



Graduate Student, Self-motivated Developer



+86 13502009660



miaodx@tju.edu.cn



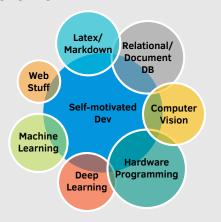
https://github.com/MiaoDX



https://miaodx.github.io/

Skills -

Overview



Programming

 $\longrightarrow 5000 LOC$ OpenCV • Python • Markdown C++ • Raspberry Pi • Arduino Java • JS • HTML

Experience -

TJU RM Member

CV, DL methods on object detection, tracking and decision making.

Teaching Assistant

Programming Design Practice I, full English course for freshmen.

Teaching Python101

Teaching python for several overseas master candidates majoring in finance.

Valunteer Teacher

Volunteered to teach in one primary school in TongChuan, Shannxi, organized by "Dripping Action" (one project of Mutualistic Symbiosis Community of Youths & Environment, Shaanxi).

Education

2016 - Now MSe., Computer Software 2012 - 2016 BEng., Computer Software

Papers

Jan 2018 Paper Accepted by ICASSP 2018 (First Author)

ACTIVE CAMERA RELOCALIZATION WITH RGBD CAMERA FROM A

Tianjin University

Xidian University

SINGLE 2D IMAGE

Paper Accepted by ICME 2018 (Oral) Mar 2018

Fast and Reliable Computational Rephotography on Mobile Device

Projects & Work

More can be found at https://github.com/MiaoDX/

July 2018 -Intern at Horizon Robotics

Present Perception algorithm engineer intern at Horizon Robotics (Bei-

jing), under the Department of Autonomous Driving. Working on

simulator, traffic modelling, DL and label tool.

Jan 2018 -**ICRA 2018 DJI ROBOMASTER AI CHALLENGE**

May 2018 Took part in ICRA 2018 DJI RM AI CHALLENGE with other five

teammates from TJU. In charge of object detection and tracking.

Got the finalist invitation.

Mar 2016 -**Active Camera Relocalization**

Present Actively relocate camera to previous pose is one fundamental re-

search area in robotics and computer vision. Major part of my

undergraduate graduation and conference papers.

Python Data Labelling tool for ML/DL

Data Label Data labelling tool to make the work less tedious with tracking

methods underneath. Export file for DLIB and Darkflow.

Virtual Env UnrealCV with Deep Learning (Faster-RCNN)

Integrate (smallcorgi/Faster-RCNN TF) with virtual environment DL

library UnrealCV. Exploring the potential benefits of synthetic data

on improving exisiting DL implements.

PacMan capture the flag with Reinforcement Learning PacMan & RL Python

Some reinforcement projects on pacman capture the flag game,

with fundamental concepts and a contest hold in class.

OpenCV Restful depth camera

Flask Expose one stereo camera (ZED) into restful one, so that it can be

accessed from other programming languages with ease.

UCI Adult database processing with scikit-learn Python

MLUse sklearn to predict whether income exceeds \$50K/yr based on

census data, got best result in class (85%+ precision).

Back propagation implementation using java Java BP_java

BP It helps a lot to understand DL by implementing ANN from scratch

before diving into those open source ML(DL) libraries.

Scholarships & Awards

2017-2018 Second-class School Scholarship 2016-2017 First-class School Scholarship

Postgraduate recommendation offer from Tianjin University

2014-2015 National Inspiration Scholarship 2014CUMCMSecond-class prize in Shaanxi Division

2013-2014 Second-class School Scholarship

2012-2013 First-class School Scholarship

Personal

RL

CET-6 Passed (460), English as working language Reading, Running, Cycling, Boxing

MiaoDX

Graduate Student, Self-motivated Developer

+86 13502009660



miaodx@tju.edu.cn



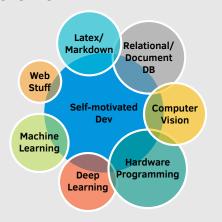
https://github.com/MiaoDX



https://miaodx.github.io/

Skills

Overview



Programming

0 LOC - $\longrightarrow 5000 LOC$

OpenCV • Python • Markdown

C++ • C • Arduino

Java • JS • HTML

Experience -

TJU RM 成员

算法组成员,基于视觉、深度学习方 法的物体检测与跟踪

研究生助教

大一新生程序设计实践 I 助教, 教授 为外籍老师,课程全英文教学

Python 101

为几位已申请到国外高校的金融专业 准硕士/博士准备的 python 课程

志愿者教师

"滴水行动",与队友一起在陕西省铜 川市一山村小学志愿教学,活动由陕 西青年与环境互助网络组织进行

教育背景

2016 - Now 硕士 软件工程 计算机视觉 2012 - 2016 学士 软件工程

天津大学 西安电子科技大学

会议文章

ICASSP 2018, CCF-B 类会议接收 (第一作者) Jan 2018

ACTIVE CAMERA RELOCALIZATION WITH RGBD CAMERA FROM A

SINGLE 2D IMAGE

ICME 2018, CCF-B 类会议接收 (Oral) Mar 2018

Fast and Reliable Computational Rephotography on Mobile Device

项目经验

列举部分近期项目,更多的请访问 github 主页 github.com/MiaoDX

地平线机器人 (Horizon Robotics) 实习 July 2018 -

地平线机器人自动驾驶研发部门感知算法工程师实习生,工作内容 Present

涉及仿真环境、交通流建模、深度学习、标注工具等。

Jan 2018 -ICRA 2018 DJI ROBOMASTER 人工智能挑战赛

搭建全自动智能车与大疆官方的 AI 智能车进行对抗。主要负责视 May 2018

觉算法,物体识别、跟踪及部分决策模块。(Finalist invitation)

主动相机位姿重定位 Mar 2016 -

主动地将相机位姿重定位到参考位置是机器人学与计算机视觉一基 Present

础研究领域,支撑了本科毕设与会议论文。

Python 机器学习/深度学习数据标注工具

物体检测数据标注工具,利用跟踪算法大幅减少手工标注的需求量, Data Label

可用于输出 Dlib 与 Darkflow 适用的物体检测训练配置文件。

Virtual Env UnrealCV 与深度学习结合 (Faster-RCNN)

DL 将 smallcorgi/Faster-RCNN TF 集成到 UnrealCV 上,探究通过虚

拟环境生成的合成数据来提升现有深度学习实现的可能性。

Python 增强学习应用到吃豆人游戏 PacMan & RL

整理了增强学习的一些基础知识,并将其应用到吃豆人游戏当中,在 RL

高级人工智能结课比赛中取得较好成绩。

OpenCV Restful 深度相机 Depth_camera & http

将一双目深度相机(ZED)扩展成为 Restful 服务,能被不同编程语 Flask

言调用,省去了为每种语言进行 SDK 移植的麻烦。

Python 利用 sklearn 库处理 UCI Adult 数据集 scikit_learning

基于人口调查结果,使用 sklearn 机器学习库来预测收入是否超过 ML

\$50K/yr, 这是一典型的分类问题, 达到 85%+ 的精度。

Java 使用 Java 实现反向传播算法

BP 在使用流行的开源 ML(DL) 库前,能够先从头实现一些基本的组件

是很重要的,可以对其理论基础与运算机理有更深的了解。

Node.js 考勤管理系统 Attendance system

为一(模拟)公司实现基于 RESTful 接口的考勤管理系统。公司成 MongoDB

员可以经由系统申请休假并等待批准,同时可以查询由系统整理得

到的历史统计数据。

荣誉奖励

2017-2018 校级二等奖学金 2016-2017 校级一等奖学金

Oct 2016 研究生推免至天津大学软件学院

2014-2015 国家励志奖学金

2014CUMCM全国大学生数学建模竞赛,陕西赛区二等奖

2013-2014 校级二等奖学金 2012-2013 校级一等奖学金

其他信息

Passed CET-6, English as working language 阅读 跑步 拳击 骑行