



Faculty of Computing and Information Technology

**University of the Punjab,
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Artificial Intelligence Lab 5

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1. Greedy Best-First Search (GBFS)

Introduction to Greedy Best-First Search (GBFS)

Greedy Best-First Search (GBFS) is a heuristic search algorithm that expands the node that appears to be closest to the goal according to a heuristic function, typically $h(n)$.

- **$h(n)$** : The estimated cost from the current node to the goal (heuristic function).
- In GBFS, the algorithm selects the node with the smallest **$h(n)$** , focusing only on which node appears to be the closest to the goal.

Problem: The 8-Puzzle Problem

The 8-puzzle consists of a 3x3 grid with numbered tiles from 1 to 8 and one empty space. The objective is to slide the tiles around until they match the goal configuration. The puzzle looks like this:

Start State:

```
1 2 3
4 0 5
6 7 8
```

Goal State:

```
1 2 3
4 5 6
7 8 0
```

- **Start State**: The initial configuration of the puzzle.
- **Goal State**: The target configuration to reach by sliding the tiles into the empty space (represented by 0).

Heuristic: Use the **Manhattan Distance** as the heuristic: $h(n) = |x_1 - x_2| + |y_1 - y_2|$

where (x_1, y_1) is the current node, and (x_2, y_2) is the goal node.

Code Template:

```
class Node:
    def __init__(self, state, parent, move, h_cost):
        # Initialize node with state, parent, move, and h_cost
        pass

    def generate_children(self):
        # Generate possible child nodes by moving in 4 directions (up, down,
        left, right)
        pass

    def calculate_heuristic(self, goal_state):
        # Calculate heuristic (h(n)) based on the current state and goal
```

```

(Manhattan Distance)
pass

class GreedyBestFirstSearch:
    def __init__(self, start_state, goal_state):
        # Initialize the search with start and goal states
        pass

    def solve(self):
        # Implement GBFS to find the goal
        pass

    def trace_solution(self, node):
        # Trace back the solution path from goal to start
        pass

```

Lab Tasks:

1. Implement the **Greedy Best-First Search** algorithm for the 2D grid.
2. Use the **Manhattan Distance** heuristic.
3. Find the path from the start position (0,0) to the goal position (4,4).

2. Minimax Algorithm

Introduction to Minimax Algorithm

The Minimax algorithm is used to minimize the possible loss in a worst-case scenario and is typically applied in two-player, zero-sum games.

- **Maximizer:** Tries to get the highest score.
- **Minimizer:** Tries to get the lowest score.
- **Terminal States:** End states of the game (e.g., win, lose, draw).

Code Template:

```

class Minimax:
    def __init__(self, game_state):
        # Initialize with the current game state
        pass

    def is_terminal(self, state):
        # Check if the game has reached a terminal state (win/lose/draw)
        pass

```

```
def utility(self, state):  
    # Return the utility value of the terminal state  
    pass  
  
def minimax(self, state, depth, maximizing_player):  
    # Implement the Minimax algorithm  
    pass  
  
def best_move(self, state):  
    # Determine the best move using Minimax  
    pass
```

Lab Tasks:

1. Implement the Minimax algorithm for a two-player game (e.g., Tic-Tac-Toe).
2. Test the algorithm for different board configurations.