## Algorithmic perspectives of kernel method

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## 1 A choice of feature mapping $\Phi$

To derive an algorithm, I choose to use Mapping 1 in the previous note for convenience.

$$\Phi \colon \mathbb{R}^{d_1 \times d_2} \to \mathcal{H}_r^{d_1} \times \mathcal{H}_c^{d_2}$$
$$\boldsymbol{X} \mapsto (\Phi_r(\boldsymbol{X}) \Phi_c(\boldsymbol{X})) \stackrel{\text{def}}{=} (\phi_r([\boldsymbol{X}]_{1:}), \dots, \phi_r([\boldsymbol{X}]_{d_1:}), \phi_c([\boldsymbol{X}]_{:1}) \dots, \phi([\boldsymbol{X}]_{:d_2})).$$

We define decision function,

$$f(\boldsymbol{X}) = \langle \boldsymbol{B}, \Phi(\boldsymbol{X}) \rangle, \text{ where } \boldsymbol{B} = (\boldsymbol{B}_r, \boldsymbol{B}_c) \in \mathcal{H}_r^{d_1} \times \mathcal{H}_c^{d_2}$$

$$= \langle \boldsymbol{B}_r, \Phi_r(\boldsymbol{X}) \rangle + \langle \boldsymbol{B}_c, \Phi_c(\boldsymbol{X}) \rangle$$

$$= \sum_{k=1}^n \alpha_k^r \sum_{i,j \in [d_2]} w_{ij}^{row} K([\boldsymbol{X}_k]_{i\cdot}, [\boldsymbol{X}]_{j\cdot}) + \sum_{k=1}^n \alpha_k^c \sum_{i,j \in [d_2]} w_{ij}^{col} K([\boldsymbol{X}_k]_{\cdot i}, [\boldsymbol{X}]_{\cdot j}),$$

$$(1)$$

where  $X^1, \dots X^n$  are sampled matrix features and  $W^{\text{col}}, W^{\text{row}}$  are some positive semi definite matrices with low rank. We estimate  $\boldsymbol{\alpha}^r = (\alpha_1^r, \dots, \alpha_n^r), \boldsymbol{\alpha}^c = (\alpha_1^c, \dots, \alpha_n^c), \boldsymbol{W}^{\text{col}},$  and  $\boldsymbol{W}^{\text{row}}$  from the training data set.

## 2 Algorithm derivation

We solve an optimization problem

$$\min_{\mathbf{B}} \frac{1}{2} \|\mathbf{B}\|_F^2 + c \sum_{i=1}^n \xi_i, \tag{2}$$
subject to  $y_i \langle \mathbf{B}, \Phi(\mathbf{X}_i) \rangle < 1 - \xi_i \text{ and } \xi_i > 0, i = 1, \dots, n$ 

subject to  $y_i \langle \boldsymbol{B}, \Phi(\boldsymbol{X}_i) \rangle \leq 1 - \xi_i$  and  $\xi_i \geq 0, i = 1, \dots, n$ .

where  $\|\boldsymbol{B}\|_F^2 = \|\boldsymbol{B}_r\|_F^2 + \|\boldsymbol{B}_c\|_F^2$ . From the low rank assumption on  $\boldsymbol{B}$  such that

$$B = (B_r, B_c) = CP^T = (C_r, C_c)(P_r, P_c)^T$$

where  $C = (C_r, C_c) \in \mathcal{H}_r^r \times \mathcal{H}_c^r$  and  $P = (P_r, P_c) \in \mathbb{R}^{d_1 \times r} \times \mathbb{R}^{d_2 \times r}$ . We assume that  $P_r, P_c$  are orthonormal matrices.

1. First we update C holding P fixed. The dual problem of Equation (2) is

$$\min_{\boldsymbol{\alpha}=(\alpha_1,\dots,\alpha_n)} - \sum_{i=1}^n \alpha_i + \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \langle \Phi(\boldsymbol{X}_i) \boldsymbol{P} \boldsymbol{P}^T, \Phi(\boldsymbol{X}_j) \boldsymbol{P} \boldsymbol{P}^T \rangle$$
subject to 
$$\sum_{i=1}^n y_i \alpha_i = 0, \text{ and } 0 \le \alpha_i \le C, i = 1, \dots, n.$$

Define  $\mathbf{K}(i,j) \in \mathbb{R}^{d_1 \times d_1} \times \mathbb{R}^{d_2 \times d_2}$  as

$$\boldsymbol{K}(i,j) = (\boldsymbol{K}_r(i,j), \boldsymbol{K}_c(i,j)) \stackrel{\text{def}}{=} \Phi(\boldsymbol{X}_i)^T \Phi(\boldsymbol{X}_j)$$

where 
$$[\mathbf{K}_r(i,j)]_{pq} = K_r([\mathbf{X}_i]_{p:}, [\mathbf{X}_i]_{q:}), \stackrel{\text{def}}{=} \langle \phi_r([\mathbf{X}_i]_{p:}), \phi_r([\mathbf{X}_j]_{q:}) \rangle,$$
  
 $[\mathbf{K}_c(i,j)]_{pq} = K_c([\mathbf{X}_i]_{:p}, [\mathbf{X}_i]_{:q}) \stackrel{\text{def}}{=} \langle \phi_c([\mathbf{X}_i]_{:p}), \phi_c([\mathbf{X}_j]_{:q}) \rangle.$ 

Therefore, we can successfully estimate  $\alpha$  with quadratic programming based on K without description of feature mapping  $\phi_r, \phi_c$ . We update C as

$$C = \sum_{i=1}^{n} \alpha_i y_i \Phi(\mathbf{X}_i) \mathbf{P} \in \mathcal{H}_r^r \times \mathcal{H}_c^r.$$
(3)

2. Second, we update P holding C fixed. The dual problem of Equation (2) is

$$\min_{\boldsymbol{\beta} = (\beta_1, \dots, \beta_n)} - \sum_{i=1}^n \beta_i + \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \beta_i \beta_j y_i y_j \langle \boldsymbol{C} \left( (\boldsymbol{C}^T \boldsymbol{C})^{-1} \boldsymbol{C}^T \boldsymbol{\Phi}(\boldsymbol{X}_i) \right), \boldsymbol{C} \left( (\boldsymbol{C}^T \boldsymbol{C})^{-1} \boldsymbol{C}^T \boldsymbol{\Phi}(\boldsymbol{X}_j) \right) \rangle, \tag{4}$$

subject to 
$$\sum_{i=1}^{n} y_i \beta_i = 0$$
, and  $0 \le \beta_i \le C, i = 1, \dots, n$ ,

Notice  $C\left((C^TC)^{-1}C^T\Phi(X_i)\right) \in \mathcal{H}^{d_1} \times \mathcal{H}^{d_2}$  is well defined by matrix product: for  $A_1 \in \mathcal{H}^r$  and  $A_2 \in \mathcal{H}^d$ ,  $A_1^TA_2 = \llbracket a_{ij} \rrbracket \in \mathbb{R}^{r \times d}$ , where  $a_{ij} = \langle [A_1]_i, [A_2]_j \rangle$ . We can find an optimizer of (4) without the feature mapping. To show this, notice that by plugging (3) into (4), we have

$$C^{T}C = \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{P}^{T} \mathbf{K}(i, j) \mathbf{P} \in \mathbb{R}^{r \times r} \times \mathbb{R}^{r \times r},$$

$$C^{T}\Phi(\mathbf{X}_{i}) = \sum_{i=1}^{n} \alpha_{i} y_{i} \mathbf{P}^{T} \mathbf{K}(i, j) \in \mathbb{R}^{r \times d_{1}} \times \mathbb{R}^{r \times d_{2}}.$$
(5)

(5) makes inner product in (4) expressed in terms of only P and  $\{K(i,j): i, j \in [n]\}$  by the following equation.

$$\langle \boldsymbol{C} \left( (\boldsymbol{C}^T \boldsymbol{C})^{-1} \boldsymbol{C}^T \Phi(\boldsymbol{X}_i) \right), \boldsymbol{C} \left( (\boldsymbol{C}^T \boldsymbol{C})^{-1} \boldsymbol{C}^T \Phi(\boldsymbol{X}_j) \right) \rangle = \operatorname{tr} \left( \left( \boldsymbol{C}^T \Phi(\boldsymbol{X}_i) \right)^T (\boldsymbol{C}^T \boldsymbol{C})^{-1} \left( \boldsymbol{C}^T \Phi(\boldsymbol{X}_i) \right) \right).$$

## 3 Relation with the previous algorithm symmetric trick

Define symmetric feature matrix  $\tilde{\boldsymbol{X}} = \begin{pmatrix} 0_{d_1 \times d_2} & \boldsymbol{X} \\ \boldsymbol{X}^t & 0_{d_2 \times d_1} \end{pmatrix} \in \mathbb{R}^{(d_1 + d_2) \times (d_1 + d_2)}$ . Feature mapping 3 is defined as

$$\tilde{\Phi} \colon \mathbb{R}^{d_1 \times d_2} \to \mathcal{H}^{d_1 + d_2}$$
$$\boldsymbol{X} \mapsto \left( \phi([\tilde{\boldsymbol{X}}]_{1:}), \dots, \phi([\tilde{\boldsymbol{X}}]_{d_1 + d_2:}) \right)$$

where  $\phi$  is induced by kernel  $K: \mathbb{R}^{(d_1+d_2)\times(d_1+d_2)} \times \mathbb{R}^{(d_1+d_2)\times(d_1+d_2)} \to \mathbb{R}$ . Since all entries of  $\Phi_r(\boldsymbol{X})$  are corresponding to  $[\tilde{\Phi}(\boldsymbol{X})]_{1:d_1}$  and  $\Phi_c(\boldsymbol{X})$  to  $[\tilde{\Phi}(\tilde{\boldsymbol{X}})]_{d_1+1:d_1+d_2}$ , we have an equivalent representation of (1)

$$f(X) = \langle B, \Phi(X) \rangle$$

$$= \langle \boldsymbol{B}_r, \Phi_r(\boldsymbol{X}) \rangle + \langle \boldsymbol{B}_c, \Phi_c(\boldsymbol{X}) \rangle$$

$$= \langle \tilde{\boldsymbol{B}}_r, [\tilde{\Phi}(\boldsymbol{X})]_{1:d_1} \rangle + \langle \tilde{\boldsymbol{B}}_c, [\tilde{\Phi}(\boldsymbol{X})]_{d_1+1:d_1+d_2} \rangle, \text{ where } \tilde{\boldsymbol{B}}_r \in \mathcal{H}^{d_1}, \tilde{\boldsymbol{B}}_c \in \mathcal{H}^{d_2}$$

$$= \langle \tilde{\boldsymbol{B}}, \tilde{\Phi}(\boldsymbol{X}) \rangle, \text{ where } \tilde{\boldsymbol{B}} = (\tilde{\boldsymbol{B}}_r, \tilde{\boldsymbol{B}}_c) \in \mathcal{H}^{d_1+d_2}.$$

Assume that  $\tilde{\boldsymbol{B}} = \tilde{\boldsymbol{C}}\tilde{\boldsymbol{P}}^T$  where  $\tilde{\boldsymbol{C}} \in \mathcal{H}^r$ ,  $\tilde{\boldsymbol{P}} = (\tilde{\boldsymbol{P}}_r, \tilde{\boldsymbol{P}}_c) \in \mathbb{R}^{(d_1+d_2)\times r}$  and  $\tilde{\boldsymbol{P}}_r \in \mathbb{R}^{d_1\times r}, \tilde{\boldsymbol{P}}_c \in \mathbb{R}^{d_2\times r}$ . Let  $\Pi_r, \Pi_c$  are permutation operators such that

$$\operatorname{Proj}_{\mathcal{H}_r} \left( \Pi_r [\tilde{\Phi}(\boldsymbol{X})]_{1:d_1} \right) = \Phi_r(\boldsymbol{X})$$
$$\operatorname{Proj}_{\mathcal{H}_c} \left( \Pi_c [\tilde{\Phi}(\boldsymbol{X})]_{d_1+1:d_1+d_2} \right) = \Phi_c(\boldsymbol{X}).$$

Here, we denote  $\operatorname{Proj}_{\mathcal{H}_c} \colon \mathcal{H} \to \mathcal{H}_r$  and  $\operatorname{Proj}_{\mathcal{H}_r} \colon \mathcal{H} \to \mathcal{H}_c$  as entry-wise projection mappings. Then the following holds

$$\begin{split} \langle \tilde{\boldsymbol{B}}, \tilde{\boldsymbol{\Phi}}(\boldsymbol{X}) \rangle &= \langle \tilde{\boldsymbol{C}}(\tilde{\boldsymbol{P}}_r, \tilde{\boldsymbol{P}}_c)^T, \tilde{\boldsymbol{\Phi}}(\boldsymbol{X}) \rangle \\ &= \langle \tilde{\boldsymbol{C}}\tilde{\boldsymbol{P}}_r^T, [\tilde{\boldsymbol{\Phi}}(\boldsymbol{X})]_{1:d_1} \rangle + \langle \tilde{\boldsymbol{C}}\tilde{\boldsymbol{P}}_C^T, [\tilde{\boldsymbol{\Phi}}(\boldsymbol{X})]_{d_1+1:d_1+d_2} \rangle \\ &= \langle \Pi_r \tilde{\boldsymbol{C}}\tilde{\boldsymbol{P}}_r^T, \Pi_r [\tilde{\boldsymbol{\Phi}}(\boldsymbol{X})]_{1:d_1} \rangle + \langle \Pi_c \tilde{\boldsymbol{C}}\tilde{\boldsymbol{P}}_c^T, \Pi_c [\tilde{\boldsymbol{\Phi}}(\boldsymbol{X})]_{d_1+1:d_1+d_2} \rangle \\ &= \langle \tilde{\boldsymbol{C}}_r \tilde{\boldsymbol{P}}_r^T, \boldsymbol{\Phi}_r(\boldsymbol{X}) \rangle + \langle \tilde{\boldsymbol{C}}_c \tilde{\boldsymbol{P}}_c^T, \boldsymbol{\Phi}_c(\boldsymbol{X}) \rangle, \end{split}$$

where  $\tilde{C}_r = \operatorname{Proj}_{\mathcal{H}_r}(\Pi_r \tilde{C})$  and  $\tilde{C}_c = \operatorname{Proj}_{\mathcal{H}_c}(\Pi_c \tilde{C})$ . Therefore, we can conclude that the low rankness of the coefficient on the feature image of  $\tilde{\Phi}(X)$  implies the same low rankness of the coefficient of the feature image of  $\Phi(X)$ . The other direction is also true.