

NeuroToys

Non-Invasive Brain Computer Interface for Real-Time Robot **Control**

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How can we enable users to control technology effortlessly and intuitively using only their brains?

The challenge:

Current external device control methods (ex: joysticks, remotes) can be restrictive for individuals with mobility impairments or those seeking new ways of interaction.

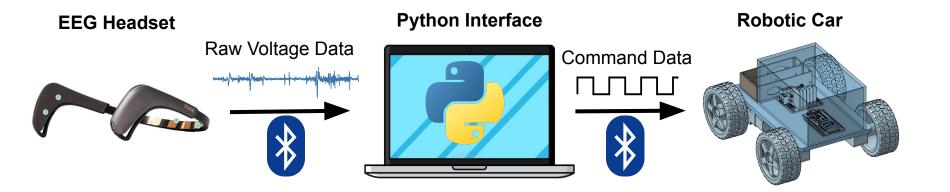
Deliverables Summary:

A <u>non-invasive brain-computer interface (BCI)</u> that translates brainwave patterns into <u>real-time commands</u> for controlling a robotic toy.



Summary of Completed Work





New Headset Adaptation

Switch EEG Headsets: from Neurosky Mindwave to Muse 2

Incorporation of Left and Right Control

Using Left vs. Right eye blink classification

RC Car Hardware

Incorporation of new mechanical and electrical components to the robotic toy



Updated EEG Headset









X Single Electrode

Unreliable connection

Required full separate application to receive data



Muse 2

X Cost (250\$)



Connects to all computers

Only requires python package to receive data

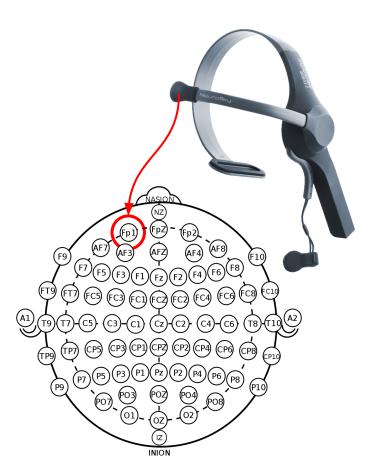


Updated EEG Headset



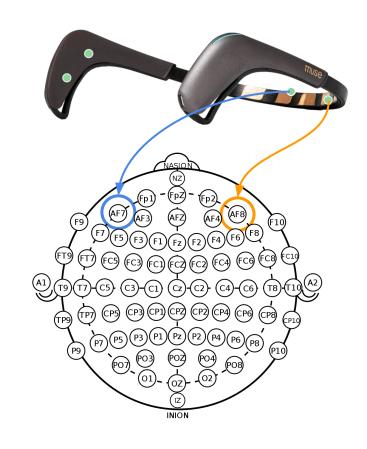
Neurosky Mindwave

Original



Muse 2

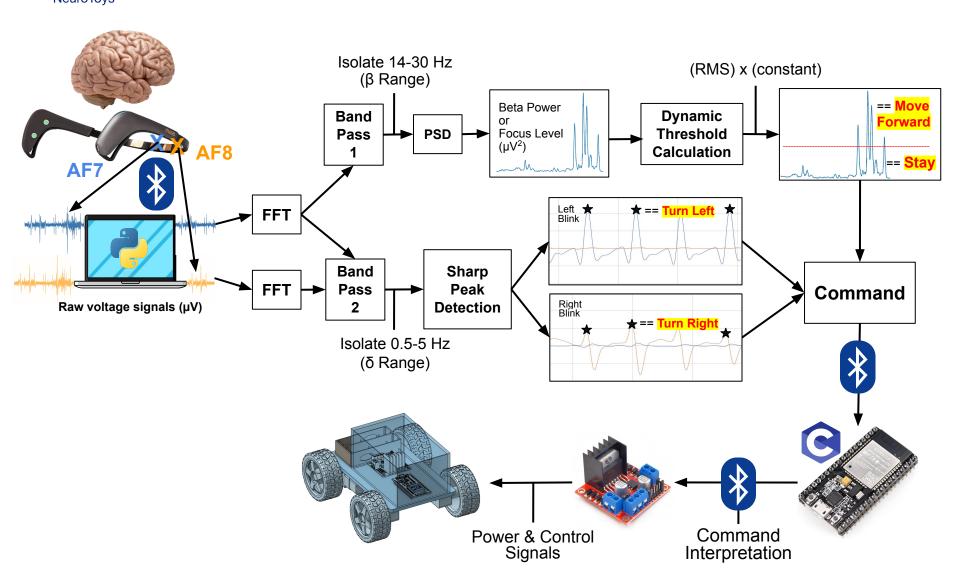
Current





Updated Signal Processing Pipeline



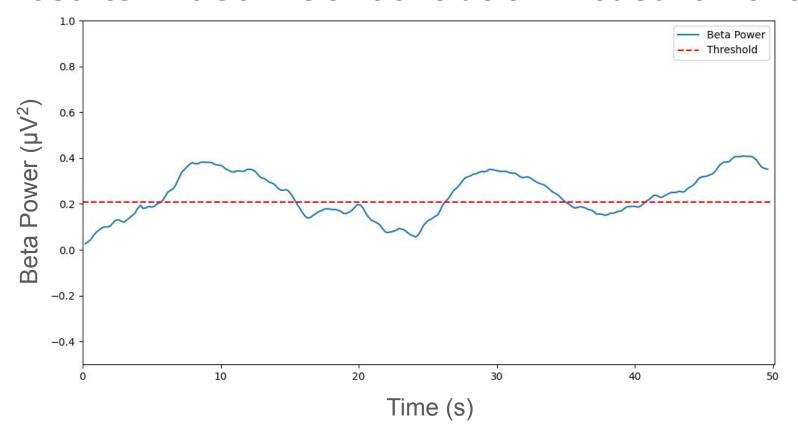




Updated Signal Processing Pipeline



Results: Muse 2 Concentration Measurements

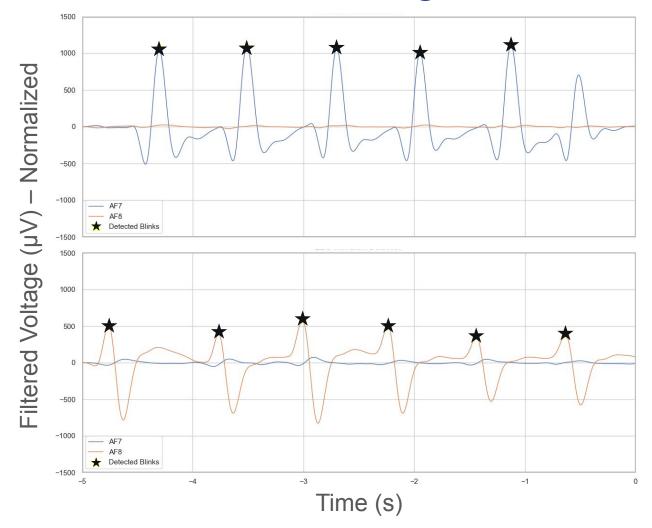




Updated Signal Processing Pipeline



Results: Muse 2 Blinking Measurements



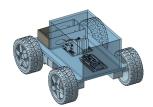


Updated RC Car Hardware



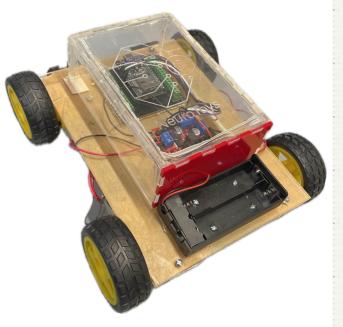
Mechanical

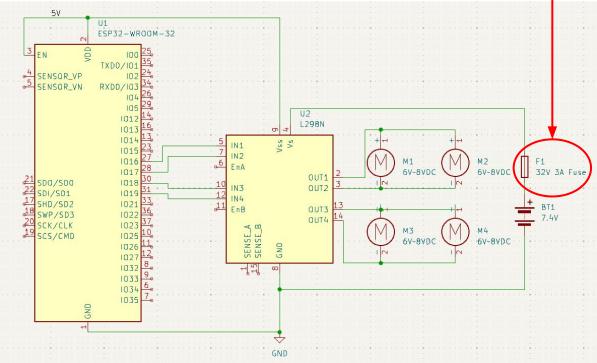
New electrical component housing – Acrylic chassis New Hinges and Improved Fasteners – Custom Aluminum hinges



ElectricalInline 32V 3A Fuse









Milestones – Work for Final Prototype



Further Improve Robustness of Blinking Detection

Currently extremely sensitive to forehead placement, varying the shape of filtered blinking signal

RC Car Hardware

Aesthetics, precision movement and steering. Priority on creating a *unique* appearance; improve wire placement.

User-Friendly Software/GUI

Minimal setup process, simplified parameter readouts and display





TASK TITLE	PHASE ONE - Final Design										PHASE TWO - Final Integration								
	WEEK 8			WEEK 9			WEEK 10			WEEK 11			WEEK 12			WEEK 13			
NeuroToys																			
Car Design Schematics																			
Car Component Fabrication											:								
Car Assembly																	:		
Signal Processing mprovements																			
Code Refactoring																			
ntegration			:								:								
Testing			:														:		