```
#include <Servo.h>
// Replacing the tablet with the LED to represent the idea
#define LedPin 8
Servo S7;
Servo S6;
Servo S10;
Servo S13;
Servo S14;
Servo S15;
void setup()
Serial.begin(9600);
 pinMode(LedPin, OUTPUT);
 S7.attach(7);
 S6.attach(6);
 S10.attach(10);
 S13.attach(13);
 S14.attach(A0);
 S15.attach(A1);
}
void loop(){
 if(Serial.available() > 0){
```

if(Serial.read() == '1'){

```
digitalWrite(LedPin, HIGH);
 S6.write(90);
 S7.write(90);
 S10.write(90);
 S13.write(90);
 S14.write(90);
 S15.write(90);
 delay(10);
 }
}
else {
digitalWrite(LedPin, LOW);
S6.write(0);
S7.write(0);
S10.write(0);
S13.write(0);
S14.write(0);
S15.write(0);
 }
```

}