## Homework 9

#### General Edge Detection

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- You are to implement following edge detectors with thresholds:
  - (a) Robert's Operator: 12
  - (b) Prewitt's Edge Detector: 24
  - (c) Sobel's Edge Detector: 38
  - (d) Frei and Chen's Gradient Operator: 30
  - (e) Kirsch's Compass Operator: 135
  - (f) Robinson's Compass Operator: 43
  - (g) Nevatia-Babu 5x5 Operator: 12500

### Outline:

- Method
- Image Result

### Method

• Robert's Operator: 計算矩陣,和其他比較不同的是它是 2\*2,沒有一個 Center; 故不需要 extend padding,若有超出邊界的座標直接縮回來。

• Prewitt's Edge Detector: 按照 table 計算權重。

• Sobel's Edge Detector: 按照 table 計算權重。

• Frei and Chen's Gradient Operator: 按照 table 計算權重。

#### Kirsch's Compass Operator:

一樣是照 Table 填,但是改了方法,將九宮格座標之值弄成陣列,與係數陣列做內積。 這樣做會讓排版好看很多,debug 也比較好找,美觀!

• Robinson's Compass Operator: 按照 table 計算權重。

• Nevatia-Babu 5x5 Operator: 按照 table 計算權重。

五乘五矩陣很長一坨 ...。

```
def get_nevatia_babu_operator(img, threshold):
  w, h = img.shape
  new_img = img.copy()
  img = extend_padding(img, 2)
  for x in range( 2,w+2 ):
     for y in range( 2,h+2 ):
        x1, y1 = x-2, y-2
        x2, y2 = x-1, y-1
x3, y3 = x+1, y+1
x4, y4 = x+2, y+2
        n5 = np.dot(np.array([100, 100, 100, 100, -32, 78, 100, 100, -100, -100
        magitude = max(n0, n1, n2, n3, n4, n5)
        if magitude >= threshold :
           new_img[x-2][y-2] = 0
           new_img[x-2][y-2] = 255
  return new_img
```

# **Image Result**

Gaussian noise, amplitude of 10







Sobel's Edge Detector: 38

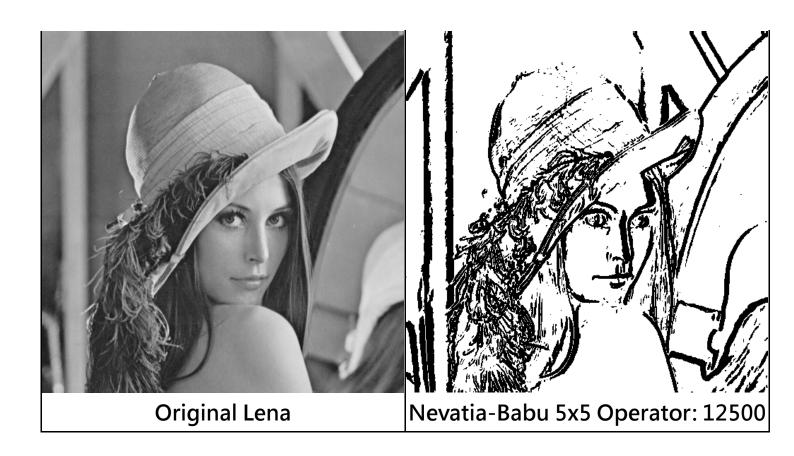


**Original Lena** 



Frei and Chen's Gradient Operator: 30





Tips:用作業說明 PDF 的矩陣跑跑看當作 Debug,會讓此作業順利許多

助教辛苦了:)

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