Hazard3

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Chapter 1. Introduction

Hazard3 is a 3-stage RISC-V processor, providing the following architectural support:

- RV32I: 32-bit base instruction set
- M: integer multiply/divide/modulo
- A: atomic memory operations, with AHB5 global exclusives
- C: compressed instructions
- Zicsr: CSR access
- Zba: address generation
- Zbb: basic bit manipulation
- Zbc: carry-less multiplication
- Zbs: single-bit manipulation
- Zbkb: basic bit manipulation for scalar cryptography
- Debug, Machine and User privilege/execution modes
- Privileged instructions ECALL, EBREAK, MRET and WFI
- External debug support
- Instruction address trigger unit (hardware breakpoints)

1.1. Architectural Overview

1.1.1. Bus Interfaces

Hazard3 implements either one or two industry-standard AHB5 bus interfaces. The AHB family is characterised by a fixed 2-phase bus pipeline, ideal for a 3-stage 2-port processor like Hazard3. AHB5 is distinguished from older AHB standards mainly by its additional bus attributes, and its support for global exclusives, which Hazard3 uses to implement multiprocessor support for the RISC-V atomics extension.

In Hazard3's single-port configuration, a single AHB5 port performs memory accesses for instruction fetch and loads/stores/AMOs. The dual-port configuration adds a dedicated port for instruction fetch. Dual-port yields around 10% higher per-clock performance, as well as a shorter critical address-phase path, but the single-port configuration is simpler to integrate.

1.1.2. Pipe Stages

In order, the three stages are:

- F: Fetch
 - Contains the data phase for instruction fetch
 - Contains the instruction prefetch buffer

- Predecodes register numbers rs1/rs2, for faster register file read and register bypass
- X: Execute
 - Decode and execute instructions
 - Drive the address phase for load/store/AMO
 - Generate jump/branch addresses
- M: Memory
 - · Contains the data phase for load/store/AMO
 - Register writeback is at the end of stage M
 - Generate exception addresses

The instruction fetch address phase is best thought of as residing in stage X, since in general execution the feedback loop between jump/branch decode and address issue in stage X, and the fetch data phase in stage F, is what defines Hazard3's jump/branch performance.

1.1.3. Multiply/Divide

For basic M-extension support, Hazard3 instantiates a sequential multiply/divide circuit (restoring divide, repeated-addition multiply), which takes 32 cycles to perform a multiply or divide.

For modest performance improvement, this circuit can be unrolled, stacking multiple identical arithmetic circuits within one cycle. This simple approach is enough for 2 or 4 bits per clock, depending on area and frequency targets.

For the best integer multiply performance, a single-cycle multiplier can be instantiated, retiring either to stage 3 (lower timing impact) or stage 2 (no dependency stall). This multiplier can implement either 32-bit mul only, which is by far the most common of the four multiply instructions, or can be extended to implement multimulhu/mulhsu as well. If all four multiplies are implemented by the single-cycle multiplier, then multiply support is removed from the sequential multiply/divide circuit.

1.2. List of RISC-V Specifications

These are links to the ratified versions of the base instruction set and extensions implemented by Hazard3.

Extension	Specification
RV32I v2.1	Unprivileged ISA 20191213
M v2.0	Unprivileged ISA 20191213
A v2.1	Unprivileged ISA 20191213
c v2.0	Unprivileged ISA 20191213
Zicsr v2.0	Unprivileged ISA 20191213
Zifencei v2.0	Unprivileged ISA 20191213

Extension	Specification
Zba v1.0.0	Bit Manipulation ISA extensions 20210628
Zbb v1.0.0	Bit Manipulation ISA extensions 20210628
Zbc v1.0.0	Bit Manipulation ISA extensions 20210628
Zbs v1.0.0	Bit Manipulation ISA extensions 20210628
Zbkb v1.0.1	Scalar Cryptography ISA extensions 20220218
Machine ISA v1.12	Privileged Architecture 20211203
Debug v0.13.2	RISC-V External Debug Support 20190322

Chapter 2. Configuration and Integration

2.1. Hazard3 Source Files

Hazard3's source is written in Verilog 2005, and is self-contained. It can be found here: github.com/Wren6991/Hazard3/blob/master/hdl.

The file hdl/hazard3.f is a list of all the source files required to instantiate Hazard3. This is supposed to be read by a tool called listfiles, to generate other file list formats, but it should be simple enough to copy and hand-edit.

Files ending with .vh are preprocessor include files used by the Hazard3 source. The most important are:

- hazard3_config.vh: the main Hazard3 configuration header. Lists and describes Hazard3's global configuration parameters, such as ISA extension support
- hazard3_config.vh: a file which propagates configuration parameters through module instantiations, all the way down from Hazard3's top-level modules through the internals

Therefore there are two ways to configure Hazard3:

- Directly edit the parameter defaults in hazard3_config.vh in your local Hazard3 checkout (and then let the top-level parameters default when instantiating Hazard3)
- Set all configuration parameters in your Hazard3 instantiation, and let the parameters propagate down through the hierarchy

2.2. Top-level Modules

Hazard3 has two top-level modules:

- hazard3_cpu_1port
- hazard3_cpu_2port

These are both thin wrappers around the hazard3_core module. hazard3_cpu_1port has a single AHB5 bus port which is shared for instruction fetch, loads, stores and AMOs. hazard3_cpu_2port has two AHB5 bus ports, one for instruction fetch, and the other for loads, stores and AMOs. The 2-port wrapper has higher potential for performance, but the 1-port wrapper may be simpler to integrate, since there is no need to arbitrate multiple bus masters externally.

The core module hazard3_core can also be instantiated directly, which may be more efficient if support for some other bus standard is desired. However, the interface of hazard3_core will not be documented and is not guaranteed to be stable.

2.3. Configuration Parameters

2.3.1. Reset state configuration

RESET_VECTOR

Address of the first instruction executed after Hazard3 comes out of reset.

Default value: all-zeroes.

MTVEC_INIT

Initial value of the machine trap vector base CSR (mtvec).

Bits clear in MTVEC_WMASK will never change from this initial value. Bits set in MTVEC_WMASK can be written/set/cleared as normal.

Default value: all-zeroes.

2.3.2. RISC-V ISA support

EXTENSION A

Support for the A extension: atomic read/modify/write. 0 for disable, 1 for enable.

Default value: 1

EXTENSION_C

Support for the C extension: compressed (variable-width). 0 for disable, 1 for enable.

Default value: 1

EXTENSION_M

Support for the M extension: hardware multiply/divide/modulo. 0 for disable, 1 for enable.

Default value: 1

EXTENSION_ZBA

Support for Zba address generation instructions. 0 for disable, 1 for enable.

Default value: 1

EXTENSION_ZBB

Support for Zbb basic bit manipulation instructions. 0 for disable, 1 for enable.

Default value: 1

EXTENSION ZBC

Support for Zbc carry-less multiplication instructions. 0 for disable, 1 for enable.

Default value: 1

EXTENSION_ZBS

Support for Zbs single-bit manipulation instructions. 0 for disable, 1 for enable.

Default value: 1

EXTENSION_ZBKB

Support for Zbkb basic bit manipulation for cryptography.

Requires: EXTENSION_ZBB. (Since Zbb and Zbkb have a large overlap, this flag enables only those instructions which are in Zbkb but aren't in Zbb. Therefore both flags must be set for full Zbkb support.)

Default value: 1

EXTENSION_XH3B

Custom bit manipulation instructions for Hazard3: h3.bextm and h3.bextmi.

Default value: 1

EXTENSION_ZIFENCEI

Support for the fence.i instruction. When the branch predictor is not present, this instruction is optional, since a plain branch/jump is sufficient to flush the instruction prefetch queue. When the branch predictor is enabled (BRANCH_PREDICTOR is 1), this instruction must be implemented.

Default value: 1

2.3.3. CSR support

NOTE

the Zicsr extension is implied by any of CSR_M_MANDATORY, CSR_M_TRAP, CSR COUNTER.

CSR_M_MANDATORY

Bare minimum CSR support e.g. misa. This flag is an absolute requirement for compliance with the RISC-V privileged specification. However, the privileged specification itself is an optional extension. Hazard3 allows the mandatory CSRs to be disabled to save a small amount of area in deeply-embedded implementations.

CSR M TRAP

Include M-mode trap-handling CSRs, and enable trap support.

CSR_COUNTER

Include the basic performance counters (cycle/instret) and relevant CSRs. Note that these

performance counters are now in their own separate extension (Zicntr) and are no longer mandatory.

U_MODE

Support the U (user) privilege level. In U-mode, the core performs unprivileged bus accesses, and software's access to CSRs is restricted. Additionally, if the PMP is included, the core may restrict Umode software's access to memory.

Requires: CSR_M_TRAP.

PMP_REGIONS

Number of physical memory protection regions, or 0 for no PMP. PMP is more useful if U mode is supported, but this is not a requirement.

Hazard3's PMP supports only the NAPOT and(if PMP_GRAIN is 0) NA4 region types.

Requires: CSR_M_TRAP.

PMP_GRAIN

This is the G parameter in the privileged spec, which defines the granularity of PMP regions. Minimum PMP region size is 1 << (G + 2) bytes.

If G > 0, pmcfg.a can not be set to NA4 (attempting to do so will set the region to OFF instead).

If G > 1, the G - 1 LSBs of pmpaddr are read-only-0 when pmpcfq.a is OFF, and read-only-1 when pmpcfg.a is NAPOT.

Default value: 0

PMP HARDWIRED

PMPADDR_HARDWIRED: If a bit is 1, the corresponding region's pmpaddr and pmpcfg registers are read-only, with their values fixed when the processor is instantiated. PMP_GRAIN is ignored on hardwired regions.

Hardwired regions are far cheaper, both in area and comparison delay, than dynamically configurable regions.

Hardwired PMP regions are a good option for setting default U-mode permissions on regions which have access controls outside of the processor, such as peripheral regions. For this case it's recommended to make hardwired regions the highest-numbered, so they can be overridden by lower-numbered dynamic regions.

Default value: all-zeroes.

PMP HARDWIRED ADDR

Values of pmpaddr registers whose PMP_HARDWIRED bits are set to 1. Has no effect on PMP

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regions which are not hardwired.

Default value: all-zeroes.

PMP_HARDWIRED_CFG

Values of pmpcfg registers whose PMP_HARDWIRED bits are set to 1. Has no effect on PMP regions

which are not hardwired.

Default value: all-zeroes.

DEBUG_SUPPORT

Support for run/halt and instruction injection from an external Debug Module, support for Debug

Mode, and Debug Mode CSRs.

Requires: CSR_M_MANDATORY, CSR_M_TRAP.

Default value: 0

BREAKPOINT_TRIGGERS

Number of hardware breakpoints. A breakpoint is implemented as a trigger that supports only exact execution address matches, ignoring instruction size. That is, a trigger which supports type=2

execute=1 (but not store/load=1, i.e. not a watchpoint).

Requires: DEBUG_SUPPORT

Default value: 0

2.3.4. External interrupt support

NUM_IRQS

Number of external IRQs implemented in meiea, meipa, meifa and meipra, if CSR_M_TRAP is

enabled. Minimum 1, maximum 512.

Default value: 32

IRQ_PRIORITY_BITS

Number of priority bits implemented for each interrupt in meipra. The number of distinct levels is

(1 << IRQ_PRIORITY_BITS). Minimum 0, max 4. Note that having more than 1 priority level with a

large number of IRQs will have a severe effect on timing.

Default value: 0

2.3.5. Identification Registers

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MVENDORID_VAL

Value of the mvendorid CSR. JEDEC JEP106-compliant vendor ID, or all-zeroes. 31:7 is continuation

code count, 6:0 is ID. Parity bit is not stored.

Default value: all-zeroes.

MIMPID_VAL

Value of the mimpid CSR. Implementation ID for this specific version of Hazard3. Should be a git

hash, or all-zeroes.

Default value: all-zeroes.

MHARTID_VAL

Value of the mhartid CSR. Each Hazard3 core has a single hardware thread. Multiple cores should

have unique IDs.

Default value: all-zeroes.

MCONFIGPTR VAL

Value of the mconfigptr CSR. Pointer to configuration structure blob, or all-zeroes. Must be at least

4-byte-aligned.

Default value: all-zeroes.

2.3.6. Performance/size options

REDUCED_BYPASS

Remove all forwarding paths except $X \rightarrow X$ (so back-to-back ALU ops can still run at 1 CPI), to save

area. This has a significant impact on per-clock performance, so should only be considered for

extremely low-area implementations.

Default value: 0

MULDIV_UNROLL

Bits per clock for multiply/divide circuit, if present. Must be a power of 2.

Default value: 1

MUL FAST

Use single-cycle multiply circuit for MUL instructions, retiring to stage 3. The sequential

multiply/divide circuit is still used for MULH*

Default value: 0

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MUL_FASTER

Retire fast multiply results to stage 2 instead of stage 3. Throughput is the same, but latency is reduced from 2 cycles to 1 cycle.

Requires: MUL_FAST.

Default value: 0

MULH FAST

Extend the fast multiply circuit to also cover MULH*, and remove the multiply functionality from the sequential multiply/divide circuit.

Requires: MUL_FAST

Default value: 0

FAST_BRANCHCMP

Instantiate a separate comparator (eq/lt/ltu) for branch comparisons, rather than using the ALU. Improves fetch address delay, especially if Zba extension is enabled. Disabling may save area.

Default value: 1

RESET_REGFILE

Whether to support reset of the general purpose registers. There are around 1k bits in the register file, so the reset can be disabled e.g. to permit block-RAM inference on FPGA.

Default value: 1

BRANCH PREDICTOR

Enable branch prediction. The branch predictor consists of a single BTB entry which is allocated on a taken backward branch, and cleared on a mispredicted nontaken branch, a fence.i or a trap. Successful prediction eliminates the 1-cyle fetch bubble on a taken branch, usually making tight loops faster.

Requires: EXTENSION_ZIFENCEI

Default value: 1

MTVEC_WMASK

MTVEC_WMASK: Mask of which bits in mtvec are writable. Full writability (except for bit 1) is recommended, because a common idiom in setup code is to set mtvec just past code that may trap, as a hardware try {···} catch block.

- The vectoring mode can be made fixed by clearing the LSB of MTVEC WMASK
- In vectored mode, the vector table must be aligned to its size, rounded up to a power of two.

Default: All writable except for bit 1.

2.4. Interfaces (Top-level Ports)

TODO lol

Chapter 3. CSRs

The RISC-V privileged specification affords flexibility as to which CSRs are implemented, and how they behave. This section documents the concrete behaviour of Hazard3's standard and nonstandard M-mode CSRs, as implemented.

All CSRs are 32-bit; MXLEN is fixed at 32 bits on Hazard3. All CSR addresses not listed in this section are unimplemented. Accessing an unimplemented CSR will cause an illegal instruction exception (mcause = 2). This includes all U-mode and S-mode CSRs.

IMPORTANT

The RISC-V Privileged Specification should be your primary reference for writing software to run on Hazard3. This section specifies those details which are left implementation-defined by the RISC-V Privileged Specification, for sake of completeness, but portable RISC-V software should not rely on these details.

3.1. Standard M-mode Identification CSRs

3.1.1. myendorid

Address: 0xf11

Vendor identifier. Read-only, configurable constant. Should contain either all-zeroes, or a valid JEDEC JEP106 vendor ID using the encoding in the RISC-V specification.

Bits	Name	Description
31:7	bank	The number of continuation codes in the vendor JEP106 ID. <i>One less than the JEP106 bank number</i> .
6:0	offset	Vendor ID within the specified bank. LSB (parity) is not stored.

3.1.2. marchid

Address: 0xf12

Architecture identifier for Hazard3. Read-only, constant.

Bits	Name	Description
31	-	0: Open-source implementation
30:0	-	0x1b (decimal 27): the registered architecture ID for Hazard3

3.1.3. mimpid

Address: 0xf13

Implementation identifier. Read-only, configurable constant.

Bits	Name	Description
31:0	-	Should contain the git hash of the Hazard3 revision from which the processor was synthesised, or all-zeroes.

3.1.4. mhartid

Address: 0xf14

Hart identification register. Read-only, configurable constant.

Bits	Name	Description
31:0	-	Hazard3 cores possess only one hardware thread, so this is a unique
		per-core identifier, assigned consecutively from 0.

3.1.5. mconfigptr

Address: 0xf15

Pointer to configuration data structure. Read-only, configurable constant.

Bits	Name	Description
31:0	-	Either pointer to configuration data structure, containing information about the harts and system, or all-zeroes. At least 4-byte-aligned.

3.1.6. misa

Address: 0x301

Read-only, constant. Value depends on which ISA extensions Hazard3 is configured with. The table below lists the fields which are *not* always hardwired to 0:

Bits	Name	Description
31:30	mxl	Always 0x1. Indicates this is a 32-bit processor.
23	X	1 if the core is configured to support trap-handling, otherwise 0. Hazard3 has nonstandard CSRs to enable/disable external interrupts on a per-interrupt basis, see meiea and meipa. The misa.x bit must be set to indicate their presence. Hazard3 does not implement any custom instructions.
20	U	1 if User mode is supported, otherwise 0.
12	m	1 if the M extension is present, otherwise 0.
2	С	1 if the C extension is present, otherwise 0.
0	а	1 if the A extension is present, otherwise 0.

3.2. Standard M-mode Trap Handling CSRs

3.2.1. mstatus

Address: 0x300

The below table lists the fields which are *not* hardwired to 0:

Bits	Name	Description
21	tw	Timeout wait. Only present if U-mode is supported. When 1, attempting to execute a WFI instruction in U-mode will instantly cause an illegal instruction exception.
17	mprv	Modify privilege. Only present if U-mode is supported. If 1, loads and stores behave as though the current privilege level were mpp. This includes physical memory protection checks, and the privilege level asserted on the system bus alongside the load/store address.
12:11	трр	Previous privilege level. If U-mode is supported, this register can store the values 3 (M-mode) or 0 (U-mode). Otherwise, only 3 (M-mode). If another value is written, hardware rounds to the nearest supported mode.
7	mpie	Previous interrupt enable. Readable and writable. Is set to the current value of mstatus.mie on trap entry. Is set to 1 on trap return.
3	mie	Interrupt enable. Readable and writable. Is set to 0 on trap entry. Is set to the current value of mstatus.mpie on trap return.

3.2.2. mstatush

Address: 0x310

Hardwired to 0.

3.2.3. medeleg

Address: 0x302

Unimplemented, as neither U-mode traps nor S-mode are supported. Access will cause an illegal instruction exception.

3.2.4. mideleg

Address: 0x303

Unimplemented, as neither U-mode traps nor S-mode are supported. Access will cause an illegal instruction exception.

3.2.5. mie

Address: 0x304

Interrupt enable register. Not to be confused with mstatus.mie, which is a global enable, having the final say in whether any interrupt which is both enabled in mie and pending in mip will actually cause the processor to transfer control to a handler.

The table below lists the fields which are *not* hardwired to 0:

Bits	Name	Description
11	meie	External interrupt enable. Hazard3 has internal custom CSRs to further filter external interrupts, see meiea.
7	mtie	Timer interrupt enable. A timer interrupt is requested when mie.mtie, mip.mtip and mstatus.mie are all 1.
3	msie	Software interrupt enable. A software interupt is requested when mie.msie, mip.mtip and mstatus.mie are all 1.

NOTE

RISC-V reserves bits 16+ of mie/mip for platform use, which Hazard3 could use for external interrupt control. On RV32I this could only control 16 external interrupts, so Hazard3 instead adds nonstandard interrupt enable registers starting at meiea, and keeps the upper half of mie reserved.

3.2.6. mip

Address: 0x344

Interrupt pending register. Read-only.

NOTE

The RISC-V specification lists mip as a read-write register, but the bits which are writable correspond to lower privilege modes (S- and U-mode) which are not implemented on Hazard3, so it is documented here as read-only.

The table below lists the fields which are *not* hardwired to 0:

Bits	Name	Description
11	meip	External interrupt pending. When 1, indicates there is at least one interrupt which is asserted (hence pending in meipa) and enabled in meiea.
7	mtip	Timer interrupt pending. Level-sensitive interrupt signal from outside the core. Connected to a standard, external RISC-V 64-bit timer.
3	msip	Software interrupt pending. In spite of the name, this is not triggered by an instruction on this core, rather it is wired to an external memory-mapped register to provide a cross-hart level-sensitive doorbell interrupt.

3.2.7. mtvec

Address: 0x305

Trap vector base address. Read-write. Exactly which bits of mtvec can be modified (possibly none) is configurable when instantiating the processor, but by default the entire register is writable. The reset value of mtvec is also configurable.

Bits	Name	Description
31:2	base	Base address for trap entry. In Vectored mode, this is <i>OR'd</i> with the trap offset to calculate the trap entry address, so the table must be aligned to its total size, rounded up to a power of 2. In Direct mode, base is word-aligned.
0	mode	0 selects Direct mode — all traps (whether exception or interrupt) jump to base. 1 selects Vectored mode — exceptions go to base, interrupts go to base mcause << 2.

NOTE

In the RISC-V specification, mode is a 2-bit write-any read-legal field in bits 1:0. Hazard3 implements this by hardwiring bit 1 to 0.

3.2.8. mscratch

Address: 0x340

Read-write 32-bit register. No specific hardware function—available for software to swap with a register when entering a trap handler.

3.2.9. mepc

Address: 0x341

Exception program counter. When entering a trap, the current value of the program counter is recorded here. When executing an mret, the processor jumps to mepc. Can also be read and written by software.

On Hazard3, bits 31:2 of mepc are capable of holding all 30-bit values. Bit 1 is writable only if the C extension is implemented, and is otherwise hardwired to 0. Bit 0 is hardwired to 0, as per the specification.

All traps on Hazard3 are precise. For example, a load/store bus error will set mepc to the exact address of the load/store instruction which encountered the fault.

3.2.10. mcause

Address: 0x342

Exception cause. Set when entering a trap to indicate the reason for the trap. Readable and writable by software.

NOTE

On Hazard3, most bits of meause are hardwired to 0. Only bit 31, and enough least-significant bits to index all exception and all interrupt causes (at least four bits), are backed by registers. Only these bits are writable; the RISC-V specification only requires that meause be able to hold all legal cause values.

The most significant bit of meause is set to 1 to indicate an interrupt cause, and 0 to indicate an exception cause. The following interrupt causes may be set by Hazard3 hardware:

Cause	Description	
3	Software interrupt (mip.msip)	
7	Timer interrupt (mip.mtip)	
11	External interrupt (mip.meip)	

The following exception causes may be set by Hazard3 hardware:

Cause	Description	
0	Instruction address misaligned	
1	Instruction access fault	
2	Illegal instruction	
3	Breakpoint	
4	Load address misaligned	
5	Load access fault	
6	Store/AMO address misaligned	
7	Store/AMO access fault	
11	Environment call	

3.2.11. mtval

Address: 0x343

Hardwired to 0.

3.2.12. mcounteren

Address: 0x306

Counter enable. Control access to counters from U-mode. Not to be confused with mcountinhibit.

This register only exists if U-mode is supported.

Bits	Name	Description
31:3	-	RES0

Bits	Name	Description
2	ir	If 1, U-mode is permitted to access the <code>instret/instreth</code> instruction retire counter CSRs. Otherwise, U-mode accesses to these CSRs will trap.
1	tm	No hardware effect, as the time/timeh CSRs are not implemented. However, this field still exists, as M-mode software can use it to track whether it should emulate U-mode attempts to access those CSRs.
0	су	If 1, U-mode is permitted to access the cycle/cycleh cycle counter CSRs. Otherwise, U-mode accesses to these CSRs will trap.

3.3. Standard Memory Protection CSRs

3.3.1. pmpcfg0...3

Address: 0x3a0 through 0x3a3

Configuration registers for up to 16 physical memory protection regions. Only present if PMP support is configured. If so, all 4 registers are present, but some registers may be partially/completely hardwired depending on the number of PMP regions present.

By default, M-mode has full permissions (RWX) on all of memory, and U-mode has no permissions. A PMP region can be configured to alter this default within some range of addresses. For every memory location executed, loaded or stored, the processor looks up the *lowest active region* that overlaps that memory location, and applies its permissions to determine whether this access is allowed. The full description can be found in the RISC-V privileged ISA manual.

Each pmpcfg register divides into four identical 8-bit chunks, each corresponding to one region, and laid out as below:

Bits	Name	Description
7	L	Lock region, and additionally enforce its permissions on M-mode as well as U-mode.
6:5	-	RES0
4:3	A	Address-matching mode. Values supported are 0 (OFF), 2 (NA4, naturally aligned 4-byte) and 3 (NAPOT, naturally aligned power-of-two). Attempting to write an unsupported value will set the region to OFF.
2	Х	Execute permission
1	W	Write permission
0	R	Read permission

3.3.2. pmpaddr0...15

Address: 0x3b0 through 0x3bf

Address registers for up to 16 physical memory protection regions. Only present if PMP support is configured. If so, all 16 registers are present, but some may fully/partially hardwired.

pmpaddr registers express addresses in units of 4 bytes, so on Hazard3 (a 32-bit processor with no virtual address support) only the lower 30 bits of each address register are implemented.

The interpretation of the pmpaddr bits depends on the A mode configured in the corresponding pmpcfg register field:

- For NA4, the entire 30-bit PMP address is matched against the 30 MSBs of the checked address.
- For NAPOT, pmpaddr bits up to and including the least-significant zero bit are ignored, and the remaining bits are matched against the MSBs of the checked address.

3.4. Standard M-mode Performance Counters

3.4.1. mcycle

Address: 0xb00

Lower half of the 64-bit cycle counter. Readable and writable by software. Increments every cycle, unless mcountinhibit.cy is 1, or the processor is in Debug Mode (as dcsr.stopcount is hardwired to 1).

If written with a value n and read on the very next cycle, the value read will be exactly n. The RISC-V spec says this about mcycle: "Any CSR write takes effect after the writing instruction has otherwise completed."

3.4.2. mcycleh

Address: 0xb80

Upper half of the 64-bit cycle counter. Readable and writable by software. Increments on cycles where mcycle has the value <code>0xfffffffff</code>, unless <code>mcountinhibit.cy</code> is 1, or the processor is in Debug Mode.

This includes when mcycle is written on that same cycle, since RISC-V specifies the CSR write takes place *after* the increment for that cycle.

3.4.3. minstret

Address: 0xb02

Lower half of the 64-bit instruction retire counter. Readable and writable by software. Increments with every instruction executed, unless mcountinhibit.ir is 1, or the processor is in Debug Mode (as dcsr.stopcount is hardwired to 1).

If some value n is written to minstret, and it is read back by the very next instruction, the value read will be exactly n. This is because the CSR write logically takes place after the instruction has otherwise completed.

3.4.4. minstreth

Address: 0xb82

Upper half of the 64-bit instruction retire counter. Readable and writable by software. Increments when the core retires an instruction and the value of minstret is 0xfffffffff, unless mcountinhibit.ir is 1, or the processor is in Debug Mode.

3.4.5. mhpmcounter3...31

Address: 0xb03 through 0xb1f

Hardwired to 0.

3.4.6. mhpmcounter3...31h

Address: 0xb83 through 0xb9f

Hardwired to 0.

3.4.7. mcountinhibit

Address: 0x320

Counter inhibit. Read-write. The table below lists the fields which are *not* hardwired to 0:

Bits	Name	Description
2	ir	When 1, inhibit counting of minstret/minstreth. Resets to 1.
0	су	When 1, inhibit counting of mcycle/mcycleh. Resets to 1.

3.4.8. mhpmevent3...31

Address: 0x323 through 0x33f

Hardwired to 0.

3.5. Standard Trigger CSRs

3.5.1. tselect

Address: 0x7a0

Unimplemented. Reads as 0, write causes illegal instruction exception.

3.5.2. tdata1...3

Address: 0x7a1 through 0x7a3

Unimplemented. Access will cause an illegal instruction exception.

3.6. Standard Debug Mode CSRs

This section describes the Debug Mode CSRs, which follow the 0.13.2 RISC-V debug specification. The Debug section gives more detail on the remainder of Hazard3's debug implementation, including the Debug Module.

All Debug Mode CSRs are 32-bit; DXLEN is always 32.

3.6.1. dcsr

Address: 0x7b0

Debug control and status register. Access outside of Debug Mode will cause an illegal instruction exception. Relevant fields are implemented as follows:

Bits	Name	Description
31:28	xdebugver	Hardwired to 4: external debug support as per RISC-V 0.13.2 debug specification.
15	ebreakm	When 1, ebreak instructions executed in M-mode will break to Debug Mode instead of trapping
12	ebreaku	When 1, ebreak instructions executed in U-mode will break to Debug Mode instead of trapping. Hardwired to 0 if U-mode is not supported.
11	stepie	Hardwired to 0: no interrupts are taken during hardware single-stepping.
10	stopcount	Hardwired to 1: mcycle/mcycleh and minstret/minstreth do not increment in Debug Mode.
9	stoptime	Hardwired to 1: core-local timers don't increment in debug mode. This requires cooperation of external hardware based on the halt status to implement correctly.
8:6	cause	Read-only, set by hardware — see table below.
2	step	When 1, re-enter Debug Mode after each instruction executed in M-mode.
1:0	prv	Read the privilege state the core was in when it entered Debug Mode, and set the privilege state it will be in when it exits Debug Mode. If U-mode is implemented, the values 3 and 0 are supported. Otherwise hardwired to 3.

Fields not mentioned above are hardwired to 0.

Hazard3 may set the following dcsr.cause values:

Cause	Description	
1	Processor entered Debug Mode due to an ebreak instruction executed in M-mode.	

Cause	Description
3	Processor entered Debug Mode due to a halt request, or a reset-halt request present when the core reset was released.
4	Processor entered Debug Mode after executing one instruction with single-stepping enabled.

Cause 5 (resethaltreq) is never set by hardware. This event is reported as a normal halt, cause 3. Cause 2 (trigger) is never used because there are no triggers. (TODO?)

3.6.2. dpc

Address: 0x7b1

Debug program counter. When entering Debug Mode, dpc samples the current program counter, e.g. the address of an ebreak which caused Debug Mode entry. When leaving debug mode, the processor jumps to dpc. The host may read/write this register whilst in Debug Mode.

3.6.3. dscratch0

Address: 0x7b2

Not implemented. Access will cause an illegal instruction exception.

To provide data exchange between the Debug Module and the core, the Debug Module's data0 register is mapped into the core's CSR space at a read/write M-custom address — see dmdata0.

3.6.4. dscratch1

Address: 0x7b3

Not implemented. Access will cause an illegal instruction exception.

3.7. Custom Debug Mode CSRs

3.7.1. dmdata0

Address: 0xbff

The Debug Module's internal data0 register is mapped to this CSR address when the core is in debug mode. At any other time, access to this CSR address will cause an illegal instruction exception.

NOTE

The 0.13.2 debug specification allows for the Debug Module's abstract data registers to be mapped into the core's CSR address space, but there is no Debug-custom space, so the read/write M-custom space is used instead to avoid conflict with future versions of the debug specification.

The Debug Module uses this mapping to exchange data with the core by injecting csrr/csrw instructions into the prefetch buffer. This in turn is used to implement the Abstract Access Register

command. See Debug.

This CSR address is given by the dataaddress field of the Debug Module's hartinfo register, and hartinfo.dataaccess is set to 0 to indicate this is a CSR mapping, not a memory mapping.

3.8. Custom Interrupt Handling CSRs

3.8.1. meiea

Address: 0xbe0

External interrupt enable array. Contains a read-write bit for each external interrupt request: a 1 bit indicates that interrupt is currently enabled. At reset, all external interrupts are disabled.

If enabled, an external interrupt can cause assertion of the standard RISC-V machine external interrupt pending flag (mip.meip), and therefore cause the processor to enter the external interrupt vector. See meipa.

There are up to 512 external interrupts. The upper half of this register contains a 16-bit window into the full 512-bit vector. The window is indexed by the 5 LSBs of the write data. For example:

```
csrrs a0, meiea, a0 // Read IRQ enables from the window selected by a0 csrw meiea, a0 // Write a0[31:16] to the window selected by a0[4:0] csrr a0, meiea // Read from window 0 (edge case)
```

The purpose of this scheme is to allow software to *index* an array of interrupt enables (something not usually possible in the CSR space) without introducing a stateful CSR index register which may have to be saved/restored around IRQs.

Bits	Name	Description
31:16	window	16-bit read/write window into the external interrupt enable array
15:5	-	RES0
4:0	index	Write-only self-clearing field (no value is stored) used to control which window of the array appears in window.

3.8.2. meipa

Address: 0xbe1

External interrupt pending array. Contains a read-only bit for each external interrupt request. Similarly to meiea, this register is a window into an array of up to 512 external interrupt flags. The status appears in the upper 16 bits of the value read from meipa, and the lower 5 bits of the value written by the same CSR instruction (or 0 if no write takes place) select a 16-bit window of the full interrupt pending array.

A 1 bit indicates that interrupt is currently asserted. IRQs are assumed to be level-sensitive, and the relevant meipa bit is cleared by servicing the requestor so that it deasserts its interrupt request.

When any interrupt of sufficient priority is both set in meipa and enabled in meiea, the standard RISC-V external interrupt pending bit mip.meip is asserted. In other words, meipa is filtered by meiea to generate the standard mip.meip flag. So, an external interrupt is taken when *all* of the following are true:

- An interrupt is currently asserted in meipa
- The matching interrupt enable bit is set in meiea
- The interrupt priority is greater than or equal to the preemption priority in meicontext
- The standard M-mode interrupt enable mstatus.mie is set
- The standard M-mode global external interrupt enable mie.meie is set

In this case, the processor jumps to either:

- mtvec directly, if vectoring is disabled (mtvec[0] is 0)
- mtvec + 0x2c, if vectoring is enabled (mtvec[0] is 1)

Bits	Name	Description
31:16	window	16-bit read-only window into the external interrupt pending array
15:5	-	RES0
4:0	index	Write-only, self-clearing field (no value is stored) used to control which window of the array appears in window.

3.8.3. meifa

Address: 0xbe2

External interrupt force array. Contains a read-write bit for every interrupt request. Writing a 1 to a bit in the interrupt force array causes the corresponding bit to become pending in meipa. Software can use this feature to manually trigger a particular interrupt.

There are no restrictions on using meifa inside of an interrupt. The more useful case here is to schedule some lower-priority handler from within a high-priority interrupt, so that it will execute before the core returns to the foreground code. Implementers may wish to reserve some external IRQs with their external inputs tied to 0 for this purpose.

Bits can be cleared by software, and are cleared automatically by hardware upon a read of meinext which returns the corresponding IRQ number in meinext.irq (no matter whether meinext.update is written).

meifa implements the same array window indexing scheme as meiea and meipa.

Bits	Name	Description
31:16	window	16-bit read/write window into the external interrupt force array
15:5	-	RES0

Bits	Name	Description
4:0	index	Write-only, self-clearing field (no value is stored) used to control which window of the array appears in window.

3.8.4. meipra

Address: 0xbe3

External interrupt priority array. Each interrupt has an (up to) 4-bit priority value associated with it, and each access to this register reads and/or writes a 16-bit window containing four such priority values. When less than 16 priority levels are available, the LSBs of the priority fields are hardwired to 0.

When an interrupt's priority is lower than the current preemption priority meicontext.preempt, it is treated as not being pending. The pending bit in meipa will still assert, but the machine external interrupt pending bit mip.meip will not, so the processor will ignore this interrupt. See meicontext.

Bits	Name	Description
31:16	window	16-bit read/write window into the external interrupt priority array, containing four 4-bit priority values.
15: 7	-	RES0
6:0	index	Write-only, self-clearing field (no value is stored) used to control which window of the array appears in window.

3.8.5. meinext

Address: 0xbe4

Get next interrupt. Contains the index of the highest-priority external interrupt which is both asserted in meipa and enabled in meiea, left-shifted by 2 so that it can be used to index an array of 32-bit function pointers. If there is no such interrupt, the MSB is set.

When multiple interrupts of the same priority are both pending and enabled, the lowest-numbered wins. Interrupts with priority less than <code>meicontext.ppreempt</code>—the <code>previous</code> preemption priority—are treated as though they are not pending. This is to ensure that a preempting interrupt frame does not service interrupts which may be in progress in the frame that was preempted.

Bits	Name	Description
31	noirq	Set when there is no external interrupt which is enabled, pending, and has sufficient priority. Can be efficiently tested with a bltz or bgez instruction.
30:11	-	RES0
10:2	irq	Index of the highest-priority active external interrupt. Zero when no external interrupts with sufficient priority are both pending and enabled.

Bits	Name	Description
1	-	RES0
0	update	Writing 1 (self-clearing) causes hardware to update meicontext according to the IRQ number and preemption priority of the interrupt indicated in noirq/irq. This should be done in a single atomic operation, i.e. csrrsi a0, meinext, 0x1.

3.8.6. meicontext

Address: 0xbe5

External interrupt context register. Configures the priority level for interrupt preemption, and helps software track which interrupt it is currently in. The latter is useful when a common interrupt service routine handles interrupt requests from multiple instances of the same peripheral.

A three-level stack of preemption priorities is maintained in the preempt, ppreempt and pppreempt fields. The priority stack is saved when hardware enters the external interrupt vector, and restored by an mret instruction if meicontext.mreteirq is set.

The top entry of the priority stack, preempt, is used by hardware to ensure that only higher-priority interrupts can preempt the current interrupt. The next entry, ppreempt, is used to avoid servicing interrupts which may already be in progress in a frame that was preempted. The third entry, pppreempt, has no hardware effect, but ensures that preempt and ppreempt can be correctly saved/restored across arbitary levels of preemption.

Bits	Name	Description
31:28	pppreempt	Previous ppreempt. Set to ppreempt on priority save, set to zero on priority restore. Has no hardware effect, but ensures that when meicontext is saved/restored correctly, preempt and ppreempt stack correctly through arbitrarily many preemption frames.
27:24	ppreempt	Previous preempt. Set to preempt on priority save, restored to to pppreempt on priority restore. IRQs of lower priority than ppreempt are not visible in meinext, so that a preemptee is not re-taken in the preempting frame.
23:21	-	RES0

Bits	Name	Description
20:16	preempt	Minimum interrupt priority to preempt the current interrupt. Interrupts with lower priority than preempt do not cause the core to transfer to an interrupt handler. Updated by hardware when when meinext.update is written, or when hardware enters the external interrupt vector. If an interrupt is present in meinext, then preempt is set to one level greater than that interrupt's priority. Otherwise, ppreempt is set to
		one level greater than the maximum interrupt priority, disabling preemption.
15	noirq	Not in interrupt (read/write). Set to 1 at reset. Set to meinext.noirq when meinext.update is written. No hardware effect.
14:13	-	RES0
12:4	irq	Current IRQ number (read/write). Set to meinext.irq when meinext.update is written.
3	mtiesave	Reads as the current value of mie.mtie, if clearts is set. Otherwise reads as 0. Writes are ORed into mie.mtie.
2	msiesave	Reads as the current value of mie.msie, if clearts is set. Otherwise reads as 0. Writes are ORed into mie.msie.
1	clearts	Write-1 self-clearing field. Writing 1 will clear mie.mtie and mie.msie, and present their prior values in the mtiesave and msiesave of this register. This makes it safe to re-enable IRQs (via mstatus.mie) without the possibility of being preempted by the standard timer and soft interrupt handlers, which may not be aware of Hazard3's interrupt hardware.
		The clear due to clearts takes precedence over the set due to mtiesave/msiesave, although it would be unusual for software to write both on the same cycle.
0	mreteirq	Enable restore of the preemption priority stack on mret. This bit is set on entering the external interrupt vector, cleared by mret, and cleared upon taking any trap other than an external interrupt.
		Provided meicontext is saved on entry to the external interrupt vector (before enabling preemption), is restored before exiting, and the standard software/timer IRQs are prevented from preempting (e.g. by using clearts), this flag allows the hardware to safely manage the preemption priority stack even when an external interrupt handler may take exceptions.

The following is an example of an external interrupt vector (mip.meip) which implements nested, prioritised interrupt dispatch using meicontext and meinext:

```
isr_external_irq:
   // Save caller saves and exception return state whilst IRQs are disabled.
   // We can't be pre-empted during this time, but if a higher-priority IRQ
   // arrives ("late arrival"), that will be the one displayed in meinext.
   addi sp, sp, -80
    sw ra, \theta(sp)
    ... snip
    sw t6, 60(sp)
   csrr a0, mepc
   sw a0, 64(sp)
   // Set bit 1 when reading to clear+save mie.mtie and mie.msie
   csrrsi a0, meicontext, 0x2
    sw a0, 68(sp)
   csrr a0, mstatus
   sw a0, 72(sp)
   j get_next_irq
dispatch irq:
   // Preemption priority was configured by meinext update, so enable preemption:
   csrsi mstatus, 0x8
   // meinext is pre-shifted by 2, so only an add is required to index table
   la a1, _external_irq_table
    add a1, a1, a0
   jalr ra, a1
   // Disable IRQs on returning so we can sample the next IRQ
   csrci mstatus, 0x8
get_next_irq:
   // Sample the current highest-priority active IRQ (left-shifted by 2) from
   // meinext, and write 1 to the LSB to tell hardware to tell hw to update
   // meicontext with the preemption priority (and IRQ number) of this IRQ
   csrrsi a0, meinext, 0x1
   // MSB will be set if there is no active IRQ at the current priority level
   bgez a0, dispatch_irq
no_more_irqs:
   // Restore saved context and return from handler
   lw a0, 64(sp)
   csrw mepc, a0
   lw a0, 68(sp)
   csrw meicontext, a0
   lw a0, 72(sp)
   csrw mstatus, a0
   lw ra, 0(sp)
    ... snip
   lw t6, 60(sp)
```

3.9. Custom Memory Protection CSRs

3.9.1. pmpcfgm0

Address: 0xbd0

PMP M-mode configuration. One bit per PMP region. Setting a bit makes the corresponding region apply to M-mode (like the pmpcfg.L bit) but does not lock the region.

PMP is useful for non-security-related purposes, such as stack guarding and peripheral emulation. This extension allows M-mode to freely use any currently unlocked regions for its own purposes, without the inconvenience of having to lock them.

Note that this does not grant any new capabilities to M-mode, since in the base standard it is already possible to apply unlocked regions to M-mode by locking them. In general, PMP regions should be locked in ascending region number order so they can't be subsequently overridden by currently unlocked regions.

Note also that this is not the same as the "rule locking bypass" bit in the ePMP extension, which does not permit locked and unlocked M-mode regions to coexist.

Bits	Name	Description
31:16	-	RES0
15:0	m	Regions apply to M-mode if this bit <i>or</i> the corresponding pmpcfg.L bit is set. Regions are locked if and only if the corresponding pmpcfg.L bit is set.

3.10. Custom Power Control CSRs

3.10.1. msleep

Address: 0xbf0

M-mode sleep control register.

Bits	Name	Description
31:3	-	RES0
2	deepsleep	Deassert the clock request signal when entering the block or WFI state, and wait for clock acknowledge to reassert before leaving the block or WFI state.

Bits	Name	Description
1	block	Write 1 to enter a WFI sleep state until either an unblock signal is received, or an interrupt is asserted that would cause a WFI to exit. Clears automatically when leaving the blocked state.
		If an unblock signal has been received since the last time block was written to 1, the write is ignored. In other words, the blocked state falls through immediately in this case.
		An unblock signal is received when another hart writes 1 to its unblock register, or for some other platform-specified reason.
0	unblock	Write 1 to post an unblock signal to other harts in the system. Always reads back as 0.

3.10.2. sleep

Address: 0x8f0

U-mode sleep control register. A subset of the fields in msleep. If mstatus.tw is 1, then attempting to access this register from U-mode causes an illegal opcode trap.

Bits	Name	Description
31:2	-	RES0
1	block	U-mode access to the msleep.block bit
0	unblock	U-mode access to the msleep.unblock bit

Chapter 4. Debug

Hazard3, along with its external debug components, implements version 0.13.2 of the RISC-V debug specification. It supports the following:

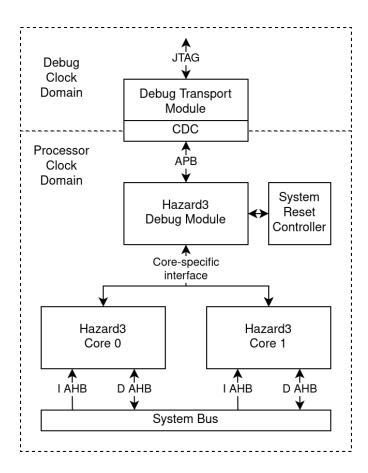
- · Run/halt/reset control as required
- · Abstract GPR access as required
- Program Buffer, 2 words plus impebreak
- Automatic trigger of abstract command (abstractauto) on data0 or Program Buffer access for efficient memory block transfers from the host
- (Optional) System Bus Access, either through a dedicated AHB-Lite master, or multiplexed with a processor load/store port
- (Optional) An instruction address trigger unit (hardware breakpoints)

4.1. Debug Topologies

Hazard3's Debug Module has the following interfaces:

- An upstream AMBA 3 APB port—the "Debug Module Interface"—for host access to the Debug Module
- A downstream Hazard3-specific interface to one or more cores (multicore support is experimental)
- Some reset request/acknowledge signals which require careful handshaking with system-level reset logic

This is shown in the example topology below.



The Debug Module *must* be connected directly to the processors without intervening registers. This implies the Debug Module is in the same clock domain as the processors, so multiple processors on the same Debug Module must share a common clock.

Upstream of the Debug Module is at least one Debug Transport Module, which bridges some host-facing interface such as JTAG to the APB Debug Module Interface. Hazard3 provides an implementation of a standard RISC-V JTAG-DTM, but any APB master could be used. The Debug Module requires at least 7 bits of word addressing, i.e. 9 bits of byte address space.

An APB arbiter could be inserted here, to allow multiple transports to be used, provided the host(s) avoid using multiple transports concurrently. This also admits simple implementation of self-hosted debug, by mapping the Debug Module to a system-level peripheral address space.

The clock domain crossing (if any) occurs on the downstream port of the Debug Transport Module. Hazard3's JTAG-DTM implementation runs entirely in the TCK domain, and instantiates a bus clock-crossing module internally to bridge a TCK-domain internal APB bus to an external bus in the processor clock domain.

It is possible to instantiate multiple Debug Modules, one per core, and attach them to a single Debug Transport Module. This is not the preferred topology, but it does allow multiple cores to be independently clocked.

4.2. Implementation-defined behaviour

Features implemented by the Hazard3 Debug Module (beyond the mandatory):

• Halt-on-reset, selectable per-hart

- Program Buffer, size 2 words, impebreak = 1.
- A single data register (data0) is implemented as a per-hart CSR accessible by the DM
- abstractauto is supported on the data0 register
- Up to 32 harts selectable via hartsel

Not implemented:

- Hart array mask selection
- · Abstract access memory
- · Abstract access CSR
- Post-incrementing abstract access GPR
- · System bus access

The core behaves as follows:

- Branch, jal, jalr and auipc are illegal in debug mode, because they observe PC: attempting to execute will halt Program Buffer execution and report an exception in abstractcs.cmderr
- The dret instruction is not implemented (a special purpose DM-to-core signal is used to signal resume)
- The dscratch CSRs are not implemented
- The DM's data0 register is mapped into the core as a CSR, dmdata0, address 0xbff.
 - Raises an illegal instruction exception when accessed outside of Debug Mode
 - The DM ignores attempted core writes to the CSR, unless the DM is currently executing an abstract command on that core
 - Used by the DM to implement abstract GPR access, by injecting CSR read/write instructions
- dcsr.stepie is hardwired to 0 (no interrupts during single stepping)
- dcsr.stopcount and dcsr.stoptime are hardwired to 1 (no counter or internal timer increment in debug mode)
- dcsr.mprven is hardwired to 0
- dcsr.prv is hardwired to 3 (M-mode)

See also Standard Debug Mode CSRs for more details on the core-side Debug Mode registers.

The debug host must use the Program Buffer to access CSRs and memory. This carries some overhead for individual accesses, but is efficient for bulk transfers: the abstractauto feature allows the DM to trigger the Program Buffer and/or a GPR tranfer automatically following every data0 access, which can be used for e.g. autoincrementing read/write memory bursts. Program Buffer read/writes can also be used as abstractauto triggers: this is less useful than the data0 trigger, but takes little extra effort to implement, and can be used to read/write a large number of CSRs efficiently.

Abstract memory access is not implemented because, for bulk transfers, it offers no better throughput than Program Buffer execution with abstractauto. Non-bulk transfers, while slower, are

still instantaneous from the perspective of the human at the other end of the wire.

The Hazard3 Debug Module has experimental support for multi-core debug. Each core possesses exactly one hardware thread (hart) which is exposed to the debugger. The RISC-V specification does not mandate what mapping is used between the Debug Module hart index hartsel and each core's mhartid CSR, but a 1:1 match of these values is the least likely to cause issues. Each core's mhartid can be configured using the MHARTID_VAL parameter during instantiation.

4.3. Debug Module to Core Interface

The DM can inject instructions directly into the core's instruction prefetch buffer. This mechanism is used to execute the Program Buffer, or used directly by the DM, issuing hardcoded instructions to manipulate core state.

The DM's data0 register is exposed to the core as a debug mode CSR. By issuing instructions to make the core read or write this dummy CSR, the DM can exchange data with the core. To read from a GPR x into data0, the DM issues a csrw data0, x instruction. Similarly csrr x, data0 will write data0 to that GPR. The DM always follows the CSR instruction with an ebreak, just like the implicit ebreak at the end of the Program Buffer, so that it is notified by the core when the GPR read instruction sequence completes.

TODO reset interface description

Appendix A: Instruction Cycle Counts

All timings are given assuming perfect bus behaviour (no downstream bus stalls), and that the core is configured with MULDIV_UNROLL = 2 and all other configuration options set for maximum performance.

A.1. RV32I

Instruction	Cycles	Note	
Integer Register-register			
add rd, rs1, rs2	1		
sub rd, rs1, rs2	1		
slt rd, rs1, rs2	1		
sltu rd, rs1, rs2	1		
and rd, rs1, rs2	1		
or rd, rs1, rs2	1		
xor rd, rs1, rs2	1		
sll rd, rs1, rs2	1		
srl rd, rs1, rs2	1		
sra rd, rs1, rs2	1		
Integer Register-immediate	9		
addi rd, rs1, imm	1	nop is a pseudo-op for addi x0, x0, 0	
slti rd, rs1, imm	1		
sltiu rd, rs1, imm	1		
andi rd, rs1, imm	1		
ori rd, rs1, imm	1		
xori rd, rs1, imm	1		
slli rd, rs1, imm	1		
srli rd, rs1, imm	1		
srai rd, rs1, imm	1		
Large Immediate	Large Immediate		
lui rd, imm	1		
auipc rd, imm	1		
Control Transfer	Control Transfer		
jal rd, label	2 ^[1]		
jalr rd, rs1, imm	2 ^[1]		

Instruction	Cycles	Note
beq rs1, rs2, label	1 or 2 ^[1]	1 if correctly predicted, 2 if mispredicted.
bne rs1, rs2, label	1 or 2 ^[1]	1 if correctly predicted, 2 if mispredicted.
blt rs1, rs2, label	1 or 2 ^[1]	1 if correctly predicted, 2 if mispredicted.
bge rs1, rs2, label	1 or 2 ^[1]	1 if correctly predicted, 2 if mispredicted.
bltu rs1, rs2, label	1 or 2 ^[1]	1 if correctly predicted, 2 if mispredicted.
bgeu rs1, rs2, label	1 or 2 ^[1]	1 if correctly predicted, 2 if mispredicted.
Load and Store		
lw rd, imm(rs1)	1 or 2	1 if next instruction is independent, 2 if dependent. [2]
lh rd, imm(rs1)	1 or 2	1 if next instruction is independent, 2 if dependent. [2]
lhu rd, imm(rs1)	1 or 2	1 if next instruction is independent, 2 if dependent. [2]
lb rd, imm(rs1)	1 or 2	1 if next instruction is independent, 2 if dependent. [2]
lbu rd, imm(rs1)	1 or 2	1 if next instruction is independent, 2 if dependent. [2]
sw rs2, imm(rs1)	1	
sh rs2, imm(rs1)	1	
sb rs2, imm(rs1)	1	

A.2. M Extension

Timings assume the core is configured with MULDIV_UNROLL = 2 and MUL_FAST = 1. I.e. the sequential multiply/divide circuit processes two bits per cycle, and a separate dedicated multiplier is present for the mul instruction.

Instruction	Cycles	Note	
32 × 32 → 32 Multiply			
mul rd, rs1, rs2	1		
32 × 32 → 64 Multiply, Upper Half			
mulh rd, rs1, rs2	1		
mulhsu rd, rs1, rs2	1		
mulhu rd, rs1, rs2	1		
Divide and Remainder			
div rd, rs1, rs2	18 or 19	Depending on sign correction	
divu rd, rs1, rs2	18		
rem rd, rs1, rs2	18 or 19	Depending on sign correction	
remu rd, rs1, rs2	18		

A.3. A Extension

Instruction	Cycles	Note	
Load-Reserved/Store-Cond	Load-Reserved/Store-Conditional		
lr.w rd, (rs1)	1 or 2	2 if next instruction is dependent ^[2] , an lr.w, sc.w or amo*.w. ^[3]	
sc.w rd, rs2, (rs1)	1 or 2	2 if next instruction is dependent ^[2] , an lr.w, sc.w or amo*.w. ^[3]	
Atomic Memory Operations			
amoswap.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amoadd.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amoxor.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amoand.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amoor.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amomin.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amomax.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amominu.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	
amomaxu.w rd, rs2, (rs1)	4+	4 per attempt. Multiple attempts if reservation is lost. [4]	

A.4. C Extension

All C extension 16-bit instructions are aliases of base RV32I instructions. On Hazard3, they perform identically to their 32-bit counterparts.

A consequence of the C extension is that 32-bit instructions can be non-naturally-aligned. This has no penalty during sequential execution, but branching to a 32-bit instruction that is not 32-bit-aligned carries a 1 cycle penalty, because the instruction fetch is cracked into two naturally-aligned bus accesses.

A.5. Privileged Instructions (including Zicsr)

Instruction	Cycles	Note
CSR Access		
csrrw rd, csr, rs1	1	
csrrc rd, csr, rs1	1	
csrrs rd, csr, rs1	1	
csrrwi rd, csr, imm	1	
esrrci rd, esr, imm	1	
csrrsi rd, csr, imm	1	
Trap Request		

Instruction	Cycles	Note
ecall	3	Time given is for jumping to mtvec
ebreak	3	Time given is for jumping to mtvec

A.6. Bit Manipulation

Instruction	Cycles	Note
Zba (address generation)	'	
sh1add rd, rs1, rs2	1	
sh2add rd, rs1, rs2	1	
sh3add rd, rs1, rs2	1	
Zbb (basic bit manipulation)		
andn rd, rs1, rs2	1	
clz rd, rs1	1	
cpop rd, rs1	1	
ctz rd, rs1	1	
max rd, rs1, rs2	1	
maxu rd, rs1, rs2	1	
min rd, rs1, rs2	1	
minu rd, rs1, rs2	1	
orc.b rd, rs1	1	
orn rd, rs1, rs2	1	
rev8 rd, rs1	1	
rol rd, rs1, rs2	1	
ror rd, rs1, rs2	1	
rori rd, rs1, imm	1	
sext.b rd, rs1	1	
sext.h rd, rs1	1	
xnor rd, rs1, rs2	1	
zext.h rd, rs1	1	
zext.b rd, rs1	1	zext.b is a pseudo-op for andi rd, rs1, 0xff
Zbc (carry-less multiply)		
clmul rd, rs1, rs2	1	
clmulh rd, rs1, rs2	1	
clmulr rd, rs1, rs2	1	

Instruction	Cycles	Note	
Zbs (single-bit manipulation)			
bclr rd, rs1, rs2	1		
bclri rd, rs1, imm	1		
bext rd, rs1, rs2	1		
bexti rd, rs1, imm	1		
binv rd, rs1, rs2	1		
binvi rd, rs1, imm	1		
bset rd, rs1, rs2	1		
bseti rd, rs1, imm	1		
Zbkb (basic bit manipulation for cryptography)			
pack rd, rs1, rs2	1		
packh rd, rs1, rs2	1		
brev8 rd, rs1	1		
zip rd, rs1	1		
unzip rd, rs1	1		

A.7. Branch Predictor

Hazard3 includes a minimal branch predictor, to accelerate tight loops:

- The instruction frontend remembers the last taken, backward branch
- If the same branch is seen again, it is predicted taken
- · All other branches are predicted nontaken
- If a predicted-taken branch is not taken, the predictor state is cleared, and it will be predicted nontaken on its next execution.

Correctly predicted branches execute in one cycle: the frontend is able to stitch together the two nonsequential fetch paths so that they appear sequential. Mispredicted branches incur a penalty cycle, since a nonsequential fetch address must be issued when the branch is executed.

- [1] A jump or branch to a 32-bit instruction which is not 32-bit-aligned requires one additional cycle, because two naturally aligned bus cycles are required to fetch the target instruction.
- [2] If an instruction in stage 2 (e.g. an add) uses data from stage 3 (e.g. a lw result), a 1-cycle bubble is inserted between the pair. A load data \rightarrow store data dependency is *not* an example of this, because data is produced and consumed in stage 3. However, load data \rightarrow load address *would* qualify, as would e.g. sc.w \rightarrow beqz.
- [3] A pipeline bubble is inserted between <code>lr.w/sc.w</code> and an immediately-following <code>lr.w/sc.w/amo*</code>, because the AHB5 bus standard does not permit pipelined exclusive accesses. A stall would be inserted between <code>lr.w</code> and <code>sc.w</code> anyhow, so the local monitor can be updated based on the <code>lr.w</code> data phase in time to suppress the <code>sc.w</code> address phase.
- [4] AMOs are issued as a paired exclusive read and exclusive write on the bus, at the maximum speed of 2 cycles per access, since the bus does not permit pipelining of exclusive reads/writes. If the write phase fails due to the global monitor reporting a lost reservation, the instruction loops at a rate of 4 cycles per loop, until success. If the read reservation is refused by the global monitor, the instruction generates a Store/AMO Fault exception, to avoid an infinite loop.

Appendix B: Instruction Pseudocode

This section is a quick reference for the operation of the instructions supported by Hazard3, in Verilog syntax. Conventions used in this section:

- rs1, rs2 and rd are 32-bit unsigned vector variables referring to the two register operands and the destination register
- imm is a 32-bit unsigned vector referring to the instruction's immediate value
- pc is a 32-bit unsigned vector referring to the program counter
- mem is an array of 8-bit unsigned vectors, each corresponding to a byte address in memory.

B.1. RV32I: Register-register

With the exception of the shift instructions, all instructions in this section have an immediate range of -2048 to 2047. Negative immediates can be useful for the bitwise operations too: for example not rd, rs1 is a pseudo-op for xori rd, rs1, -1.

Shift instructions have an immediate range of 0 to 31.

B.1.1. add

Add register to register.

Syntax:

```
add rd, rs1, rs2
```

Operation:

```
rd = rs1 + rs2;
```

B.1.2. sub

Subtract register from register.

Syntax:

```
sub rd, rs1, rs2
```

```
rd = rs1 - rs2;
```

B.1.3. slt

Set if less than (signed).

Syntax:

```
slt rd, rs1, rs2
```

Operation:

```
rd = $signed(rs1) < $signed(rs2);
```

B.1.4. sltu

Set if less than (unsigned).

Syntax:

```
sltu rd, rs1, rs
```

Operation:

```
rd = rs1 < rs2;
```

B.1.5. and

Bitwise AND.

Syntax:

```
and rd, rs1, rs2
```

Operation:

```
rd = rs1 & rs2;
```

B.1.6. or

Bitwise OR.

or rd, rs1, rs2'

Operation:

rd = rs1 | rs2;

B.1.7. xor

Bitwise XOR.

Syntax:

xor rd, rs1, rs2

Operation:

rd = rs1 ^ rs2;

B.1.8. sll

Shift left, logical.

Syntax:

sll rd, rs1, rs2

Operation:

rd = rs1 << rs2;

B.1.9. srl

Shift right, logical.

Syntax:

srl rd, rs1, rs2

Operation:

rd = rs1 >> rs2;

B.1.10. sra

Shift right, arithmetic.

Syntax:

```
sra rd, rs1, rs2
```

Operation:

```
rd = rs1 >>> rs2;
```

B.2. RV32I: Register-immediate

B.2.1. addi

Add register to immediate.

Syntax:

```
addi rd, rs1, imm
```

Operation:

```
rd = rs1 + imm
```

B.2.2. slti

Set if less than immediate (signed).

Syntax:

```
slti rd, rs1, imm
```

Operation:

```
rd = $signed(rs1) < $signed(imm);</pre>
```

B.2.3. sltiu

Set if less than immediate (unsigned).

sltiu rd, rs1, imm

Operation:

```
rd = rs1 < imm;
```

B.2.4. andi

Bitwise AND with immediate.

Syntax:

```
andi rd, rs1, imm
```

Operation:

```
rd = rs1 & imm;
```

B.2.5. ori

Bitwise OR with immediate.

Syntax:

```
ori rd, rs1, imm
```

Operation:

```
rd = rs1 \| imm;
```

B.2.6. xori

Bitwise XOR with immediate.

Syntax:

```
xori rd, rs1, imm
```

```
rd = rs1 ^ imm;
```

B.2.7. slli

Shift left, logical, immediate.

Syntax:

```
slli rd, rs1, imm
```

Operation:

```
rd = rs1 << imm;
```

B.2.8. srli

Shift right, logical, immediate.

Syntax:

```
srli rd, rs1, imm
```

Operation:

```
rd = rs1 >> imm;
```

B.2.9. srai

Shift right, arithmetic, immediate.

Syntax:

```
srai rd, rs1, imm
```

Operation:

```
rd = rs1 >>> imm;
```

B.3. RV32I: Large immediate

B.3.1. lui

Load upper immediate.

```
lui rd, imm
```

```
rd = imm;
```

(imm is a 20-bit value followed by 12 zeroes)

B.3.2. auipc

Add upper immediate to program counter.

Syntax:

```
auipc rd, imm
```

Operation:

```
rd = pc + imm;
```

(imm is a 20-bit value followed by 12 zeroes)

B.4. RV32I: Control transfer

B.4.1. jal

Jump and link.

Syntax:

```
jal rd, label
j label  // rd is implicitly x0
```

Operation:

```
rd = pc + 4;
pc = label;
```

NOTE

the 16-bit variant, c.jal, writes pc + 2 to rd, rather than pc + 4. The rd value always points to the sequentially-next instruction.

B.4.2. jalr

Jump and link, target is register.

Syntax:

```
jalr rd, rs1, imm // imm is implicitly 0 if omitted.
jr rs1, imm // rd is implicitly x0. imm is implicitly 0 if omitted.
ret // pseudo-op for jr ra
```

Operation:

```
rd = pc + 4;
pc = rs1 + imm;
```

NOTE

the 16-bit variant, c.jalr, writes pc + 2 to rd, rather than pc + 4. The rd value always points to the sequentially-next instruction.

B.4.3. beq

Branch if equal.

Syntax:

```
beq rs1, rs2, label
```

Operation:

```
if (rs1 == rs2)
  pc = label;
```

B.4.4. bne

Branch if not equal.

Syntax:

```
bne rs1, rs2, label
```

```
if (rs1 != rs2)
  pc = label;
```

B.4.5. blt

Branch if less than (signed).

Syntax:

```
blt rs1, rs2, label
```

Operation:

```
if ($signed(rs1) < $signed(rs2))
  pc = label;</pre>
```

B.4.6. bge

Branch if greater than or equal (signed).

Syntax:

```
bge rs1, rs2, label
```

Operation:

```
if ($signed(rs1) >= $signed(rs2))
  pc = label;
```

B.4.7. bltu

Branch if less than (unsigned).

Syntax:

```
bltu rs1, rs2, label
```

Operation:

```
if (rs1 < rs2)
  pc = label;</pre>
```

B.4.8. bgeu

Branch if less than or equal (unsigned).

Syntax:

```
bgeu rs1, rs2, label
```

Operation:

```
if (rs1 >= rs2)
  pc = label;
```

B.5. RV32I: Load and Store

B.5.1. lw

Load word.

Syntax:

```
lw rd, imm(rs1)
lw rd, (rs1) // imm is implicitly 0 if omitted.
```

Operation:

```
rd = {
    mem[rs1 + imm + 3],
    mem[rs1 + imm + 2],
    mem[rs1 + imm + 1],
    mem[rs1 + imm]
};
```

B.5.2. lh

Load halfword (signed).

Syntax:

```
lh rd, imm(rs1)
lh rd, (rs1) // imm is implicitly 0 if omitted.
```

```
mem[rs1 + imm]
};
```

B.5.3. lhu

Load halfword (unsigned).

Syntax:

```
lhu rd, imm(rs1)
lhu rd, (rs1) // imm is implicitly 0 if omitted.
```

Operation:

```
rd = {
    16'h0000, // Zero-extend
    mem[rs1 + imm + 1],
    mem[rs1 + imm]
};
```

B.5.4. lb

Load byte (signed).

Syntax:

```
lb rd, imm(rs1)
  lb rd, (rs1)  // imm is implicitly 0 if omitted.
```

Operation:

```
rd = {
     {24{mem[rs1 + imm][7]}}, // Sign-extend
     mem[rs1 + imm]
};
```

B.5.5. lbu

Load byte (unsigned).

```
lbu rd, imm(rs1)
lbu rd, (rs1) // imm is implicitly 0 if omitted.
```

```
rd = {
    24'h000000, // Zero-extend
    mem[rs1 + imm]
};
```

B.5.6. sw

Store word.

Syntax:

```
sw rs2, imm(rs1)
sw rs2, (rs1) // imm is implicitly 0 if omitted.
```

Operation:

```
mem[rs1 + imm] = rs2[7:0];

mem[rs1 + imm + 1] = rs2[15:8];

mem[rs1 + imm + 2] = rs2[23:16];

mem[rs1 + imm + 3] = rs2[31:24];
```

B.5.7. sh

Store halfword.

Syntax:

```
sh rs2, imm(rs1)
sh rs2, (rs1) // imm is implicitly 0 if omitted.
```

Operation:

```
mem[rs1 + imm] = rs2[7:0];
mem[rs1 + imm + 1] = rs2[15:8];
```

B.5.8. sb

Store byte.

```
sb rs2, imm(rs1)
```

```
sb rs2, (rs1) // imm is implicitly 0 if omitted.
```

```
mem[rs1 + imm] = rs2[7:0];
```

B.6. M Extension

B.6.1. mul

Multiply $32 \times 32 \rightarrow 32$.

Syntax:

```
mul rd, rs1, rs2
```

Operation:

```
rd = rs1 * rs2;
```

B.6.2. mulh

Multiply signed (32) by signed (32), return upper 32 bits of the 64-bit result.

Syntax:

```
mulh rd, rs1, rs2
```

Operation:

```
// Both operands are sign-extended to 64 bits:
wire [63:0] result_full = {{32{rs1[31]}}, rs1} * {{32{rs2[31]}}, rs2};
rd = result_full[63:32];
```

B.6.3. mulhsu

Multiply signed (32) by unsigned (32), return upper 32 bits of the 64-bit result.

```
mulhsu rd, rs1, rs2
```

```
// rs1 is sign-extended, rs2 is zero-extended:
wire [63:0] result_full = {{32{rs1[31}}, rs1} * {32'h00000000, rs2};
rd = result_full[63:32];
```

B.6.4. mulhu

Multiply unsigned (32) by unsigned (32), return upper 32 bits of the 64-bit result.

Syntax:

```
mulhu rd, rs1, rs2
```

Operation:

```
wire [63:0] result_full = {32'h00000000, rs1} * {32'h00000000, rs2};
rd = result_full[63:32];
```

B.6.5. div

Divide (signed).

Syntax:

```
div rd, rs1, rs2
```

Operation:

```
if (rs2 == 32'h0)
    rd = 32'hffffffff;
else if (rs1 == 32'h80000000 && rs2 == 32'hffffffff) // Signed overflow
    rd = 32'h80000000;
else
    rd = $signed(rs1) / $signed(rs2);
```

B.6.6. divu

Divide (unsigned).

```
divu rd, rs1, rs2
```

```
if (rs2 == 32'h0)
    rd = 32'hffffffff;
else
    rd = rs1 / rs2;
```

B.6.7. rem

Remainder (signed).

Syntax:

```
rem rd, rs1, rs2
```

Operation:

```
if (rs2 == 32'h0)
    rd = rs1;
else
    rd = $signed(rs1) % $signed(rs2);
```

B.6.8. remu

Remainder (unsigned).

Syntax:

```
remu rd, rs1, rs2
```

Operation:

```
if (rs2 == 32'h0)
    rd = rs1;
else
    rd = rs1 % rs2;
```

B.7. A Extension

(TODO)

B.8. C Extension

All C extension instructions are 16-bit aliases of 32-bit instructions from other extensions (in the case of Hazard3, entirely from the RV32I base extension). They behave identically to their 32-bit counterparts.

B.9. Zba: Bit manipulation (address generation)

B.9.1. sh1add

Add, with the first addend shifted left by 1.

Syntax:

```
sh1add rd, rs1, rs2
```

Operation:

```
rd = (rs1 << 1) + rs2;
```

B.9.2. sh2add

Add, with the first addend shifted left by 2.

Syntax:

```
sh2add rd, rs1, rs2
```

Operation:

```
rd = (rs1 << 2) + rs2;
```

B.9.3. sh3add

Add, with the first addend shifted left by 3.

Syntax:

```
sh3add rd, rs1, rs2
```

```
rd = (rs1 << 3) + rs2;
```

B.10. Zbb: Bit manipulation (basic)

B.10.1. andn

Bitwise AND with inverted operand.

Syntax:

```
andn rd, rs1, rs2
```

Operation:

```
rd = rs1 & ~rs2;
```

B.10.2. clz

Count leading zeroes (starting from MSB, searching LSB-ward).

Syntax:

```
clz rd, rs1
```

Operation:

B.10.3. cpop

Population count.

```
cpop rd, rs1
```

```
rd = 0;
for (i = 0; i < 32; i = i + 1)
rd = rd + rs1[i];
```

B.10.4. ctz

Count trailing zeroes (starting from LSB, searching MSB-ward).

Syntax:

```
ctz rd, rs1
```

Operation:

B.10.5. max

Maximum of two values (signed).

Syntax:

```
max rd, rs1, rs2
```

```
if ($signed(rs1) < $signed(rs2))
    rd = rs2;
else
    rd = rs1;</pre>
```

B.10.6. maxu

Maximum of two values (unsigned).

Syntax:

```
maxu rd, rs1, rs2
```

Operation:

```
if (rs1 < rs2)
    rd = rs2;
else
    rd = rs1;</pre>
```

B.10.7. min

Minimum of two values (signed).

Syntax:

```
min rd, rs1, rs2
```

Operation:

```
if ($signed(rs1) < $signed(rs2))
    rd = rd1;
else
    rd = rs2;</pre>
```

B.10.8. minu

Minimum of two values (unsigned).

Syntax:

```
minu rd, rs1, rs2
```

```
if (rs1 < rs2)
    rd = rs1;
else
    rd = rs2;</pre>
```

B.10.9. orc.b

Or-combine of bits within each byte.

Syntax:

```
orc.b rd, rs1
```

Operation:

B.10.10. orn

Bitwise OR with inverted operand.

Syntax:

```
orn rd, rs1, rs2
```

Operation:

```
rd = rs1 | ~rs2;
```

B.10.11. rev8

Reverse bytes within word.

Syntax:

```
rev8 rd, rs1
```

```
rd = {
    rs1[7:0],
    rs1[15:8],
    rs1[23:16],
    rs1[31:24]
```

```
};
```

B.10.12. rol

Rotate left.

Syntax:

```
rol rd, rs1, rs2
```

Operation:

```
if (rs2[4:0] == 0)
    rd = rs1;
else
    rd = (rs1 << rs2[4:0]) | (rs1 >> (32 - rs2[4:0]));
```

B.10.13. ror

Rotate right.

Syntax:

```
ror rd, rs1, rs2
```

Operation:

```
if (rs2[4:0] == 0)
    rd = rs1;
else
    rd = (rs1 >> rs2[4:0]) | (rs1 << (32 - rs2[4:0]));</pre>
```

B.10.14. rori

Rotate right, immediate.

Syntax:

```
ror rd, rs1, imm
```

```
if (imm[4:0] == 0)
```

```
rd = rs1;
else
rd = (rs1 >> imm[4:0]) | (rs1 << (32 - imm[4:0]));
```

B.10.15. sext.b

Sign-extend from byte.

Syntax:

```
sext.b rd, rs1
```

Operation:

B.10.16. sext.h

Sign-extend from halfword.

Syntax:

```
sext.h rd, rs1
```

Operation:

B.10.17. xnor

Bitwise XOR with inverted operand.

Syntax:

```
xnor rd, rs1, rs2
```

```
rd = rs1 ^ ~rs2;
```

B.10.18. zext.h

Zero-extend from halfword.

Syntax:

```
zext.h rd, rs1
```

Operation:

```
rd = {
    16'h0000,
    rs1[15:0]
};
```

B.10.19. zext.b

Zero-extend from byte.

Syntax:

```
zext.b rd, rs1
```

Operation:

```
// Pseudo-op for RV32I instruction andi rd, rs1, 0xff
```

B.11. Zbc: Bit manipulation (carry-less multiply)

Each of these three instructions returns a 32-bit slice of the following 64-bit result:

```
reg [63:0] clmul_result;

always @ (*) begin
    clmul_result = 0;
    for (i = 0; i < 32; i = i + 1) begin
        if (rs2[i])) begin
            clmul_result = clmul_result ^ ({32'h0, rs1} << i);
        end
end</pre>
```

end

B.11.1. clmul

Carry-less multiply, low half.

Syntax:

```
clmul rd, rs1, rs2
```

Operation:

```
rd = cmul_result[31:0];
```

B.11.2. clmulh

Carry-les multiply, high half.

Syntax:

```
clmulh rd, rs1, rs2
```

Operation:

```
rd = clmul_result[63:32];
```

B.11.3. clmulr

Bit-reverse of carry-less multiply of bit-reverse.

Syntax:

```
clmulr rd, rs1, rs2
```

Operation:

```
rd = clmul_result[32:1];
```

B.12. Zbs: Bit manipulation (single-bit)

B.12.1. bclr

Clear single bit.

Syntax:

```
bclr rd, rs1, rs2
```

Operation:

```
rd = rs1 & ~(32'h1 << rs2[4:0]);
```

B.12.2. bclri

Clear single bit (immediate).

Syntax:

```
bclri rd, rs1, imm
```

Operation:

```
rd = rs1 & ~(32'h1 << imm[4:0]);
```

B.12.3. bext

Extract single bit.

Syntax:

```
bext rd, rs1, rs2
```

Operation:

```
rd = (rs1 >> rs2[4:0]) & 32'h1;
```

B.12.4. bexti

Extract single bit (immediate).

bexti rd, rs1, imm

Operation:

```
rd = (rs1 >> imm[4:0]) & 32'h1;
```

B.12.5. binv

Invert single bit.

Syntax:

```
binv rd, rs1, rs2
```

Operation:

```
rd = rs1 ^ (32'h1 << rs2[4:0]);
```

B.12.6. binvi

Invert single bit (immediate).

Syntax:

```
binvi rd, rs1, imm
```

Operation:

```
rd = rs1 ^ (32'h1 << imm[4:0]);
```

B.12.7. bset

Set single bit.

Syntax:

```
bset rd, rs1, rs2
```

```
rd = rs1 | (32'h1 << rs2[4:0])
```

B.12.8. bseti

Set single bit (immediate).

Syntax:

```
bseti rd, rs1, imm
```

Operation:

```
rd = rs1 | (32'h1 << imm[4:0]);
```

B.13. Zbkb: Basic bit manipulation for cryptography

NOTE

Zbkb has a large overlap with Zbb (basic bit manipulation). This section covers only those instruction in Zbkb but not in Zbb.

B.13.1. brev8

Bit-reverse within each byte.

Syntax:

```
brev8 rd, rs1
```

Operation:

```
for (i = 0; i < 32; i = i + 8) begin
  for (j = 0; j < 8; j = j + 1) begin
    rd[i + j] = rs1[i + (7 - j)];
  end
end</pre>
```

B.13.2. pack

Pack halfwords into word.

Syntax:

```
pack rd, rs1, rs2
```

```
rd = {
    rs2[15:0],
    rs1[15:0]
};
```

B.13.3. packh

Pack bytes into halfword.

Syntax:

```
packh rd, rs1, rs2
```

Operation:

```
rd = {
    16'h0000,
    rs2[7:0],
    rs1[7:0]
};
```

B.13.4. zip

Interleave upper/lower half of register into odd/even bits of result.

Syntax:

```
zip rd, rs1
```

Operation:

```
for (i = 0; i < 32; i = i + 2) begin
  rd[i] = rs1[i / 2];
  rd[i + 1] = rs1[i / 2 + 16];
end</pre>
```

B.13.5. unzip

Deinterleave odd/even bits of register into upper/lower half of result.

```
unzip rd, rs1
```