Classification algorithm based on matrix kernels

Miaoyan Wang, Aug 18, 2020

1 Notation

- 1. $\mathbb{O}(d,r) := \{ \boldsymbol{P} \in \mathbb{R}^{d \times r} \colon \boldsymbol{P}^T \boldsymbol{P} = \boldsymbol{I}_r \}$, the collection of *d*-by-*r* matrices whose columns are orthonormal. When no confusion arises, I use the term "projection matrix" to denote either the matrix $\boldsymbol{P}\boldsymbol{P}^T \in \mathbb{R}^{d \times d}$ or the matrix $\boldsymbol{P} \in \mathbb{R}^{d \times r}$.
- 2. $\mathcal{K}^{\text{row}}(i, j, \boldsymbol{X}, \boldsymbol{X}') := \langle \Phi(\boldsymbol{X}_{i:}), \Phi(\boldsymbol{X}'_{j:}) \rangle$ denotes the value of row kernel evaluated at the vector pair, (*i*-th row of matrix \boldsymbol{X} , *j*-th row of matrix \boldsymbol{X}').
- 3. I sometimes use the shorthand $\mathcal{K}^{\text{row}}(i,j)$ to denote $\mathcal{K}^{\text{row}}(i,j,\boldsymbol{X},\boldsymbol{X}')$, when the feature pair $(\boldsymbol{X},\boldsymbol{X}')$ is clear given the contexts. Note that $\mathcal{K}^{\text{row}}(i,j)$ can be calcualted without explicit feature mapping. Similar convention for $\mathcal{K}^{\text{col}}(i,j,\boldsymbol{X},\boldsymbol{X}')$.
- 4. Let $\mathbf{W}^{\text{row}} = \mathbf{P}_r \mathbf{P}_r^T = \llbracket w_{ij}^{\text{row}} \rrbracket \in \mathbb{R}^{d_1 \times d_1}$ and $\mathbf{W}^{\text{col}} = \mathbf{P}_c \mathbf{P}_c^T = \llbracket w_{ij}^{\text{col}} \rrbracket \in \mathbb{R}^{d_2 \times d_2}$ denote the rowand column-wise projection matrices, respectively.

2 Algorithm based on bilinear maps

Consider the bilinear mapping,

$$\Phi \colon \mathbb{R}^{d_1 \times d_2} \to (\mathcal{H}_r \times \mathcal{H}_c)^{d_1 \times d_2}$$
$$\boldsymbol{X} \mapsto [\Phi(\boldsymbol{X})_{ij}], \quad \text{where } \Phi(\boldsymbol{X})_{ij} \stackrel{\text{def}}{=} (\phi_c(\boldsymbol{X}_{i:}), \ \phi_r(\boldsymbol{X}_{:j})).$$

Primal problem:

$$\min_{\boldsymbol{P}_r, \boldsymbol{P}_c} \min_{\boldsymbol{C}} \quad \frac{1}{2} \|\boldsymbol{C}\|_F^2 + c \sum_{i=1}^n \xi_i,
\text{subject to} \quad y_i \langle \boldsymbol{P}_r \boldsymbol{C} \boldsymbol{P}_c^T, \ \Phi(\boldsymbol{X}_i) \rangle \leq 1 - \xi_i \text{ and } \xi_i \geq 0, \ i = 1, \dots, n.$$
(1)

Parameters in the primal problem: $(\boldsymbol{P}_r, \boldsymbol{P}_c, \boldsymbol{C})$, where $\boldsymbol{P}_r \in \mathbb{O}(d_1, r_1)$, $\boldsymbol{P}_c \in \mathbb{O}(d_2, r_2)$, and $\boldsymbol{C} = [(\boldsymbol{c}_i^{\text{row}}, \ \boldsymbol{c}_i^{\text{col}})] \in (\mathcal{H}_r \times \mathcal{H}_c)^{r_1 \times r_2}$ is the "core matrix" consisting of linear coefficients.

1. Update C, given (P_r, P_c) .

implicit update
$$C \leftarrow \sum_{i} \alpha_{i} y_{i} P_{r}^{T} \Phi(X_{i}) P_{c}$$
.

Saved quantities: dual variables $\alpha \in \mathbb{R}^n$.

Intermediate quantities: kernel $\mathcal{K}(X, X')$ specified below.

Objective value: objective value for the dual problem.

Details: We use kernel trick to solve for α without explicit feature mapping. Given the projections (P_r, P_c) , the optimization (1) is a standard SVM with kernel

$$\mathcal{K}(\boldsymbol{X}, \boldsymbol{X}') = \langle \boldsymbol{P}_r^T \Phi(\boldsymbol{X}) \boldsymbol{P}_c, \ \boldsymbol{P}_r^T \Phi(\boldsymbol{X}') \boldsymbol{P}_c \rangle
= (\sum_{i,j} w_{ij}^{\text{col}}) (\sum_{i,j} w_{ij}^{\text{row}} K^{\text{row}}(i,j)) + (\sum_{i,j} w_{ij}^{\text{row}}) (\sum_{i,j} w_{ij}^{\text{col}} K^{\text{col}}(i,j)).$$
(2)

for all feature pairs (X, X'). Here I have used the shorthand $K^{\text{row}}(i, j)$ to denote the value of row kernel evaluated on the *i*-th row of X and *j*-th row of X'.

Remark 1 (Computational consideration). We can compute the summations in (2) without explicit loop. In particular, both identities hold: $\sum_{i,j} w_{ij}^{\text{col}} = \|\mathbf{1}^T \boldsymbol{P}_c\|_2^2$ and $\sum_{i,j} w_{ij}^{\text{row}} K^{\text{row}}(i,j) = \text{trace}(\boldsymbol{W}^T \boldsymbol{K})$, where $\boldsymbol{K} \leftarrow [\![K^{\text{row}}(i,j,\boldsymbol{X},\boldsymbol{X}')]\!]$ is a pre-stored matrix (or array, if we go through all possible feature pairs $(\boldsymbol{X},\boldsymbol{X}')$).

2. Update P_r , given (C, P_c) .

explicit update
$$\tilde{\boldsymbol{P}}_r^{\text{new}} \leftarrow \sum_i \beta_i y_i \Phi(\boldsymbol{X}_i) \boldsymbol{P}_c \boldsymbol{C}^T = \sum_{i,j} \beta_i \alpha_j y_i y_j \underbrace{\Phi(\boldsymbol{X}_i) \boldsymbol{P}_c \boldsymbol{P}_c^T \Phi^T(\boldsymbol{X}_j)}_{d_1\text{-by-}d_1 \text{ matrix over } \mathbb{R}} \boldsymbol{P}_r$$
normalize $\boldsymbol{P}_r^{\text{new}} \leftarrow \text{QR}$ decomposition of $\tilde{\boldsymbol{P}}_r^{\text{new}}$.

Saved quantities: $\mathbf{P}^{\text{new}} \in \mathbb{O}(d_1, r_1)$.

Intermediate quantities: matrix $\Phi(\mathbf{X}_i)\mathbf{P}_c\mathbf{P}_c^T\Phi^T(\mathbf{X}_j)$ and its trace, dual variables $\boldsymbol{\beta} \in \mathbb{R}^n$. Objective value: objective value for the dual problem.

Details: for each feature pair $(i, j) \in [n]^2$, we compute the matrix $\Phi(\mathbf{X}_i)\mathbf{P}_c\mathbf{P}_c^T\Phi^T(\mathbf{X}_j)$ without explicit feature mapping,

$$\Phi(\boldsymbol{X}_{i})\boldsymbol{P}_{c}\boldsymbol{P}_{c}^{T}\boldsymbol{\Phi}^{T}(\boldsymbol{X}_{j}) = \left(\sum_{s,s'}w_{ss'}^{\text{col}}\right)\begin{bmatrix}K^{\text{row}}(1,1,\boldsymbol{X}_{i},\boldsymbol{X}_{j}) & \cdots & K^{\text{row}}(1,d_{1},\boldsymbol{X}_{i},\boldsymbol{X}_{j})\\ \vdots & \vdots & \vdots\\ K^{\text{row}}(d_{1},1,\boldsymbol{X}_{i},\boldsymbol{X}_{j}) & \cdots & K^{\text{row}}(d_{1},d_{1},\boldsymbol{X}_{i},\boldsymbol{X}_{j})\end{bmatrix} + \left(\sum_{s,s'}w_{ss'}^{\text{col}}K^{\text{col}}(s,s',\boldsymbol{X}_{i},\boldsymbol{X}_{j})\right)\begin{bmatrix}1 & 1 & \cdots & 1\\ \vdots & \vdots & \vdots & \vdots\\ 1 & 1 & \cdots & 1\end{bmatrix}, \quad (3)$$

where $K^{\text{row}}(s, s', \boldsymbol{X}_i, \boldsymbol{X}_j)$ denotes the value of row kernel value evaluated on the s-th row of \boldsymbol{X}_i and s'-th row of \boldsymbol{X}_j , and likewise for $K^{\text{col}}(s, s', \boldsymbol{X}_i, \boldsymbol{X}_j)$.

The coefficient β is obtained from a standard SVM with kernel

$$\mathcal{K}(\boldsymbol{X},\boldsymbol{X}') = \operatorname{trace}(\Phi(\boldsymbol{X})\boldsymbol{P}_{\!c}\boldsymbol{P}_{\!c}^T\Phi^T(\boldsymbol{X}')) = \operatorname{trace} \text{ of matrix specified in (3)},$$

for all feature pairs (X, X').

3. Update P_c , given (C, P_r) .

explicitle update
$$P_c^{\text{new}} \leftarrow \sum_i \gamma_i y_i \Phi^T(\boldsymbol{X}_i) P_r \boldsymbol{C} = \sum_{i,j} \gamma_i \alpha_j y_i y_j \underbrace{\Phi^T(\boldsymbol{X}_i) P_r P_r^T \Phi(\boldsymbol{X}_j)}_{d_2\text{-by-}d_2 \text{ matrix over } \mathbb{R}} P_c$$
normalize $P_c^{\text{new}} \leftarrow \text{QR}$ decomposition of \tilde{P}_c^{new} .

The intermediate quantities, $\Phi^T(\mathbf{X}_i)\mathbf{P}_r\mathbf{P}_r^T\Phi(\mathbf{X}_j)$ and $\boldsymbol{\gamma}$, are calculated similarly as in step 2.

3 Outputs

- 1. Convergence criterum? Objective value in the dual problem.
- 2. How to read off the decision function from the algorithm?

$$f(\boldsymbol{X}_{\text{new}}) = \langle \boldsymbol{P}_r^T \Phi(\boldsymbol{X}_{\text{new}}) \boldsymbol{P}_c, \sum_i \alpha_i y_i \boldsymbol{P}_r^T \Phi(\boldsymbol{X}_i) \boldsymbol{P}_c \rangle$$

$$= \sum_i \alpha_i y_i \left\{ \left(\sum_{s,s'} w_{ss'}^{\text{col}} \right) \left(\sum_{s,s'} w_{ss'}^{\text{row}} K^{\text{row}}(s,s',\boldsymbol{X}_i,\boldsymbol{X}_{\text{new}}) \right) + \left(\sum_{s,s'} w_{ss'}^{\text{row}} \right) \left(\sum_{s,s'} w_{ss'}^{\text{col}} K^{\text{col}}(s,s',\boldsymbol{X}_i,\boldsymbol{X}_{\text{new}}) \right) \right\}.$$

3. How to estimate the intercept in the primal problem?

$$\hat{b}_0 = \underset{b_0 \in \mathbb{R}}{\operatorname{arg \, min}} \left\{ \sum_{i=1}^n (1 - y_i f(\mathbf{X}_i) - y_i b_0)_+ \right\}.$$

4. The objective value in the primal problem? The primal objective is $\frac{1}{2} \| \boldsymbol{C} \|_F^2 + c \sum_{i=1}^n (1 - y_i f(\boldsymbol{X}_i) - y_i b_0)_+$, where

$$\|\boldsymbol{C}\|_F^2 = \sum_{i,j} \alpha_i \alpha_j y_i y_j \operatorname{trace}(\Phi(\boldsymbol{X}_i) \boldsymbol{P}_c \boldsymbol{P}_c^T \Phi^T(\boldsymbol{X}_j) \boldsymbol{P}_r \boldsymbol{P}_r^T).$$

We omit the explicit expression of C because it is not needed in the algorithm.