

A Distributed Triangulation Algorithm for Wireless Sensor Networks on 2D and 3D Surface

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OUTLINE

- Introduction
- Triangulation Algorithm
- Extension to 3D Surface
- Application and Simulation Results
- Conclusion



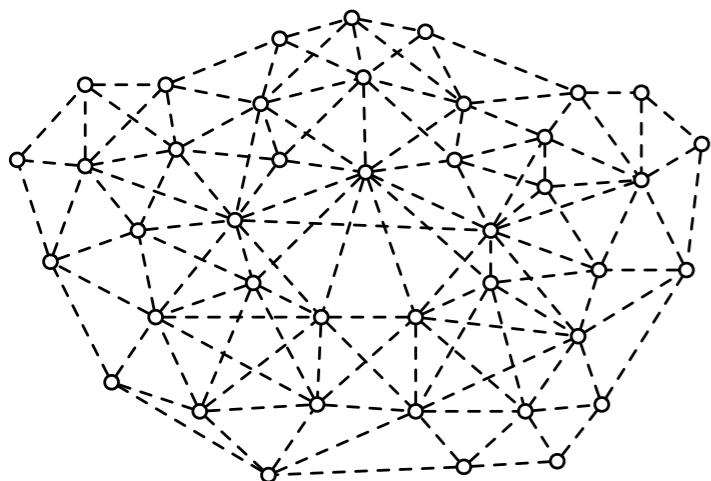
INTRODUCTION

- Wireless sensor network exhibits randomness
- Wireless sensor network topology is a graph
- Triangulation is a subgraph of the topology
- Triangulation mesh is very important for many applications of sensor networks:
geometry-based routing, localization, coverage,
segmentation, data segmentation

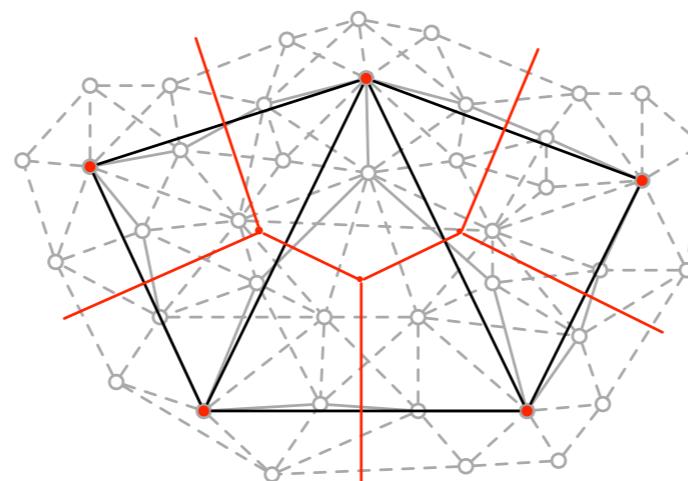


INTRODUCTION

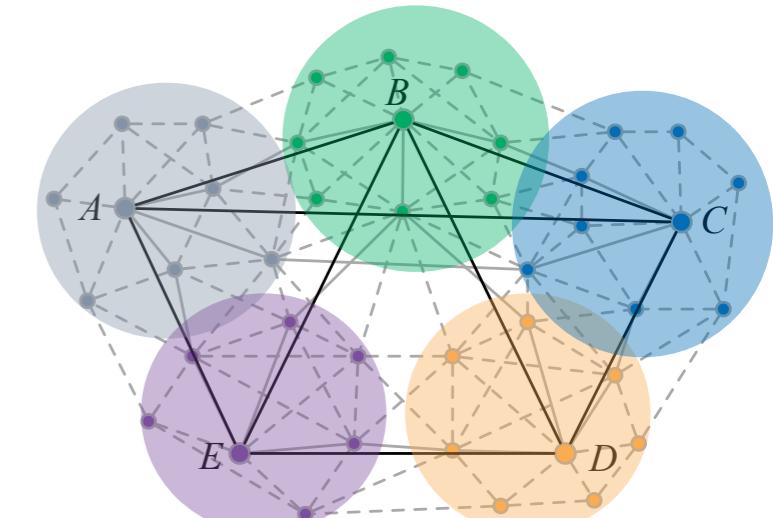
- Related work



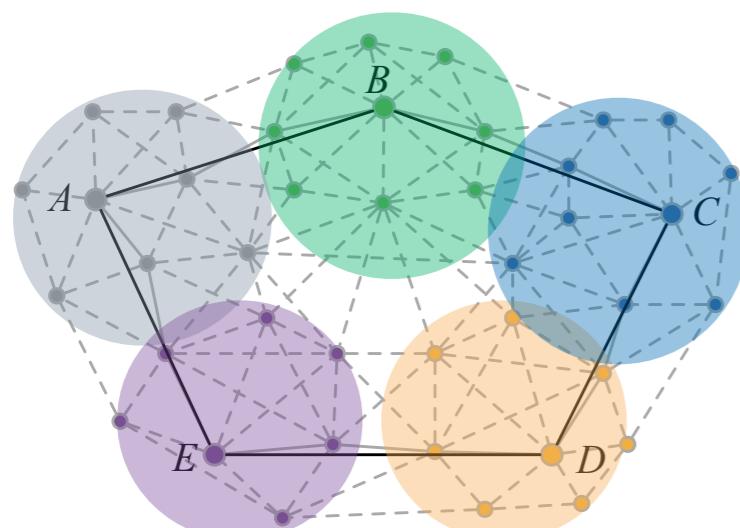
(a) A 2D network graph.



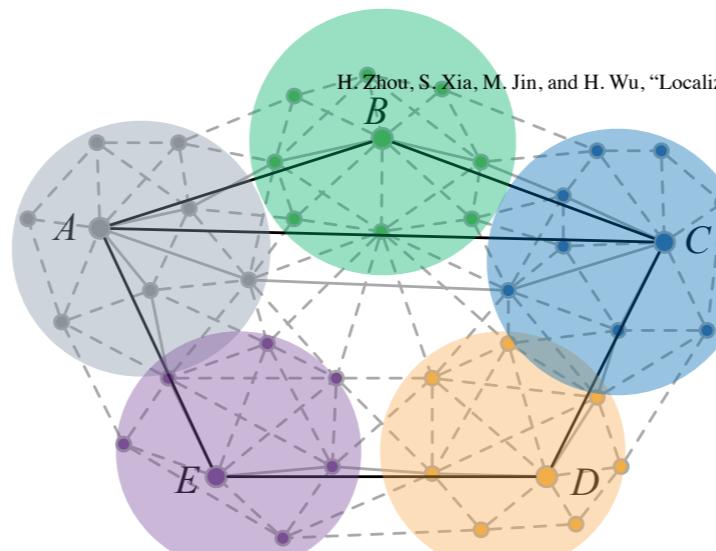
(b) Triangulation under ideal CDG.



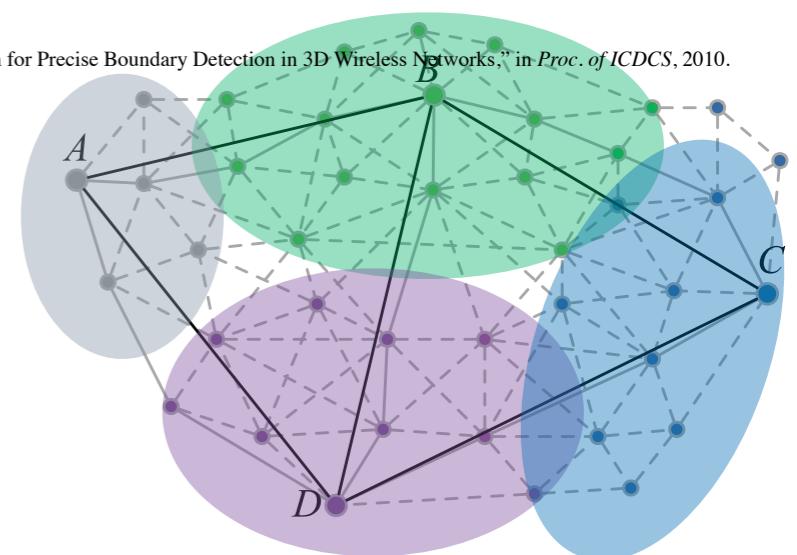
(c) CDG (k=1): not planar.



(d) CDM (k=1): planar but not triangulated.



(e) Failed triangulation.



(f) CDG (k=2): triangulated but coarse.

[2] R. Sarkar, X. Yin, J. Gao, F. Luo, and X. D. Gu, “Greedy Routing with Guaranteed Delivery Using Ricci Flows,” in *Proc. of IPSN*, 2009.

[3] H. Zhou, S. Xia, M. Jin, and H. Wu, “Localized Algorithm for Precise Boundary Detection in 3D Wireless Networks,” in *Proc. of ICDCS*, 2010.



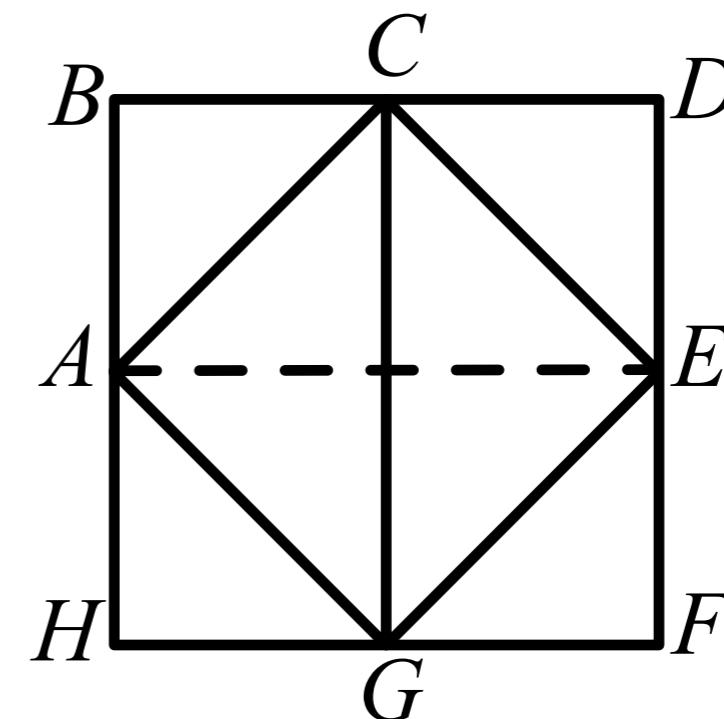
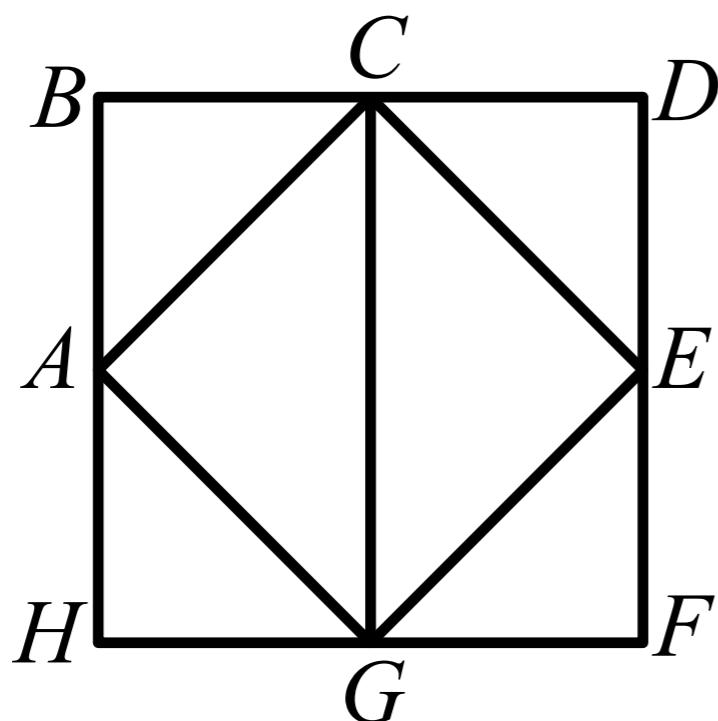
INTRODUCTION

- We proposed a distributed triangulation algorithm
 - works for any arbitrary 2D sensor networks without communication model constraint, and we prove the correctness of the algorithm in 2D sensor networks
 - tolerates some measurement errors
 - also works for 3D open or closed surfaces



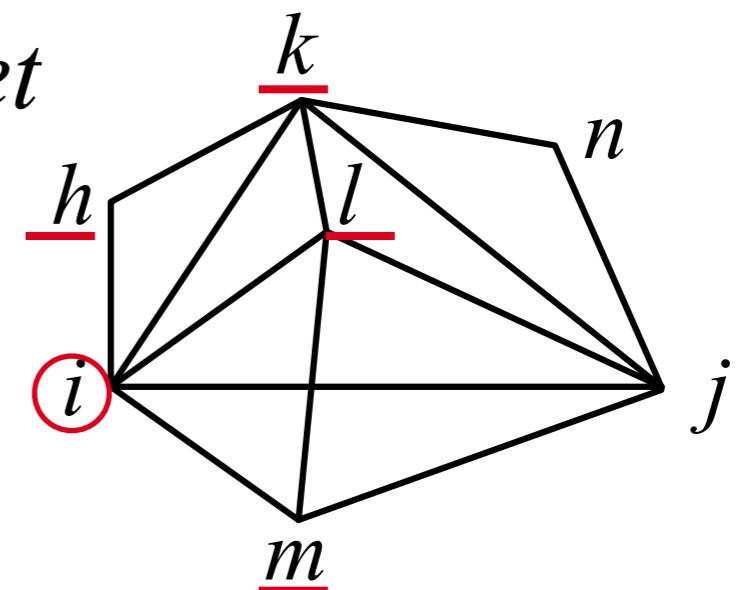
TRIANGULATION ALGORITHM

- Basic idea
 - Each triangulation mesh edge will associate with **two** triangles, except boundary edge
 - If we add extra edges into triangulation mesh, they will change this association
 - The association can be used to identify these extra edges.



TRIANGULATION ALGORITHM

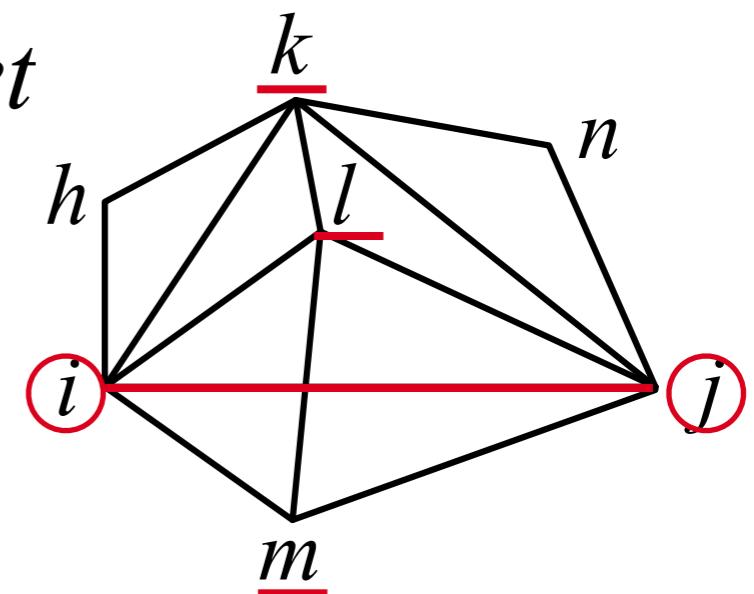
- Definitions
 - *node neighbor set (NNS)*, $N_v(i)=\{h,k,l,m\}$
 - *edge neighbor set (ENS)*, $N_e(e_{ij})=N_v(i)\cap N_v(j)=\{k,l,m\}$
 - *refined edge neighbor set (RNS)*, $R_e(e_{ij})=\{l,m\}$
 - *edge weight*, $W(e_{ij})=2$, $W(e_{hk})=2$
 - *associated edge neighbor set (AENS)*, $A(e_{ij})=\{e_{il}, e_{im}, e_{jl}, e_{jm}\}$
 - *equivalent edges*, e_{ij}, e_{lm}
 - *critical edge*, e_{kj}



TRIANGULATION ALGORITHM

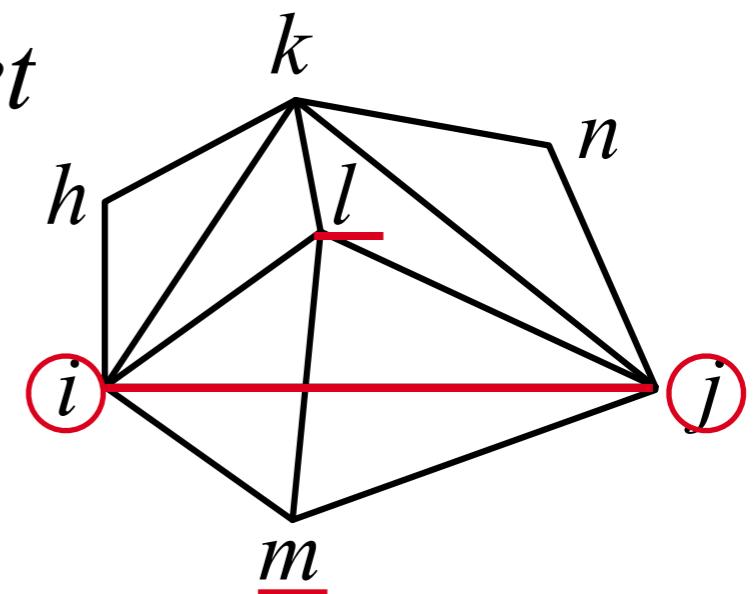
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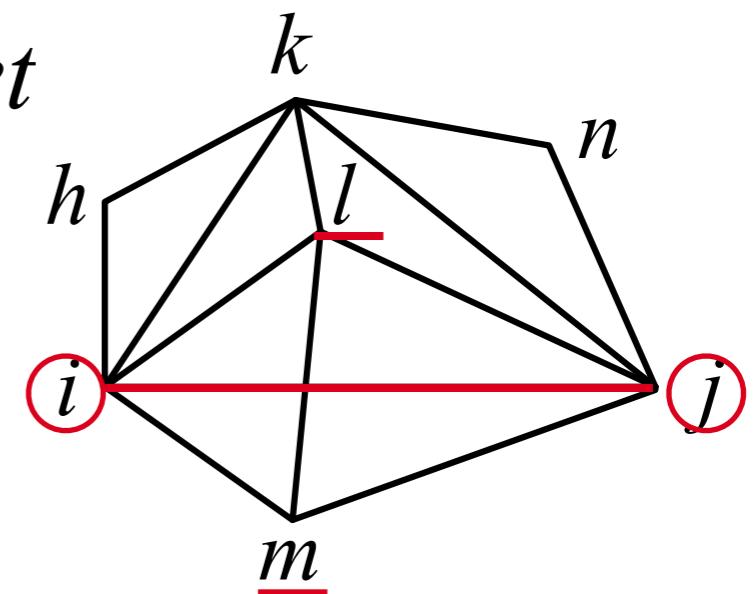
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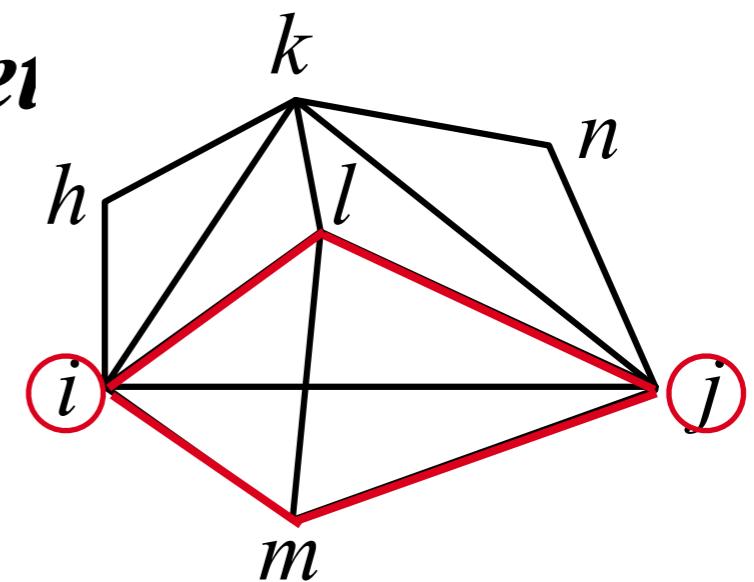
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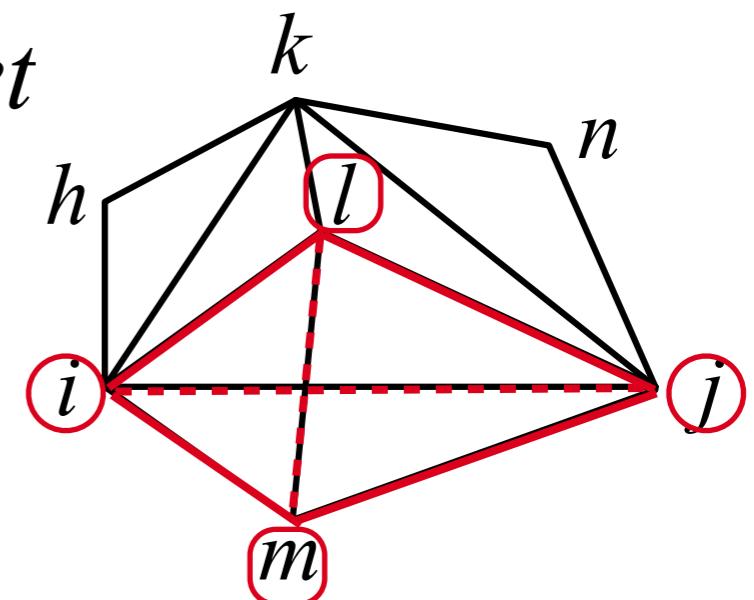
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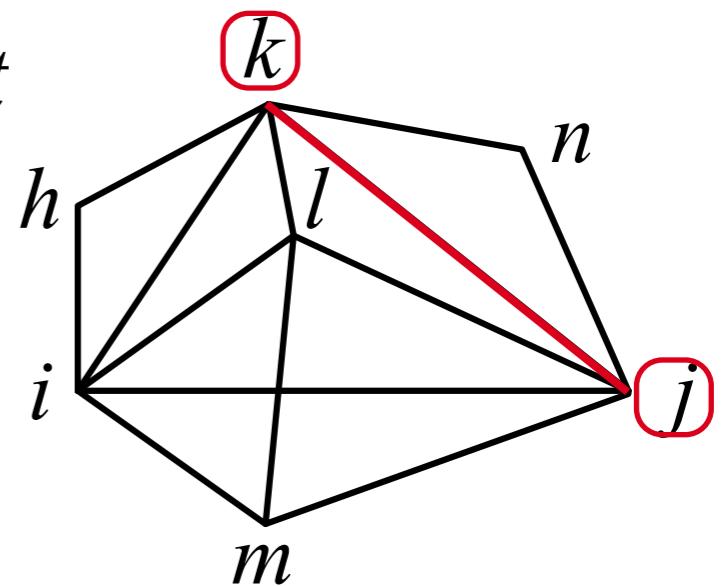
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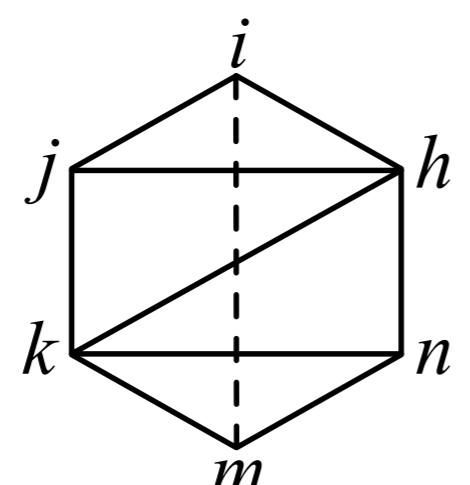
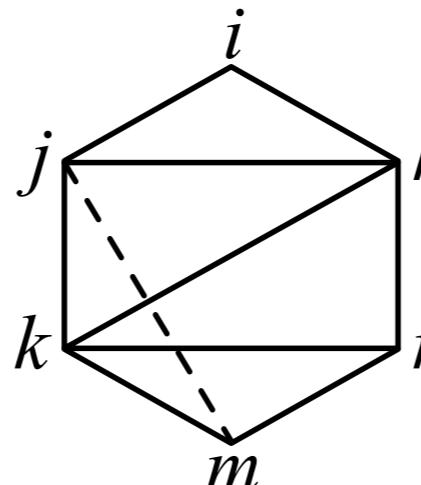
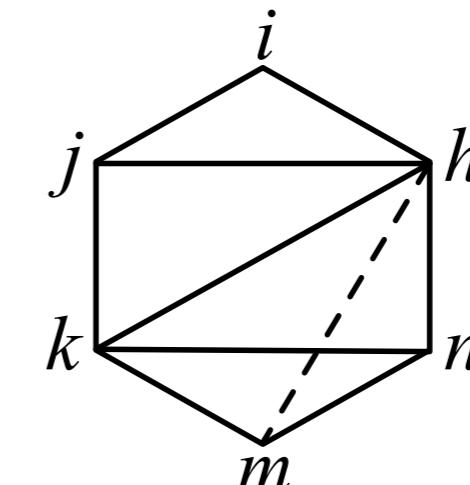
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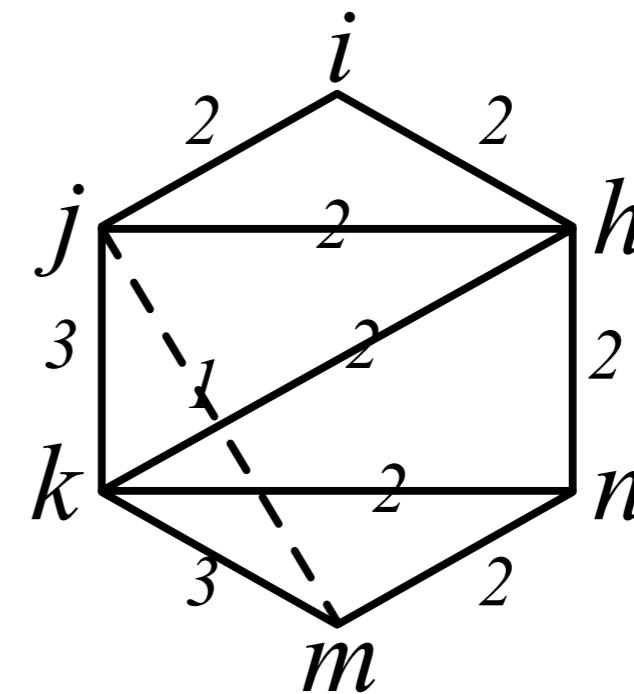
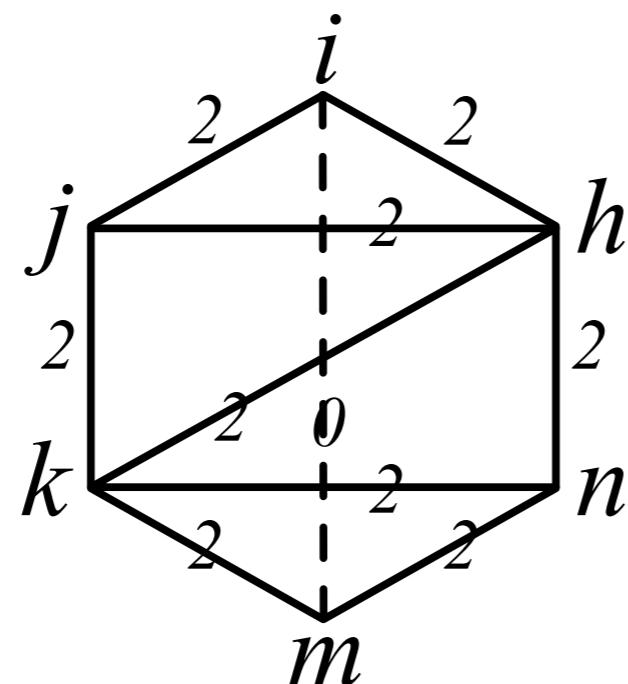
TRIANGULATION ALGORITHM

- **Lemma 1:** A subgraph of G is triangulated *if and only if* every edge of the subgraph has a weight of two.
- Given a graph G and a *triangulation subgraph* T , *extra edges* are $G-T$
- **Objective:** remove all extra edges
- There are three type of *extra edges*, e_0 , e_1 , e_2

(a) e_0 (b) e_1 (c) e_2 

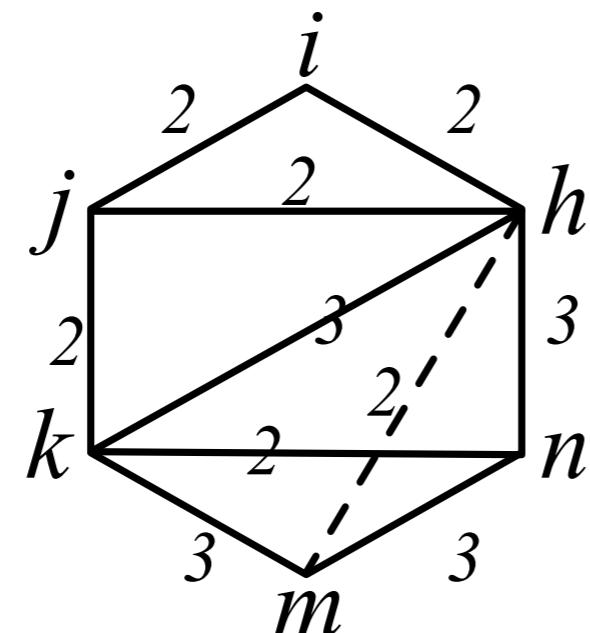
TRIANGULATION ALGORITHM

- **Theorem 1:** An edge with a weight *less than two* must be removed in order to produce a triangulated subgraph.



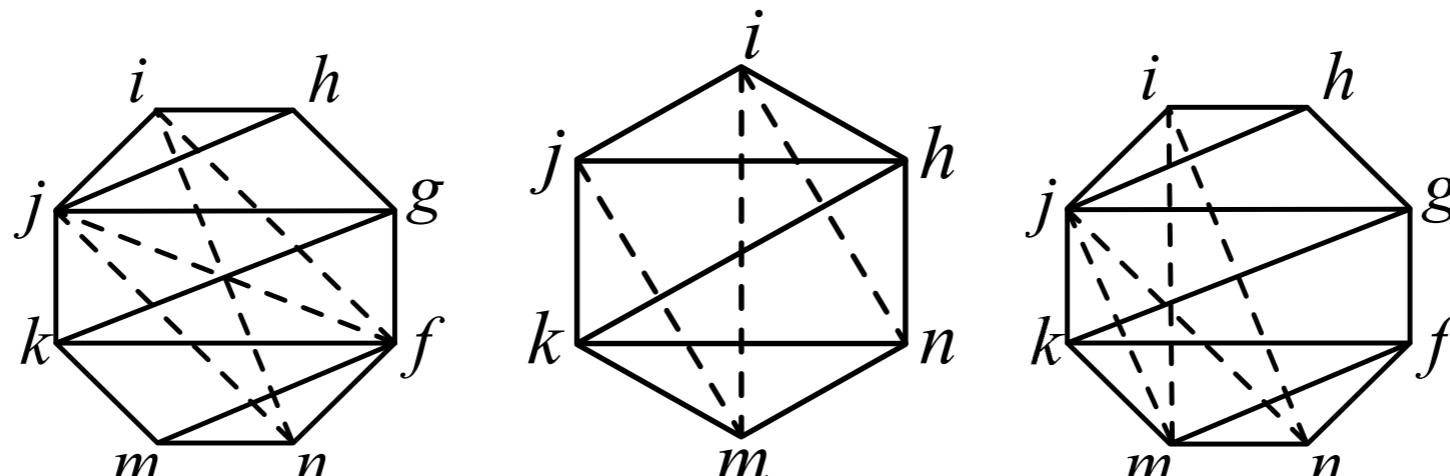
TRIANGULATION ALGORITHM

- **Theorem 2:** An *non-critical edge* can be recognized as an e_2 edge and safely removed if all edges in its *AENS* have their weight greater than two.

(c) e_2 

TRIANGULATION ALGORITHM

- **Lemma 2:** An e_0 extra edge can exist in G'' , only if it depends on at least two other *extra edges*.
- **Lemma 3:** An e_1 extra edge can exist in G'' , only if it at least depends on another extra edge.



(a) Loop chain.

(b) Non-loop chain.

(c) Same head and tail.



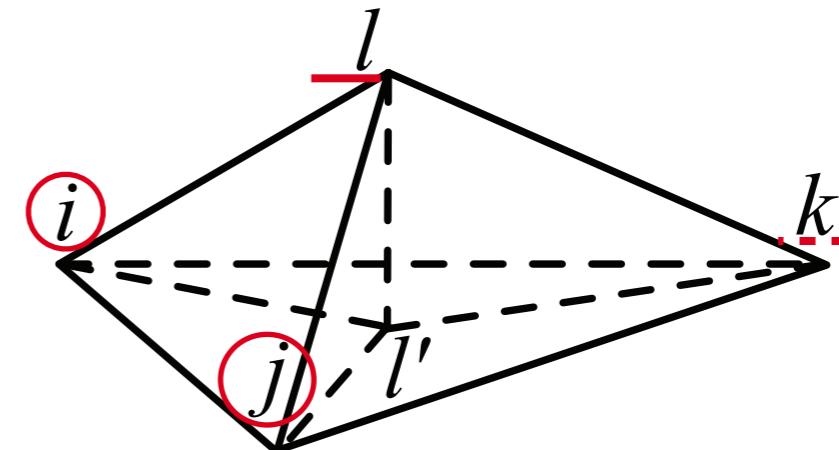
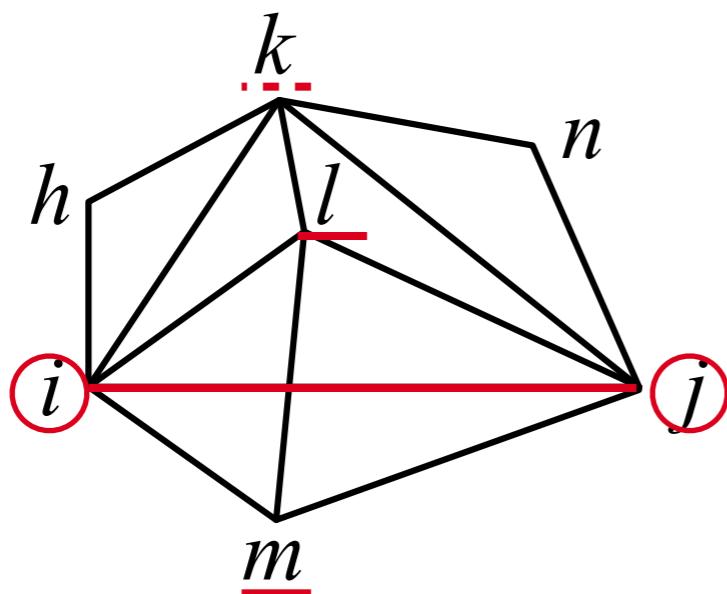
TRIANGULATION ALGORITHM

- Step1: Initialization.
each edge calculate NNS , ENS , $RENS$, $AENS$,
and *edge weight*;
- Step2: Iterative edge removal according to
Theorems 1 and 2;
- Step3: Removal of e_0 and e_1 chains.



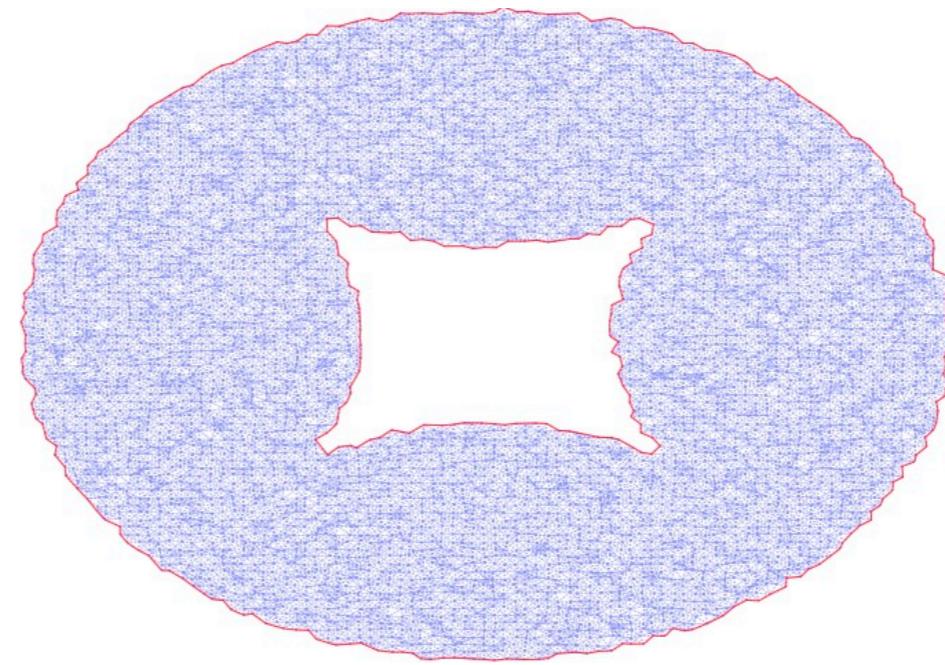
EXTENSION TO 3D SURFACE

- Similar algorithm can be applied in a sensor network on 3D surface with minor modification in determining *RNS* and *edge weight*

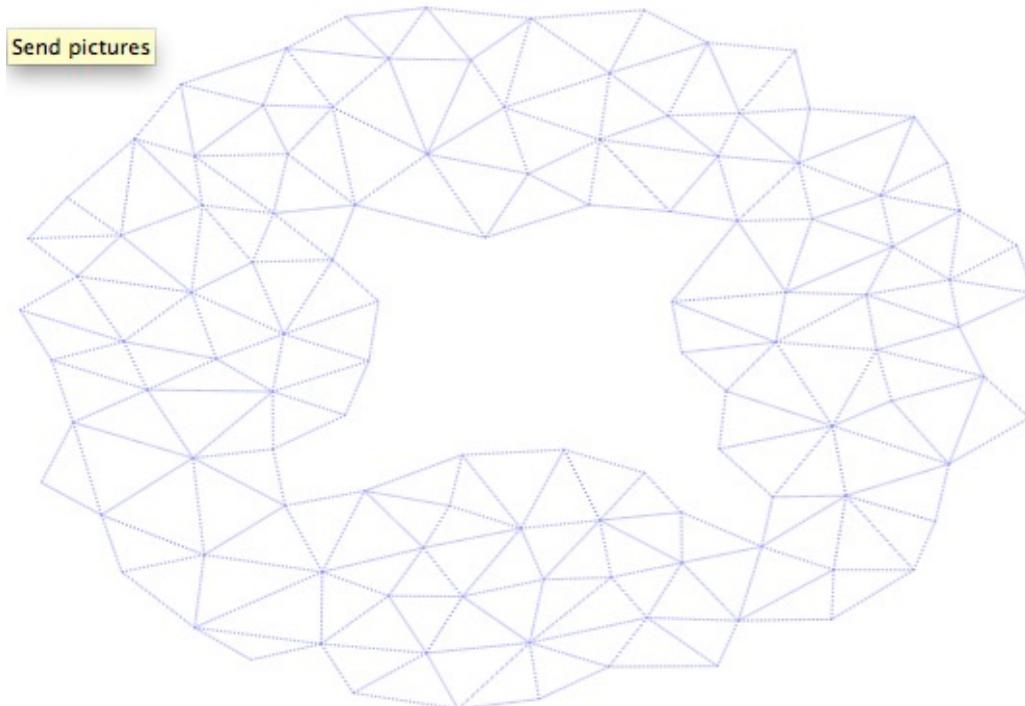


APPLICATION AND SIMULATION RESULTS

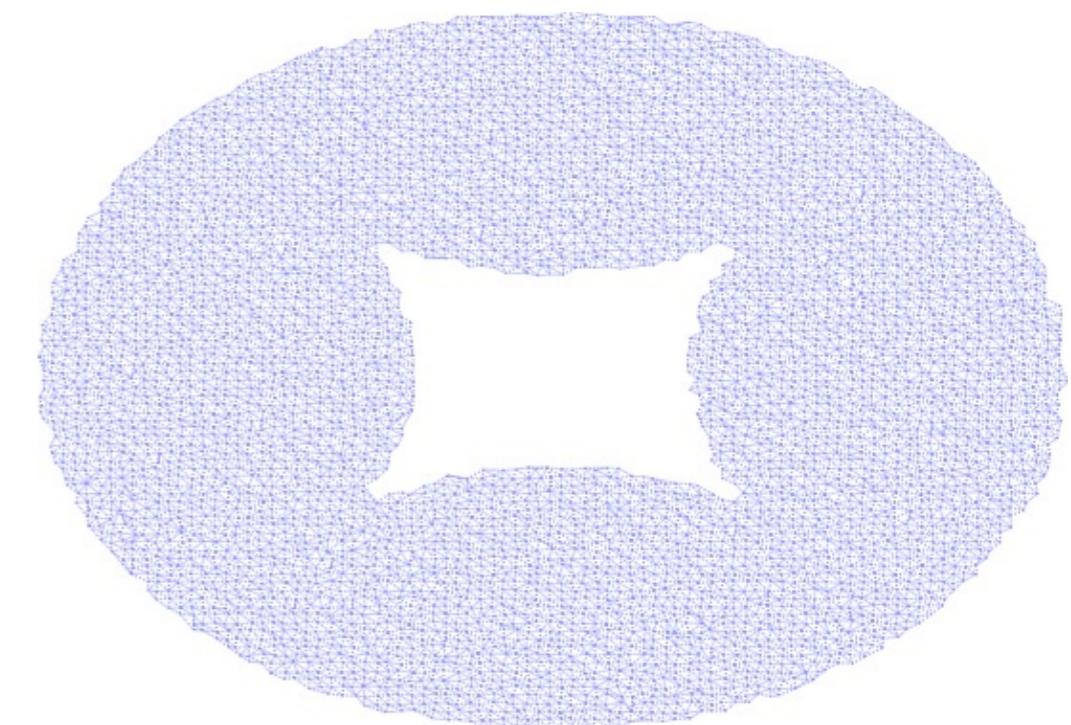
2D network



(a) Sensor network topology



(b) Finest triangulation by [2]



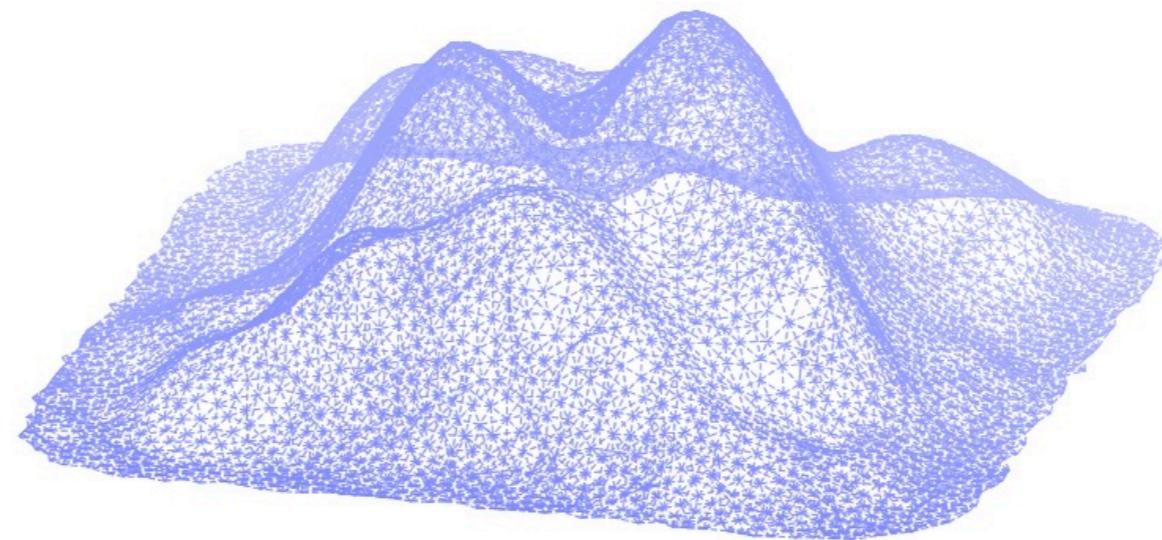
(c) Proposed triangulation



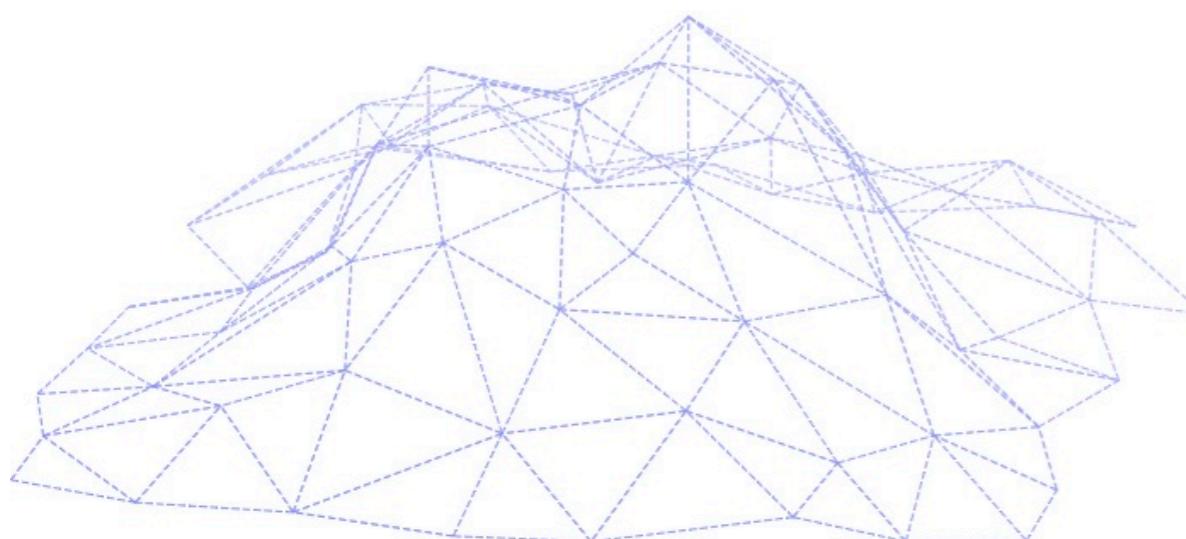
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APPLICATION AND SIMULATION RESULTS

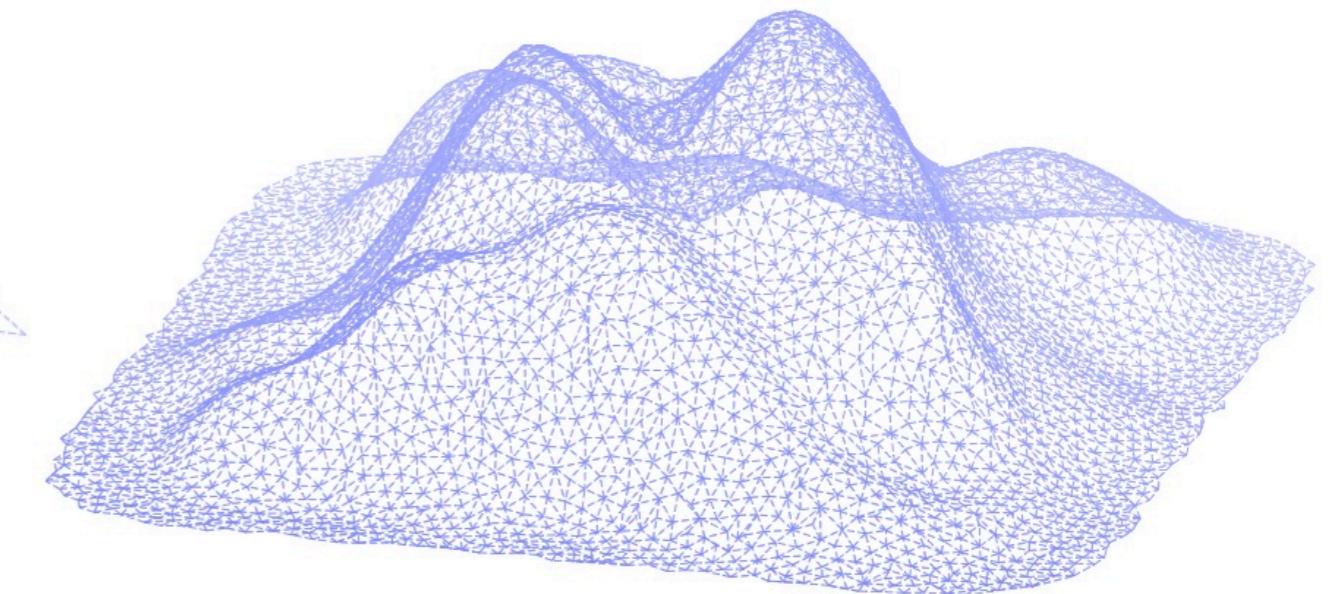
3D network with open surface



(a) Sensor network topology



(b) Finest triangulation by [3]



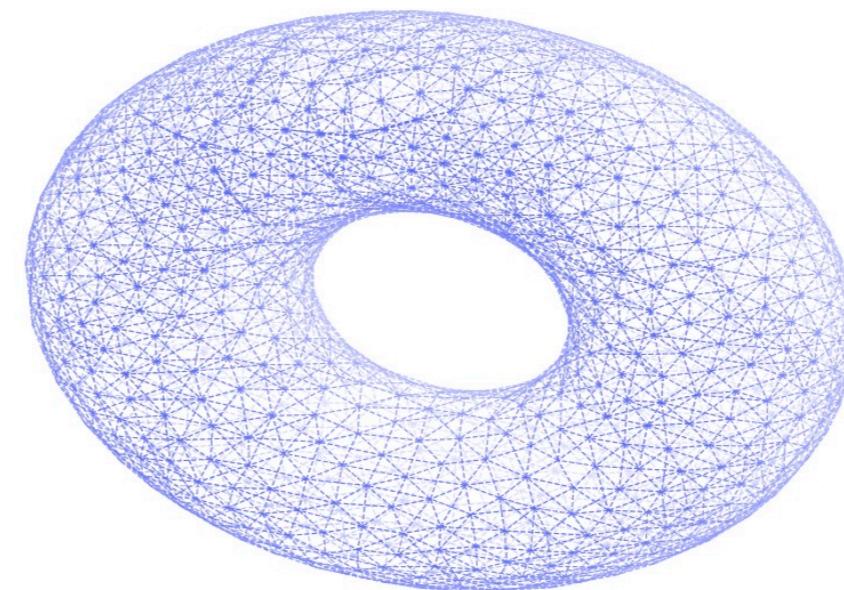
(c) Proposed triangulation



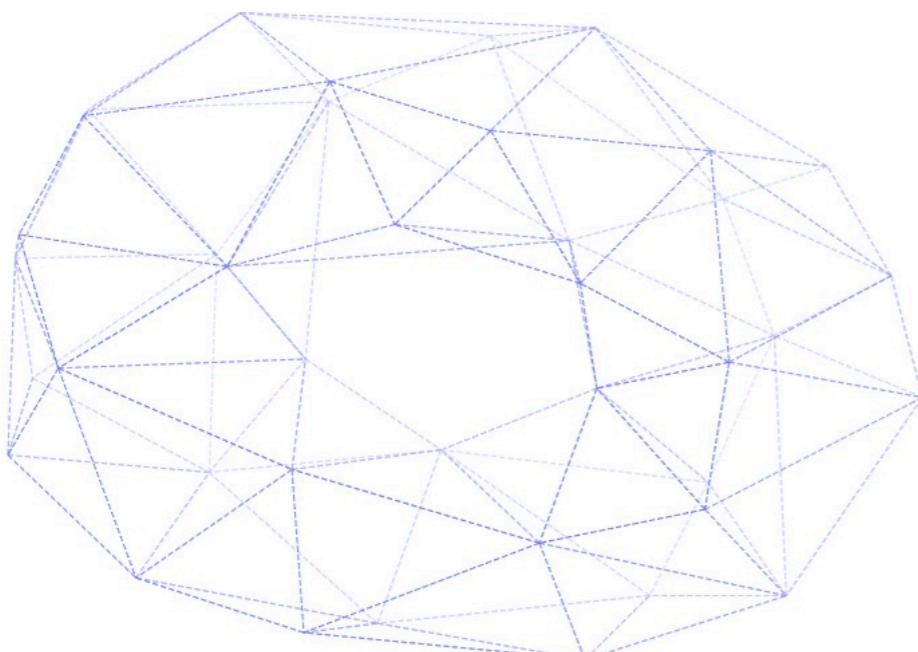
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APPLICATION AND SIMULATION RESULTS

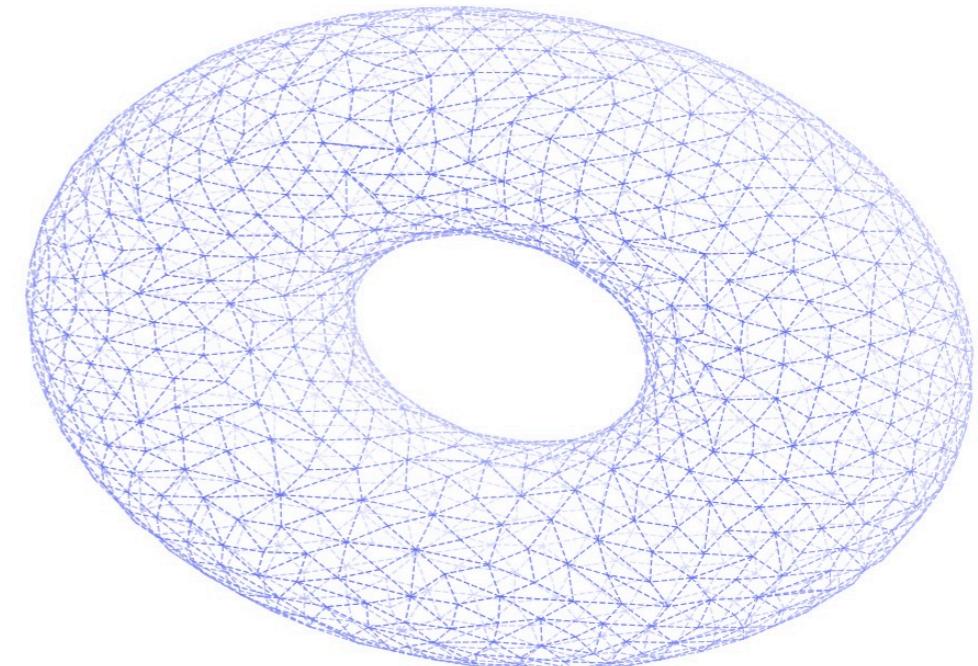
3D network with
closed surface



(a) Sensor network topology



(b) Finest triangulation by [3]

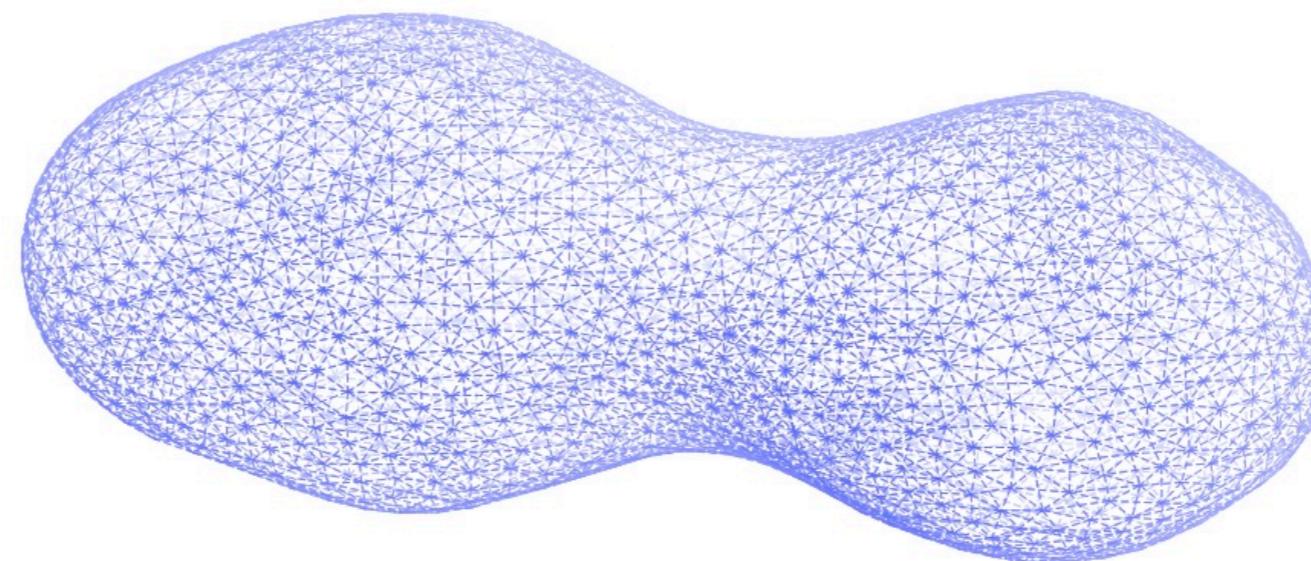


(c) Proposed triangulation

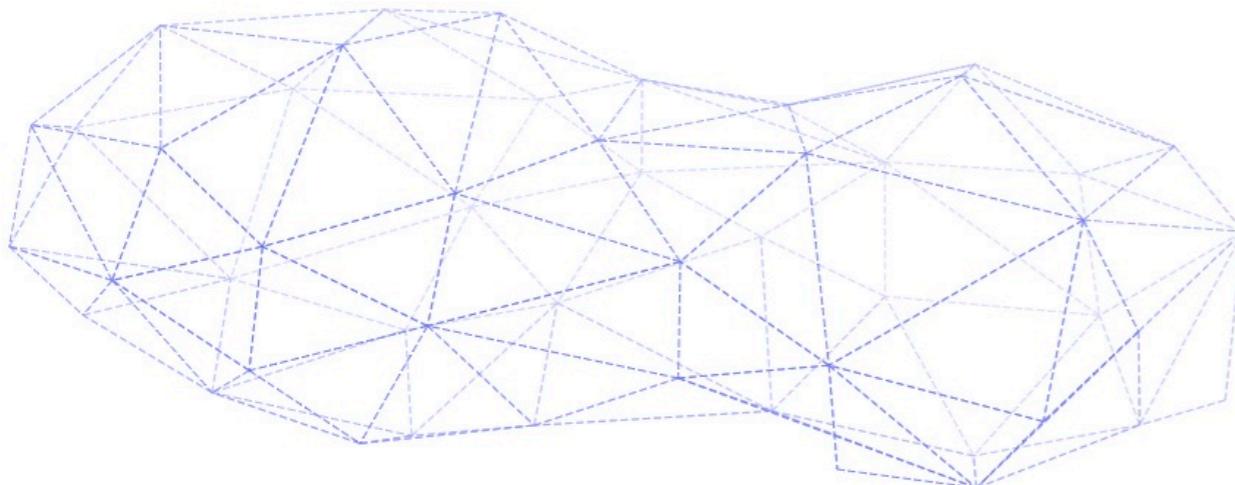


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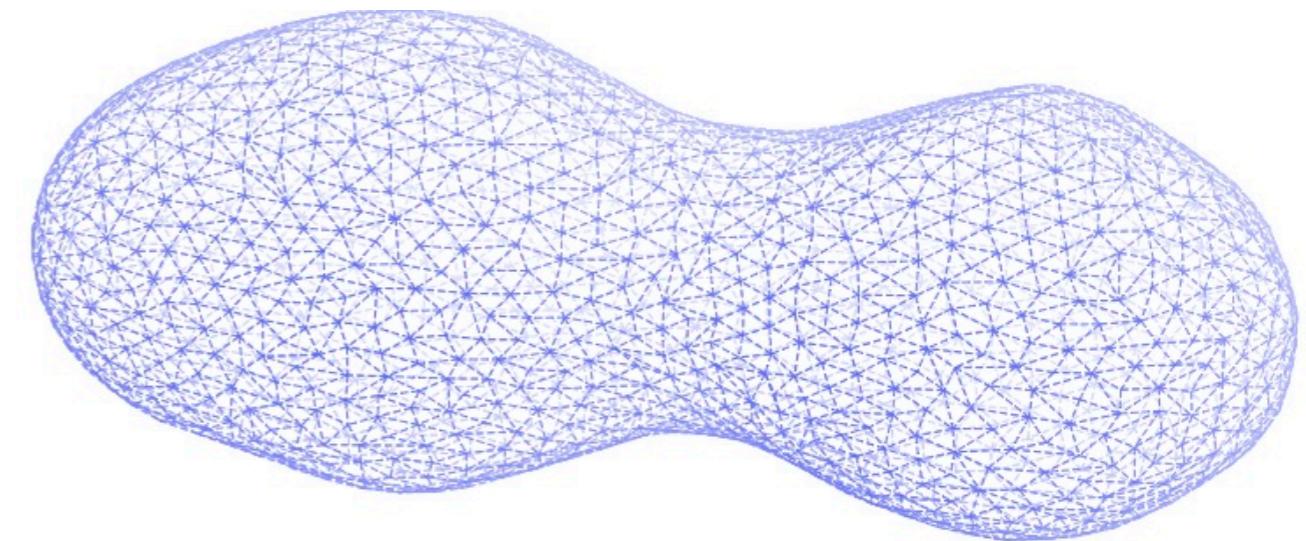
3D network with
closed surface



(a) Sensor network topology



(b) Finest triangulation by [3]

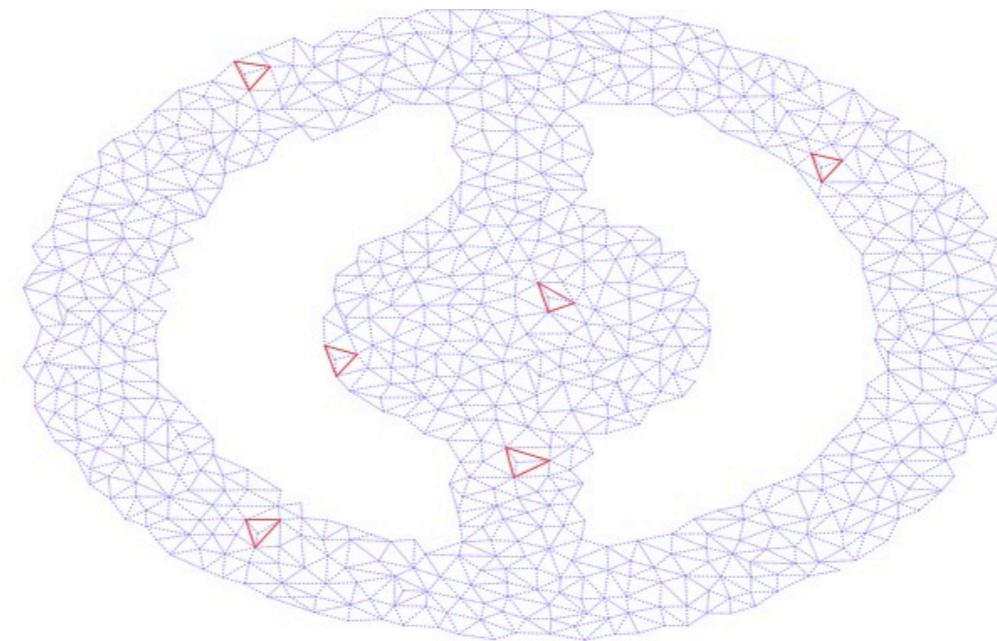


(c) Proposed triangulation

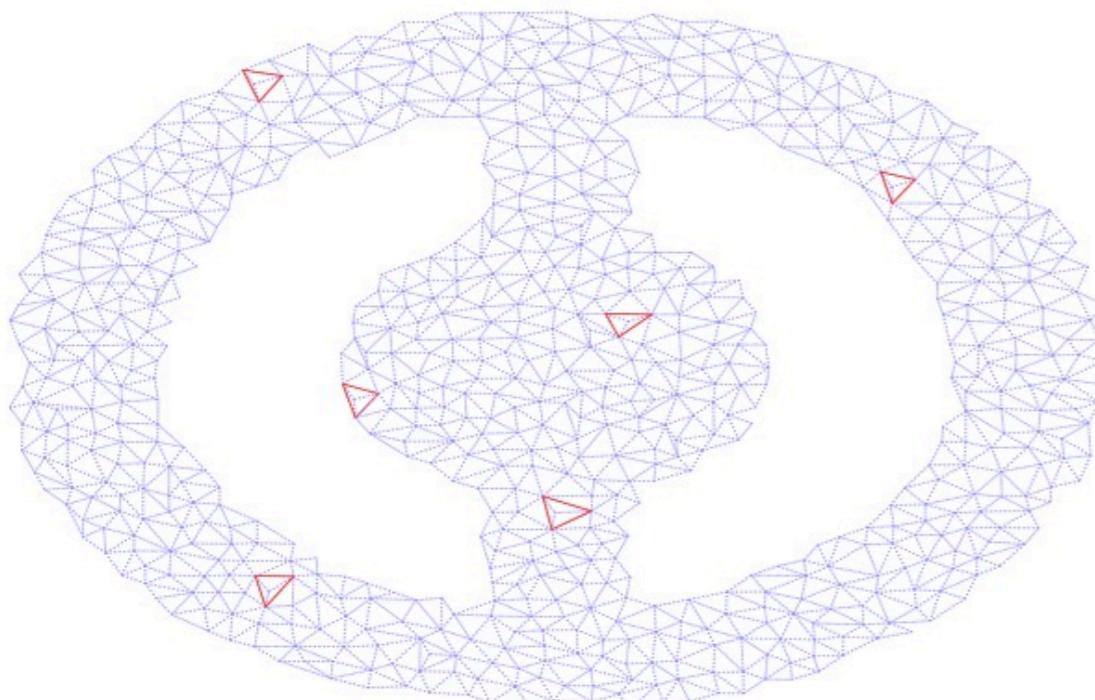


APPLICATION AND SIMULATION RESULTS

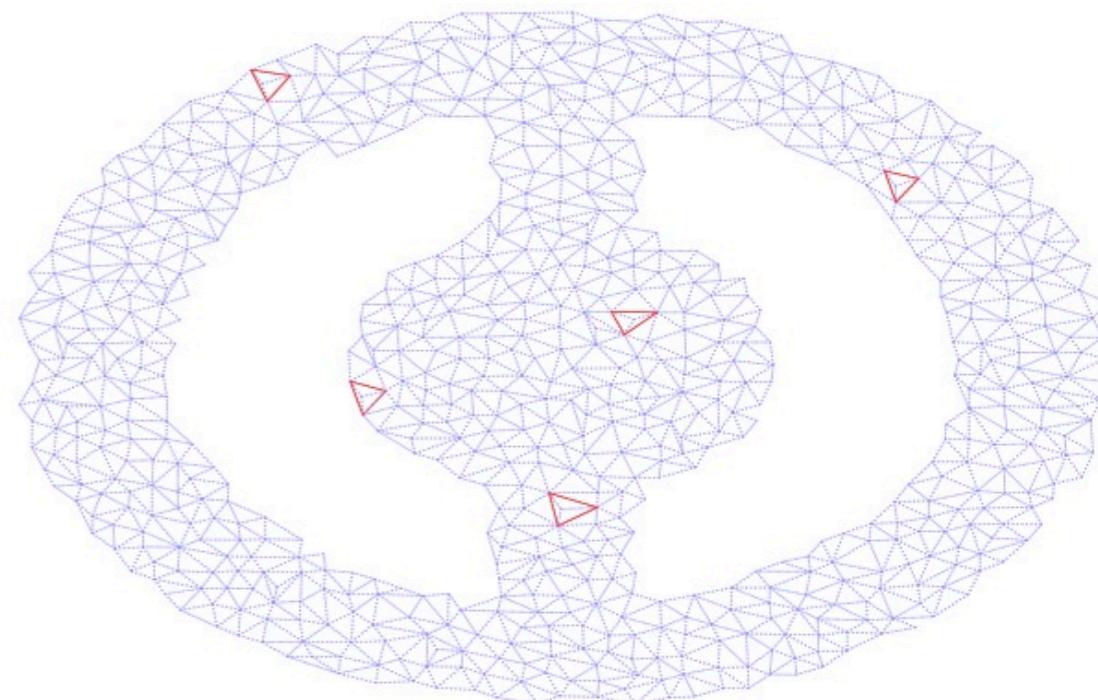
2D network with distance errors



(a) Triangulation under 10% distance errors.



(b) Triangulation under
20% distance errors.

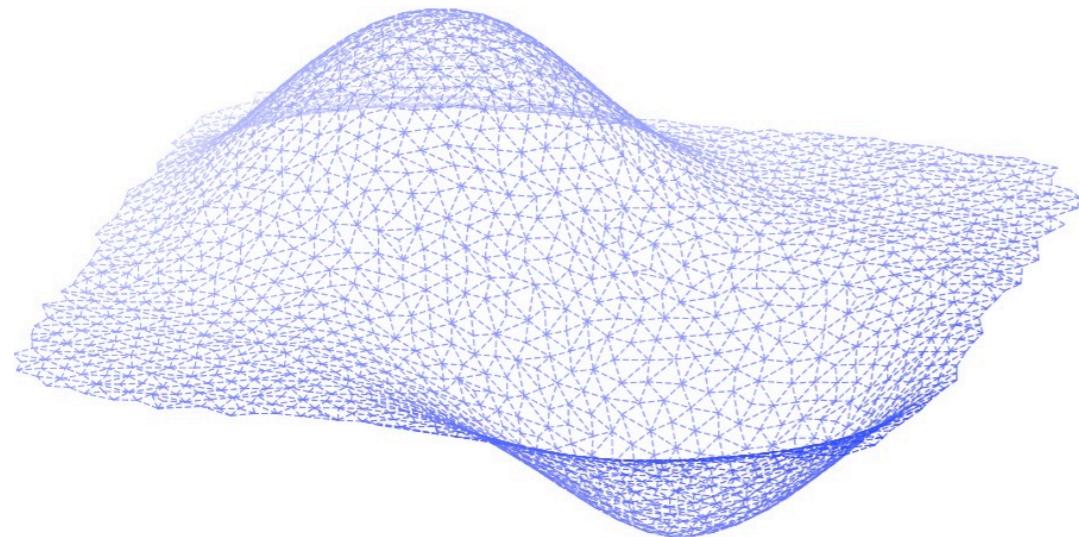


(c) Triangulation under
30% distance errors.

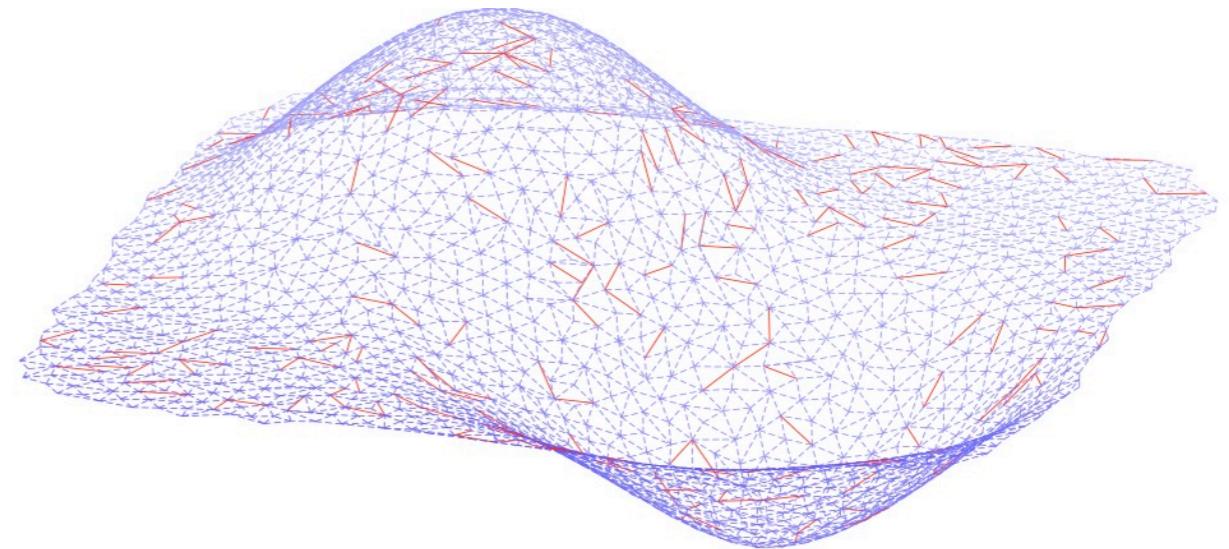


APPLICATION AND SIMULATION RESULTS

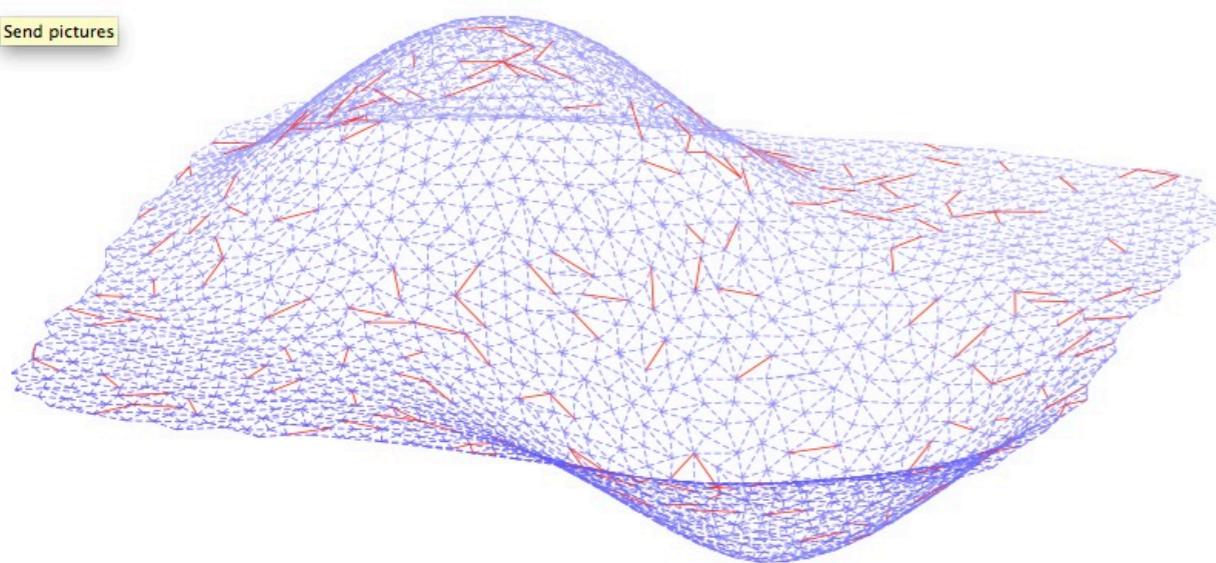
Difference Communication Models



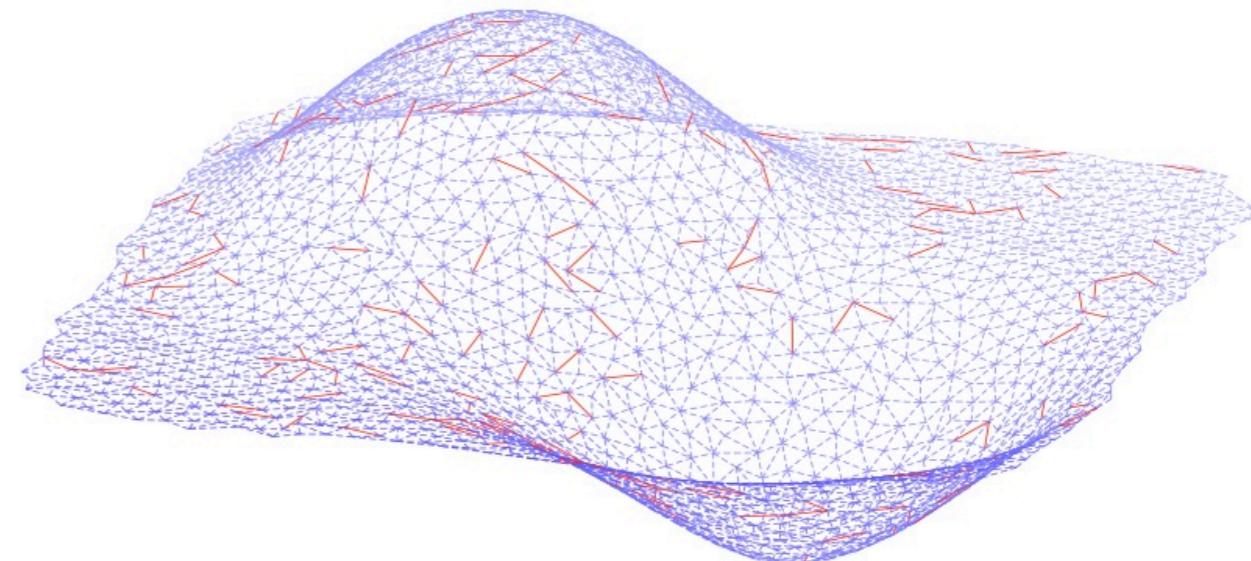
(a) UDG



(b) Triangulation under Quasi-UDG
($\alpha = 0.4$).



(c) Triangulation under Quasi-UDG
($\alpha = 0.6$)



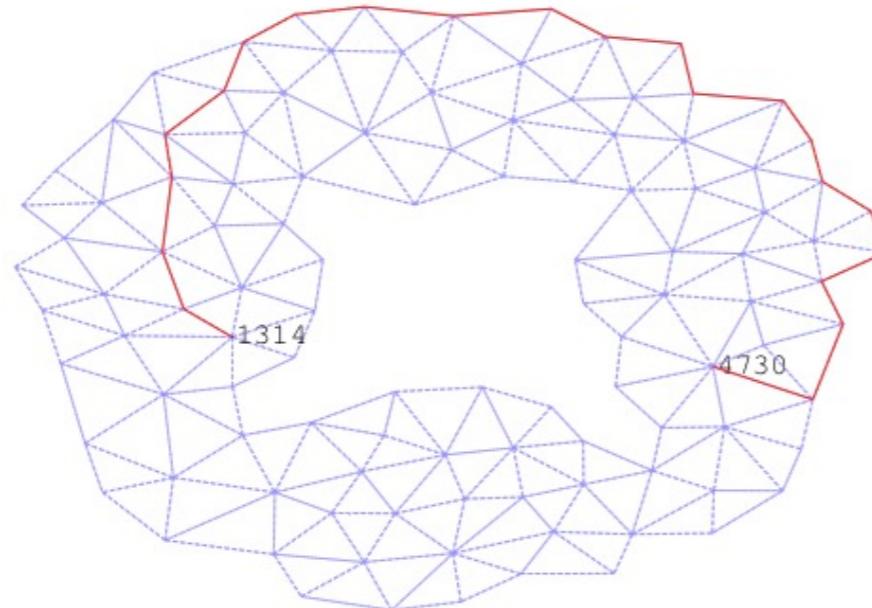
(d) Triangulation under Log-normal.



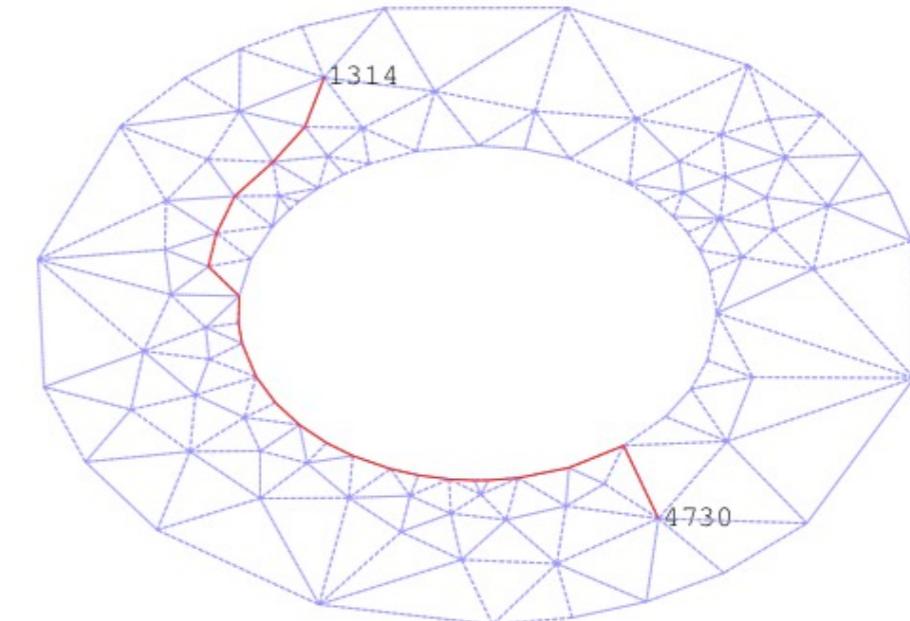
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APPLICATION AND SIMULATION RESULTS

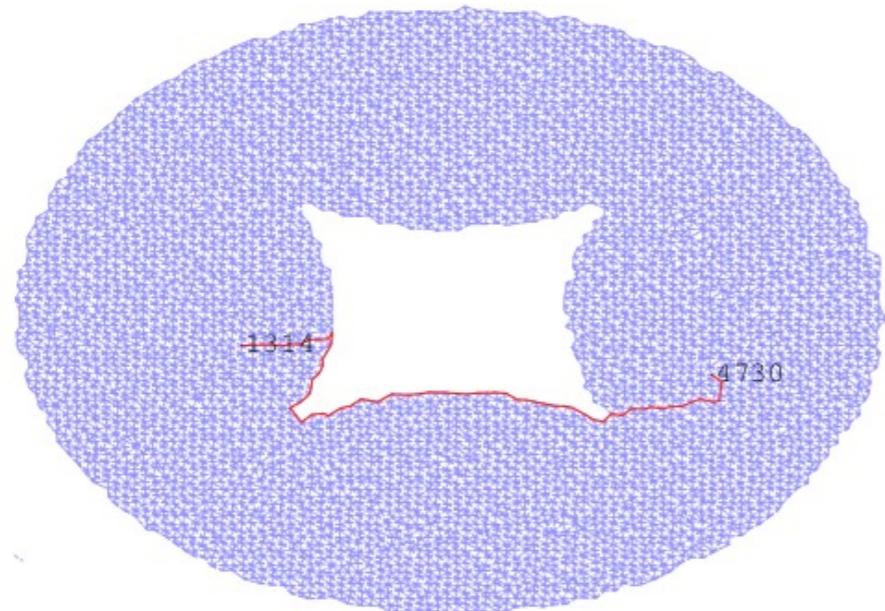
Greedy routing based on Ricci flow in 2D networks



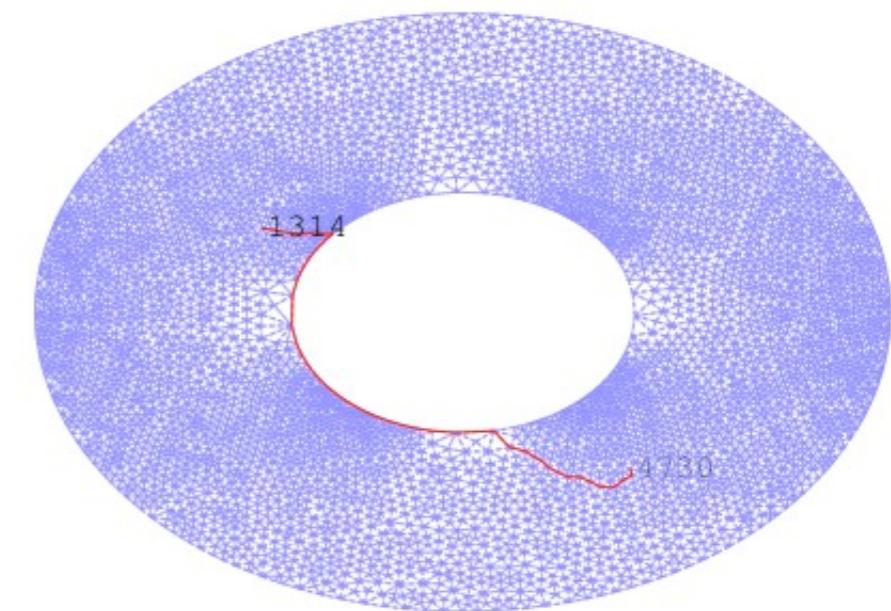
(a) Finest triangulation by [2]



(b) Ricci embedding



(c) Proposed triangulation



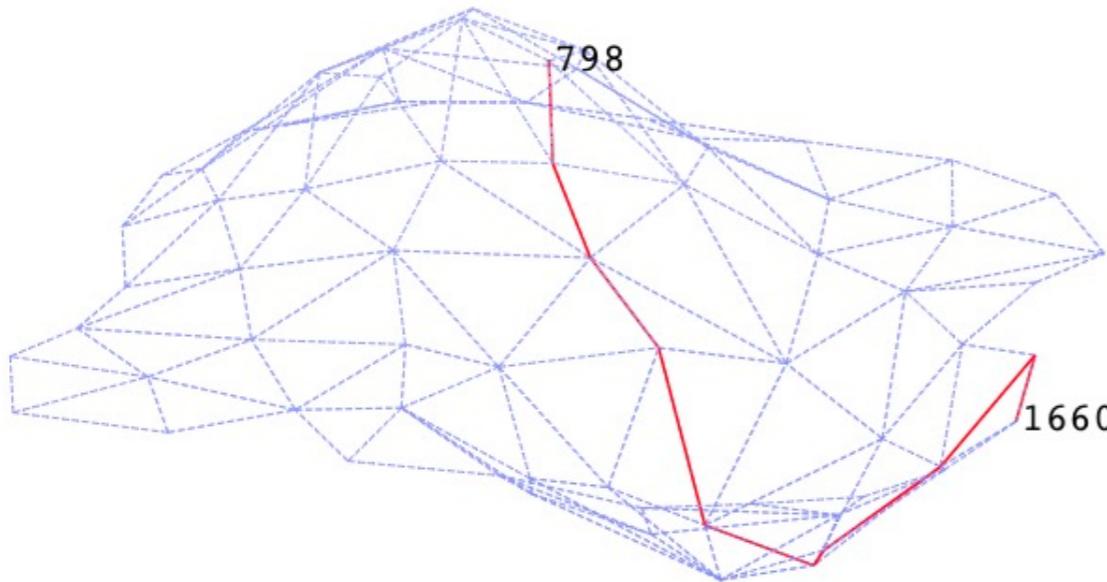
(d) Ricci embedding



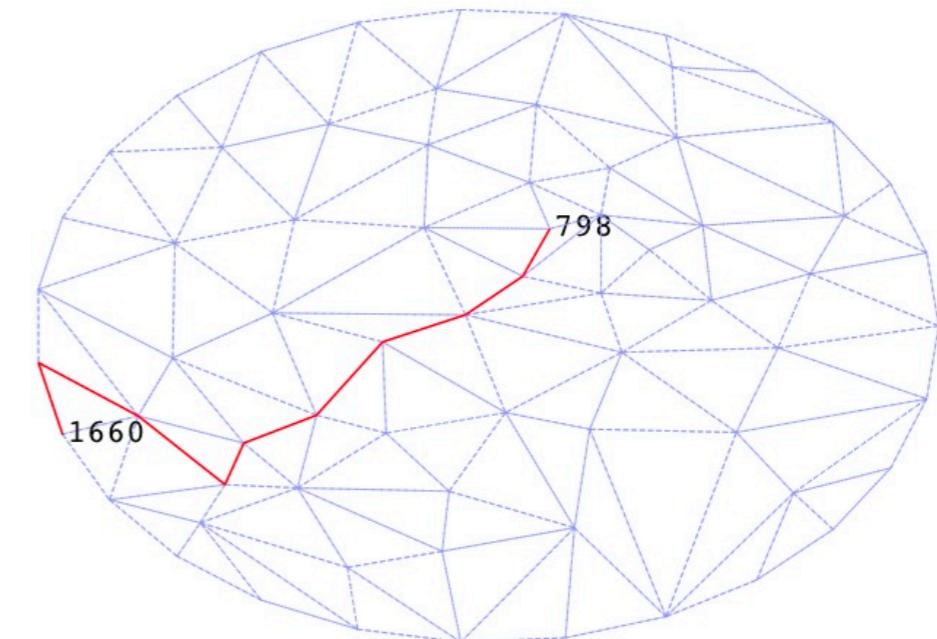
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APPLICATION AND SIMULATION RESULTS

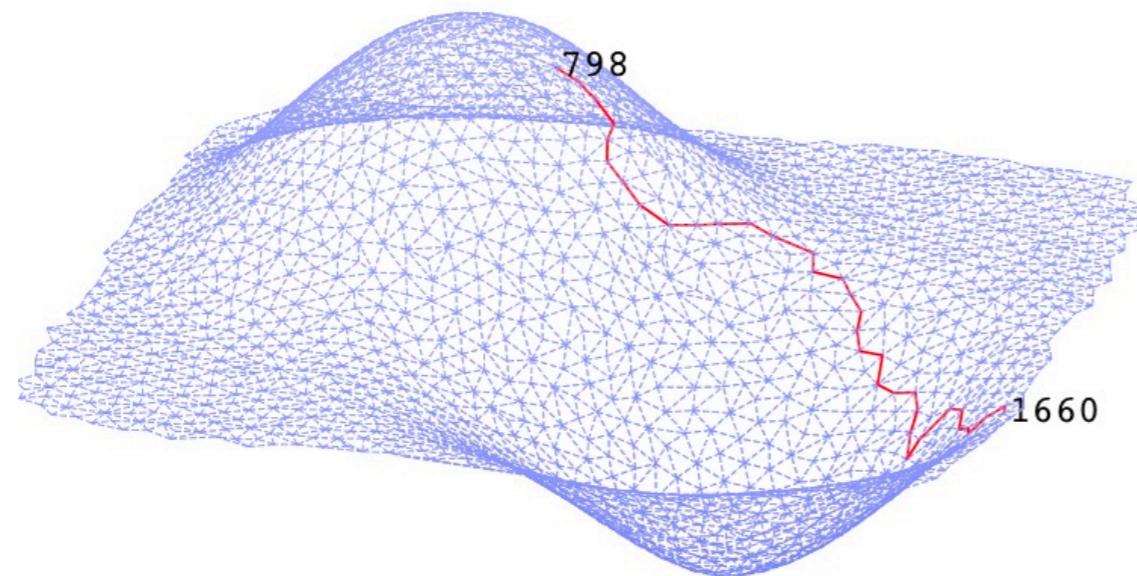
Greedy routing based on Ricci flow in 3D networks



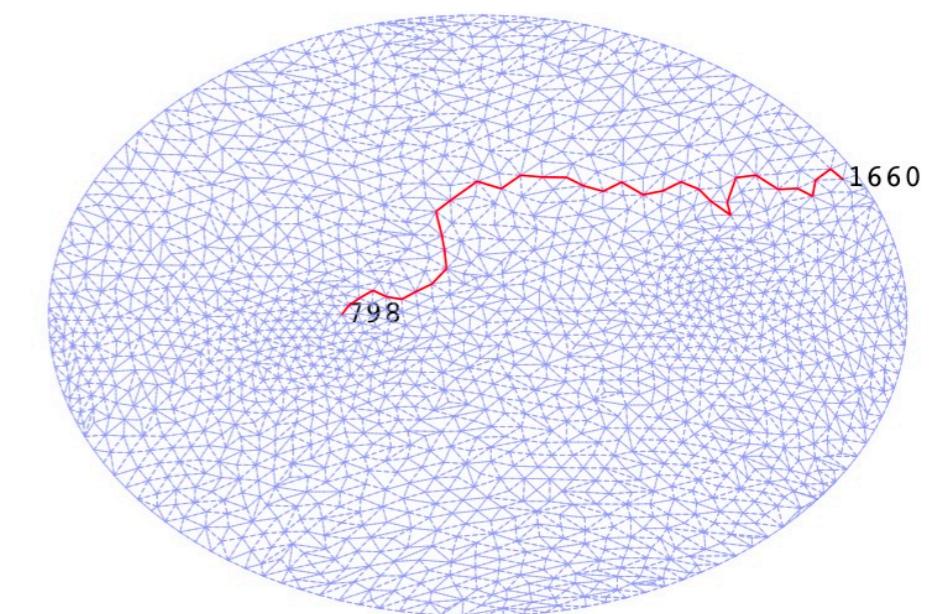
(a) Finest triangulation by [3]



(b) Ricci embedding



(c) Proposed triangulation



(d) Ricci embedding

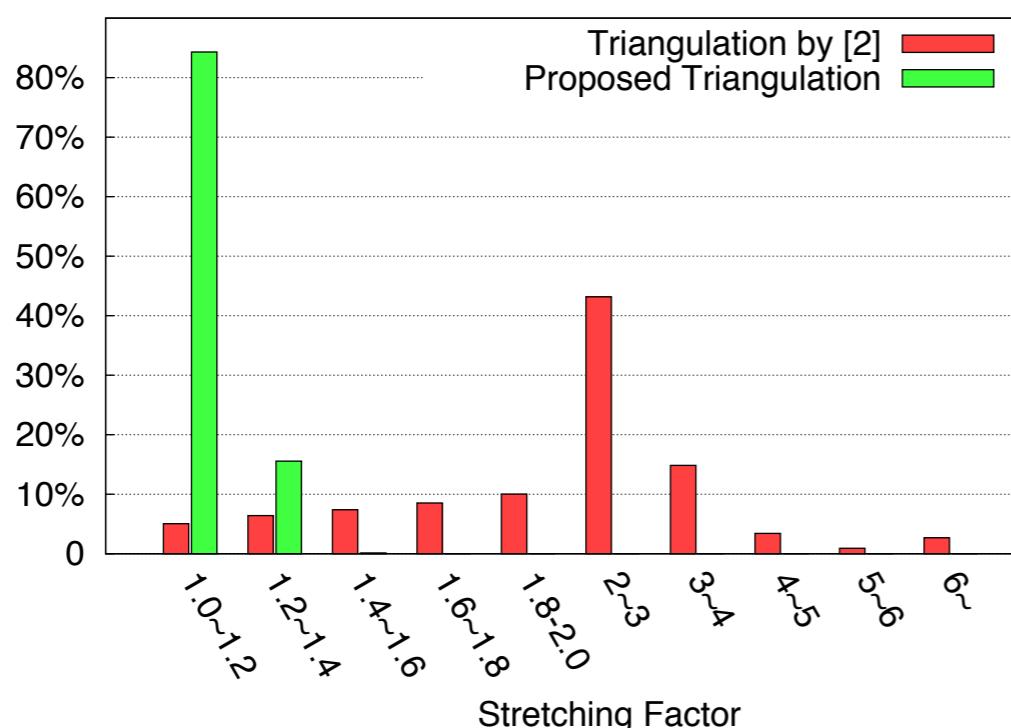


APPLICATION AND SIMULATION RESULTS

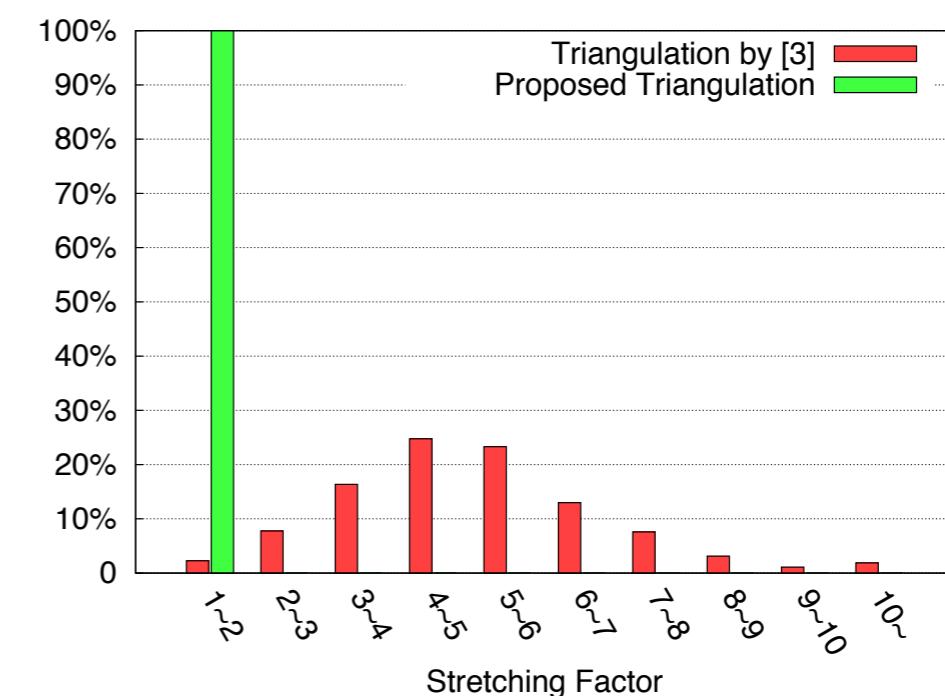
COMPARISON OF STRETCH FACTOR IN GREEDY ROUTING.

	2D networks	3D networks
Triangulation by [2], [3]	2.065	5.417
Proposed Triangulation	1.214	1.091

Distribution of stretch factor in greedy routing



(a) 2D networks



(b) 3D networks



CONCLUSION

- In summary, we have proposed a distributed algorithm that can triangulate an arbitrary sensor network without position information.
- The algorithm can achieve the finest triangulation and tolerate distance measurement errors.
- We have proven its correctness in 2D and extended it to 3D surface.
- A range of geometry-based network algorithms can benefit from the proposed triangulation.

