

Recall: • A vector valued function is a function whose domain is a set of real #s and range is a set of vectors.

• $\vec{r}(t) = f(t)\hat{i} + g(t)\hat{j} + h(t)\hat{k} = \langle f(t), g(t), h(t) \rangle$

• $\lim_{t \rightarrow a} \vec{r}(t) = \lim_{t \rightarrow a} f(t)\hat{i} + \lim_{t \rightarrow a} g(t)\hat{j} + \lim_{t \rightarrow a} h(t)\hat{k}$

• $\vec{r}(t)$ is CTS on an interval $I \Leftrightarrow \lim_{t \rightarrow a} \vec{r}(t) = \vec{r}(a)$ for each $a \in I$.

\Leftrightarrow components of $\vec{r}(t)$ are CTS on I .

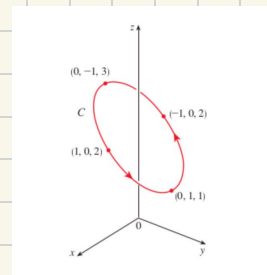
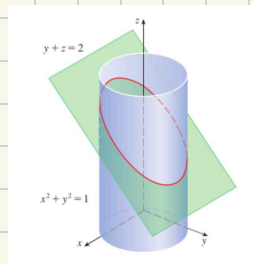
• Space curve: For CTS functions f, g, h on an interval I , the set of points $C = \{(x, y, z) : x = f(t), y = g(t), z = h(t) \text{ for some } t \in I\}$ is called a space curve.

Find a vector function that represents the curve of intersection of the cylinder $x^2 + y^2 = 1$ and the plane $y + z = 2$.

A: $x = \cos t, y = \sin t, 0 \leq t < 2\pi$

Plug $y = \sin t$ into $y + z = 2 \Rightarrow z = 2 - \sin t$

$\Rightarrow C$ is represented by $\vec{r}(t) = \langle \cos t, \sin t, 2 - \sin t \rangle$



$$\cdot \frac{d\vec{r}}{dt} = \lim_{h \rightarrow 0} \frac{\vec{r}(t+h) - \vec{r}(t)}{h}$$

$$= \left\langle \lim_{h \rightarrow 0} \frac{f(t+h) - f(t)}{h}, \lim_{h \rightarrow 0} \frac{g(t+h) - g(t)}{h}, \lim_{s \rightarrow 0} \frac{h(t+s) - h(t)}{s} \right\rangle$$

• If $\vec{r}(t) = f(t)\hat{i} + g(t)\hat{j} + h(t)\hat{k}$ where f, g, h are differentiable. Then

$$\vec{r}'(t) = \frac{d\vec{r}}{dt} = f'(t)\hat{i} + g'(t)\hat{j} + h'(t)\hat{k} = \langle f'(t), g'(t), h'(t) \rangle$$

• Unit Tangent Vector. $\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$

3 Theorem

Suppose \mathbf{u} and \mathbf{v} are differentiable vector functions, c is a scalar, and f is a real-valued function. Then

$$1. \frac{d}{dt}[\mathbf{u}(t) + \mathbf{v}(t)] = \mathbf{u}'(t) + \mathbf{v}'(t)$$

$$2. \frac{d}{dt}[c\mathbf{u}(t)] = c\mathbf{u}'(t)$$

$$3. \frac{d}{dt}[f(t)\mathbf{u}(t)] = f'(t)\mathbf{u}(t) + f(t)\mathbf{u}'(t)$$

$$4. \frac{d}{dt}[\mathbf{u}(t) \cdot \mathbf{v}(t)] = \mathbf{u}'(t) \cdot \mathbf{v}(t) + \mathbf{u}(t) \cdot \mathbf{v}'(t)$$

$$5. \frac{d}{dt}[\mathbf{u}(t) \times \mathbf{v}(t)] = \mathbf{u}'(t) \times \mathbf{v}(t) + \mathbf{u}(t) \times \mathbf{v}'(t)$$

$$6. \frac{d}{dt}[\mathbf{u}(f(t))] = f'(t)\mathbf{u}'(f(t)) \quad (\text{Chain Rule})$$

} linearity

} product rules

4 Theorem

If $|\mathbf{r}(t)| = c$ (a constant), then $\mathbf{r}'(t)$ is orthogonal to $\mathbf{r}(t)$ for all t .

$$\int_a^b \vec{r}(t) dt = \left(\int_a^b f(t) dt \right) \hat{i} + \left(\int_a^b g(t) dt \right) \hat{j} + \left(\int_a^b h(t) dt \right) \hat{k}.$$

Suppose $\vec{r}'(t) = \vec{v}(t)$ then $\int_a^b \vec{v}(t) dt = \vec{r}(b) - \vec{r}(a)$

Eg: $\vec{r}(t) = 2\cos t \hat{i} + \sin t \hat{j} + t^2 \hat{k}$

$$\begin{aligned} \Rightarrow \int \vec{r} dt &= (2 \sin t + C_1) \hat{i} + (-\cos t + C_2) \hat{j} + (t^2 + C_3) \hat{k} \\ &= 2 \sin t \hat{i} - \cos t \hat{j} + t^2 \hat{k} + \vec{C} \\ &= C_1 \hat{i} + C_2 \hat{j} + C_3 \hat{k}. \end{aligned}$$

$$\Rightarrow \int_0^{\pi/2} \vec{r} dt = [2 \sin t \hat{i} - \cos t \hat{j} + t^2 \hat{k}] \Big|_0^{\pi/2} = 2\hat{i} + \hat{j} + \frac{\pi^2}{4} \hat{k}.$$

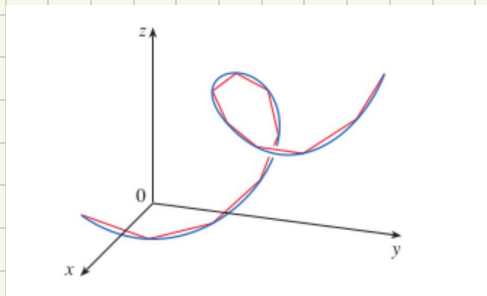
13.3: Arc Length and Curvature:

Definition: Suppose that $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ on the domain $[a, b]$ and

f', g', h' are continuous on $[a, b]$. Then the arc length of the curve is

$$L = \int_a^b \underbrace{\|\mathbf{r}'(t)\|}_{\langle f', g', h' \rangle} dt = \int_a^b \sqrt{(f'(t))^2 + (g'(t))^2 + (h'(t))^2} dt$$

Intuition: $\|\mathbf{r}'(t)\|$ is the length of an infinitesimal matchstick along the curve.
 $\Rightarrow \sum \|\mathbf{r}'(t)\|$ is the total length.



Remark: If the curve is traversed exactly once as t increases from a to b then L is the length of the curve.

• The arc length is invariant under reparametrization.

Example: $\vec{r}_1(t) = \langle t, t^2, t^3 \rangle$, $1 \leq t \leq 2$ and $\vec{r}_2(u) = \langle e^u, e^{2u}, e^{3u} \rangle$, $0 \leq u \leq \ln 2$ have the same arc length.

Example 1

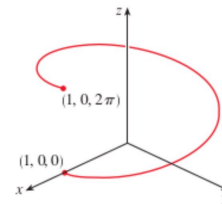
Find the length of the arc of the circular helix with vector equation $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + t \mathbf{k}$ from the point $(1, 0, 0)$ to the point $(1, 0, 2\pi)$.

$$\underline{A}: \quad \mathbf{r}(t) = \langle \cos t, \sin t, t \rangle \Rightarrow \mathbf{r}'(t) = \langle -\sin t, \cos t, 1 \rangle$$

$$\Rightarrow \|\mathbf{r}'(t)\| = \sqrt{(-\sin t)^2 + (\cos t)^2 + 1^2} = \sqrt{\sin^2 t + \cos^2 t + 1} = \sqrt{1+1} = \sqrt{2}.$$

From $(1, 0, 0) \rightarrow (1, 0, 2\pi)$ t increases from 0 to 2π

$$\Rightarrow L = \int_0^{2\pi} \sqrt{2} \, dt = (2\pi - 0)\sqrt{2} = 2\sqrt{2}\pi.$$



The Arc Length Function:

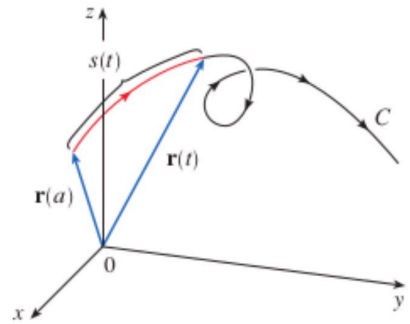
Suppose that a space curve C is given by $\vec{r} = \langle f(t), g(t), h(t) \rangle$, $a \leq t \leq b$ where $\vec{r}'(t)$ is CTS on $[a, b]$ and C is traversed exactly once as t increases from a to b .

Definition: Under the above hypothesis, it's arc length function is defined by

$$s(t) = \int_a^t \|\vec{r}'(u)\| du$$

• Consequence of Fundamental Theorem of Calculus:

$$\frac{ds}{dt} = \|\vec{r}'(t)\|$$



Parametrizing a curve with respect to arc length:

Goal: Reparametrize the curve, say with parameter s , so that as s increases from a to b $\vec{r}(s)$ is a position vector of the point ' s ' units along the curve from its starting point.

Algorithm:

- Find $s(t)$.
- Solve for t as a function of s .
- $\vec{r}(t(s))$ is the desired reparametrization.

Eg: $\vec{r}(t(3))$ is 3 units from the start in "time" and along the space curve.

Example 2

Reparametrize the helix $\vec{r}(t) = \cos t \, \hat{i} + \sin t \, \hat{j} + t \, \hat{k}$ with respect to arc length measured from $(1, 0, 0)$ in the direction of increasing t .

$$\Rightarrow s(t) = \int_0^t \sqrt{2} \, du = \sqrt{2} \, t \quad \Rightarrow \quad t = \frac{1}{\sqrt{2}} s.$$

$$\Rightarrow \text{Desired reparametrization is } \vec{r}(s) = \cos\left(\frac{s}{\sqrt{2}}\right) \hat{i} + \sin\left(\frac{s}{\sqrt{2}}\right) \hat{j} + \left(\frac{s}{\sqrt{2}}\right) \hat{k}.$$

Curvature:

- A parametrization $\vec{r}(t)$ of a curve C on an interval I is called smooth if

$\vec{r}'(t)$ is CTS on I and $\vec{r}'(t) \neq 0$ on I .

✓ (no sharp turns or cusps) (tangent vector always tells us where the "next" point is).

- A curve is called smooth if it has a smooth parametrization.

- Recall: $\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$

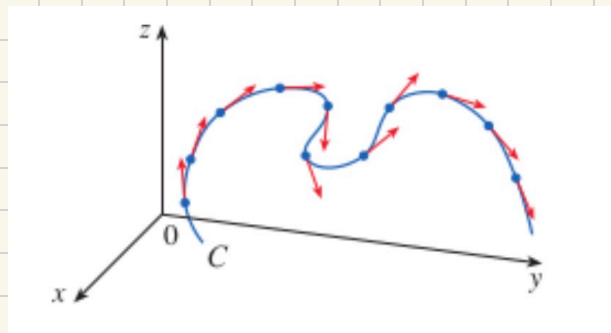
- Definition: The curvature of a curve is

Greek letter kappa

$$\kappa = \left\| \frac{d\vec{T}}{ds} \right\| = \frac{\|d\vec{T}/dt\|}{\|ds/dt\|} = \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|}$$

↑
arc length

$$\frac{d\vec{T}}{ds} = \frac{d\vec{T}}{dt} \cdot \frac{dt}{ds} = \frac{d\vec{T}/dt}{ds/dt}$$



Example 3

Show that the curvature of a circle of radius a is $1/a$.

Take $C = \{(x, y) : x^2 + y^2 = a^2\}$ parametrize by $x = a \cos t$, $y = a \sin t$, $0 \leq t < 2\pi$

so we want $\kappa = \frac{\|T'(t)\|}{\|\vec{r}'(t)\|}$ where $\vec{r} = \langle a \cos t, a \sin t \rangle$, $0 \leq t < 2\pi$.

$$\begin{aligned} \cdot \vec{r}'(t) = \langle -a \sin t, a \cos t \rangle &\Rightarrow \|\vec{r}'(t)\| = \sqrt{(-a \sin t)^2 + (a \cos t)^2} = \sqrt{a^2 \sin^2 t + a^2 \cos^2 t} \\ &= \sqrt{a^2} = a \end{aligned}$$

$$\cdot T(t) = \frac{1}{\|\vec{r}'(t)\|} \cdot \vec{r}'(t) = \frac{1}{a} \langle -a \sin t, a \cos t \rangle = \left\langle \frac{1}{a} \cdot (-a \sin t), \frac{1}{a} (a \cos t) \right\rangle = \langle -\sin t, \cos t \rangle$$

$$\Rightarrow T'(t) = \langle -\cos t, -\sin t \rangle \Rightarrow \|T'(t)\| = \sqrt{(-\cos t)^2 + (-\sin t)^2} = \sqrt{\cos^2 t + \sin^2 t} = 1$$

$$\Rightarrow \kappa = \frac{1}{a}$$