CSC520 - Artificial Intelligence Lecture 8

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February 1, 2025

Agenda

Multiagent Environments Adversarial agents with conflicting goals

- Adversarial search
- MinMax algorithm
- Alpha-Beta pruning

Games

- Games are competitive or cooperative environments with two or more agents (players)
- Different types of games
 - Deterministic vs stochastic
 - ▶ 1, 2, ..., n players. Large $n \Rightarrow economy$
 - Zero sum vs win-win
 - Perfect information (fully observable) vs imperfect information (partially observable)
- Study adversarial search algorithms on games
- Intent is to compute a strategy or policy which recommends a move from each state

Two-player, Zero-sum Game Problem Formulation

Deterministic, two-players, turn-taking, perfect information, zero-sum

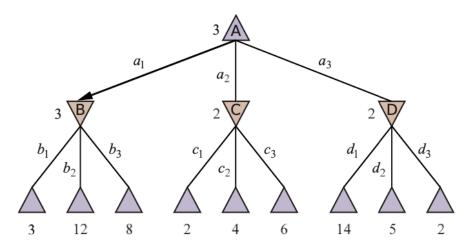
- S₀: initial state
- TO-MOVE(s): the player to move in state s
- ACTIONS(s): legal moves in state s
- RESULT(s, a): transition model; state resulting from taking action a
 in s
- IS-TERMINAL(s): if true, game is over in s
- UTILITY(s, p): value of s to player p

Minimax Search

- State-space search tree
- Players alternate turns
- Compute each node's minimax value
 - Minimax value is the best achievable utility assuming both players play optimally, that is both are rational

Minimax Search Example

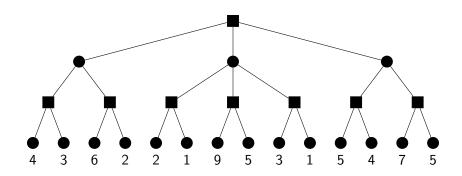
Two player, deterministic, zero-sum, and perfect information game



Minimax Search Algorithm

```
function MINIMAX-DECISION(state) return an action
    v \leftarrow \text{MAX-VALUE}(state)
    return the action in ACTIONS(state) which leads to a state with value v
function MAX-VALUE(state) return a utility value
    if IS-TERMINAL(state) return the UTILITY(state)
    v \leftarrow -\infty
    for a in ACTIONS(state) do
        v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(state, a)))
   return v
function MIN-VALUE(state) return a utility value
   if IS-TERMINAL(state) return the UTILITY(state)
    v \leftarrow \infty
    for a in ACTIONS(state) do
        v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(state, a)))
   return v
```

Minimax Algorithm Example



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Minimax Properties

- Similar to depth first search
- Time complexity: $O(b^m)$
- Space complexity: O(bm)

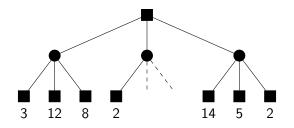
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- For example, chess has $b \approx 35$, $m \approx 100$
 - Too large to compute exact solution

Minimax Properties

- Similar to depth first search
- Time complexity: $O(b^m)$
- Space complexity: O(bm)
- For example, chess has $b \approx 35, m \approx 100$
 - Too large to compute exact solution
- How to reduce the complexity?
 - Dynamic pruning of the search tree
 - ▶ Early cutoff of the search tree using a heuristic evaluation function

Tree Pruning



function ALPHA-BETA-SEARCH(state) return an action

$$v, move \leftarrow \text{MAX-VALUE}(\textit{state}, -\infty, +\infty) \text{ return } \textit{move}$$

function MAX-VALUE(state, α , β) return (utility, move) pair

if IS-TERMINAL(state) then return UTILITY(state)

$$v \leftarrow -\infty$$

for a in ACTIONS(state) do

$$v2$$
, $a2 \leftarrow MIN-VALUE(RESULT(state, a), $\alpha, \beta)$$

if v2 > v then

$$v$$
, $move \leftarrow v2$, $a2$

$$\alpha \leftarrow \text{MAX}(\alpha, v)$$

if $v \ge \beta$ then return v, move

return v, move

- α = best choice found so far for MAX (at least)
- $\beta = \text{best choice found so far for MIN}$ (at most)

function MIN-VALUE(state, α , β) return (utility, move) pair

if ${\tt IS-TERMINAL}(state)$ then return ${\tt UTILITY}(state)$

$$v \leftarrow +\infty$$

for a in ACTIONS(state) do

$$v2$$
, $a2 \leftarrow MAX-VALUE(RESULT(state, a), $\alpha, \beta)$$

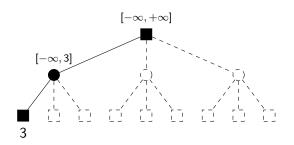
if v2 < v then

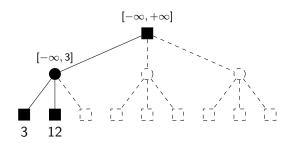
$$v$$
, move $\leftarrow v2$, a2

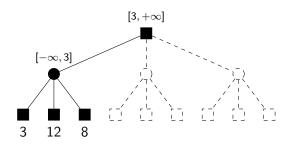
$$\beta \leftarrow \min(\beta, v)$$

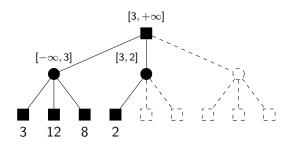
if $v \leq \alpha$ then return v, move

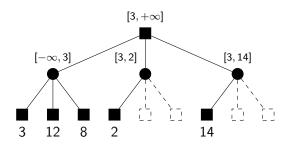
return v, move

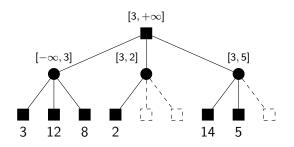


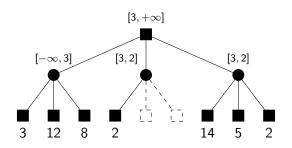






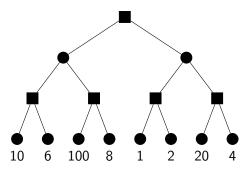




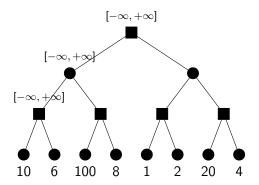


- Pruning does not affect the final result
- Effectiveness of pruning depends upon the order of successors
 - ▶ More pruning is possible if successors likely to be best are examined first
- With perfect ordering time complexity drops to $O(b^{m/2})$
 - Can look ahead roughly twice as deep as minimax in the same amount of time

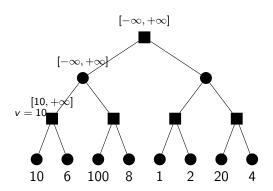
Apply Alpha-Beta search to the game tree below.



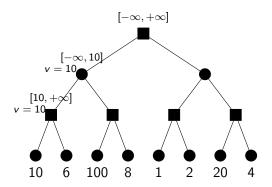
MAX-VALUE prunes if $v \ge \beta$ and updates $\alpha \leftarrow \text{MAX}(\alpha, v)$ MIN-VALUE prunes if $v \le \alpha$ and updates $\beta \leftarrow \text{MIN}(\beta, v)$



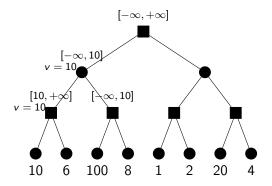
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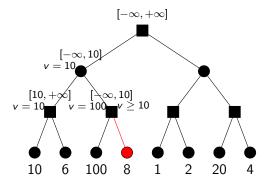
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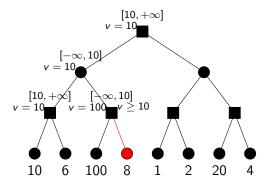
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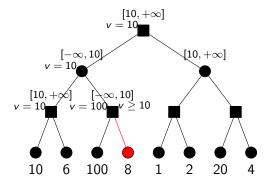
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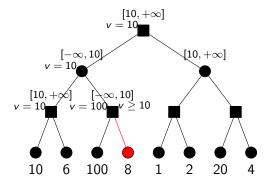
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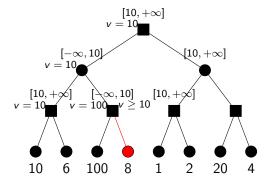
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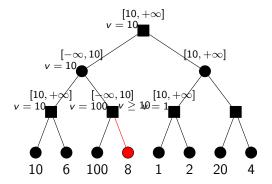
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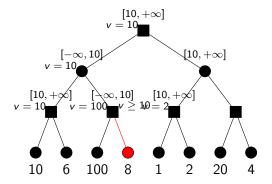
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