view frames Result Recorded at time: 48.864 world Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 0.000 (48.864 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base link table Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 42.614 Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 0.000 (48.864 sec old) Most recent transform: 48.812 (0.052 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 1.056 sec kinect camera_visor base shoulder link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 42.614 Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 48.812 (0.052 sec old) Buffer length: 0.000 sec Buffer length: 1.056 sec upper_arm_link kinect camera base Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 42.614 Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 48.812 (0.052 sec old) Buffer length: 0.000 sec Buffer length: 1.056 sec forearm_link kinect_camera_body Broadcaster: /robot state publisher Average rate: 42.614 Hz Most recent transform: 48.812 (0.052 sec old) Buffer length: 1.056 sec wrist_1_link Broadcaster: /robot state publisher Average rate: 42.614 Hz Most recent transform: 48.812 (0.052 sec old) Buffer length: 1.056 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 42.614 Hz Most recent transform: 48.812 (0.052 sec old) Buffer length: 1.056 sec wrist 3 link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 0.000 (48.864 sec old) Most recent transform: 0.000 (48.864 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec tool0 ee_link realsense camera link Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz
Most recent transform: 0.000 (48.864 sec old) Average rate: 10000.000 Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 0.000 (48.864 sec old) Most recent transform: 0.000 (48.864 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec robotiq_arg2f_base_link realsense_usb_plug_link robotiq_ur_coupler realsense camera bottom screw frame Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher Average rate: 42.614 Hz Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 42.614 Hz Average rate: 42.614 Hz Average rate: 42.614 Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 48.812 (0.052 sec old) Buffer length: 0.000 sec Buffer length: 1.056 sec Buffer length: 1.056 sec Buffer length: 1.056 sec Buffer length: 1.056 sec robotiq_2f_85_base robotiq_2f_85_left_driver robotiq_2f_85_right_driver robotiq_2f_85_left_spring_link robotiq_2f_85_right_spring_link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 42.614 Hz Average rate: 42.614 Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 48.812 (0.052 sec old) Most recent transform: 48.812 (0.052 sec old) Most recent transform: 0.000 (48.864 sec old) Buffer length: 1.056 sec Buffer length: 1.056 sec Buffer length: 0.000 sec Buffer length: 0.000 sec robotiq_2f_85_right_coupler robotiq_2f_85_left_pad robotiq_2f_85_right_pad robotiq_2f_85_left_coupler Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (48.864 sec old) Most recent transform: 0.000 (48.864 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec robotiq_2f_85_left_follower robotiq_2f_85_right_follower