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# THE PROOF OF THEOREM 1 IN REBUTTAL LETTER

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## 1 Notations

$\mathbf{c}^{(k)} \in \mathbb{R}^{d_k}$ : unknown mode-k cluster membership vector with element  $c_{i_k}^{(k)}$  refers to the true label of  $i_k$ th fiber in mode  $k$ ,  $\forall k \in [K]$ ,  $i_k \in [d_k]$ ;

$\hat{\mathbf{c}}^{(k)} \in \mathbb{R}^{d_k}$ : mode-k cluster assignment vector with element  $\hat{c}_{i_k}^{(k)}$  refers to the assigned label of  $i_k$ th fiber in mode  $k$ ,  $\forall k \in [K]$ ,  $i_k \in [d_k]$ ;

$\mathbf{p}^{(k)} \in \mathbb{R}^{R_k}$ : mode-k cluster proportion vector with element  $p_{r_k}^{(k)} = \frac{\sum_{i_k=1}^{d_k} \mathbb{I}\{c_{i_k}^{(k)} = r_k\}}{d_k}$ ,  $\forall k \in [K]$ ,  $r_k \in [R_k]$ ;

$\hat{\mathbf{p}}^{(k)} \in \mathbb{R}^{R_k}$ : mode-k label proportion vector with element  $\hat{p}_{r_k}^{(k)} = \frac{\sum_{i_k=1}^{d_k} \mathbb{I}\{\hat{c}_{i_k}^{(k)} = r_k\}}{d_k}$ , can be seen as a function of  $\hat{\mathbf{c}}^{(k)}$ ,  $\forall k \in [K]$ ,  $r_k \in [R_k]$ ;

$\mathbf{D}^{(k)} = [D_{a_k r_k}^{(k)}] \in \mathbb{R}^{R_k \times R_k}$ : mode-k confusion matrix with element  $D_{r_k, r'_k}^{(k)} = \frac{1}{d_k} \sum_{i_k=1}^{d_k} \mathbb{I}\{c_{i_k}^{(k)} = r_k, \hat{c}_{i_k}^{(k)} = r'_k\}$ , can be seen as a function of  $(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})$ ,  $\forall k \in [K]$ ,  $r_k \in [R_k]$ ;

$\mathcal{J}_\tau = \{(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) : \hat{p}_{r_1}^{(1)}(\hat{\mathbf{c}}^{(1)}) > \tau, \dots, \hat{p}_{r_K}^{(K)}(\hat{\mathbf{c}}^{(K)}) > \tau, r_k \in [R_k], k \in [K]\}$ ;

$\mathcal{I}_d \subset 2^{[d_1]} \times \dots \times 2^{[d_K]}$ : is the set of all the blocks that satisfy that  $p_{i_k}^{(k)} > \tau$ ,  $\forall i_k \in [d_k]$ ,  $\forall k \in [K]$ ;

$L_d = \inf\{|I| : I \in \mathcal{I}_d\}$ ;

$\|\mathbf{A}\|_\infty = \max_{r_1, \dots, r_K} |\mathbf{A}_{r_1, \dots, r_K}|$  for any tensor  $\mathbf{A} \in \mathbb{R}^{R_1 \times \dots \times R_K}$ .

*Remark.* 1.  $\mathbf{D}^{(k)} \mathbf{1} = \mathbf{p}^{(k)}$ ,  $\mathbf{D}^{(k)T} \mathbf{1} = \hat{\mathbf{p}}^{(k)}$ . If  $\mathbf{D}^{(k)}$  is diagonal, then the assigned labels match the true cluster in mode  $k$ ,  $\forall k \in [K]$ .

2. Because our model satisfies the irreducible core assumption, there is always exists a  $\tau$  such that our estimator  $(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) \in \mathcal{J}_\tau$ . We denote it as marginal assumption in this proof.

## 2 Definition

$$\text{CER}(\mathbf{M}_k, \mathbf{M}'_k) = \frac{1}{d_k} \sum_{i \in [d_k]} \mathbb{I}\{\mathbf{M}_k(i) \neq \mathbf{M}'_k(i)\}$$

$$\text{MCR}(\mathbf{M}_k, \mathbf{M}'_k) = \max_{r_k \in [R_k], a_k \neq a'_k \in [R_k]} \min\{D_{a_k r_k}^{(k)}, D_{a'_k r_k}^{(k)}\}$$

*Remark.* By the definition of MCR and the marginal assumption, obviously, when  $\text{MCR}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, \text{true}})$  is small enough, the  $\text{CER}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, \text{true}})$  would be very small, too.

### 3 Introduction

**Theorem 3.1.** Consider a sub-Gaussian tensor block model with variance parameter  $\sigma^2$  and non-degenerate clusterings,  $\delta_{min} = \min\{\min_{r_1 \neq r'_1} \max_{r_2, \dots, r_K} (c_{r_1, \dots, r_K} - c_{r'_1, \dots, r_K})^2, \dots, \min_{r_K \neq r'_K} \max_{r_1, \dots, r_{K-1}} (c_{r_1, \dots, r_K} - c_{r_1, \dots, r'_K})^2\}$ ,  $\exists k \in [K]$ ,

$$\mathbb{P}(\text{MCR}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, true}) \geq \varepsilon) \leq 2^{1+\sum_{k=1}^K d_k} \exp\left(-\frac{C_2 \varepsilon^2 \delta_{min}^2 \prod_{k=1}^K d_k}{\sigma^2}\right)$$

To prove the theorem, considering our least-square estimator

$$\begin{aligned} \hat{\Theta} &= \underset{\Theta \in \mathcal{P}}{\text{argmin}} \{-2 \langle \mathcal{Y}, \Theta \rangle + \|\Theta\|_F^2\} \\ &= \underset{\Theta \in \mathcal{P}}{\text{argmax}} \{\langle \mathcal{Y}, \Theta \rangle - \frac{\|\Theta\|_F^2}{2}\} \end{aligned}$$

the  $\langle \mathcal{Y}, \Theta \rangle - \frac{\|\Theta\|_F^2}{2}$  is the log-likelihood of the data tensor when our model is a Gaussian tensor block model.

Then the profile log-likelihood  $F(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})$  satisfies

$$\begin{aligned} F(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) &= \sup_{\Theta \in \mathcal{P}} \{\langle \mathcal{Y}, \Theta \rangle - \frac{\|\Theta\|_F^2}{2}\} \\ &= \sup_{\Theta \in \mathcal{P}} \left\{ \sum_{i_1, \dots, i_K} y_{i_1, \dots, i_K} c_{r_1(i_1), \dots, r_K(i_K)} - \frac{1}{2} \sum_{i_1, \dots, i_K} c_{r_1(i_1), \dots, r_K(i_K)}^2 \right\} \\ &= \frac{1}{2} \sum_{i_1, \dots, i_K} \overline{y_{r_1(i_1), \dots, r_K(i_K)}}^2 \\ &= \sum_{r_1, \dots, r_K} \prod_{k=1}^K \hat{p}_{r_k}^{(k)} f(\overline{y_{r_1(i_1), \dots, r_K(i_K)}}) \end{aligned}$$

where  $f(x) = \frac{x^2}{2}$ . Thus our clustering estimator can be represented as

$$(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) = \underset{(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) \in \mathcal{J}_\tau}{\text{argmax}} F(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) \quad (1)$$

The error  $\|\hat{\Theta} - \Theta\|_F^2$  comes from two aspects: noise and clustering. To measure the error which is from noise, we define a new function  $G(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})$ :

$$G(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) = \sum_{r_1, \dots, r_K} [\mathbf{D}^{(1)T} \mathbf{1}]_{r_1} \cdots [\mathbf{D}^{(K)T} \mathbf{1}]_{r_K} f(E_{r_1, \dots, r_K})$$

where  $\mathbf{E}(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) = [E(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})_{r_1, \dots, r_K}] \in \mathbb{R}^{R_1 \times R_2 \times \cdots \times R_K}$ ,

$$E(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})_{r_1, \dots, r_K} = \frac{\sum_{i_1, \dots, i_K} \sum_{j_1, \dots, j_K} c_{j_1, \dots, j_K} \mathbb{I}\{c_{i_1}^{(1)} = j_1, \hat{c}_{i_1}^{(1)} = r_1\} \cdots \mathbb{I}\{c_{i_K}^{(K)} = j_K, \hat{c}_{i_K}^{(K)} = r_K\}}{\sum_{i_1, \dots, i_K} \mathbb{I}\{\hat{c}_{i_1}^{(1)} = r_1, \dots, \hat{c}_{i_K}^{(K)} = r_K\}}$$

is the average value of  $E y_{i_1, \dots, i_K}$  over the block defined by labels  $r_1, \dots, r_K$ . Additionally, we define normalized residual matrix  $\mathbf{R}(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) = [\mathbf{R}(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})_{r_1, \dots, r_K}] \in \mathbb{R}^{R_1 \times \cdots \times R_K}$ :

$$\mathbf{R}(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})_{r_1, \dots, r_K} = \overline{Y_{r_1, \dots, r_K}} - E(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})_{r_1, \dots, r_K}$$

### 4 Proof

We use  $G(\mathbf{D}^{(1)}, \dots, \mathbf{D}^{(K)}) - \sum_{r_1, \dots, r_K} p_{r_1}^{(1)} \cdots p_{r_K}^{(K)} f(c_{r_1, \dots, r_K})$  to measure the loss. Under the condition of

$\text{MCR}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, true}) \geq \varepsilon$  for all  $k \in [K]$ , we can turn our goal into find the upper bound for the total loss. The following lemma gives the rigorous proof.

**Lemma 4.1.** For all  $\tau > 0$ , for  $(\hat{c}^{(1)}, \dots, \hat{c}^{(K)}) \in \mathcal{J}_\tau$  and  $\text{MCR}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, \text{true}}) \geq \varepsilon$ ,  $\exists k \in [K]$ ,

$$G(\mathbf{D}^{(1)}, \dots, \mathbf{D}^{(K)}) - \sum_{r_1, \dots, r_K} p_{r_1}^{(1)} \cdots p_{r_K}^{(K)} f(c_{r_1, \dots, r_K}) \leq -\frac{\varepsilon \tau^{K-1} \delta_{\min}}{4}$$

*Proof.* If  $\text{MCR}(\hat{\mathbf{M}}_1, \mathbf{P}_1 \mathbf{M}_{1, \text{true}}) \geq \varepsilon$ , then for some  $r_1$  and some  $a_1 \neq a'_1$ ,  $\min\{D_{a_1 r_1}^{(1)}, D_{a'_1 r_1}^{(1)}\} \geq \varepsilon$ . Since the core tensor is irreducible according to our basic assumption in paper, there exist  $a_2, \dots, a_K$  such that  $c_{a_1, \dots, a_K} \neq c_{a'_1, \dots, a_K}$ . Select the  $a_2, \dots, a_K$  such that  $(c_{a_1, \dots, a_K} - c_{a'_1, \dots, a_K})^2 = \min_{a_1 \neq a'_1} \max_{a_2, \dots, a_K} (c_{a_1, \dots, a_K} - c_{a'_1, \dots, a_K})^2$ . Let  $W = [\mathbf{D}^{(1)^T} \mathbf{1}]_{r_1} \cdots [\mathbf{D}^{(K)^T} \mathbf{1}]_{r_K}$ , this is nonzero according to the selection of  $r_1, \dots, r_K$ . Now, there exists  $c_* \in \mathbb{R}$  such that

$$\begin{aligned} [\mathcal{N} \times_1 \mathbf{D}^{(1)^T} \times_2 \cdots \times_K \mathbf{D}^{(K)^T}]_{r_1, \dots, r_K} &= D_{a_1 r_1}^{(1)} \cdots D_{a_K r_K}^{(K)} f(c_{a_1, \dots, a_K}) + D_{a'_1 r_1}^{(1)} \cdots D_{a_K r_K}^{(K)} f(c_{a'_1, \dots, a_K}) \\ &\quad + (W - D_{a_1 r_1}^{(1)} \cdots D_{a_K r_K}^{(K)} - D_{a'_1 r_1}^{(1)} \cdots D_{a_K r_K}^{(K)}) f(c_*) \end{aligned} \quad (2)$$

Here  $\mathcal{N} = [f(c_{a_1, \dots, a_K})] \in \mathbb{R}^{R_1 \times \cdots \times R_K}$  is the loss function evaluated at each block where  $[\mathcal{N} \times_1 \mathbf{D}^{(1)^T} \times_2 \cdots \times_K \mathbf{D}^{(K)^T}]_{r_1, \dots, r_K}$  is the weighted value of the loss function. Let  $z = \frac{[\mathcal{N} \times_1 \mathbf{D}^{(1)^T} \times_2 \cdots \times_K \mathbf{D}^{(K)^T}]_{r_1, \dots, r_K}}{W}$  where  $z_{r_1, \dots, r_K}$  is the  $(r_1, \dots, r_K)$ -th weighted entry of the block means. By Taylor expansion and basic inequality  $\frac{a+b}{2} \leq \sqrt{\frac{a^2+b^2}{2}}$ ,

$$\begin{aligned} &\frac{[\mathcal{N} \times_1 \mathbf{D}^{(1)^T} \times_2 \cdots \times_K \mathbf{D}^{(K)^T}]_{r_1, \dots, r_K}}{W} - f(z) \\ &\geq \frac{\min\{D_{a_1 r_1}^{(1)}, D_{a'_1 r_1}^{(1)}\} D_{a_2 r_2}^{(2)} \cdots D_{a_K r_K}^{(K)}}{4W} (c_{a_1, \dots, a_K} - c_{a'_1, \dots, a_K})^2 \\ &\geq \frac{\varepsilon D_{a_2 r_2}^{(2)} \cdots D_{a_K r_K}^{(K)}}{4W} (c_{a_1, \dots, a_K} - c_{a'_1, \dots, a_K})^2 \end{aligned} \quad (3)$$

Note the inequality (3) only holds for a certain  $r_1 \in [R_1]$ , for any other  $r'_1 \in [R_1] \in [R_1]/r_1$ , by Jensen's inequality we have

$$\frac{[\mathcal{N} \times_1 \mathbf{D}^{(1)^T} \times_2 \cdots \times_K \mathbf{D}^{(K)^T}]_{r_1, \dots, r_K}}{W} - f(z) \geq 0 \quad (4)$$

With  $\sum_{r_k=1}^{R_k} D_{a_k r_k}^{(k)} = \hat{p}_{a_k}^{(k)} \geq \tau$ , combining the sum of (3) over  $(r_2, \dots, r_K)$  and (4) gives

$$\begin{aligned} &G(\mathbf{D}^{(1)}(\hat{c}^{(1)}), \dots, \mathbf{D}^{(K)}(\hat{c}^{(K)})) - \sum_{r_1, \dots, r_K} \prod_{k=1}^K p_{r_k}^{(k)} f(c_{r_1, \dots, r_K}) \\ &= \sum_{r_1, \dots, r_K} [\mathbf{D}^{(1)^T} \mathbf{1}]_{r_1} \cdots [\mathbf{D}^{(K)^T} \mathbf{1}]_{r_K} f\left(\frac{[\mathcal{N} \times_1 \mathbf{D}^{(1)^T} \times_2 \cdots \times_K \mathbf{D}^{(K)^T}]_{r_1, \dots, r_K}}{[\mathbf{D}^{(1)^T} \mathbf{1}]_{r_1} \cdots [\mathbf{D}^{(K)^T} \mathbf{1}]_{r_K}}\right) \\ &\leq -\varepsilon \sum_{r_2, \dots, r_K} \frac{D_{a_2 r_2}^{(2)} \cdots D_{a_K r_K}^{(K)}}{4} (c_{a_1, \dots, a_K} - c_{a'_1, \dots, a_K})^2 \\ &\leq -\frac{\varepsilon \tau^{K-1} \delta_{\min}}{4} \end{aligned}$$

Similarly, the proof also goes through if  $\text{MCR}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, \text{true}}) \geq \varepsilon$ ,  $k \in [K]$ . □

By lemma 4.1, we obtained

$$\begin{aligned}
& \mathbb{P}\left(\text{MCR}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, \text{true}}) \geq \varepsilon\right) \\
& \leq \mathbb{P}\left(G(\mathbf{D}^{(1)}, \dots, \mathbf{D}^{(K)}) - \sum_{r_1, \dots, r_K} p_{r_1}^{(1)} \cdots p_{r_K}^{(K)} f(c_{r_1, \dots, r_K}) \leq -\frac{\varepsilon \tau^{K-1} \delta_{\min}}{4}\right) \\
& = \mathbb{P}\left(G(\mathbf{D}^{(1)}(\hat{\mathbf{c}}^{(1)}), \dots, \mathbf{D}^{(K)}(\hat{\mathbf{c}}^{(K)})) - F(\mathbf{c}^{(1)}, \dots, \mathbf{c}^{(K)}) \leq -\frac{\varepsilon \tau^{K-1} \delta_{\min}}{4}\right)
\end{aligned} \tag{5}$$

Additionally, letting  $r_d = \sup_{\mathcal{J}_\tau} |F(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) - G(\mathbf{D}^{(1)}(\hat{\mathbf{c}}^{(1)}), \dots, \mathbf{D}^{(K)}(\hat{\mathbf{c}}^{(K)}))|$  which refers to the loss caused only by noise, when  $G(\mathbf{D}^{(1)}(\hat{\mathbf{c}}^{(1)}), \dots, \mathbf{D}^{(K)}(\hat{\mathbf{c}}^{(K)})) - F(\mathbf{c}^{(1)}, \dots, \mathbf{c}^{(K)}) \leq -\frac{\varepsilon \tau^{K-1} \delta_{\min}}{4}$ , we have

$$F(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) - F(\mathbf{c}^{(1)}, \dots, \mathbf{c}^{(K)}) \leq 2r_d - \frac{\varepsilon \tau^{K-1} \delta_{\min}}{4} \tag{6}$$

Plug the inequality (6) back into inequality (5), we obtain

$$\begin{aligned}
& \mathbb{P}\left(\text{MCR}(\hat{\mathbf{M}}_k, \mathbf{P}_k \mathbf{M}_{k, \text{true}}) \geq \varepsilon\right) \\
& \leq \mathbb{P}\left(F(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) - F(\mathbf{c}^{(1)}, \dots, \mathbf{c}^{(K)}) \leq 2r_d - \frac{\varepsilon \tau^{K-1} \delta_{\min}}{4}\right) \\
& \leq \mathbb{P}\left(r_d \geq \frac{\varepsilon \tau^{K-1} \delta_{\min}}{8}\right)
\end{aligned} \tag{7}$$

Now we convert our problem into find the upper bound of  $\mathbb{P}\left(r_d \geq \frac{\varepsilon \tau^{K-1} \delta_{\min}}{8}\right)$ . Consider  $\mathbb{P}(r_d \leq t)$ , because  $f$  is locally lipschitz continuous with lipschitz constant  $c = \sup |f'(\mu)|$  for  $\mu$  in a neighborhood of the convex hull of the entries of  $\mathcal{C}$ ,

$$\begin{aligned}
& |F(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)}) - G(\mathbf{D}^{(1)}(\hat{\mathbf{c}}^{(1)}), \dots, \mathbf{D}^{(K)}(\hat{\mathbf{c}}^{(K)}))| \\
& \leq \sum_{r_1, \dots, r_K} \hat{p}_{r_1}^{(1)} \hat{p}_{r_2}^{(2)} \cdots \hat{p}_{r_K}^{(K)} |f(\overline{Y_{r_1, \dots, r_K}}) - f(E_{r_1, \dots, r_K})| \\
& \leq c \|\mathbf{R}(\hat{\mathbf{c}}^{(1)}, \dots, \hat{\mathbf{c}}^{(K)})\|_\infty
\end{aligned} \tag{8}$$

Combining (7), (8), Hoeffding's inequality,  $L_d \geq \tau^K \prod_{k=1}^K d_k$  and  $C_2 = \frac{\tau^{3K-2}}{128c^2}$  yields the desired conclusion.

## References

[1] Cheryl J. Flynn and Patrick O. Perry. Consistent Bicustering. arXiv:1206.6927v3 [stat:ME]