view frames Result Recorded at time: 39.318 world Broadcaster: /robot state publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (39.318 sec old) Buffer length: 0.000 sec table Broadcaster: /robot state publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (39.318 sec old) Buffer length: 0.000 sec base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 41.987 Hz Average rate: 10000.000 Hz Most recent transform: 39.308 (0.010 sec old) Most recent transform: 0.000 (39.318 sec old) Most recent transform: 0.000 (39.318 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.120 sec shoulder link base kinect camera visor Broadcaster: /robot_state_publisher Average rate: 41.987 Hz Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (39.318 sec 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realSense_depth_optical_frame realSense color frame Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (39.318 sec old) Buffer length: 0.000 sec robotiq_2f_85_left_coupler robotiq_2f_85_right_coupler realsense_camera_link realSense_left_ir_optical_frame realSense_right_ir_optical_frame Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 41.987 Hz Average rate: 41.987 Hz Most recent transform: 39.308 (0.010 sec old) Most recent transform: 39.308 (0.010 sec old) Buffer length: 3.120 sec Buffer length: 3.120 sec robotiq_2f_85_right_follower robotiq_2f_85_left_follower Broadcaster: /robot state 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