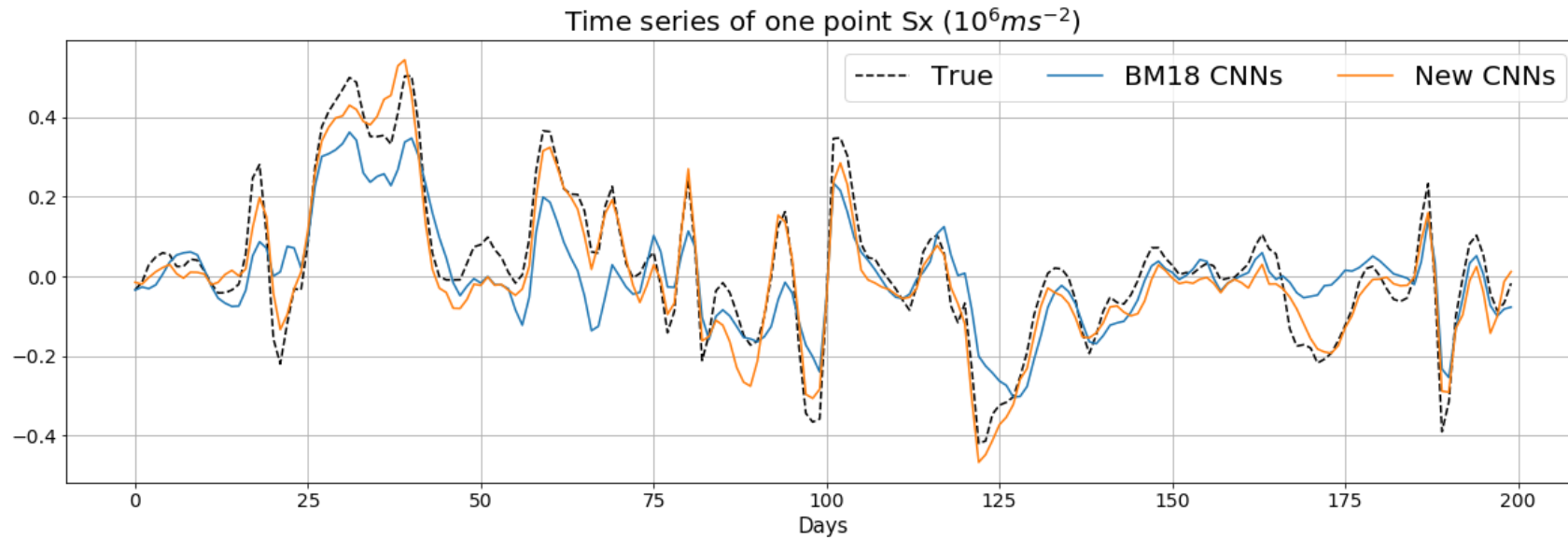


Correlation between  $S_x$  and prediction



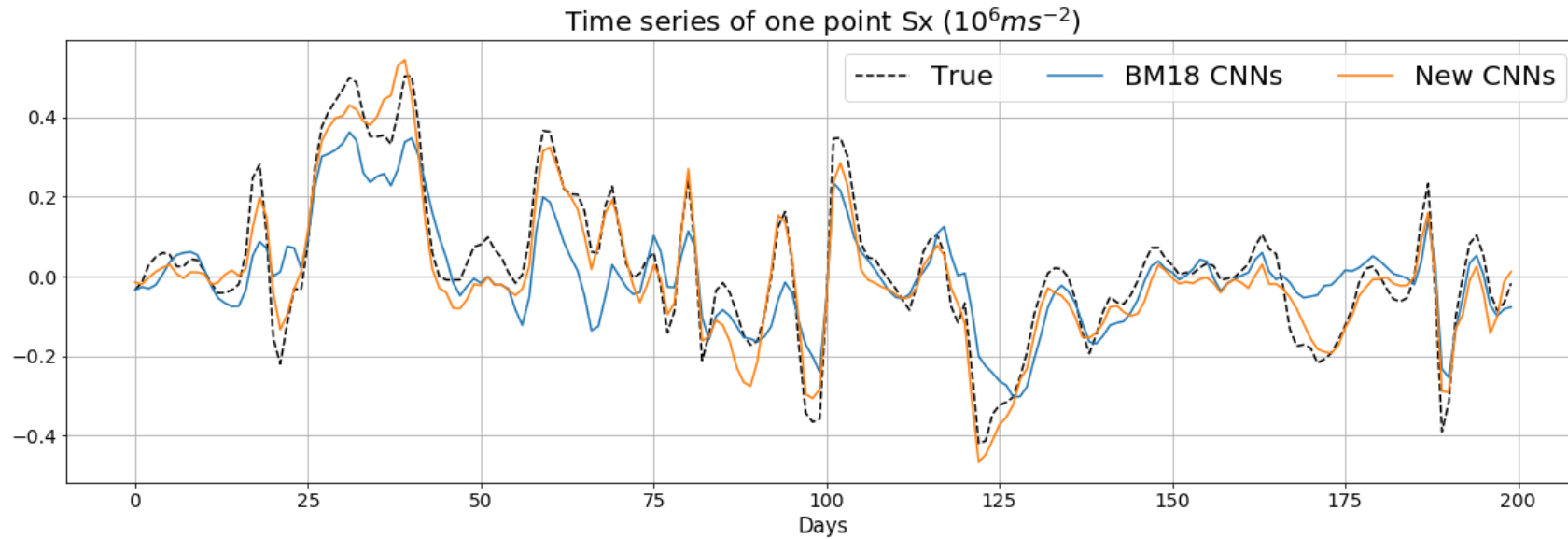


### 3.1 Gyre case : comparison with BM18



- The two time series of predictions generally match the fluctuation of true  $S_x$ ,
- New CNNs have better performance in amplitude most parts.

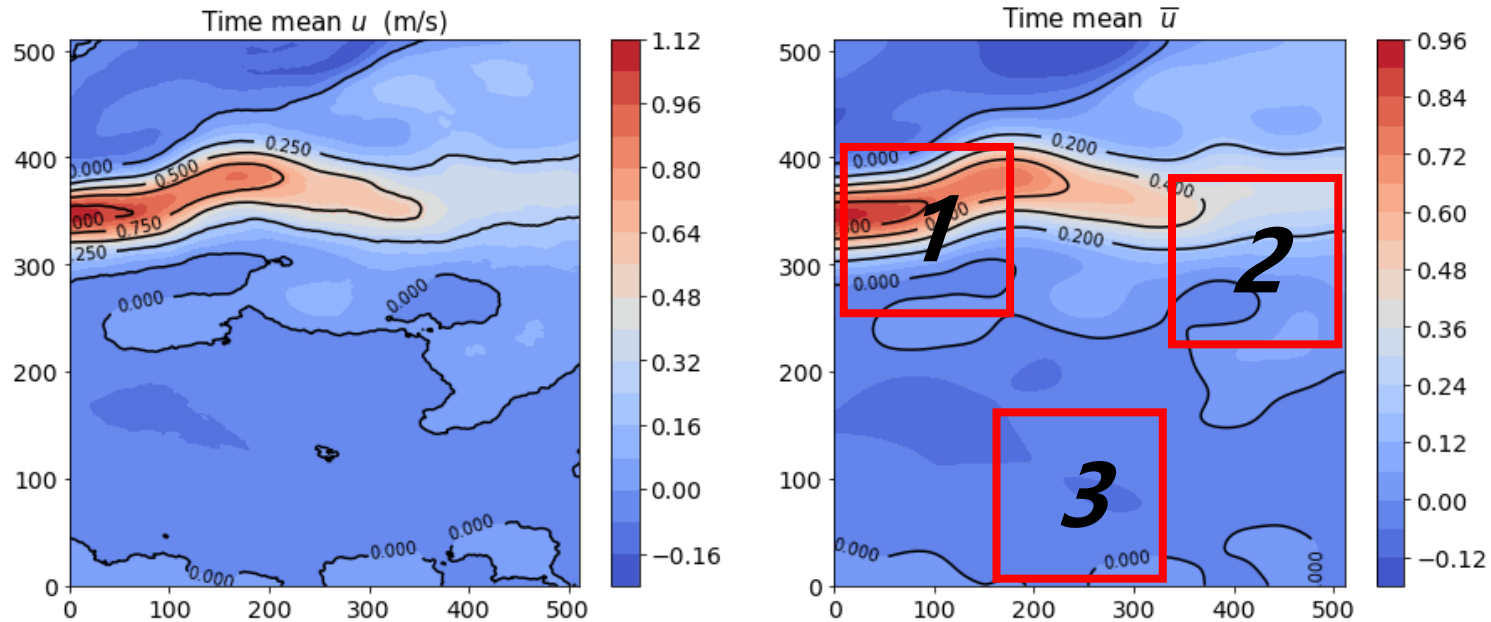
## 3.1 Gyre case : comparison with BM18



- Both good performance
- Both High correlation in the Western boundary
- New CNNs:  
Fewer parameters to train, much less time to compute

## 3.2 The Realistic simulation: the GS region

### Study Regions



### Study Regions(160 x 160):

**Region 1**  
**Region 2**  
**Region 3**

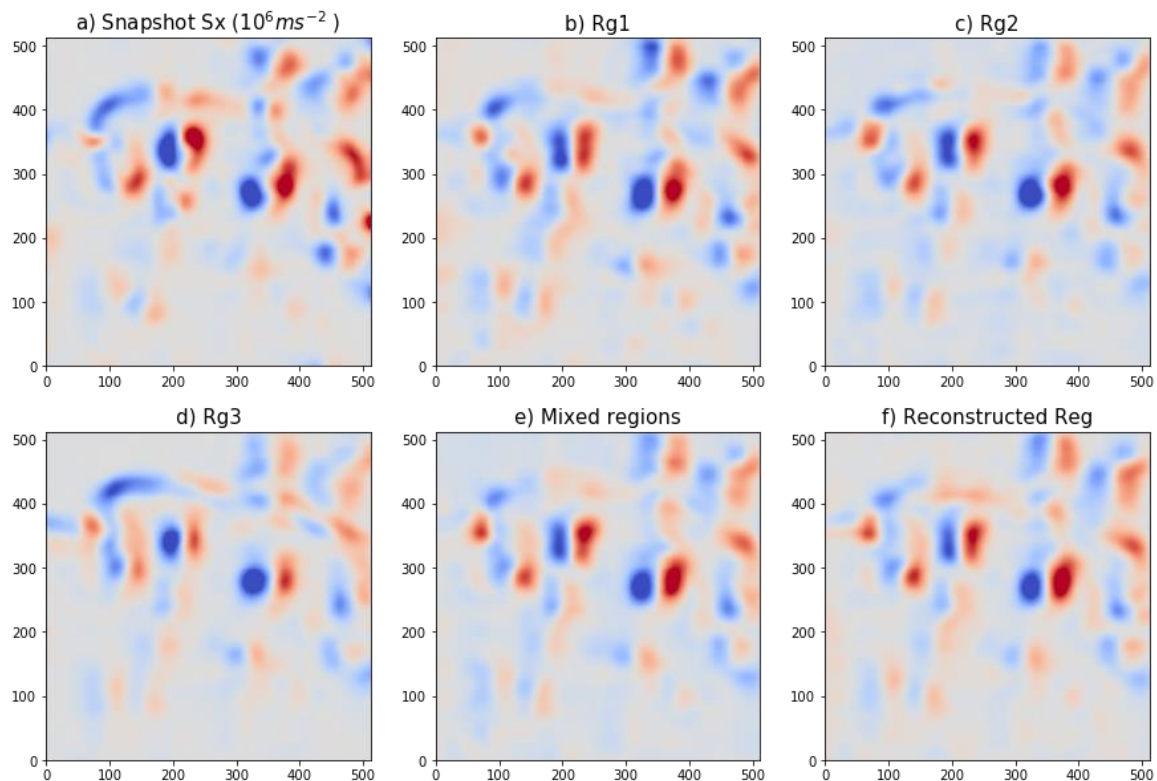
**Region 4** : mixed three regions  
(33%,33%,34%)

**Region 5** : random region

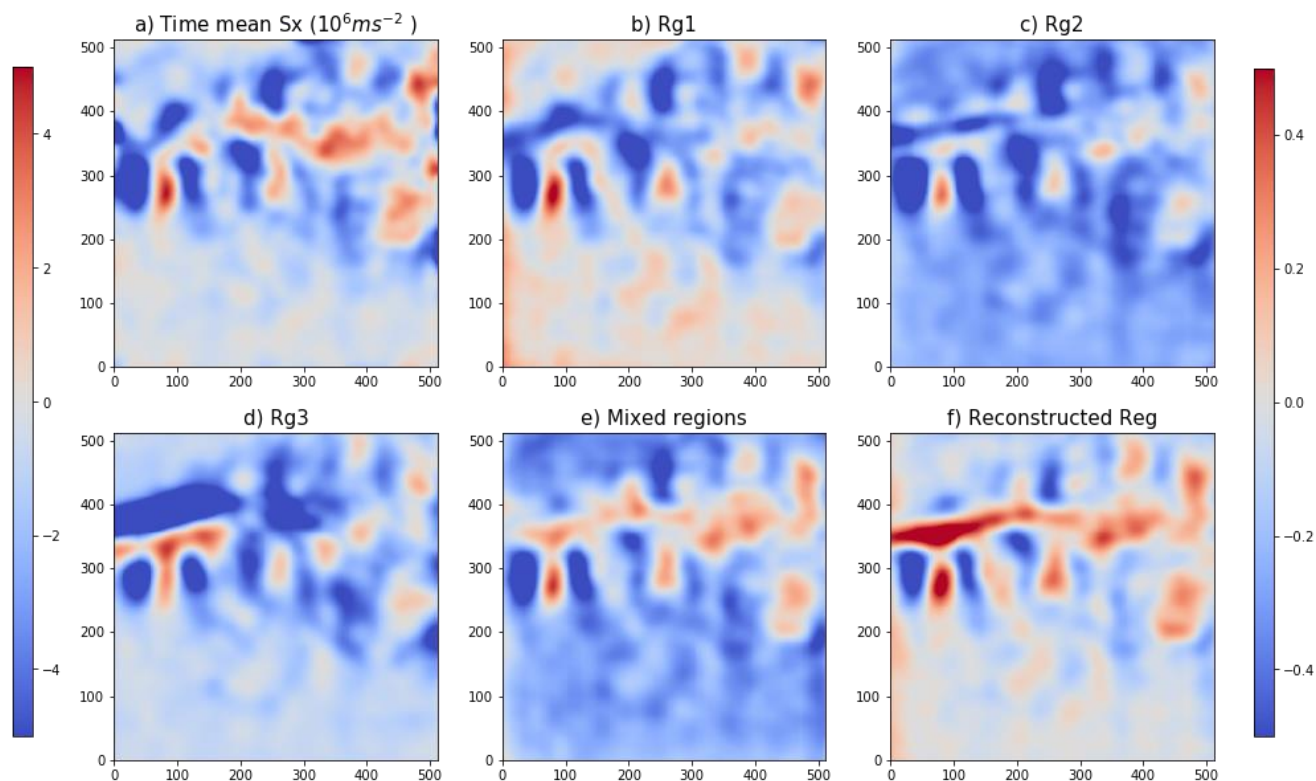
## 3.2 The Realistic simulation: the GS region

### Non-Local Predictions

- Snapshot of  $S_x$



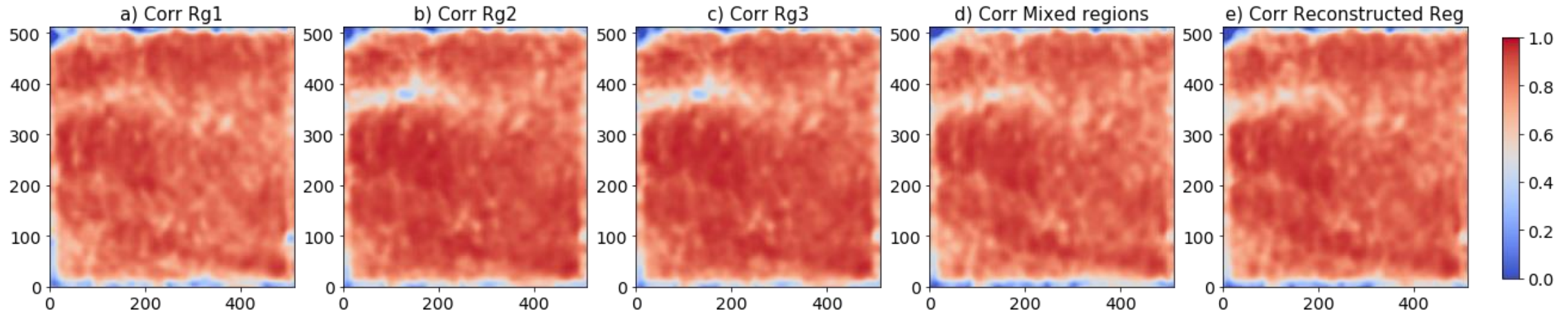
- Time mean of  $S_x$



## 3.2 The Realistic simulation: the GS region

### Non-Local Predictions

- **Correlation between true  $S_x$  and prediction**



Overall averaged:

0.86

0.85

0.73

0.85

0.84

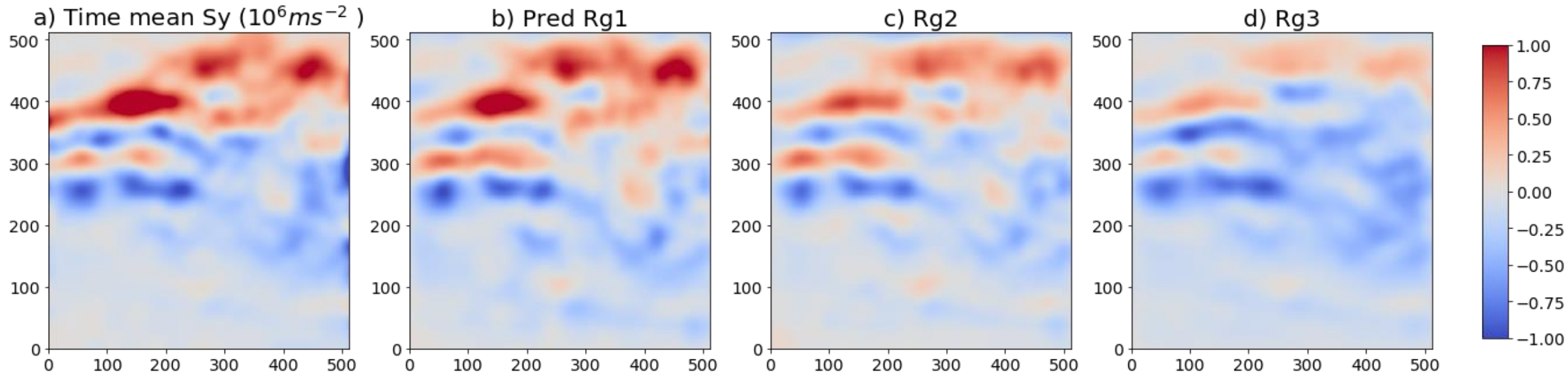
- • Correlation decreases visibly along the path of the jet near the western boundary.
- Better prediction in the Southern in Region 2, 3



## 3.2 The Realistic simulation: the GS region

### Non-Local Predictions

- Time mean of  $S_y$

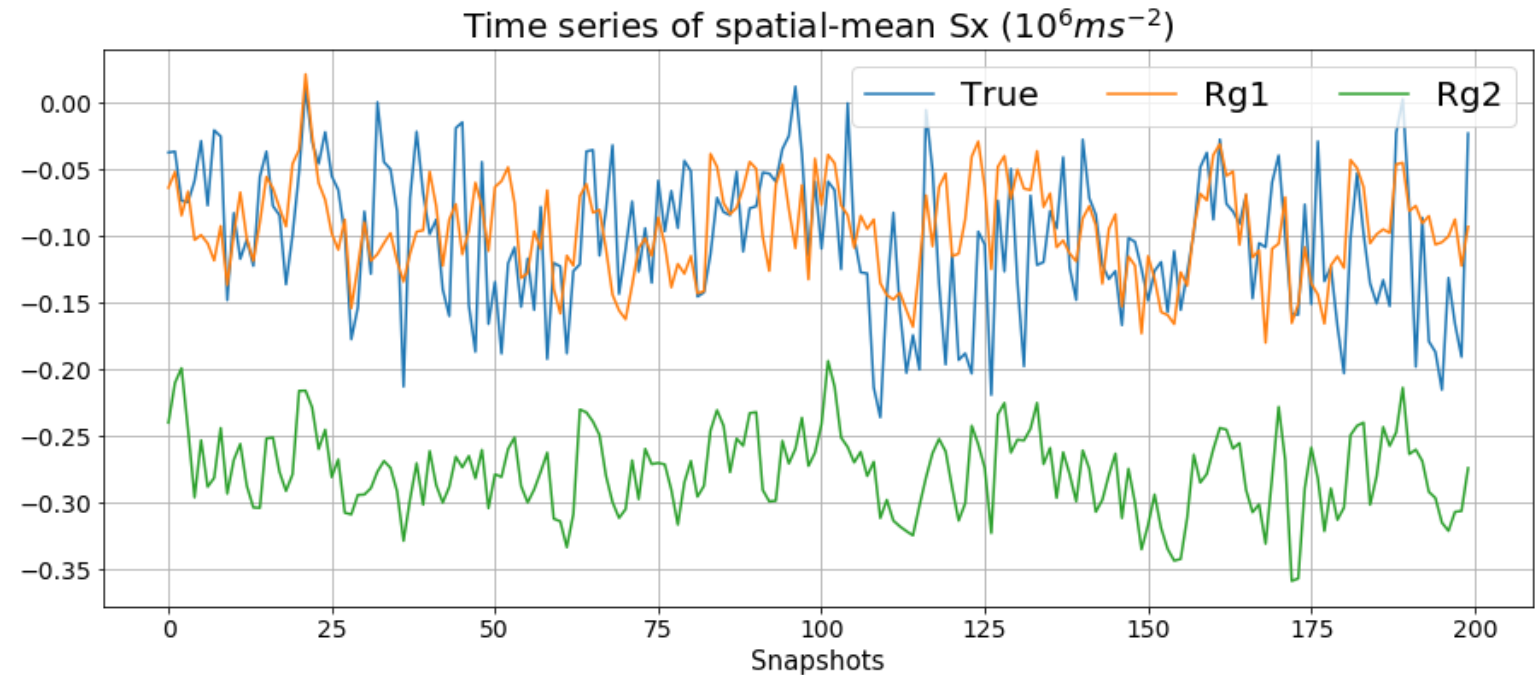
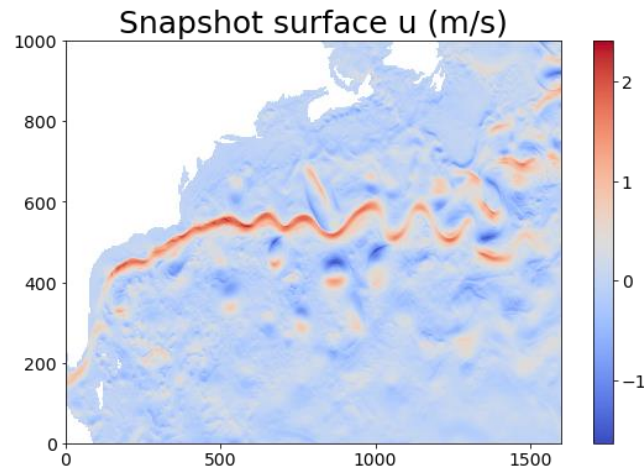


## 3.2 The Realistic simulation: the GS region

### Conservation of energy



- For a whole simulation domain:  
a zero spatially-integrated momentum tendency
- In extracted region here:  
Small amount of negative momentum

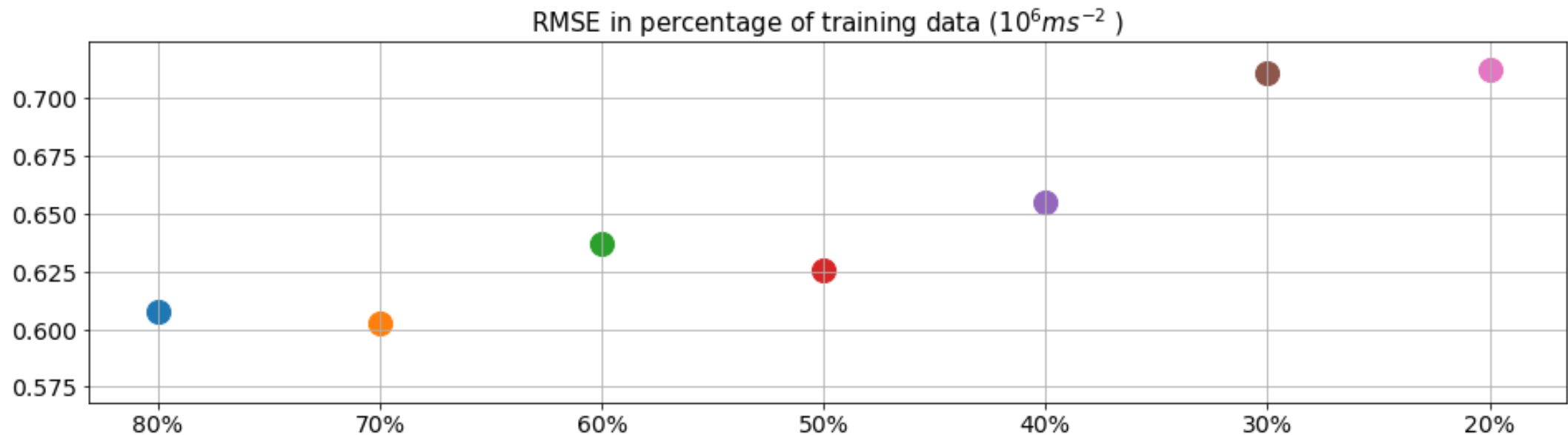


## 3.2 The Realistic simulation: the GS region

### Sensitivity of CNNs

- The amount of training data :

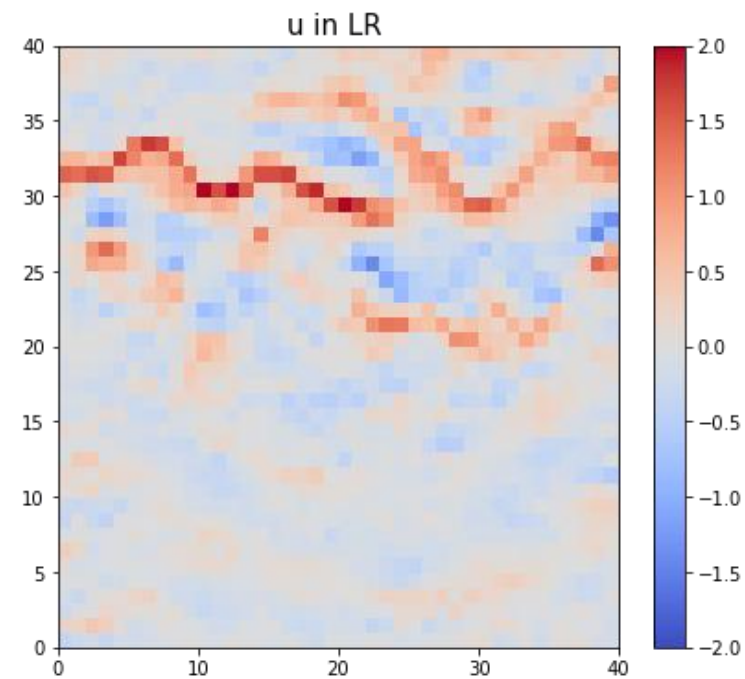
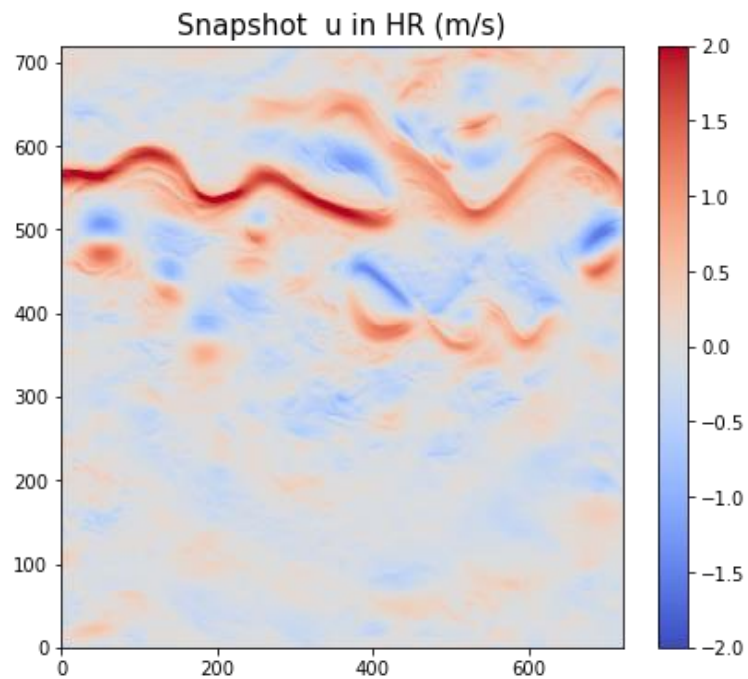
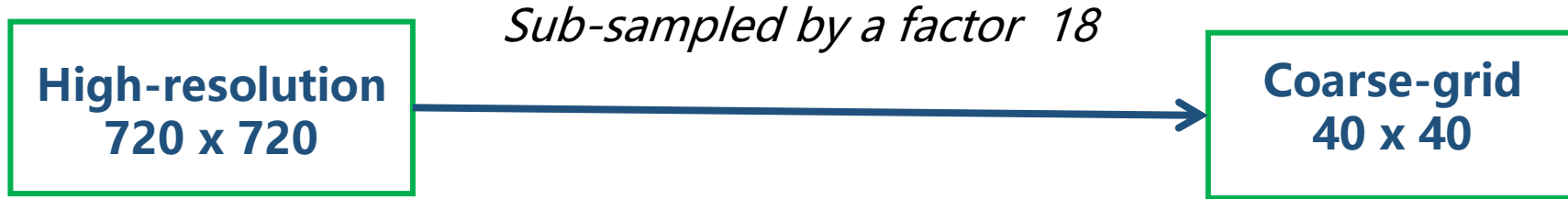
- • BM 18 : 9-years daily training data, and 1-year validation
- Here, 800-snapshots training and 200 for validation





### 3.3. Implementation in low-resolution

#### Training Strategy



### 3.3. Implementation in low-resolution

#### Training Strategy

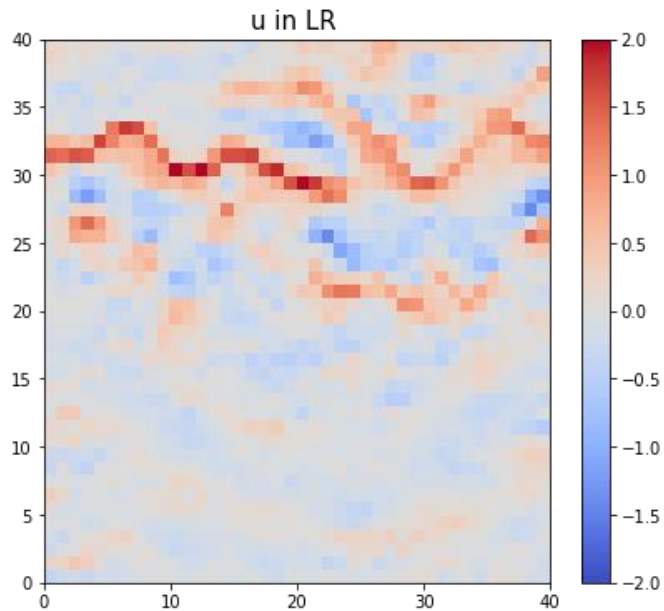
**Total Dataset :**

Training dataset  
(60%)

Validation  
(20%)

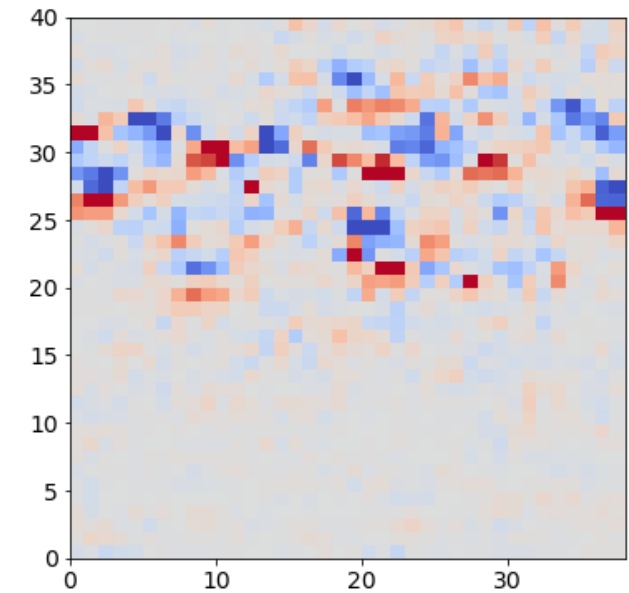
Test dataset  
(20%)

Training data :  $u$   
(40 x 40)



CNNs

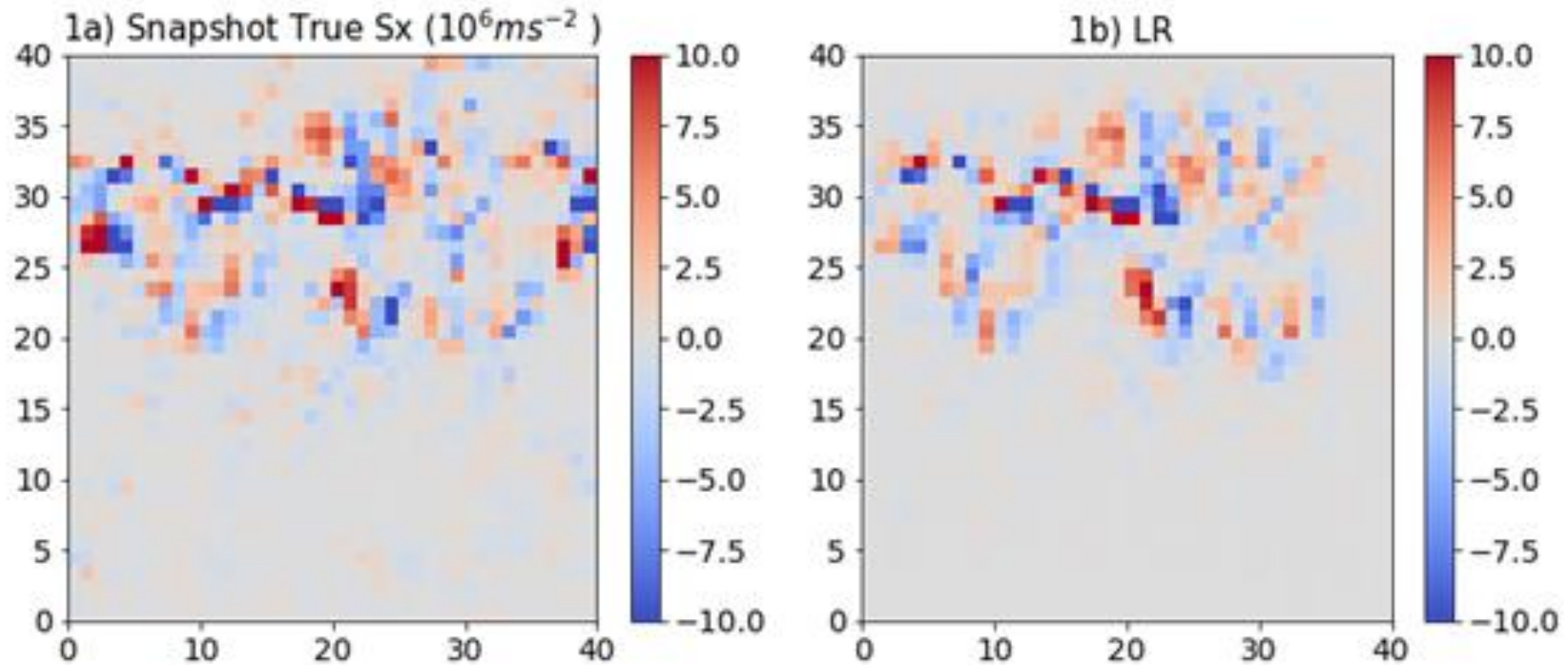
Prediction:  $Sx$   
(40 x 40)



### 3.3. Implementation in low-resolution

#### Prediction

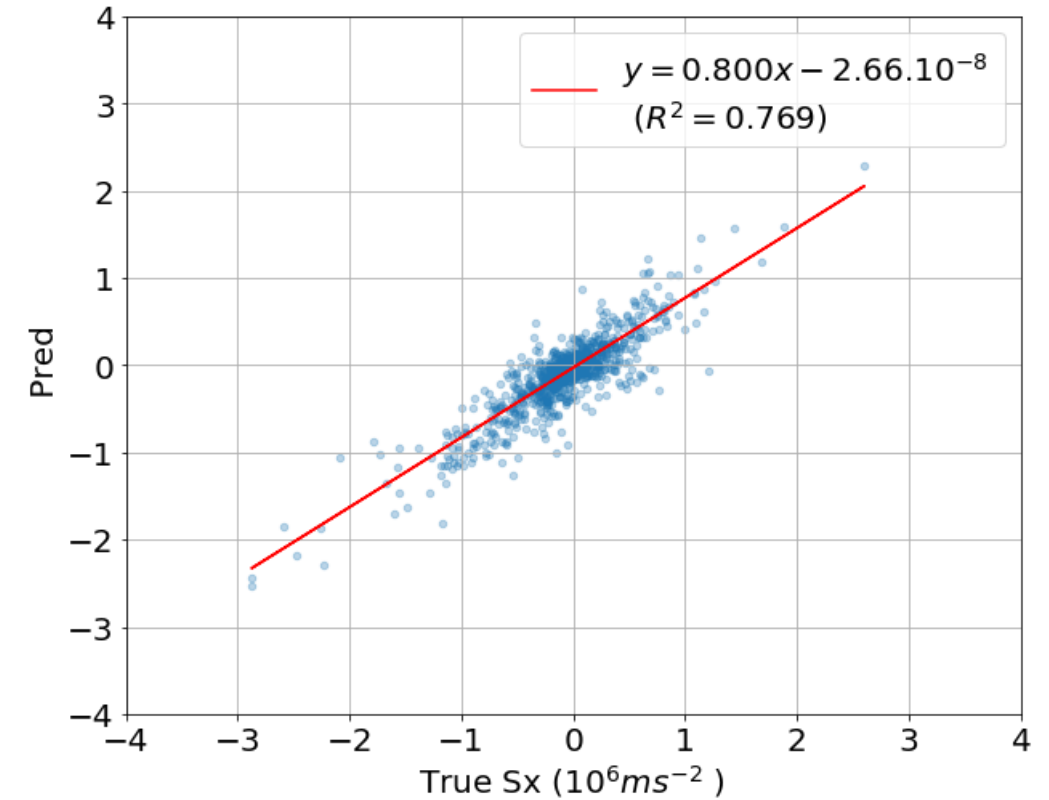
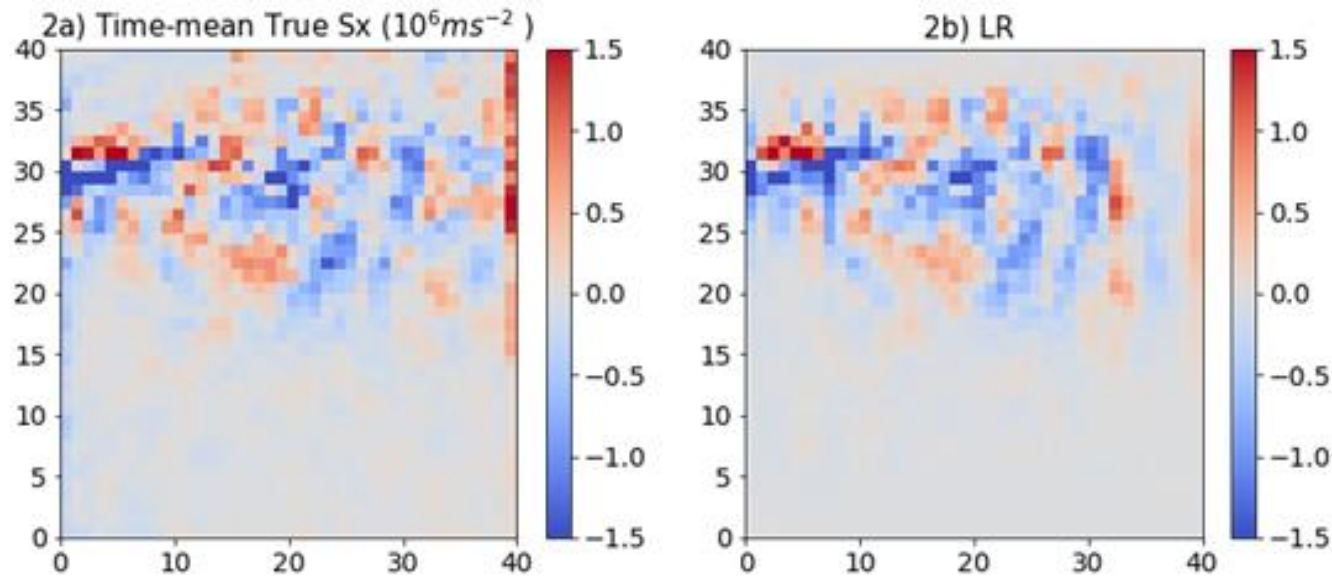
- Snapshot of  $S_x$



### 3.3. Implementation in low-resolution

#### Prediction

#### Time-mean of Sx

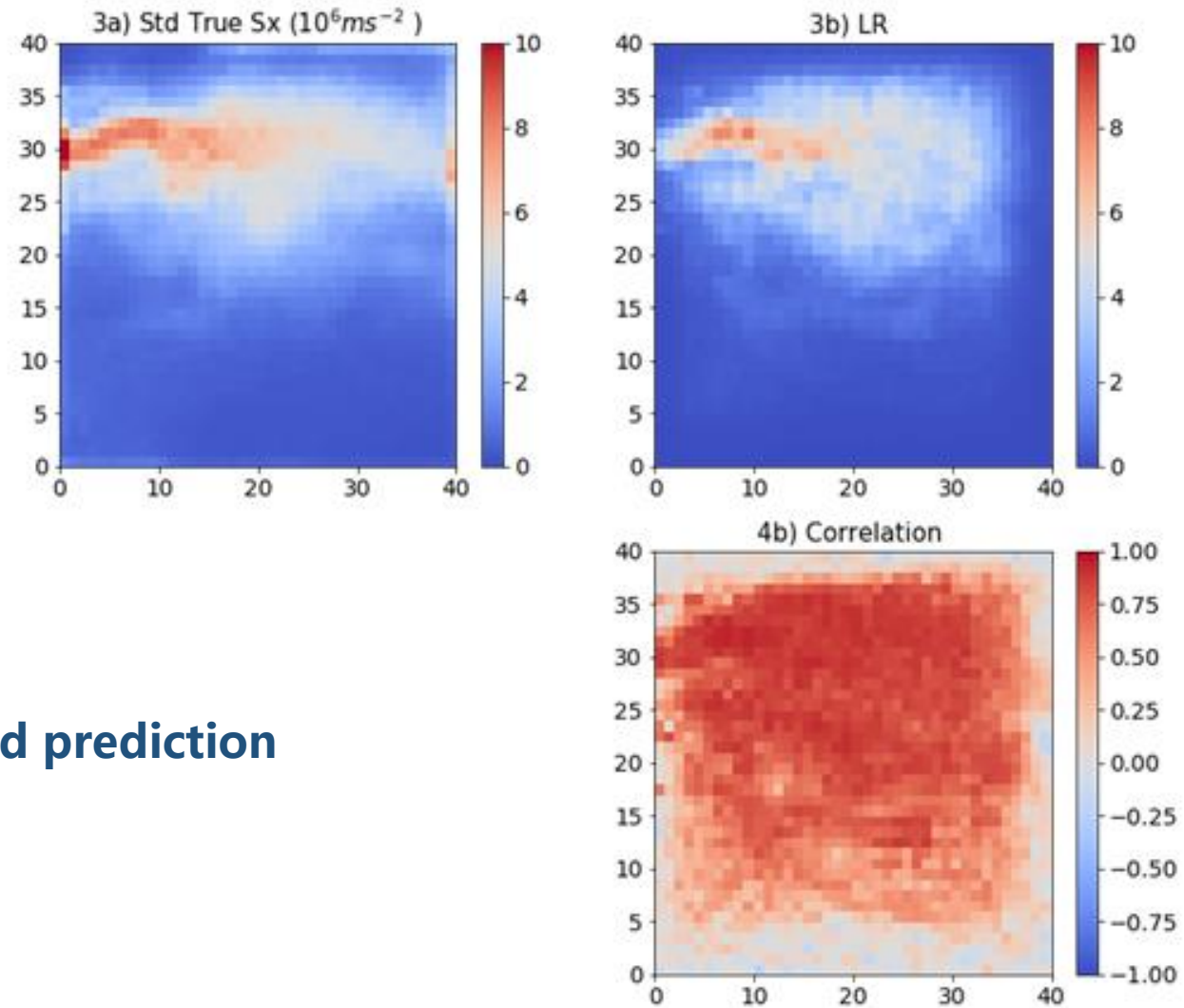


Scatterplot between time-averaged true Sx and corresponding prediction

### 3.3. Implementation in low-resolution

#### Prediction

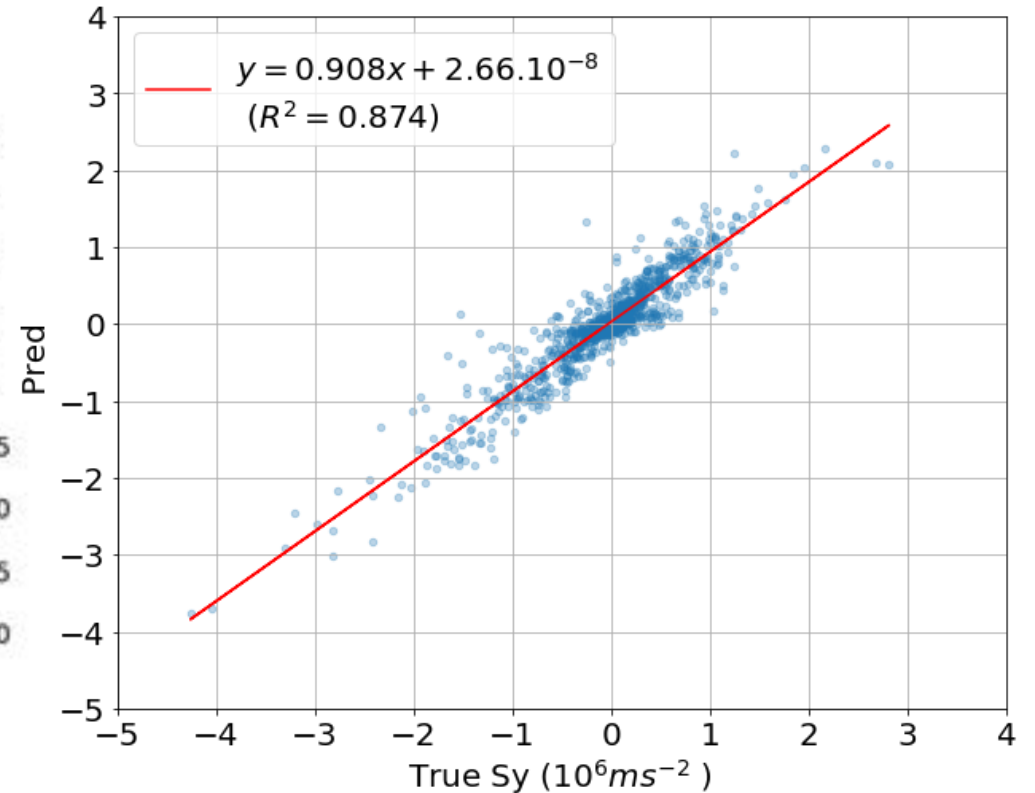
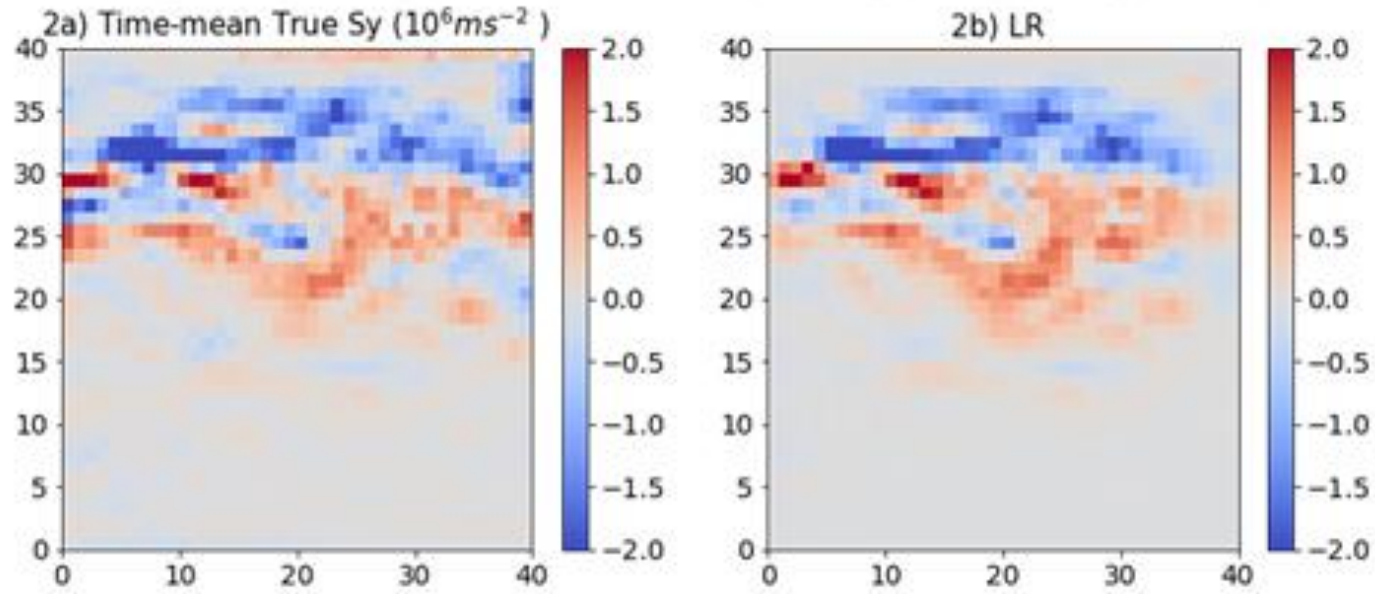
- Standard deviation of  $S_x$
- Correlation between true  $S_x$  and prediction



### 3.3. Implementation in low-resolution

#### Prediction

#### Time-mean of Sy



Scatterplot between time-averaged true Sy and corresponding prediction



PART Four  
Conclusion



## 4. Conclusion

1. CNNs can predict the spatial and temporal variability of the eddy momentum forcing in high-resolution. A limited amount of data is sufficient for good performance.
2. Using sub-sampled data from high-resolution, CNNs can accurately represent both the spatial and temporal variability of the eddy momentum forcing comparable to the high-resolution model.
3. Potential in using machine learning as an eddy parameterization to augment the low-resolution ocean models in the future.