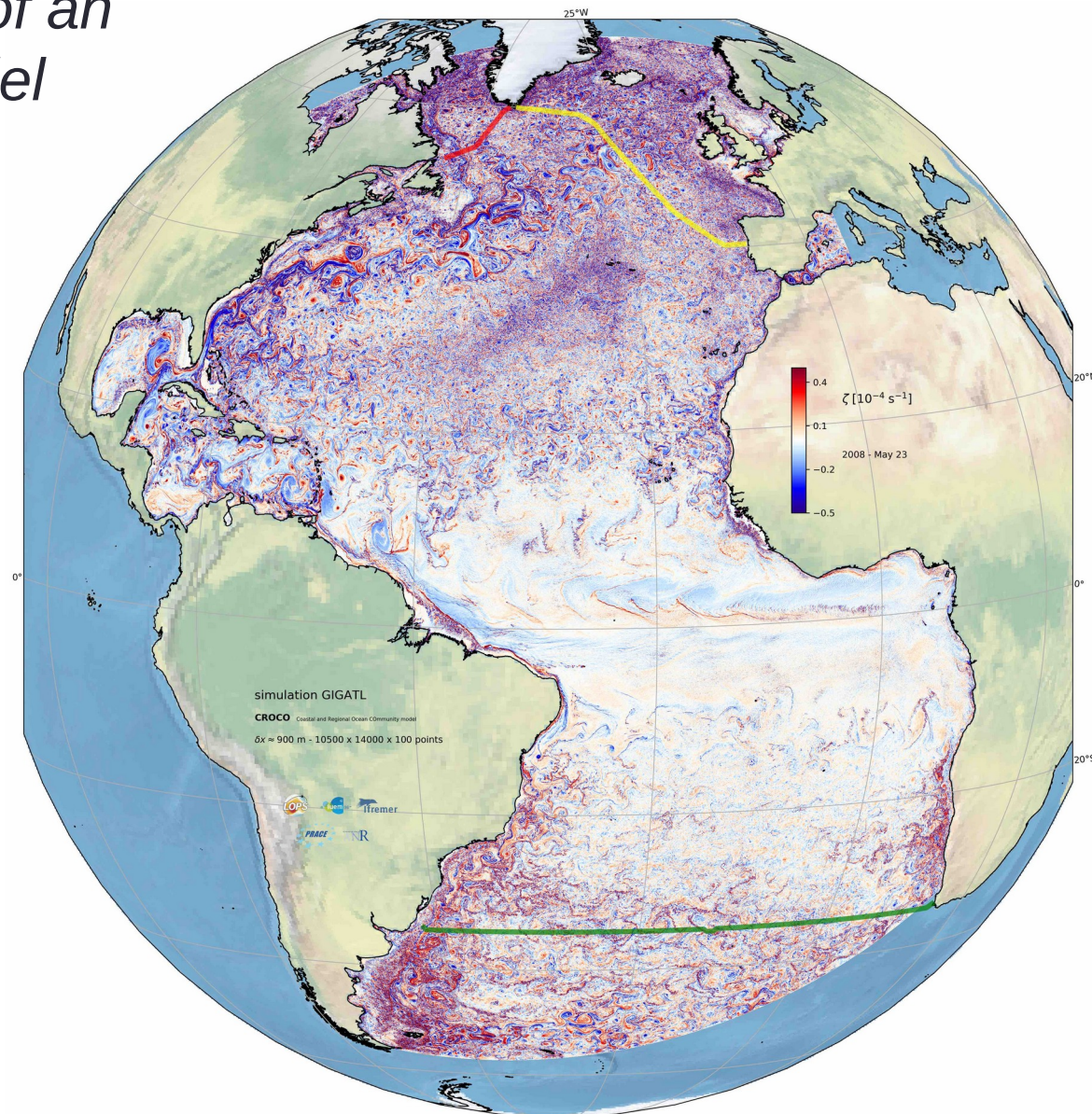


Numerical Modelling

Jonathan GULA
gula@univ-brest.fr

*the anatomy of an
ocean model*



- **Lesson 1 : [D109]**

- Introduction
- Equations of motions
- *Activity 1 [run an ocean model]*

- **Lesson 2 : [B012]**

- Horizontal Discretization
- *Activity 2 [Dynamics of an ocean gyre]*

- **Lesson 3 : [B012]**

- Presentation of the model CROCO
- Dynamics of the ocean gyre
- *Activity 2 [Dynamics of an ocean gyre]*

- **Lesson 4 : [D109]**

- Numerical schemes
- *Activity 3 [Impacts of numerics]*

- **Lesson 5 : [D109]**

- Vertical coordinates
- *Activity 3 [Impact of topography]*

- **Lesson 6 : [D109]**

- Boundary Forcings
- *Activity 4 [Design a realistic simulation]*

- **Lesson 7 : [D109]**

- Diagnostics and validation
- *Activity 5 [Analyze a realistic simulation]*

- **Lesson 8 : [D109]**

- *Work on your projet*

Presentations and material
will be available at :

jgula.fr/ModNum/

Useful references

Extensive courses:

- MIT:
<https://ocw.mit.edu/courses/earth-atmospheric-and-planetary-sciences/12-950-atmospheric-and-oceanic-modeling-spring-2004/lecture-notes/>
- Princeton: https://stephengriffies.github.io/assets/pdfs/GFM_lectures.pdf

Overview on ocean modelling and current challenges:

- Griffies et al., 2000, Developments in ocean climate modelling, Ocean Modelling.
<http://jgula.fr/ModNum/Griffiesetal00.pdf>
- Griffies, 2006, "Some Ocean Model Fundamentals", In "Ocean Weather Forecasting: An Integrated View of Oceanography", 2006, Springer Netherlands. http://jgula.fr/ModNum/Griffies_Chapter.pdf
- Fox-Kemper et al, 19, "Challenges and Prospects in Ocean Circulation Models"
<http://jgula.fr/ModNum/FoxKemperetal19.pdf>

ROMS/CROCO:

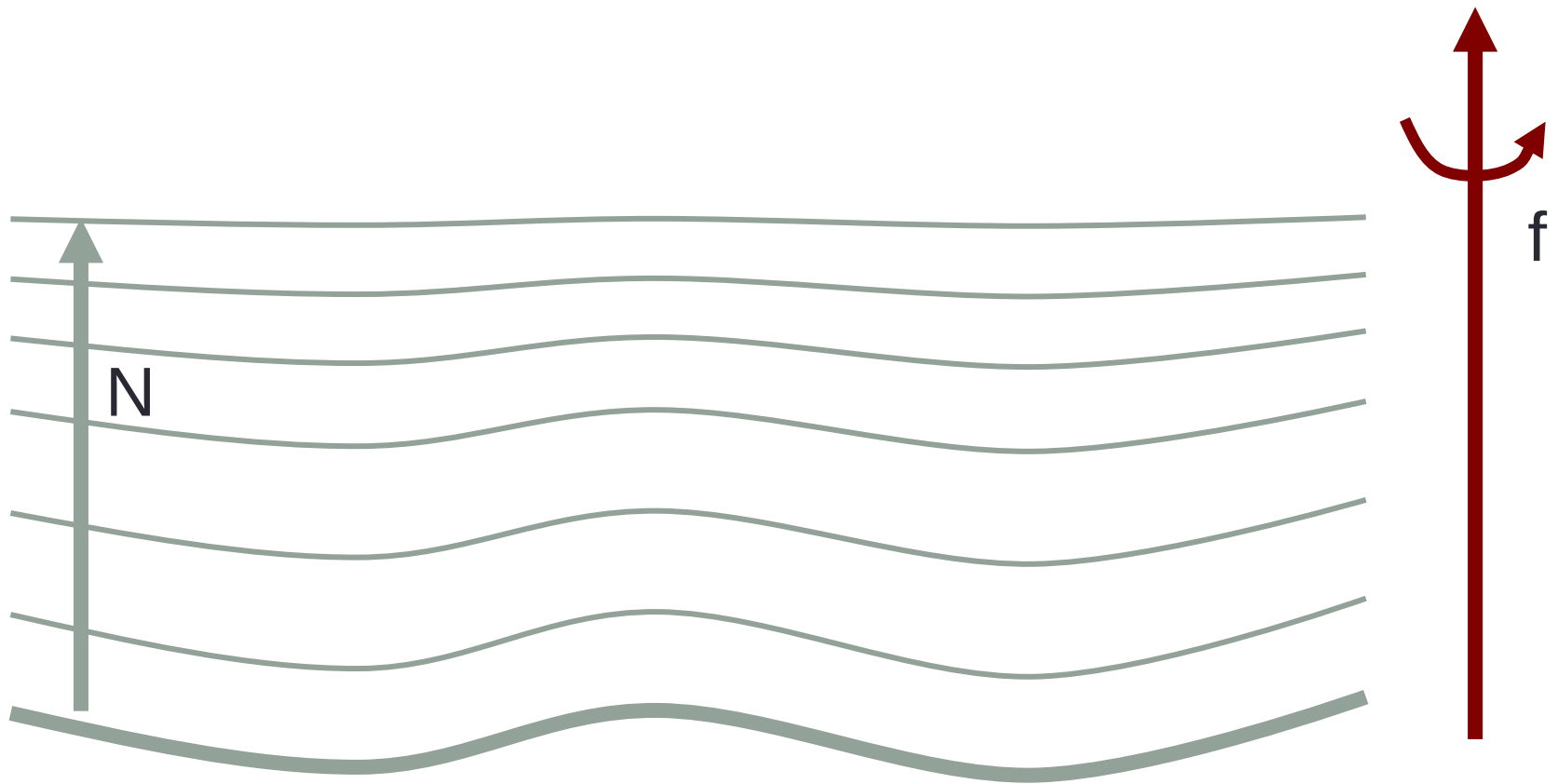
- <https://www.myroms.org/wiki/>
- Shchepetkin, A., and J. McWilliams, 2005: The Regional Oceanic Modeling System (ROMS): A split-explicit, free-surface, topography-following- coordinate ocean model. Ocean Modell.
<http://jgula.fr/ModNum/ShchepetkinMcWilliams05.pdf>

#1 Which Equations?

Which Equations?

(See chapter 3 of Cushman-Roisin and Beckers)

Ingredients : rotation + stratification



Which Equations?

(See chapter 3 of Cushman-Roisin and Beckers)

-

-

-

-

-

[XX equations for the XX variables: ...]

Which Equations?

(See chapter 3 of Cushman-Roisin and Beckers)

- Momentum equations (3d)
- Conservation of mass
- Conservation of heat
- Conservation of salinity
- Equation of state :

$$\frac{D\vec{u}}{Dt} = \dots$$

$$\partial_t \rho + \nabla \cdot (\rho \vec{u}) = 0$$

$$\frac{DT}{Dt} = \mathcal{S}_T$$

$$\frac{DS}{Dt} = \mathcal{S}_S$$

$$\rho = \rho(T, S, p)$$

[7 equations for the 7 variables: u,v,w,p,T,S, ρ]

Which Equations?

(See chapter 3 of Cushman-Roisin and Beckers)

- Momentum equations (3d)
- Conservation of mass

$$\frac{D\vec{u}}{Dt} = \dots$$

$$\partial_t \rho + \nabla \cdot (\rho \vec{u}) = 0$$

- Conservation of heat
- Conservation of salinity
- Equation of state :

$$\frac{DT}{Dt} = \mathcal{S}_T$$

$$\frac{DS}{Dt} = \mathcal{S}_S$$

$$\rho = \rho(T, S, p)$$

[7 equations for the 7 variables: u,v,w,p,T,S, ρ]

→ Cannot be integrated forward in time consistently

We need further approximations

Which Equations?

(See chapter 3 of Cushman-Roisin and Beckers)

- The different approximations to obtain HPE:

- Adiabatic motion

$$\partial_{\theta}\rho|_{S,P}=\partial_S\rho|_{\theta,P}=0$$

- Boussinesq approximation

(Incompressible flow)

$$\rho(x,y,z,t)=\rho_0+\rho'(x,y,z,t)$$

- Hydrostatic approximation

$$\delta=\frac{H}{L}=\frac{W}{U}\ll 1$$

- Traditional approximation

(Horizontal Coriolis)

$$(\tilde{f} w, \tilde{f} u)\ll(fu, fv)$$

Equations for momentum/mass?

- Navier-Stokes Equations (NS)
- Non-hydrostatic Primitive Equations (NH)
- Hydrostatic Primitive Equations (PE)
- Shallow-water (SW)
- Quasi-geostrophic (QG)
- 2D Euler equations
- Etc.

Type of models

Navier
Stokes

- DNS = Direct Numerical Simulation
- LES = Large Eddy Simulation

PE

- PE = Primitive Equations models

SW

- SW = Shallow-Water models

SQG

- SQG = Surface Quasi-Geostrophic models

QG

- QG = Quasi-Geostrophic models
- Etc.

CFD

Process
studies

Ocean
Circulation
Models

Idealized
models

Equations for momentum/mass?

Navier-Stokes Equations:

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + g\vec{k} = -\frac{\vec{\nabla} P}{\rho} + \vec{\mathcal{F}}$$

Momentum equations

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$

Mass conservation
(no source/sink)

Equations for momentum/mass?

Navier-Stokes Equations:

$$\underbrace{\frac{\partial \vec{u}}{\partial t}}_{\text{Time variation}} + \underbrace{\vec{u} \cdot \vec{\nabla} \vec{u}}_{\text{Advection (inertia)}} + \underbrace{2\vec{\Omega} \times \vec{u}}_{\text{Rotation}} + \underbrace{g\vec{k}}_{\text{Gravity}} = \underbrace{-\frac{\vec{\nabla} P}{\rho}}_{\text{Pressure gradient}} + \underbrace{\vec{\mathcal{F}}}_{\text{Forcings + Dissipation}}$$

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$

Mass conservation
(no source/sink)

Equations for momentum/mass?

Navier-Stokes Equations:

Linearized momentum equations	$\rho_0 \frac{\partial \vec{u}}{\partial t} = -\vec{\nabla} P$
+ continuity equation	$\frac{\partial P}{\partial t} = -\rho_0 c_s^2 \vec{\nabla} P \cdot \vec{u}$
+ adiabatic motion :	
= Acoustic modes (sound waves)	$\partial_{tt} P = c_s^2 \nabla^2 P$

With $c_s \approx 1500 \text{ m s}^{-1}$ in water,
a model requires a very small time-step to solve these equations.

→ *Ex: sound waves would take about 1/30 sec
to cross a 50-m long swimming pool*

Equations for momentum/mass?

Boussinesq Approximation:

Density perturbations small compared to mean background value:

$$\rho = \rho_0 + \rho' \qquad \rho' \ll \rho_0$$

Linearize all terms involving a product with density,
except the gravity term which is already linear:

$$\rho \vec{u} \rightarrow \rho_0 \vec{u}$$

$$\rho g \rightarrow \rho g$$

Equations for momentum/mass?

Boussinesq Approximation :

[+ incompressibility or adiabatic]

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$



Continuity equation

$$\begin{aligned} \partial_t \rho + \vec{\nabla} \cdot \rho \vec{u} &= \partial_t \rho + \rho \vec{\nabla} \cdot \vec{u} + \vec{u} \cdot \vec{\nabla} \rho \\ &= (\rho_0 + \rho') \vec{\nabla} \cdot \vec{u} + D_t \rho' \\ &\sim \rho_0 \vec{\nabla} \cdot \vec{u} \end{aligned}$$

$$\vec{\nabla} \cdot \vec{u} = 0$$

Mass conservation → Volume conservation

Equations for momentum/mass?

Non hydrostatic boussinesq (NH):

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + \frac{\rho}{\rho_0} g \vec{k} = -\frac{\vec{\nabla} P}{\rho_0} + \frac{\vec{\mathcal{F}}}{\rho_0} + \frac{\vec{\mathcal{D}}}{\rho_0}$$

$$\vec{\nabla} \cdot \vec{u} = 0$$

Easier to solve than Navier-Stokes, but still requires to invert a 3d elliptic equation for P (computationally expansive)

Equations for momentum/mass?

Hydrostatic balance:

The vertical component of the Boussinesq momentum equations is

$$\partial_t w + \vec{u} \cdot \vec{\nabla} w + 2\Omega \cos \phi u + \boxed{\frac{\rho}{\rho_0} g} = \frac{1}{\rho_0} \partial_z P + F_w + D_w$$

For long horizontal motions ($L \gg H$) the dominant balance is

$H \sim 3000 \text{ m}$
 $L \sim 3000 \text{ km}$

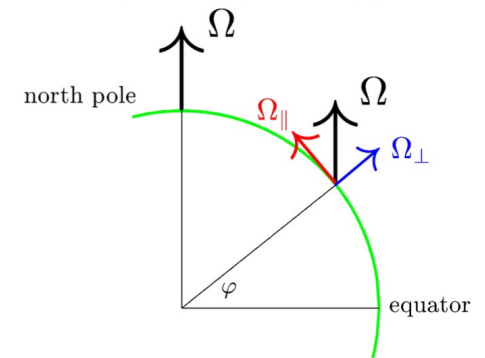
$$\frac{\partial P}{\partial z} = -\rho g$$

Such that pressure is just a vertical integral:

$$P = \int_z^\eta g \rho dz$$

Equations for momentum/mass?

Traditional approximation
= neglect horizontal Coriolis term



$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + \frac{\rho}{\rho_0} g \vec{k} = -\frac{\vec{\nabla} P}{\rho_0} + \vec{\mathcal{F}} + \vec{\mathcal{D}}$$



$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + f\vec{k} \times \vec{u} + \frac{\rho}{\rho_0} g \vec{k} = -\frac{\vec{\nabla} P}{\rho_0} + \vec{\mathcal{F}} + \vec{\mathcal{D}}$$

Equations for momentum/mass?

Hydrostatic Primitive Equations (PE)

- 2d momentum with Boussinesq approximation:

$$\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - f v = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$$

$$\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + f u = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$$

- Hydrostatic:
$$\frac{\partial P}{\partial z} = -\rho g$$

- Continuity equation for an incompressible fluid:
$$\vec{\nabla} \cdot \vec{u} = 0$$

Equations for PE Ocean Models

Hydrostatic Primitive Equations (PE)

- 2d momentum with Boussinesq approximation:

$$\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - f v = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$$

$$\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + f u = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$$

$$\frac{\partial P}{\partial z} = -\rho g$$

- Hydrostatic:

- Continuity equation for an incompressible fluid: $\vec{\nabla} \cdot \vec{u} = 0$

- Conservation of heat and salinity $\frac{DT}{Dt} = \mathcal{S}_T$ $\frac{DS}{Dt} = \mathcal{S}_S$

- Equation of state : $\rho = \rho(T, S, z)$

Equations for PE Ocean Models

Hydrostatic Primitive Equations (PE)

- 4 prognostics equations for u , v , T , S
- 3 diagnostics equations for w , ρ , P

Equations for PE Ocean Models

Hydrostatic Primitive Equations (PE)

- 2d momentum with Boussinesq approximation:

$$\begin{aligned} \frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - f v &= -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u \\ \frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + f u &= -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v \end{aligned}$$

?

- Hydrostatic:

$$\frac{\partial P}{\partial z} = -\rho g$$

- Continuity equation for an incompressible fluid:

$$\vec{\nabla} \cdot \vec{u} = 0$$

- Conservation of heat and salinity

$$\frac{DT}{Dt} = \mathcal{S}_T \quad \frac{DS}{Dt} = \mathcal{S}_S$$

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Equations for PE Ocean Models

Hydrostatic Primitive Equations (PE)

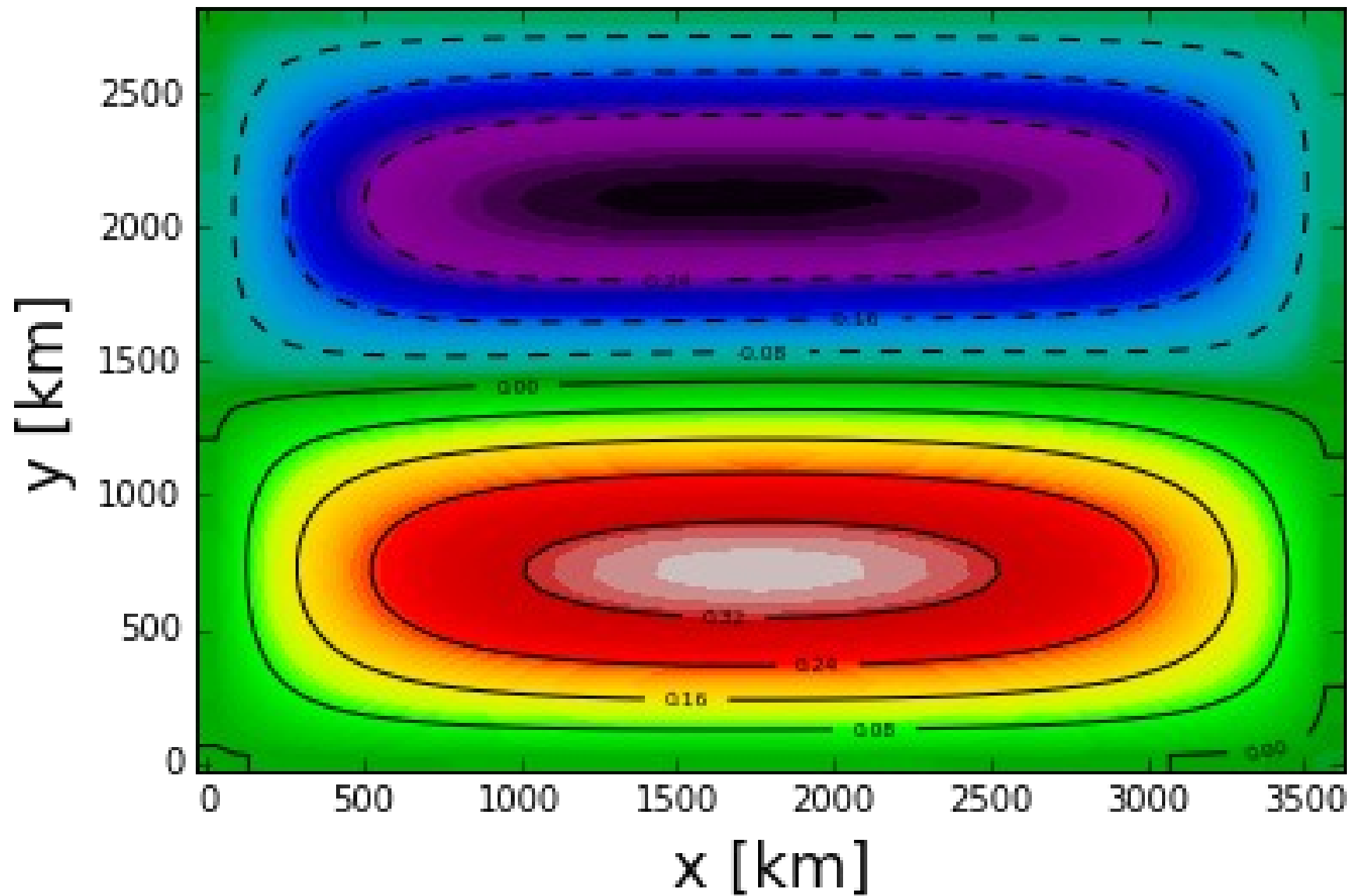
- 4 prognostics equations for u , v , T , S
- 3 diagnostics equations for w , ρ , P

+ Forcings (wind, heat flux)

+ sub-grid scale parameterizations (bottom drag, mixing, etc.)

Activity 1 – Run an idealized ocean basin

SSH



Activity 1 – Run an idealized ocean basin

- **Jobcomp** (compilation)
- **cppdefs.h** (Numerical/physical options)
- **param.h** (gris size/ parallelisation)
- **croco.in** (choice of variables, parameter values, etc.)

1) Preparing and compiling the model

For that use the the jobcomp bash file
`./jobcomp`

1. Set library path
2. Automatic selection of option accordingly the platform used
3. Use of makefile
 - C-preprocessing step : `.F` \Rightarrow `.f` using the CPP keys definitions (in `cppdefs.h` file, customization of the code)
 - Compilation step : `.f` \Rightarrow `.o` (object) using Fortran compiler
 - Linking step : link all the `.o` file and the library (Netcdf, MPI, AGRIF)
--
 - --> produce the executable **roms**

1) Preparing and compiling the model

Edit the param.h and cppdefs.h file to set-up the model

param.h defines the size of the arrays in ROMS:

```
...  
#elif defined REGIONAL  
# if defined BENGUELA  
    parameter (LLm0=23, MMm0=31, N=32) <---- Southern Benguela test Model  
# else  
    parameter (LLm0=??, MMm0=??, N=??)  
# endif  
...
```

Given by running make_grid

Southern Benguela test Model

Defined in romstools_param.m

cppdefs.h:

- Basic options
- More advanced options

- Define CPP keys used by the C-preprocessor when compiling the model.
- Reduce the code to its minimal size: fast compilation.
- Avoid FORTRAN logical statements: efficient coding.

1) Preparing and compiling the model

View
cppdef.h
file



```
!-----  
!          BASIC OPTIONS  
!-----  
*/  
/*          Configuration Name */  
# define BENGUELA  
/*          Parallelization */  
# undef OPENMP  
# undef MPI  
/*          Embedding */  
# undef AGRIF  
/*          Open Boundary Conditions */  
# undef TIDES  
# define OBC_EAST  
# undef OBC_WEST  
# define OBC_NORTH  
# define OBC_SOUTH  
*/  
          Embedding conditions */  
# ifdef AGRIF  
#   undef AGRIF_OBC_EAST  
#   define AGRIF_OBC_WEST  
#   define AGRIF_OBC_NORTH  
#   define AGRIF_OBC_SOUTH  
# endif  
/*          Applications */  
# undef BIOLOGY  
# undef FLOATS  
# undef STATIONS  
# undef PASSIVE_TRACER  
# undef SEDIMENTS  
# undef BBL
```

```
!-----  
!          MORE ADVANCED OPTIONS  
!-----  
*/  
/*          Model dynamics */  
# define SOLVE3D  
# define UV_COR  
# define UV_ADV  
# ifdef TIDES  
#   define SSH_TIDES  
#   define UV_TIDES  
#   define TIDERAMP  
# endif  
/*          Grid configuration */  
# define CURVGRID  
# define SPHERICAL  
# define MASKING  
/*          Input/Output & Diagnostics */  
# define AVERAGES  
# define AVERAGES_K  
# define DIAGNOSTICS_TS  
# define DIAGNOSTICS_UV  
/*          Equation of State */ ...  
/*          Surface Forcing */ ...  
/*          Lateral Forcing */ ...  
/*          Input/Output & Diagnostics */ ...  
*          Bottom Forcing */ ...  
/*          Point Sources - Rivers */ ...  
/*          Lateral Mixing */ ...  
/*          Vertical Mixing */ ...  
/*          Open Boundary Conditions */ ...  
/*          Embedding conditions */ ...
```

2) Running the model

The namelist roms.in

roms.in provides the run time parameters for ROMS:

```
title:
    Southern Benguela
time_stepping: NTIMES dt[sec] NDTFAST NINFO
    480 5400 60 1
S-coord: THETA_S, THETA_B, Hc (m)
    6.0d0 0.0d0 10.0d0
grid: filename
    ROMS_FILES/roms_grd.nc
forcing: filename
    ROMS_FILES/roms_frc.nc
bulk_forcing: filename
    ROMS_FILES/roms_blk.nc
climatology: filename
    ROMS_FILES/roms_clm.nc
boundary: filename
    ROMS_FILES/roms_bry.nc
initial: NRREC filename
    1
    ROMS_FILES/roms_ini.nc
restart: NRST, NRPFRST / filename
    480 -1
    ROMS_FILES/roms_rst.nc
```

Warning ! These should be identical to the ones in romstools_param.m

```
history: LDEFHIS, NWRT, NRPFHIS / filename
```

```
T 480 0
```

```
ROMS_FILES/roms_his.nc
```

```
averages: NTS AVG, NAVG, NRPFAVG / filename
```

```
1 48 0
```

```
ROMS_FILES/roms_avg.nc
```

```
primary_history_fields: zeta UBAR VBAR U V wrtT(1:NT)
```

```
T F F F F 10*F
```

```
auxiliary_history_fields: rho Omega W Akv Akt Aks HBL Bostr
```

```
F F F F F F F F
```

```
primary_averages: zeta UBAR VBAR U V wrtT(1:NT)
```

```
T T T T T 10*T
```

```
auxiliary_averages: rho Omega W Akv Akt Aks HBL Bostr
```

```
F T T F T F T T
```

```
rho0:
```

```
1025.d0
```

```
lateral_visc: VISC2, VISC4 [m^2/sec for all]
```

```
0. 0.
```

```
tracer_diff2: TNU2(1:NT) [m^2/sec for all]
```

```
10*0.d0
```

```
bottom_drag: RDRG [m/s], RDRG2, Zob [m], Cdb_min, Cdb_max
```

```
0.0d-04 0.d-3 1.d-2 1.d-4 1.d-1
```

```
gamma2:
```

```
1.d0
```

```
sponge: X_SPONGE [m], V_SPONGE [m^2/sec]
```

```
100.e3 800.
```

```
nudg_cof: TauT_in, TauT_out, TauM_in, TauM_out [days for all]
```

```
1. 360. 10. 360.
```

Activity 1 – Run an idealized ocean basin

- **param.h**

```
parameter (LLm0=60, MMm0=50, N=10)
```

- **cppdefs.h**

```
# define UV_COR  
# define UV_VIS2  
# define TS_DIF2  
  
# define ANA_GRID  
# define ANA_INITIAL
```

- **ana_grid.F**

```
f0=1.E-4  
beta=0
```

- **croco.in**

```
bottom_drag:  RDRG(m/s),  RDRG2, Zob [m],  Cdb_min, Cdb_max  
              3.e-4      0.    0.    0.    0.  
gamma2:  
              1.  
lin_EOS_cff:  R0 [kg/m3], T0 [Celsius], S0 [PSU], TCOEF [1/Celsius], SCOEF [1/PSU]  
              30.    0.    0.    0.28    0.  
lateral_visc:  VISC2    [m^2/sec]  
              1000.  0.  
tracer_diff2:  TNU2    [m^2/sec]  
              1000.  0.
```

Homework

- For next time:
 - Read <https://www.jgula.fr/ModNum/Stommel48.pdf>
 - Read <https://www.jgula.fr/ModNum/Munk50.pdf>