

The z-transform



TABLE 3.1 SOME COMMON z-TRANSFORM PAIRS

Sequence	Transform	ROC
1. $\delta[n]$	1	All z
2. $u[n]$	$\frac{1}{1-z^{-1}}$	$ z > 1$
3. $-u[-n-1]$	$\frac{1}{1-z^{-1}}$	$ z < 1$
4. $\delta[n-m]$	z^{-m}	All z except 0 (if $m > 0$) or ∞ (if $m < 0$)
5. $a^n u[n]$	$\frac{1}{1-az^{-1}}$	$ z > a $
6. $-a^n u[-n-1]$	$\frac{1}{1-az^{-1}}$	$ z < a $
7. $na^n u[n]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	$ z > a $
8. $-na^n u[-n-1]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	$ z < a $
9. $\cos(\omega_0 n) u[n]$	$\frac{1 - \cos(\omega_0)z^{-1}}{1 - 2\cos(\omega_0)z^{-1} + z^{-2}}$	$ z > 1$
10. $\sin(\omega_0 n) u[n]$	$\frac{\sin(\omega_0)z^{-1}}{1 - 2\cos(\omega_0)z^{-1} + z^{-2}}$	$ z > 1$
11. $r^n \cos(\omega_0 n) u[n]$	$\frac{1 - r \cos(\omega_0)z^{-1}}{1 - 2r \cos(\omega_0)z^{-1} + r^2 z^{-2}}$	$ z > r$
12. $r^n \sin(\omega_0 n) u[n]$	$\frac{r \sin(\omega_0)z^{-1}}{1 - 2r \cos(\omega_0)z^{-1} + r^2 z^{-2}}$	$ z > r$
13. $\begin{cases} a^n, & 0 \leq n \leq N-1, \\ 0, & \text{otherwise} \end{cases}$	$\frac{1-a^N z^{-N}}{1-az^{-1}}$	$ z > 0$

Pole finding:

$$\frac{1}{z-6z^{-1}}$$

$$z \cdot 6z^{-1} = 0 \Leftrightarrow z = 6z^{-1}$$

$$z^{-1} = \frac{z}{6} \Leftrightarrow \underline{z=3}$$

$|z| < |a|$ and left side.

$$\frac{1}{z-\frac{1}{2}z^{-1}} \Rightarrow z = \frac{1}{2}z^{-1} \Rightarrow$$

$$4 = z^{-1} \Rightarrow \underline{z = \frac{1}{4}}$$

$|z| > |a|$ and right sided.

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Negativ / standard

$$\frac{Qz^{-M}}{1-Az^{-1}} \xRightarrow{\text{using 5}} QA^{n-M}u[n-M]$$

Husk fortejrn for M. Som standard er neg

$$\frac{Qz^{-M}}{1-Az^{-1}} \xRightarrow{\text{using 6}} Q(-A)^{n-M}u[-n-1-M]$$

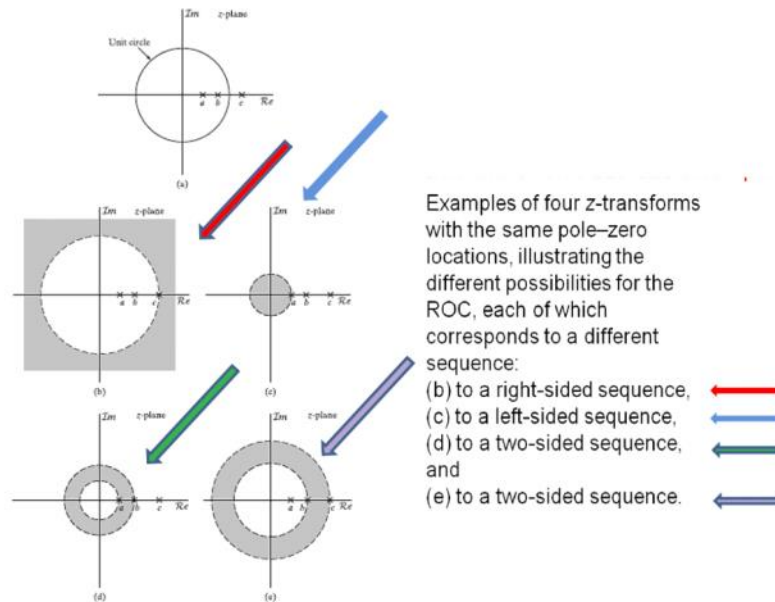
Positive / -- standard

$$\frac{Qz^{+M}}{1-Az^{-1}} \Rightarrow QA^{n+M}u[n+M]$$

Her er den positiv

$$\frac{Qz^{+M}}{1-Az^{-1}} \Rightarrow Q(-A)^{n+M}u[-n-1-M]$$

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TABLE 3.2 SOME z-TRANSFORM PROPERTIES

Property Number	Section Reference	Sequence	Transform	ROC
		$x[n]$	$X(z)$	R_x
		$x_1[n]$	$X_1(z)$	R_{x_1}
		$x_2[n]$	$X_2(z)$	R_{x_2}
1	3.4.1	$ax_1[n] + bx_2[n]$	$aX_1(z) + bX_2(z)$	Contains $R_{x_1} \cap R_{x_2}$
2	3.4.2	$x[n - n_0]$	$z^{-n_0} X(z)$	R_x , except for the possible addition or deletion of the origin or ∞
3	3.4.3	$z_0^n x[n]$	$X(z/z_0)$	$ z_0 R_x$
4	3.4.4	$nx[n]$	$-z \frac{dX(z)}{dz}$	R_x
5	3.4.5	$x^*[n]$	$X^*(z^*)$	R_x
6		$\mathcal{R}\{x[n]\}$	$\frac{1}{2}[X(z) + X^*(z^*)]$	Contains R_x
7		$\mathcal{I}\{x[n]\}$	$\frac{1}{2j}[X(z) - X^*(z^*)]$	Contains R_x
8	3.4.6	$x^*[-n]$	$X^*(1/z^*)$	$1/R_x$
9	3.4.7	$x_1[n] * x_2[n]$	$X_1(z)X_2(z)$	Contains $R_{x_1} \cap R_{x_2}$

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$$H(z) = \frac{Y(z)}{X(z)}$$

j $Y(z)(a+b+e \dots) = X(z)(d+e+f) \dots$

$$\frac{Y(z)}{X(z)} = \frac{d+e+f}{a+b+c} = H(z)$$

How to inverse z-transform!

$$X(z) = \frac{2z^{-1}}{1-z^{-1}} + \frac{z^3}{1-\frac{4}{7}z^{-1}} \quad \text{given ROC } |z| > 1$$

Det betyder vi bruger denne basis

$$5) a^n u[n] \leftrightarrow \frac{1}{1-az^{-1}}$$

$$\frac{2z^{-1}}{1-z^{-1}} = 2 \frac{z^{-1}}{1-z^{-1}} ; \quad \frac{z^3}{1-\frac{4}{7}z^{-1}}$$

$$2 \cdot \frac{z^{-1}}{1-z^{-1}} \rightarrow 2 \cdot 1^{n-1} u[n-1] = 2u[n-1]$$

$$\frac{z^3}{1-\frac{4}{7}z^{-1}} \rightarrow \frac{4^{n+3}}{7} u[n+3]$$

$$\underline{2u[n-1] + \left(\frac{4}{7}\right)^{n+3} u[n+3]}$$

Let's inverse some more

$$X(z) = \frac{3}{1-2z^{-1}} + \frac{z^{-1}}{1-z^{-1}} \quad \text{ROC } |z| < 1$$

Which means we use this

$$6) -a^n u[-n-1] \leftrightarrow \frac{1}{1-az^{-1}}$$

$$\frac{3}{1-2z^{-1}} + \frac{z^{-1}}{1-z^{-1}}$$

$3 - (z)^n u[-n-1] + -1^{n-1} u[-n-1-1]$

from formula

$-1^{n-1} = 1$

$-n-1+1 = -n$

da bleiben -- = +
 da nur det der minus

$$\underline{\underline{-3(z)^n u[-n-1] - u[-n]}}$$



A stable LTI system is characterized by this difference equation:

$$y[n] - 3y[n-1] = 5x[n-2]$$

$$y[n-0] - 3y[n-1] = 5x[n-2]$$

$$\mathcal{Z}\{\leftrightarrow\}$$

$$Y(z) \cdot z^0 - 3Y(z) \cdot z^{-1} = 5X(z) \cdot z^{-2}$$

$$Y(z) \cdot (z^0 - 3 \cdot z^{-1}) = X(z) (5 \cdot z^{-2})$$

And then we know that $H(z) = \frac{Y(z)}{X(z)}$

..

$$\left[\frac{Y(z)}{X(z)} (1 - 3z^{-1}) = 5z^{-2} \Rightarrow \frac{Y(z)}{X(z)} = \frac{5z^{-2}}{1 - 3z^{-1}} = H(z) \right]$$

THIS IS IMPORTANT

$$H(z) = \frac{Y(z)}{X(z)} = \frac{5 \cdot z^{-2}}{1 - 3z^{-1}}$$

og det kan vi bruge inverse
Z transform på

ROC = 3 which means left-sided and therefore
 $|z| < 3$

som betyder vi bruger

$$-a^n u[-n-1] \Rightarrow \frac{1}{1 - az^{-1}}$$

$$5 \cdot \frac{z^{-2}}{1 - 3z^{-1}} \Rightarrow \mathcal{Z}^{-1} \left\{ 5 - 3^{n-2} u[-n-1-2] \right\}$$

$$\underline{\underline{-5(3)^{n-2} u[-n+1]}}$$

and is non causal as $[-n+1]$
is positive



Apply $\mathcal{Z}^{-1} \{ \}$ to

$$H(z) = \frac{1 - 3z^{-1}}{2 - 4z^{-1}} = \frac{1}{2 - 4z^{-1}} - \frac{3z^{-1}}{2 - 4z^{-1}}$$

for ROC $2-4z^{-1} \rightarrow 2-4\frac{1}{2}z^{-1} = 0$

Then ROC $|z| < |a|$

6) $-a^n u[-n-1] \Leftrightarrow \frac{1}{1-az^{-1}}$

$$\frac{1}{2-4z^{-1}} - 3 \frac{z^{-1}}{2-4z^{-1}} = \frac{1}{2} \frac{1}{1-2z^{-1}} - \frac{3}{2} \frac{z^{-1}}{1-2z^{-1}}$$

$$\frac{1}{2} \cdot -(z)^n u[-n-1] - \frac{3}{2} \cdot -(z)^{n+1} u[-n-1-1]$$

$$-\frac{1}{2} z^n u[-n-1] + \frac{3}{2} (z)^{n+1} u[-n]$$

5 $a^n u[n] \Leftrightarrow \frac{1}{1-az^{-1}}$ ROC $|z| > |a|$

$$\frac{1}{2} \frac{1}{1-2z^{-1}} - \frac{3}{2} \frac{z^{-1}}{1-2z^{-1}}$$

$$\frac{1}{2} 2^n u[n] - \frac{3}{2} 2^{n-1} u[n-1]$$



Opgaveeks. 7

Given a causal linear time invariant system with the following transfer function:

$$H(z) = \frac{1-3z^{-1}}{2-4z^{-1}},$$

calculate the impulse response $h_i[n]$ of the inverse system.

Solution: $h_i[n] = 2(3)^n u[n] - 4(3)^{n-1} u[n-1]$, or $h_i[n] = -2(3)^n u[-n-1] + 4(3)^{n-1} u[-n]$.

Så opdag nu lige at det skal
være den inverse

$$H(z) = \mathcal{Z}^{-1} \left\{ \frac{1}{H(z)} \right\}$$

$$H(z) = \mathcal{Z}^{-1} \left\{ \frac{1}{H(z)} \right\}$$

$$H(z)^{-1} = \frac{2 - 4z^{-1}}{1 - 3z^{-1}} = 2 \frac{1}{1 - 3z^{-1}} - \frac{4z^{-1}}{1 - 3z^{-1}}$$

$$2(3)^n [n] - 4(3)^{n-1} [n-1]$$

formel 5)

OR

$$-2(3)^n [-n-1] + 4(3)^{n-1} [-n]$$

formel 6)