

- Lines:
- For any point $P(x, y, z)$ it's position vector is $\vec{OP} = \langle x, y, z \rangle$.
 - A line L is defined by a point on the line $P_0(x_0, y_0, z_0)$ and direction vector $\vec{v} = \langle a, b, c \rangle$.

$$L = \{ (x, y, z) \in \mathbb{R}^3 : \langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle \text{ for some } t \in \mathbb{R} \}$$

$$= \{ \vec{r}(t) \in \mathbb{R}^3 : \vec{r}(t) = \vec{r}_0 + t \vec{v} \text{ for some } t \in \mathbb{R} \}$$

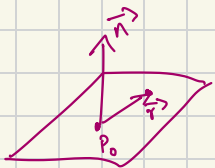
[where $\vec{r}(t)$ and \vec{r}_0 are position vectors of points on the line,
 t is a parameter, and \vec{v} is a direction vector.]

$$= \{ (x, y, z) \in \mathbb{R}^3 : x = x_0 + at, y = y_0 + bt, z = z_0 + ct \text{ for some } t \in \mathbb{R} \}.$$

$$= \{ (x, y, z) \in \mathbb{R}^3 : \frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c} \}$$

with position vector
 $\vec{r}_0 = \langle x_0, y_0, z_0 \rangle$
 \downarrow

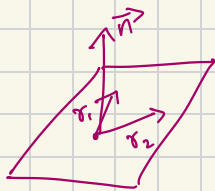
- Planes:
- A plane is defined by a normal vector $\vec{n} = \langle a, b, c \rangle$ and a point on the plane $P_0(x_0, y_0, z_0)$



$$P = \{ (x, y, z) \in \mathbb{R}^3 : \langle a, b, c \rangle \cdot (\langle x, y, z \rangle - \langle x_0, y_0, z_0 \rangle) = 0 \}$$

$$= \{ (x, y, z) \in \mathbb{R}^3 : \vec{n} \cdot (\vec{r} - \vec{r}_0) = 0 \}$$

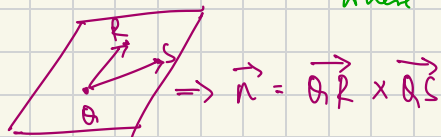
$$= \{ (x, y, z) \in \mathbb{R}^3 : a(x - x_0) + b(y - y_0) + c(z - z_0) = 0 \}$$



$$= \{ (x, y, z) \in \mathbb{R}^3 : ax + by + cz + d = 0 \} \text{ where } d = -(ax_0 + by_0 + cz_0).$$

$$= \{ (x, y, z) \in \mathbb{R}^3 : \langle x, y, z \rangle = s \vec{r}_1 + t \vec{r}_2 \text{ for some parameters } s, t \in \mathbb{R} \}.$$

where \vec{r}_1 and \vec{r}_2 are direction vectors for the plane.



Intersections of Lines, and Planes.

• Intersections of just lines: In \mathbb{R}^2 {

In \mathbb{R}^3 {

• How to figure out which scenario?

$$L_1 : X_1 = P_1 + a_1 t, X_2 = P_2 + a_2 t, X_3 = P_3 + a_3 t$$

fixed point on the line (P_1, P_2, P_3) , direction vector $\langle a_1, a_2, a_3 \rangle$

$$L_2 : Y_1 = Q_1 + b_1 t, Y_2 = Q_2 + b_2 t, Y_3 = Q_3 + b_3 t$$

$(Q_1, Q_2, Q_3), \langle b_1, b_2, b_3 \rangle$

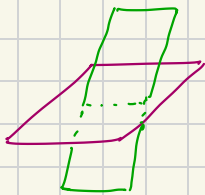
Rewrite $L_2: Y_1 = Q_1 + b_1 s, Y_2 = Q_2 + b_2 s, Y_3 = Q_3 + b_3 s.$

- Parallel: check if $\langle a_1, a_2, a_3 \rangle$ and $\langle b_1, b_2, b_3 \rangle$ are parallel.
- Intersecting: solve the system
$$\left. \begin{aligned} P_1 + a_1 t &= Q_1 + b_1 s \\ P_2 + a_2 t &= Q_2 + b_2 s \\ P_3 + a_3 t &= Q_3 + b_3 s \end{aligned} \right\} \begin{array}{l} \text{That is find } (X_1, X_2, X_3) \\ \text{and } (Y_1, Y_2, Y_3) \text{ are the} \\ \text{same.} \end{array}$$
- Prerequisite: Figure out how to solve a single equation and 2×2 systems.
- Skew lines: prove that lines are not parallel, nor do they intersect.
- Intersections of planes:



parallel

\Leftrightarrow normal vectors
are parallel



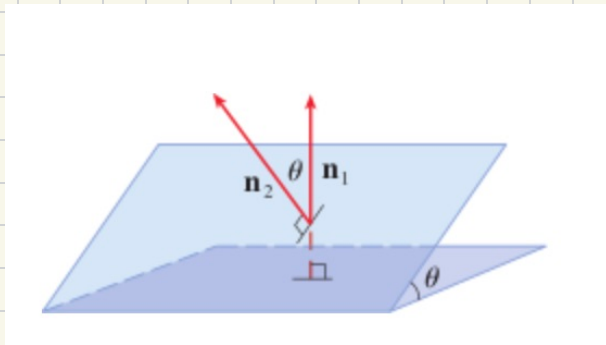
Intersecting
planes

\rightarrow Find line at
the intersection



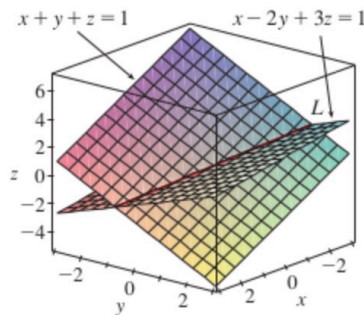
same plane

Definition: Angle between planes is the angle between the normal vectors.



Example 7

- (a) Find the angle between the planes $x + y + z = 1$ and $x - 2y + 3z = 1$.
 (b) Find symmetric equations for the line of intersection L of these two planes.



(a) $M_1: x + y + z = 1$

$M_2: x - 2y + 3z = 1$

Let \vec{n}_1 be the normal vector for M_1 ,

and \vec{n}_2 be that for M_2 . $\Rightarrow \cos \theta = \frac{\vec{n}_1 \cdot \vec{n}_2}{\|\vec{n}_1\| \cdot \|\vec{n}_2\|} \xrightarrow{\Delta \text{IY}} \theta = \cos^{-1} \left(\frac{2}{\sqrt{42}} \right)$

(b) Method 1: Solve for x, y, z in $\begin{cases} x + y + z = 1 \\ x - 2y + 3z = 1 \end{cases}$ for example via row reduction. } If you know some linear

Method 2: Find two points on the line.

Eg.: plug in $z=0$ in the system $\rightarrow \begin{cases} x+y=1 \\ x-2y=1 \end{cases} \Rightarrow (x,y,z) = (1,0,0)$
 call this point P.

• plug in $z=1$ in the system $\rightarrow \begin{cases} x+y=0 \rightarrow y=-x \\ x-2y=-2 \end{cases}$
 $\rightarrow x+2x=-2$
 $\rightarrow x = -\frac{2}{3}$
 $\rightarrow y = \frac{2}{3}$
 \Rightarrow Call the second point $Q(-\frac{2}{3}, \frac{2}{3}, 1)$

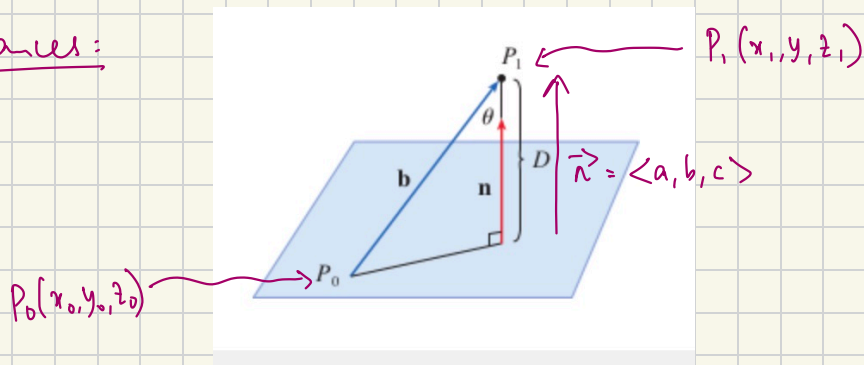
\Rightarrow Take the direction vector as $\overrightarrow{PQ} = \langle -\frac{5}{3}, \frac{2}{3}, 1 \rangle$

$\Rightarrow \vec{r}(t) = \underbrace{\overrightarrow{OP}} + \overrightarrow{PQ} \Rightarrow \left. \begin{aligned} x &= 1 - \frac{5}{3}t \\ y &= 0 + \frac{2}{3}t \\ z &= 0 + t \end{aligned} \right\} \Rightarrow \frac{x-1}{-5/3} = \frac{y}{2/3} = \frac{z}{1}$

$P = (x,y,z)$
 $\Rightarrow \overrightarrow{OP} = \langle x-0, y-0, z-0 \rangle$

Method 3: Direction vector for L can be taken as $\vec{n}_1 \times \vec{n}_2$.

Distances:



We want the shortest distance of a point to the plane.

Let $\vec{b} = \vec{P_0P_1} = \langle x_1 - x_0, y_1 - y_0, z_1 - z_0 \rangle$

$$\text{Then } D = \left| \text{comp}_{\vec{n}} \vec{b} \right| = \left| \frac{\vec{n} \cdot \vec{b}}{|\vec{n}|} \right| = \left| \frac{a(x_1 - x_0) + b(y_1 - y_0) + c(z_1 - z_0)}{\sqrt{a^2 + b^2 + c^2}} \right|$$

$$= \left| \frac{ax_1 + by_1 + cz_1 - (ax_0 + by_0 + cz_0)}{\sqrt{a^2 + b^2 + c^2}} \right| = \left| \frac{ax_1 + by_1 + cz_1 + d}{\sqrt{a^2 + b^2 + c^2}} \right|$$

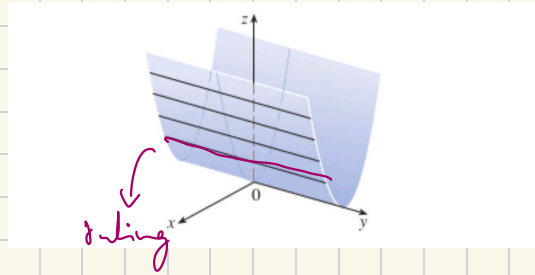
P_0 is a point on the plane $ax+by+cz+d=0$

Cylinders:

Definition: Cylinder is a surface that consists of all lines that are parallel to a given line through a plane curve.

Example 1

Sketch the graph of the surface $z = x^2$.



Eg: any plane curve that has rulings parallel to an axis

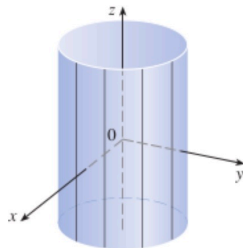
Example 2

Identify and sketch the surfaces.

(a) $x^2 + y^2 = 1$

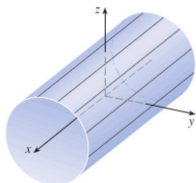
(b) $y^2 + z^2 = 1$

(a)



note: z is missing in $x^2 + y^2 = 1$

(b)



Pop Quiz 1:

① Find the cross product $a \times b$

$$a = 2j - 4k$$

$$b = -i + 3j + k$$

② Find the scalar projection of b onto a

$$\underbrace{\text{comp}_a b = \frac{b \cdot a}{|a|}}$$

$$a = \langle 4, 7, -4 \rangle$$

$$b = \langle 3, -1, 1 \rangle$$