AXIOM Beta Main Board and AXIOM Remote



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AXIOM Beta Main Board

Introduction

Components at Bottom Side

Components at Top Side

Connections

AXIOM Remote

Introduction

General Concepts

Operation

Hardware

Electronics

GUI



AXIOM Beta Main Board

Introduction

- ▶ Equivalent to a PC's motherboard for the camera
- ► A central hub, where all the data from sensors and other interfaces are routed as per need
- ► Hosts two medium-speed shield connectors and two high-speed plugin module slot connectors
- ▶ Bottom side interfaces with the power board, followed by MicroZed board
- ▶ Top side interfaces with the interface board, and shields



- ▶ A Centre Solder-On (CSO) area used to interface chips like orientation sensors, acceleration etc. (as directly behind the image sensor)
- ▶ 2x board connectors (JX1 & JX2) at North and South of board, connect directly to the Zynq SoC GPIOs (on the MicroZed board) through the power board
- ➤ 2x PCIE connectors (North and South), used to interface plugins (USB, HDMI etc.)



- ➤ 2x board connectors (PB-NW & PB-SE), interface with the power board for power and I2C buses (coming from Zynq)
- ▶ 4x Power headers (PWR-XX), to receive various power rails from power board
- ▶ 2x PIC16s (West and East), to interface with the routing fabrics through various interfaces like JTAG, I2C, SPI etc.



- ► A Centre Solder-On (CSO) area
- ▶ 2x board interface connectors (X-WEST & X-EAST) that interface with the interface board
- ➤ 2x pin header connectors each on the West (HDR-XW) and East (HDR-XE) side, to interface with the West shield and East shield respectively
- ▶ 2x Lattice MachXO2 FPGAs (RFW & RFE) used as routing fabrics, to route connections from the shields, plugins and centre area to the Zynq SoC (on MicroZed board)



CSO 8

- ▶ 2x 4 GPIOs, to RFW and RFE
- ▶ 2x power rails, to PWR-XX
- ▶ 2x power rails, to JX1 & JX2



JX1 & JX2

- ▶ Comes from power board, which in turn is from MicroZed
- ▶ 2x 24 LVDS pairs (High speed) as GPIOs
- ▶ 7x BANK-13 LVDS pairs as GPIOs
- ▶ 1x BANK-13 pin as power rail, to RFW and its PIC16
- ➤ 2x JXX pairs as power rails, another pin to RFE and its PIC16
- ▶ Various other control/debug pins and power rails to CSO, PCIEs, Shields etc.



- ▶ Power rails from JXX
- ▶ 6x Zynq LVDS pairs (High speed) each, to JXX
- ▶ 8x GPIOs each, to RFW and RFE
- ▶ 1x I2C bus each, muxed and connected to RFW and its PIC16
- ► I2C bus power supply from JX2



- ➤ 1x I2C bus each, to each PIC16 (Zynq to PIC16 communication)
- ▶ Various power rails, to X-WEST and X-EAST



- ▶ VDD from PWR-NW and PWR-SE
- ► ICSP clock and data through I2C bus, from PB-NW & PB-SE
- ▶ VPP from PB-NW & PB-SE (supply for programming)
- ▶ JTAG, I2C & SPI interface pins (through IO ports), to RFW & RFE
- ▶ Various control signal pins for the FPGAs



- ▶ JTAG, I2C & SPI interface pins, to RFW & RFE
- ▶ 18x LVDS pairs (High speed) each, to JX1 & JX2
- ▶ Various power rails from PB-NW & PB-SE



- ► HDR-NW & HDR-SW form West shield, HDR-NE & HDR-SE form East shield
- ▶ 20x GPIOs (10 North, 10 South) each, to RFW & RFE
- For West shield, 4x LVDS pairs (2 North, 2 South) each, to RFW
- ► For East shield, 4x LVDS pairs (2 North, 2 South) each (High Speed), to JX1 & JX2
- ▶ Power rails from PWR-NW & PWR-SE



RFW 15

- ► Supply for IOs and VCC from PWR-NW
- ► GPIOs from PCIE-NORTH & PCIE-SOUTH
- ► Shield GPIOs from HDR-XW
- ▶ LVDS pairs from HDR-XW
- ▶ GPIOs from Centre area (West)



- ► SPI & JTAG interfaces to X-WEST
- ▶ 2x I2C buses to X-WEST
- ▶ 1x BANK13 LVDS pair, to JX1
- ► SPI & JTAG interfaces to PIC16 (West)
- A common I2C bus to PIC16 (West) as well as the PCIE connectors (muxed)
- ► MachXO2 FPGA controls (DONE, INITN, PROGRAMN, etc.), to PIC16 (West)



RFE 1

- ▶ Supply for IOs and VCC from PWR-SE
- ► Shield GPIOs from HDR-XE
- ► GPIOs from Centre area (East)
- ▶ 2x SPI buses to X-EAST
- ▶ 2x I2C buses to X-EAST



RFE (Cont.)

- ▶ 2x Zynq LVDS pairs, to JX1 & JX2 respectively
- ▶ I2C, SPI & JTAG interfaces to PIC16 (East)
- ► MachXO2 FPGA controls, to PIC16 (East)
- Various unused GPIOs



AXIOM Remote

Introduction

- ► A remote control with buttons, dials and an LCD for menu/settings
- ► Hardware prototype based on a PIC32 CPU and 320x240 pixel LCD
- ► The software runs "bare metal"
- ► There is no graphics acceleration



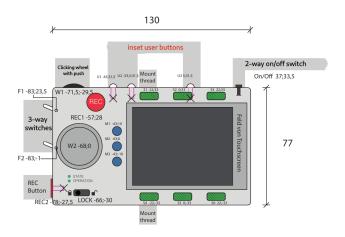


Figure: AXIOM Remote Button Positions



Operation



Figure: AXIOM Remote



- ► Six buttons to select the options
- ► Currently in the new design only "home" and "back" buttons are present
- In the older version there are left/right buttons to change the pages, a page number button to goto a particular page and for the menu items which are not self-explanatory there is a "?" (help) button



Hardware 24

- ▶ PCB Version 2 Prototype
 - ► The second knob is removed
 - ▶ Remove left side rocker switches
 - ► Remove top side pushbuttons
 - ► Having one white LED per pushbutton
 - ▶ 4 more holes to PCB
 - ► Replace slide switches for ON/OFF and LOCK with pushbuttons



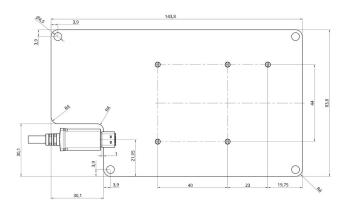


Figure: PCB



Electronics 26

▶ PIC32MZ was chosen as core processor, two PIC16 are used for handling push button, rotary encoder and LED IO

- ▶ 2.8" 320x240 TFT from Adafruit as a display
- ► USB-C Connector
- Currently powered externally via 5V DC supply
- ► The firmware is programmed with a PICkit2 directly into the flash memory



GUI

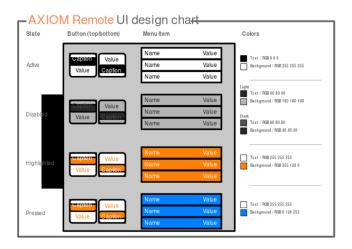


Figure: Color Scheme



27