

LECTURE 8

LOGIC PROGRAMMING

Let us look now how PROLOG finds REFUTATION PROOF.

By looking at some examples we outline (formally defined later) the PROLOG's REFUTATION.

Consider Example 4 from LECTURE 4 or Lab 1.

Example 1:

$$\Delta = \{ p; q; r; w \leftarrow p, r; v \leftarrow w, q, s; s \leftarrow w \}$$

$$\boxed{\Delta \models V} \quad ?$$

How does PROLOG find REFUTATION

We shall outline some aspects of
SLD - REFUTATION

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$\sim v$ is added to Δ .

1 Step:

root goal $\equiv \sim v$

resolved with head of clause $\in \Delta$

$$\frac{\sim v}{v \leftarrow w, q, s}$$

$$\leftarrow w, q, s$$

Resolvent - 1

↑
1st clause
that matches!

2 Step: the current goal is the last Resolvent (i.e. RESOLVENT-1)

QUESTION: which atom to choose?

w? or q? or s?

PROLOG selects the 1st left-most one. So

$$\leftarrow \cancel{w}, q, s$$

$$\frac{w \leftarrow p, r}{\leftarrow p, r}$$

1st clause $\in \Delta$
that matches
w

Next question: $\leftarrow p, r, q, s$? or 1)
Which Resolvent? $\leftarrow q, s, p, r$? 2)

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PROLOG implements version 1)

i.e. moves all remaining atoms from the RESOLVENT-1 (current goal) to the right of the program clause body. Thus

$$\frac{\begin{array}{c} \leftarrow N, q, s. \\ \hline N \leftarrow P, r. \end{array}}{\leftarrow \underline{P}, \underline{r}, q, s.}$$

RESOLVENT 2
current goal

3. Step:

$$\frac{\begin{array}{c} \leftarrow P, r, q, s. \\ \hline P \\ \hline \leftarrow \underline{r}, q, s. \end{array}}{\leftarrow \underline{r}, q, s.}$$

RESOLVENT 3
current goal

4. Step:

$$\frac{\begin{array}{c} \leftarrow \underline{r}, q, s. \\ \hline r \\ \hline \leftarrow q, s. \end{array}}{\leftarrow q, s.}$$

RESOLVENT 4
current goal

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5. Step:

$$\frac{\begin{array}{c} \leftarrow q, s \\ \cancel{q} \\ \hline \end{array}}{\leftarrow s}$$

RESOLVENT_5
current goal

6. Step:

$$\frac{\begin{array}{c} \leftarrow s' \\ s \leftarrow w \\ \hline \end{array}}{\leftarrow w}$$

RESOLVENT_6
current goal

7. Step:

$$\frac{\begin{array}{c} \leftarrow w \\ w \leftarrow p, r \\ \hline \end{array}}{\leftarrow p, r}$$

RESOLVENT_7
current goal

8. Step:

$$\frac{\begin{array}{c} \leftarrow p, r. \\ \cancel{p} \\ \hline \end{array}}{\leftarrow r}$$

RESOLVENT_8
current goal

9. Step:

$$\frac{\begin{array}{c} \leftarrow r \\ \cancel{r} \\ \hline \end{array}}{\square}$$

RESOLVENT_9
contradiction

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Of course, there may exists other refutations which are not:

SLD - refutations e.g.

$$\begin{array}{c} \leftarrow v \\ \underline{v \leftarrow w, q, s} \\ \leftarrow w, q, s \\ \leftarrow s \leftarrow w \\ \leftarrow w, q \\ \leftarrow \underline{q} \\ \leftarrow w \\ \leftarrow p, r \\ \leftarrow p, r \\ \leftarrow r \\ \hline \end{array}$$

2 STEPS
are not part
of SLD-REFUTATION

A CONTRADICTION

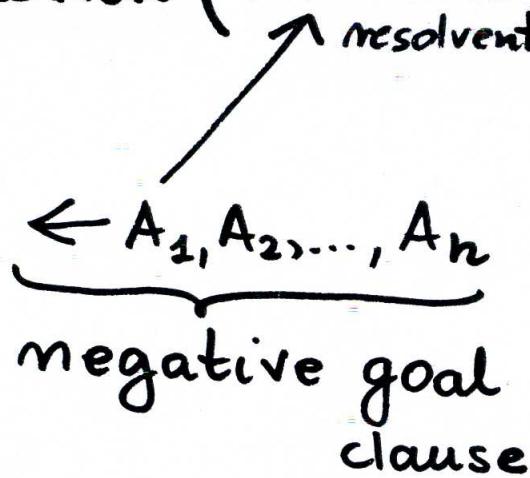
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SLD - REFUTATION SATISFIES THE FOLLOWING :

- a) always the resolution takes:

RESOLUTION (current goal, clause)



1st program
clause which
head "matches"

- b) in selecting atoms from the body of current goal we select first left-most one i.e. A₁

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c) once we resolve

$$\leftarrow A_1, A_2, \dots, A_n. \quad \begin{matrix} \text{current} \\ \text{goal} \end{matrix}$$
$$A_1 \leftarrow B_1, B_2, \dots, B_m. \quad \begin{matrix} \nwarrow \\ \text{program clause} \end{matrix}$$

we put A_2, \dots, A_n on the right-hand side of B_1, B_2, \dots, B_m :

$$\leftarrow B_1, B_2, \dots, B_m, A_2, \dots, A_n. \quad \begin{matrix} \text{RESOLVENT} \end{matrix}$$

d) if a given selected atom does not yield for a given program clause a \square (contradiction)

then we take the 2nd clause in Δ which "matches" selected atom, and so on - BACKTRACKING.

e) Recall:

$$\leftarrow B_1, \dots, B_n \quad \text{or}$$
$$A_1, \dots, A_k \leftarrow C_1, \dots, C_m \quad k \geq 2$$

clauses not allowed in Δ .

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REMARK:

- so-far A_i were variable free
- in general case we need
SLD-RESOLUTION to be covered
(later, UNIFICATION & SUBSTITUTION)

SLD- REFUTATION

OUTLINED IN a) - d) + e)

is a restriction to general
logic programming REFUTATION.

- (i) Δ - with different orders
of clauses is semantically
equivalent
- (ii) Δ - with clauses having different
order of atoms in their bodies
is also semantically equivalent.

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But for



above (i) & (ii) have impact on execution of the program.

So:

- order of program clauses
- order of atoms in program clauses

matter!

This is the 1st difference between

- theoretical logic programming
- PROLOG & programming.

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Example 2:

$$\Delta_{P_1} = \{ q \leftarrow p ; p \leftarrow q ; p \leftarrow r ; r \}$$

$$\Delta_{P_2} = \{ r ; p \leftarrow r ; q \leftarrow p ; p \leftarrow q \}$$

Both Δ_{P_1} & Δ_{P_2} differ only by order of clauses — semantically equivalent

Thus
for

$$\begin{array}{l} \Delta_{P_1} \models q \\ \Delta_{P_2} \models q \end{array}$$

we should have either No (for both queries) or Yes (for both queries).

For Δ_{P_1} we have:

$\neg q$ - an infinite loop

$$\frac{q \leftarrow p}{\frac{\leftarrow p}{\frac{p \leftarrow q}{\frac{\leftarrow q}{-10-}}}}$$

in PROLOG:
"out of local stack"

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For Δ_{P_2}

$$\begin{array}{c} \leftarrow q \\ q \leftarrow p \\ \hline \leftarrow p \\ p \leftarrow r \\ \hline \leftarrow r \\ r \leftarrow \\ \hline \square \end{array} \Rightarrow \Delta_{P_2} \models q$$

PROLOG: yes

□.

To see potential ∞ -loops
one may draw the corresponding
search space for a given $\Delta_P \models Q$

SLD - TREE*

* - formal definition later

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Example 3 :

$$\begin{aligned}
 & P(X, Z) :- q(X, Y), P(Y, Z). \quad 1) \\
 \Delta_P = & \begin{cases} P(X, X). \\ q(a, b). \end{cases} \quad 2) \\
 & \quad 3)
 \end{aligned}$$

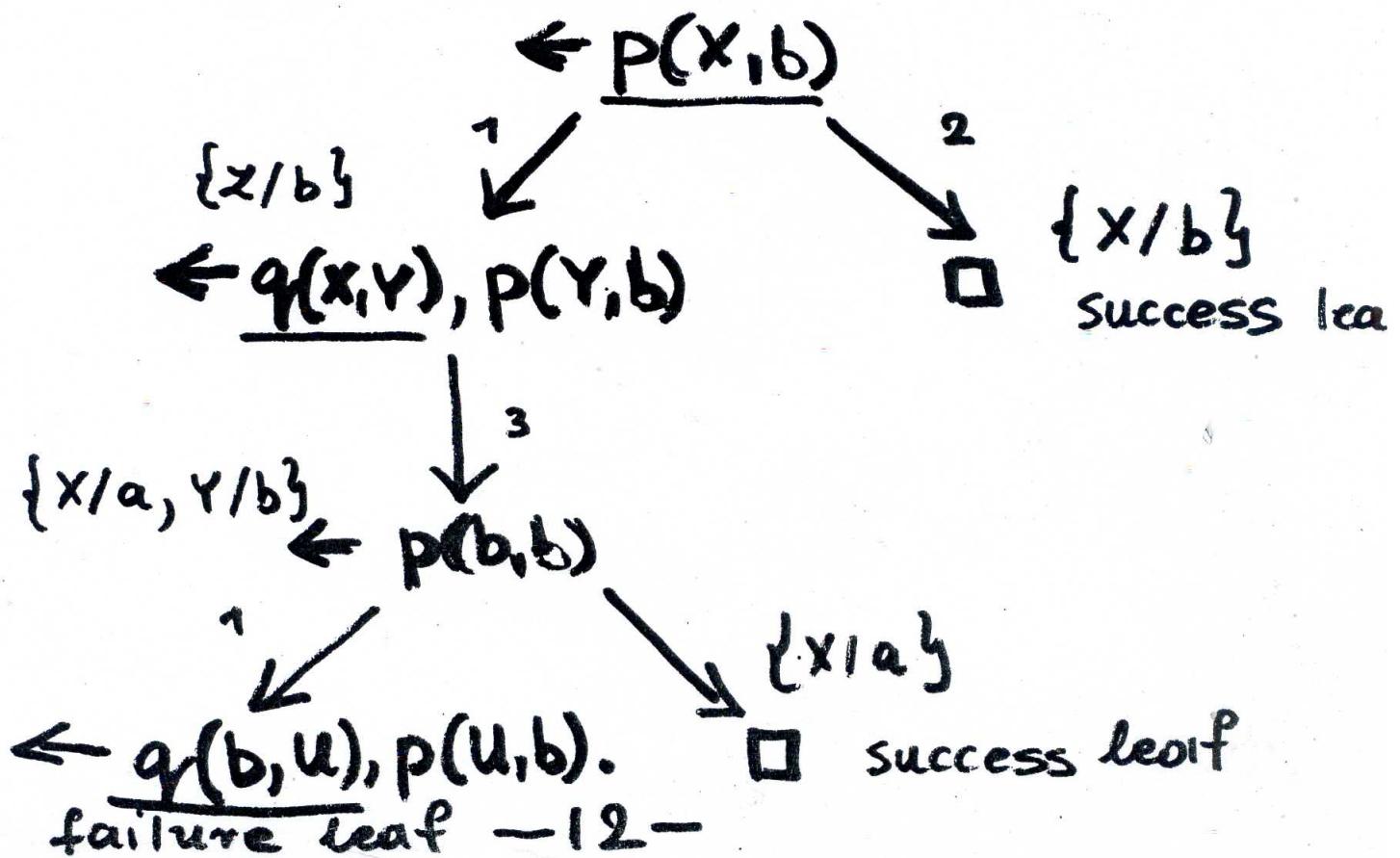
Note that 1) & 2) are UNIVERSALLY QUANTIFIED

QUERY:

$$\Delta_P \models P(X, b).$$

$$\equiv \sim (\exists x \, p(X, b))$$

SLD-TREE



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This is the whole search space for PROLOG & Δp with $\boxed{Q \equiv \exists x P(x,b)}$.

This tree is searched* by depth-first search from left to right.

Once 1st success is reached with substitution $\{X/a\}$

PROLOG will reply: $X=a$ yes
and waits:

- if RTN is hit \Rightarrow we terminate searching the SLD tree. PROLOG waits for the next QUERY.
- If ";" semicolon is hit the search for \square resumes and we get 2nd success with $X=b$ yes

* later explained more.

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- again if RTN is hit \Rightarrow PROLOG terminates the search for next successes in SLD tree , and waits for the next QUERY.
- If ; is hit then PROLOG resumes searching SLD tree. There are no more \Rightarrow it reports No & waits for the next QUERY.

REMARK:

It is easy to prove that:

$$\exists y p(f(y)) \leftarrow \forall x p(x) \quad (\Delta)$$

is VALID - i.e. true for each interpretation.

The "would-be counterexample"

$$\begin{cases} D = [0, 1] & f(y) = y - 1 \\ \text{Then as (i) is true} & p(x) \text{ is true if } x \geq 0 \\ & (ii) \text{ is false} \Rightarrow (\Delta) \text{ is false} \\ \text{fails as } f: D \not\rightarrow D. & \end{cases}$$

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REMARK:

- (i) $P(X):-q(X).$ $\equiv \forall X P(X) \leftarrow q(X).$
(ii) $q(X).$ $\equiv \forall X q(X).$

It is clear that:

— x appearing in 2 different clauses (i) & (ii) are in fact not the same as (i) & (ii) \equiv

- (i) $P(X):-q(X).$
(ii) $q(Y).$

— x appearing in the same clause cannot be changed i.e $P(X,Y) \leftarrow q(X).$

$$\frac{P(X,Y) \leftarrow q(X)}{P(X,Y) \leftarrow q(Z)}$$

as they are bound by the same universal quantifier.

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The last remark is important when the "so-called
"occur check"

for

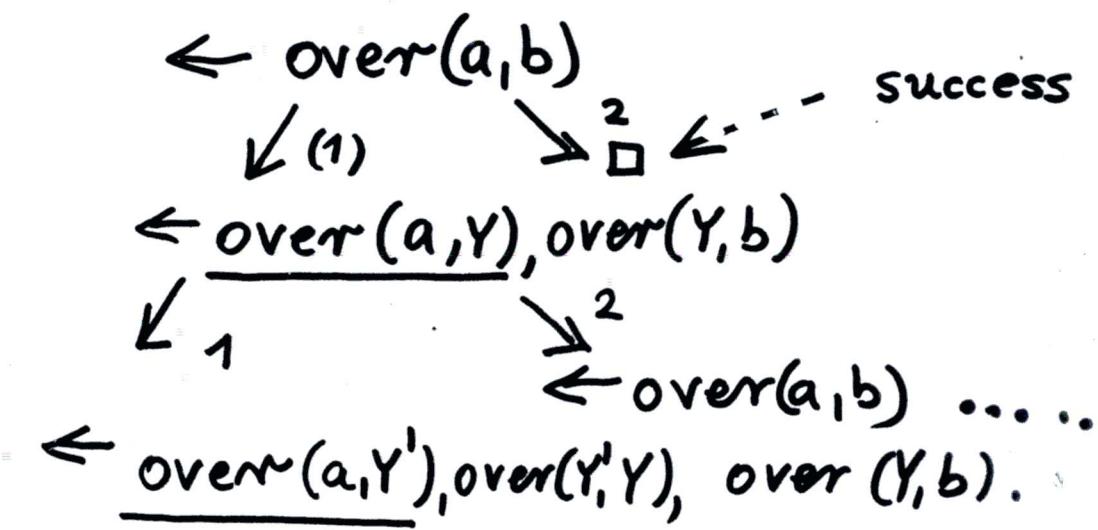
UNIFICATION ALGORITHM

is discussed.

Example 4:

1) over(X,Z):- over(X,Y), over(Y,Z)
over(a,b).
over(b,c). over(c,d).

FOR ■ in Example 8 (LECTURE 7)



So we build the goal

"out of local stack"

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One method is to move boundary conditions in front of 1).

But it may not help.

Check also an alternative :

from Example 8 (LECTURE 7).

□

Before we pass in the next lecture
to

- a) SUBSTITUTION
- b) UNIFICATION

let us sum-up the overall procedure in logic programming
(including PROLOG SLD-refutation)

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- we may ask to resume searching for next successes by hitting ";"
- by proving $\Box \in (\Delta \cup \{\neg Q\})^*$
we use the result that $\Delta \Vdash \neg Q$.

Proving Validity of a given formula requires a formal proof.

e.g.

$$\neg \exists x Q(x) \equiv \forall x \neg Q(x)$$

' \equiv ' is equivalent to

$$\begin{array}{c} \text{LEFT} \qquad \qquad \qquad \text{RIGHT} \\ \text{LEFT} \leftarrow \text{RIGHT} \quad \& \quad \text{RIGHT} \leftarrow \text{LEFT} \\ (i) \qquad \qquad \qquad (ii) \end{array}$$

So we prove now both (i) & (ii).

Assume I is an arbitrary interpretation:

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- a) D is arbitrary
- b) constant symbols \rightarrow specific symbols from D
 $a_i \rightarrow a'_i$ arbitrary

- c) function symbols \rightarrow specific symbols of functions

$f_i/m_i \rightarrow f'_i/m'_i$ arbitrary

- d) predicate symbols \rightarrow specific symbols of predicates

$P_j/n_j \rightarrow P'_j/m_j$

(i) Assume $I(\forall x \sim Q(x)) = \text{true}$.

For each $e \in D \sim Q'(e)$ is true

For each $e \in D \quad Q'(e)$ is false

$\exists x \quad Q(x)$ is false

$\sim \exists x \quad Q(x)$ is true. Thus LEFT is true

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(ii) Assume $\exists (\sim \exists x Q(x)) = \text{true}$

$\exists x Q(x)$ is false

for each $e \in D$ $Q'(e)$ is false

for each $e \in D$ $\sim Q'(e)$ is true

$\forall x \sim Q(x)$ is true

Thus Right is true.

The proof is complete.

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- program Δ consists of non-negative Horn clauses

$A \leftarrow A_1, A_2, \dots, A_n.$ (rules)

$A \leftarrow$ (facts)

- the query is

(*) $\exists y_1 \exists y_2 \dots \exists y_m (B_1 \wedge B_2 \wedge \dots \wedge B_n)$

$$\frac{\parallel}{\Delta} ?$$

- PROLOG uses SLD-refutation & negates (*) to add negative clause

$\forall y_1 \forall y_2 \dots \forall y_m \sim B_1 \vee \sim B_2 \vee \dots \vee \sim B_n$

- shows whether there exists or not SLD-refutation
- if YES it reports the successful SUBSTITUTION
- if NO it reports NO.