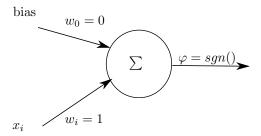
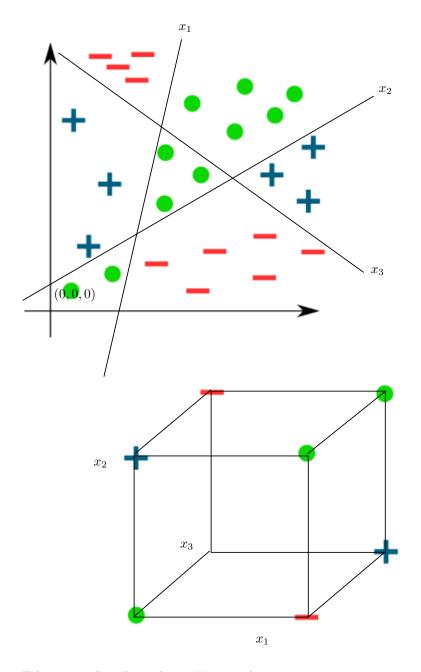
## ML II: Exercise 2

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## Simple Networks



Generalization to higher dimensions: Draw hyperdimensional decision boundaries each dividing the input space into two subspaces. The number of boundaries relates to the dimension of the hypercube.



## **Linear Activation Function**

Using any linear activation function  $\varphi(x)=x$  leads to the following outputs:

$$z_1 = \varphi(B_1 z_0) = B_1 z_0$$

$$z_2 = B_2 z_1 = B_2 B_1 z_0$$
2

This could be replaced by a single layer with the parameters  $B = B_1 B_2$ .

## Weight Decay

1.

$$Loss(w) = Loss_0(w) + \frac{\lambda}{2N} w^{\tau} w$$

$$\frac{\partial Loss}{\partial w} = \frac{\partial}{\partial w} Loss_0 + \frac{\lambda}{N} w$$

$$w = w - \tau \frac{\partial}{\partial w} Loss_0 - \tau \frac{\lambda}{N} w$$

$$= (1 - \frac{\tau \lambda}{N}) w - \tau \frac{\partial}{\partial w} Loss_0$$

$$\to \epsilon = \frac{\tau \lambda}{N}$$

2. The weight decays in proportion to its size. Thus, larger weights are penalized and weights with a small magnitude are preferred which avoids overfitting.

3.

$$Loss(w) = Loss_0(w) + \frac{\lambda}{2N}|w|$$
$$\frac{\partial Loss}{\partial w} = \frac{\partial}{\partial w}Loss_0 + \frac{\lambda}{N}sgn(w)$$
$$w = w - \tau \frac{\partial}{\partial w}Loss_0 - \tau \frac{\lambda}{N}sgn(w)$$

4. Since the biases are fixed and representing the offset, not the curvature of the model, the regularization has little effect on them.