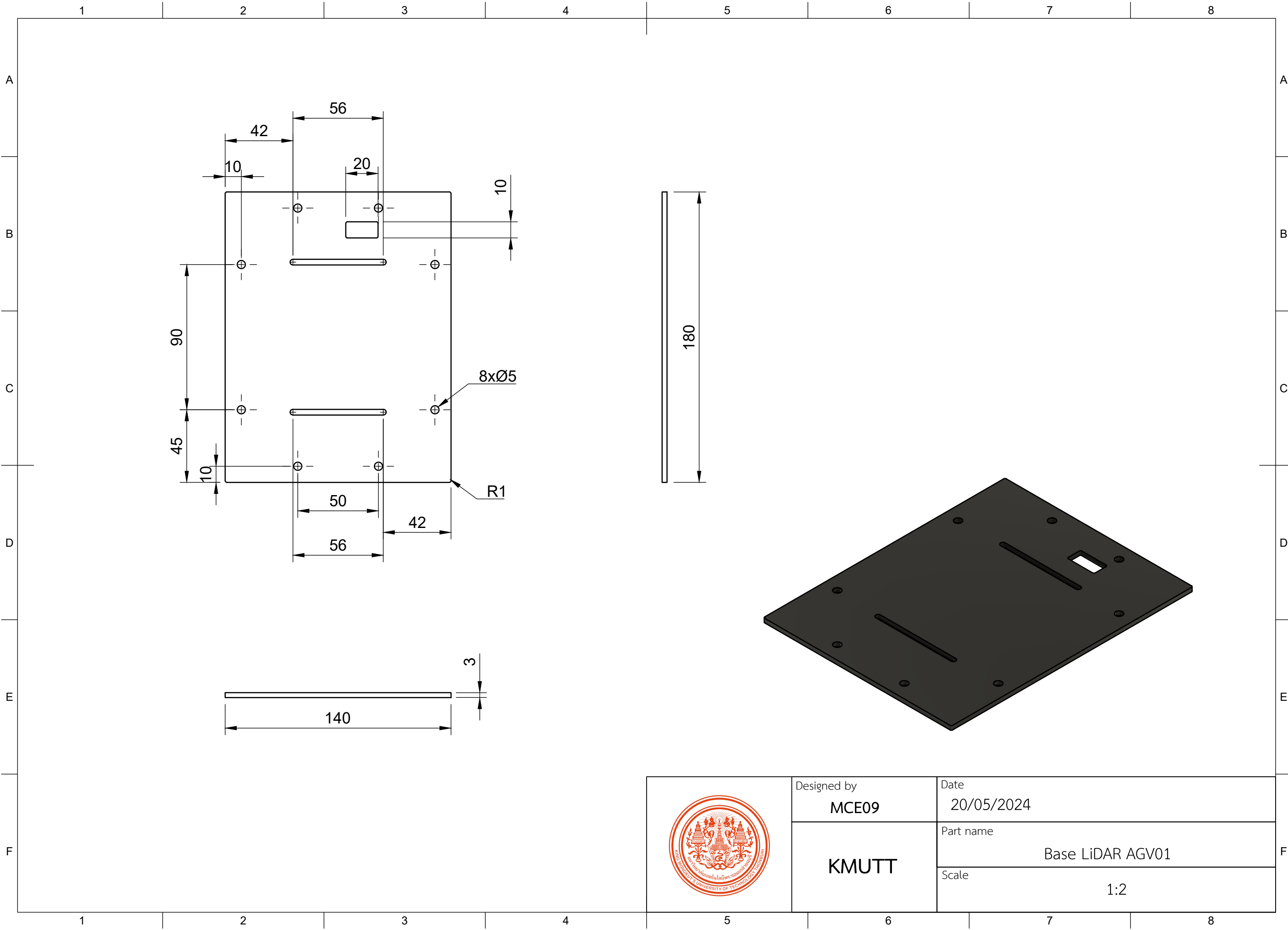
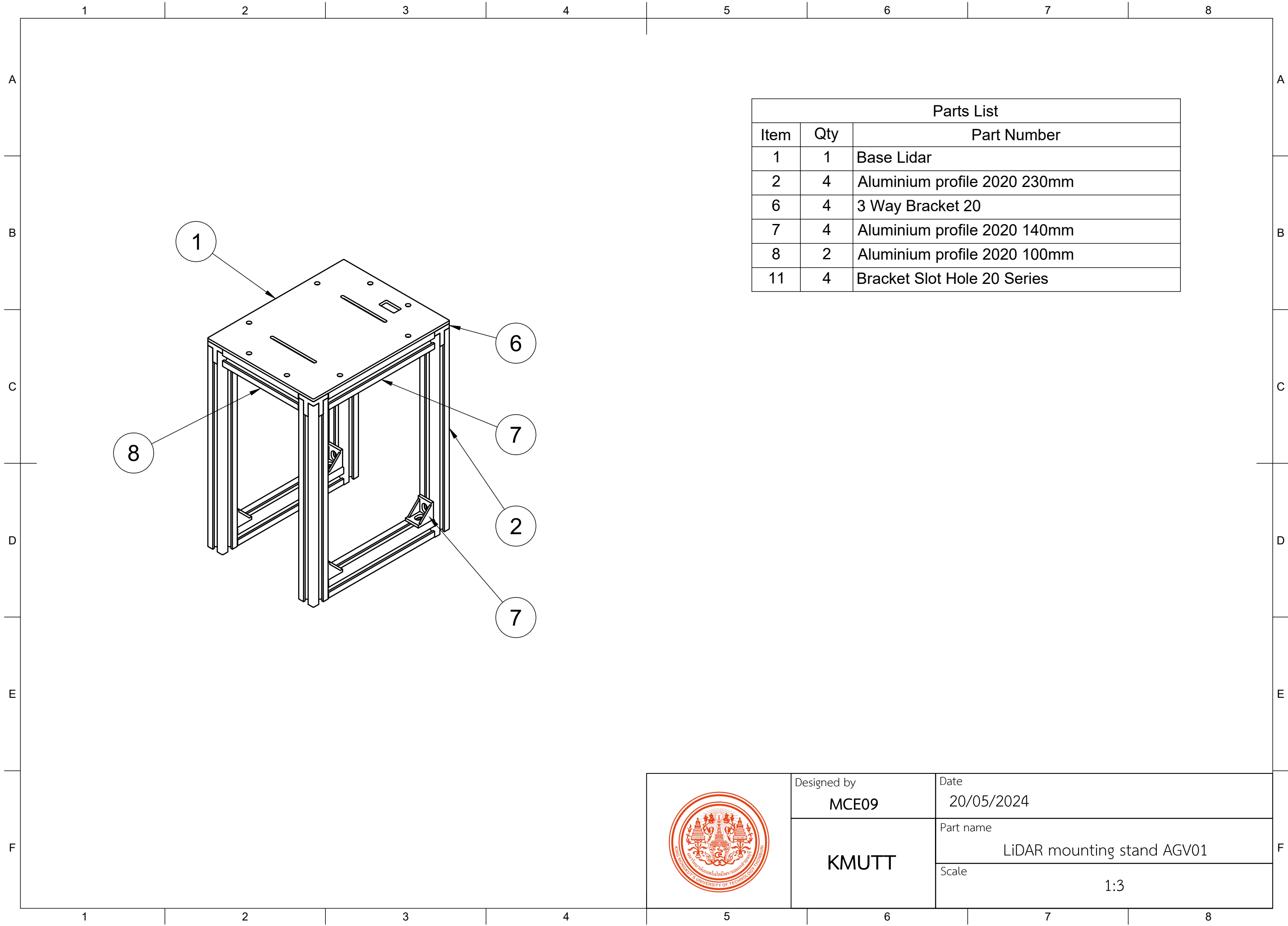


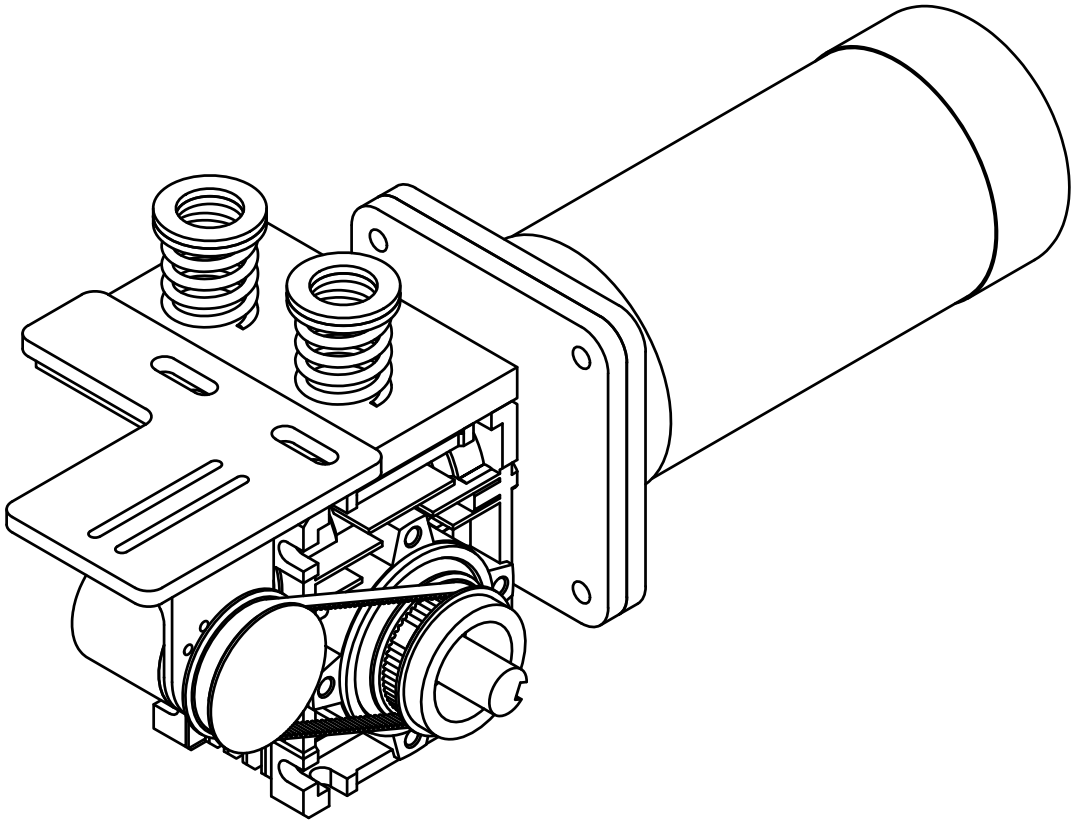
Designed by	MCE09		Date		20/05/2024	
	KMUTT		Part name		AGV01	
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Designed by MCE09 KMUTT	Date 20/05/2024
	Part name Base LiDAR AGV01
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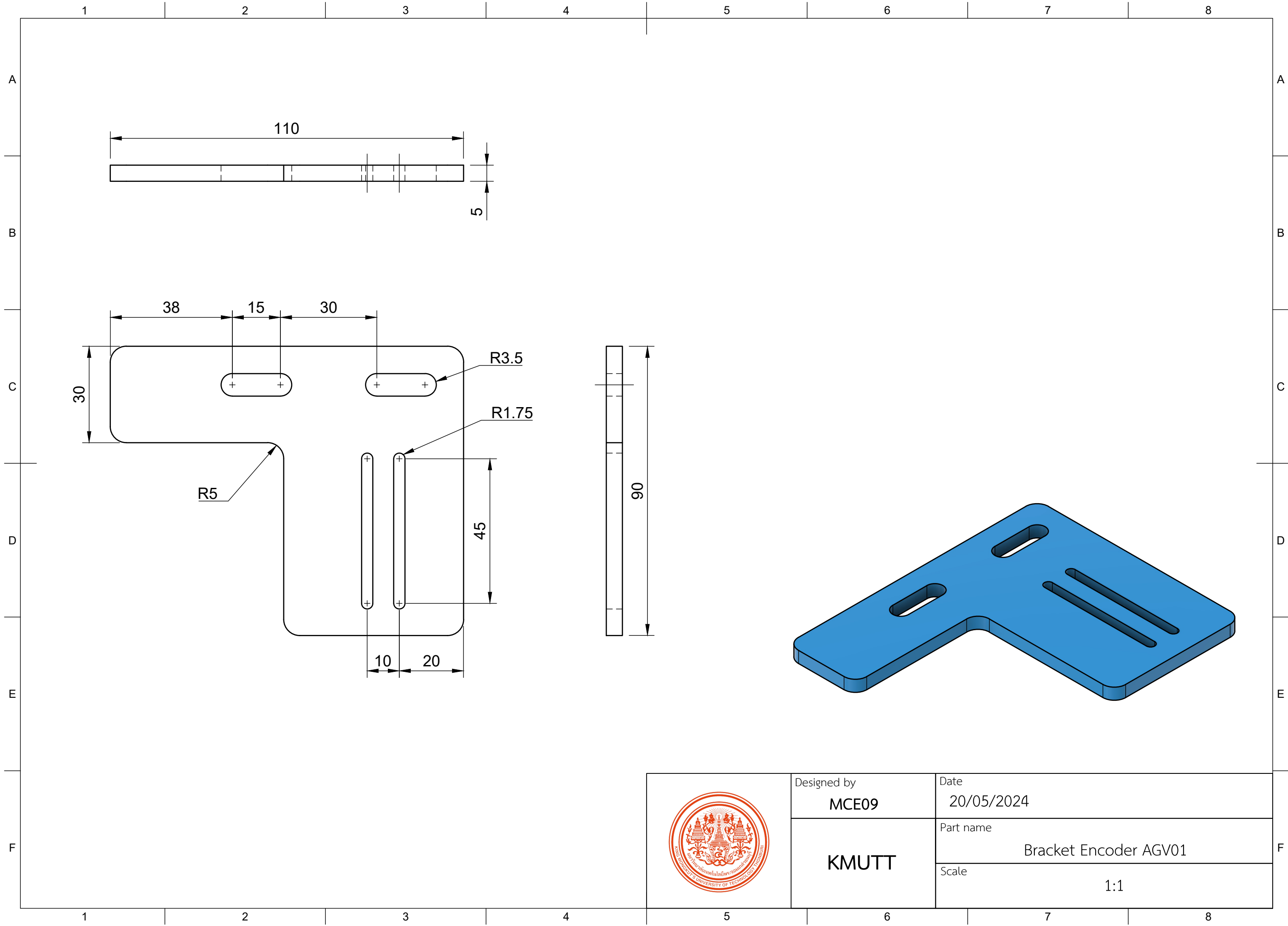


Designed by	MCE09	Date	20/05/2024
	KMUTT	Part name	LiDAR mounting stand AGV01
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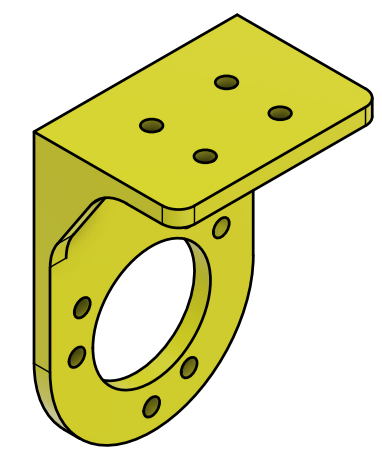
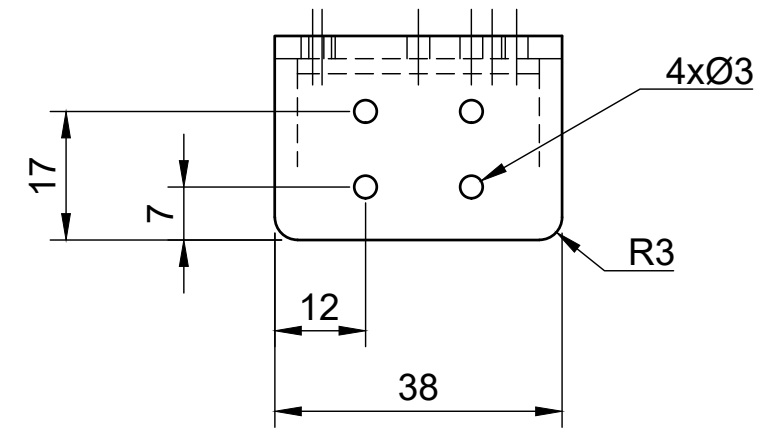
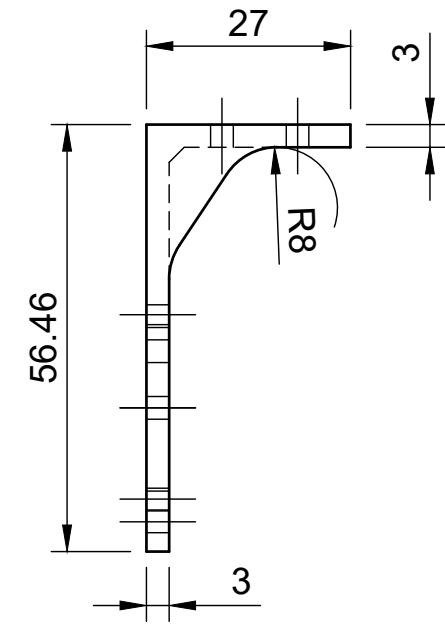
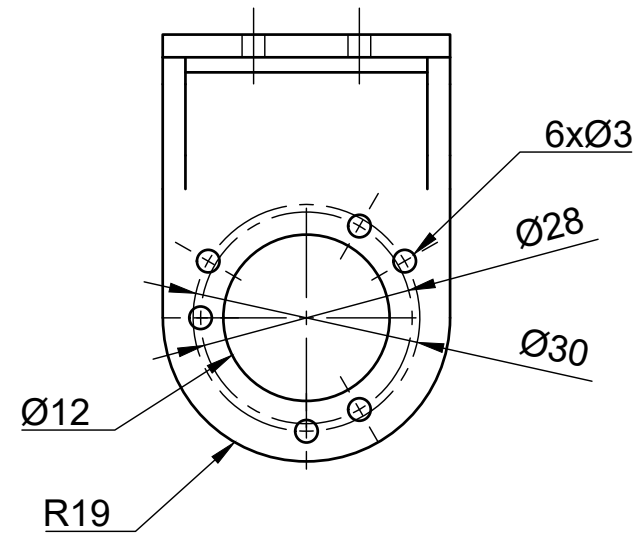


Parts List		
Item	Qty	Part Name
1	2	DC motor 24V
2	2	Encoder
3	2	Bracket motor
4	2	Bracket Encoder AGV01
5	2	Bracket Encoder hold AGV01
6	2	60 Teeth Timing Pulley Rotary Encoder AGV01
7	2	60 Teeth Timing Pulley Rotary Wheel AGV01
8	2	Belt 280 mm

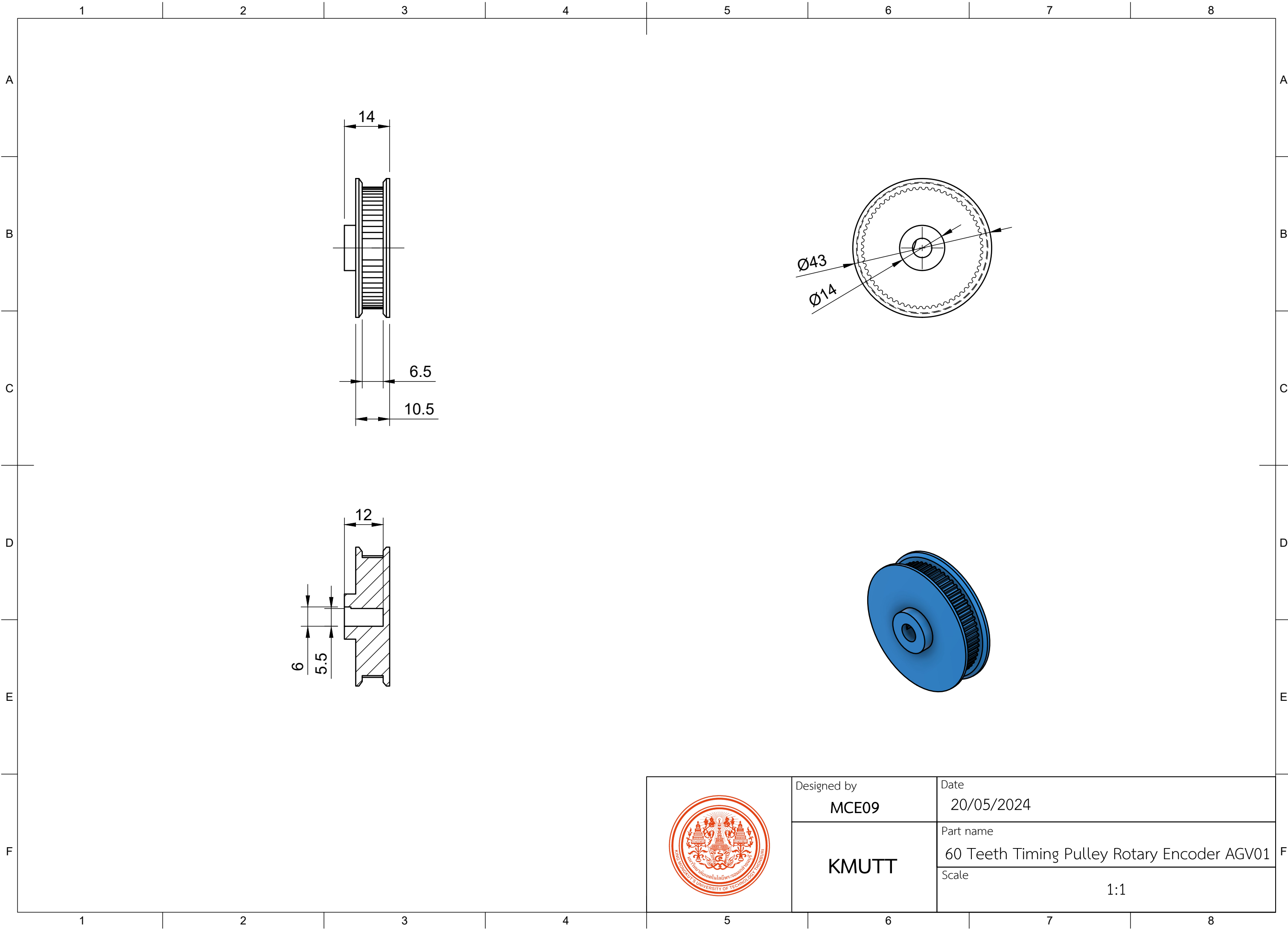
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	KMUTT	Part name Base Camera AGV01
		Scale 1:2




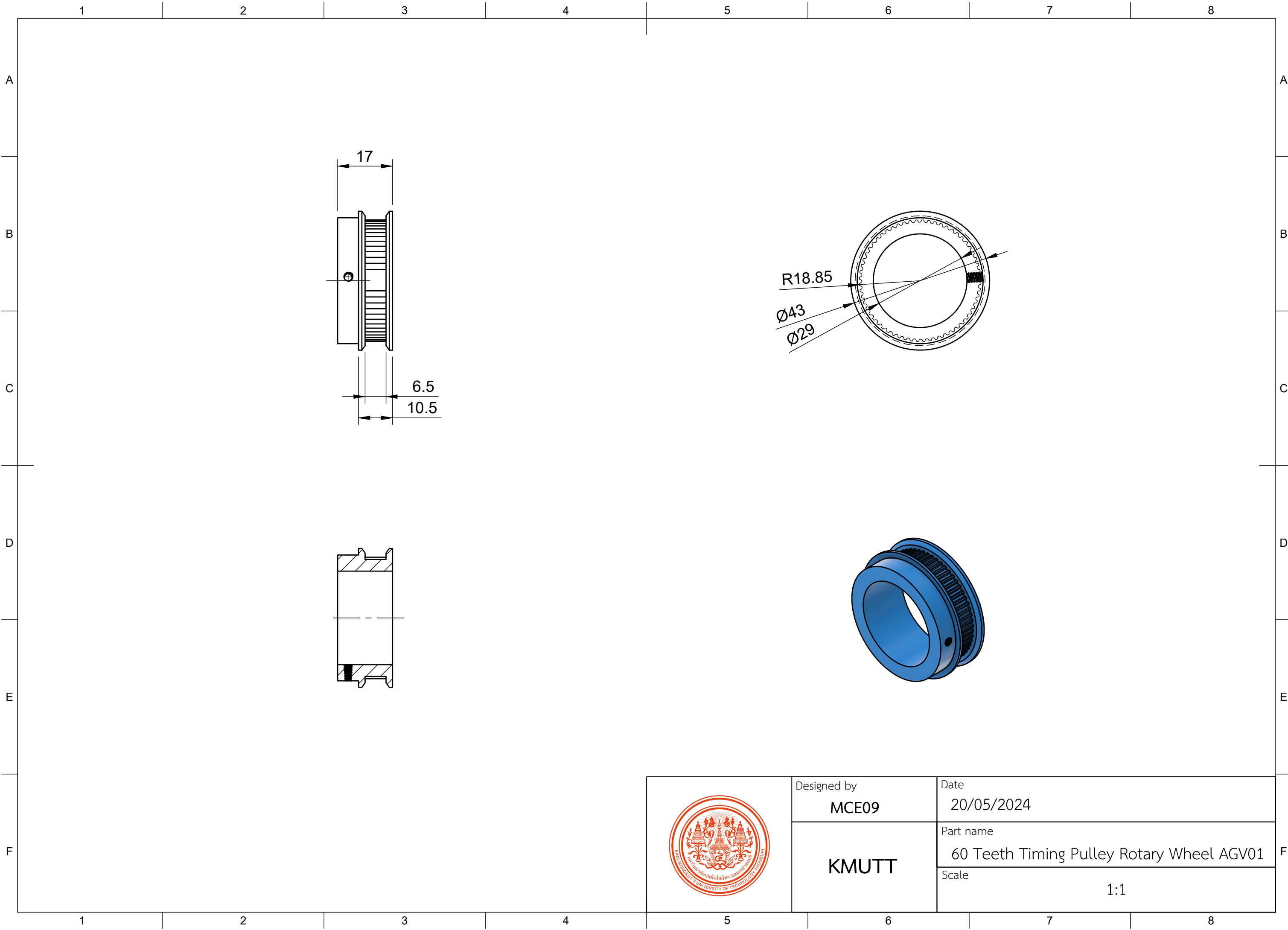
Designed by	MCE09	Date	20/05/2024
	KMUTT	Part name	Bracket Encoder AGV01
		Scale	1:1




<div>Designed by</div> <div>MCE09</div>	<div>Date</div> <div>20/05/2024</div>	
	<div>Part name</div> <div>Bracket Encoder hold AGV01</div>	
	<div>Scale</div> <div>1:1</div>	



	Designed by MCE09	Date 20/05/2024
	KMUTT	Part name 60 Teeth Timing Pulley Rotary Encoder AGV01
		Scale 1:1



	Designed by MCE09	Date 20/05/2024
	KMUTT	Part name 60 Teeth Timing Pulley Rotary Wheel AGV01
		Scale 1:1