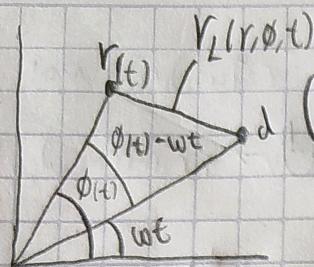


4) C-



Note el triángulo formado por $r_{(t)}$, d , 0
 Usando ley de coseno tendremos:

$$r_L^2(r, \phi, t) = r_{(t)}^2 + d^2 - 2 r_{(t)} d \cos(\phi_{(t)} - \omega t)$$

$$\Rightarrow r_L(r, \phi, t) = \sqrt{r_{(t)}^2 + d^2 + 2 r_{(t)} d \cos(\phi_{(t)} - \omega t)} //$$

D- Energía cinética: $T = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) = \frac{1}{2} m (\dot{r}^2 + \dot{\phi}^2 r^2)$

Energía en Potencial: $V = V_{\text{nave-Tierra}} + V_{\text{nave-Luna}} = -G \frac{m_n M_T}{r_{(t)}} - G \frac{m_n M_L}{r_L(r, \phi, t)}$

$$L = \frac{1}{2} m (\dot{r}^2 + \dot{\phi}^2 r^2) + G \frac{m_n M_T}{r_{(t)}} + G \frac{m_n M_L}{r_L(r, \phi, t)}$$

$$P_r = \frac{\partial L}{\partial \dot{r}} = m \dot{r} \Rightarrow \dot{r} = \frac{P_r}{m}$$

$$P_\phi = \frac{\partial L}{\partial \dot{\phi}} = m \dot{\phi} r^2 \Rightarrow \dot{\phi} = \frac{P_\phi}{mr^2}$$

$$\Rightarrow H = \sum P_i \dot{q}_i - L = \frac{P_r^2}{m} + \frac{P_\phi^2}{mr^2} - \frac{1}{2} m \left(\frac{P_r^2}{m^2} + \frac{P_\phi^2}{r^2 m^2} \right) - G m_n \left(\frac{M_T}{r_{(t)}} + \frac{M_L}{r_L(r, \phi, t)} \right)$$

$$\Rightarrow H = \frac{P_r^2}{2m} + \frac{P_\phi^2}{2mr^2} - G m_n \left(\frac{M_T}{r_{(t)}} + \frac{M_L}{r_L(r, \phi, t)} \right) //$$

$$e - \dot{q}_i = \frac{\partial H}{\partial p_{q_i}} ; \dot{p}_{q_i} = - \frac{\partial H}{\partial q_i}$$

$$\Rightarrow \dot{r} = \frac{\partial H}{\partial p_r} = \frac{p_r}{M} ; \dot{q} = \frac{\partial H}{\partial p_\phi} = \frac{p_\phi}{Mr^2}$$

$$\Rightarrow \dot{p}_r = - \frac{\partial H}{\partial r} = GM_n \left(-\frac{M_r}{r^2} - \frac{M_L}{2} [2r - d\cos(\phi - wt)] \left[r^2 + d^2 + 2rd\cos(\phi - wt) \right]^{-\frac{3}{2}} \right)$$

$$\dot{p}_r = GM_n \left[\frac{M_r}{r^2} + \frac{M_L}{r^3} (r - d\cos(\phi - wt)) \right]$$

$$\Rightarrow \dot{p}_\phi = - \frac{\partial H}{\partial \phi} = - \frac{GM_n M_L}{2} [2rd\sin(\phi - wt)] \left[r^2 + d^2 - 2rd\cos(\phi - wt) \right]^{-\frac{3}{2}}$$

$$\dot{p}_\phi = - \frac{GM_n M_L}{r^3} [rd\sin(\phi - wt)],$$

$$F: \tilde{r} = \frac{r}{d}, \phi, \tilde{\dot{r}}_r = \frac{\dot{r}_r}{md}, \tilde{\dot{\phi}}_r = \frac{\dot{\phi}_r}{md^2}$$

$$\rightarrow \ddot{\tilde{r}} = \frac{\dot{\tilde{r}}}{d} = \frac{\dot{r}_r}{md} = \tilde{\dot{r}}_r \quad ; \quad \ddot{\phi} = \frac{\dot{\phi}_r}{mr^2} = \frac{\tilde{\dot{\phi}}_r d^2}{\tilde{r}^2} = \frac{\tilde{\dot{\phi}}_r}{\tilde{r}^2}$$

$$\rightarrow \ddot{\tilde{r}}_r = \frac{\dot{\tilde{r}}}{md} = \frac{1}{md} \left[\frac{\dot{\phi}^2}{mr^3} - \frac{GM_m M_T}{r^2} - \frac{GM_m M_L}{r^3} (r - d \cos(\phi - wt)) \right]$$

$$= \frac{1}{d} \left[\frac{md^4 \dot{\phi}^2}{mr^3} - GM_T \left[\frac{1}{r^2} - \frac{M_L [r - d \cos(\phi - wt)]}{M_T d^3 (\sqrt{1 + (\frac{r}{d})^2} - 2 \frac{r}{d} \cos(\phi - wt))^3} \right] \right]$$

$$= \frac{\ddot{\tilde{r}}_r}{\tilde{r}^3} - \Delta \dot{\phi}^2 \left[\frac{1}{r^2} - \frac{M}{d^2 \tilde{r}^3} (\tilde{r} - \cos(\phi - wt)) \right]$$

$$\ddot{\tilde{r}} = \frac{\ddot{\tilde{r}}_r}{\tilde{r}^3} - \Delta \left\{ \frac{1}{\tilde{r}^2} - \frac{M}{\tilde{r}^3} [\tilde{r} - \cos(\phi - wt)] \right\} //$$

$$\rightarrow \ddot{\tilde{r}}_\phi = \frac{\ddot{\tilde{r}}_r}{md^2} = \frac{1}{md^2} \left[-G \frac{m M_L}{r^3} (r d \cos(\phi - wt)) \right] = -G \frac{M_L M_T r \cos(\phi - wt)}{M_T d^4 \left(\sqrt{1 + (\frac{r}{d})^2} - 2 \frac{r}{d} \cos(\phi - wt) \right)^3}$$

$$= -\frac{\Delta M}{\tilde{r}^3} \tilde{r} \cos(\phi - wt) //$$

$$\begin{aligned}
 \text{g. } \tilde{P}_r &= \frac{\dot{r}}{m d_{TL}} = \frac{\dot{r}}{dt} = \frac{1}{d_{TL}} \frac{d}{dt} \sqrt{x^2 + y^2} = \frac{1}{2 d_{TL}} (x^2 + y^2)^{1/2} (2x\dot{x} + 2y\dot{y}) \\
 &= \frac{1}{d_{TL} r} (x\dot{x} + y\dot{y}) = \frac{r \cos \phi v \cos \theta + r v \sin \phi v \sin \theta}{d_{TL} r} = \frac{v}{d_{TL}} \cos(\theta - \phi) = \tilde{v} \cos(\theta - \phi), \\
 \tilde{P}_\phi &= \frac{mr^2\phi}{md^2_{TL}} = \tilde{r}^2 \frac{d}{dt} \phi = \tilde{r}^2 \frac{d}{dt} \arctan(y/x) = \frac{\tilde{r}^2}{1 + \frac{y^2}{x^2}} \cdot \frac{d}{dt} \left(\frac{y}{x} \right) = \frac{\tilde{r}^2}{1 + \frac{y^2}{x^2}} (y\dot{x} - y\dot{x}) \\
 &= \frac{\tilde{r}^2}{x^2 + y^2} (y\dot{x} - y\dot{x}) = \frac{\tilde{r}^2}{r^2} (v r \sin \theta \cos \phi - v r \sin \phi \cos \theta) = \frac{\tilde{r}^2 v}{r} \sin(\theta - \phi) \\
 &= \frac{\tilde{r}^2 v}{\tilde{r} d_{TL}} \sin(\theta - \phi) = \tilde{r} \tilde{v} \sin(\theta - \phi)
 \end{aligned}$$