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1 Notations

 $c^{(k)} \in \mathbb{R}^{d_k}$: unknown mode-k cluster membership vector with element $c^{(k)}_{i_k}$ refers to the true label of i_k th fiber in mode k, $\forall k \in [K], \ i_k \in [d_k]$;

 $\hat{c}^{(k)} \in \mathbb{R}^{d_k}$: mode-k cluster assignment vector with element $\hat{c}^{(k)}_{i_k}$ refers to the assigned label of i_k th fiber in mode k, $\forall k \in [K], \ i_k \in [d_k];$

 $\boldsymbol{p}^{(k)} \in \mathbb{R}^{R_k} \text{: mode-k cluster proportion vector with element } p_{r_k}^{(k)} = \frac{\sum_{i_k=1}^{d_k} \mathbb{I}\{c_{i_k}^{(k)} = r_k\}}{d_k}, \forall k \in [K], \ r_k \in [R_k];$

 $\hat{\boldsymbol{p}}^{(k)} \in \mathbb{R}^{R_k}$: mode-k label proportion vector with element $\hat{p}_{r_k}^{(k)} = \frac{\sum_{i_k=1}^{d_k} \mathbb{I}\{\hat{c}_{i_k}^{(k)} = r_k\}}{d_k}$, can be seen as a function of $\hat{\boldsymbol{c}}^{(k)}$, $\forall k \in [K], \ r_k \in [R_k]$;

 $m{D}^{(k)} \in \mathbb{R}^{R_k imes R_k}$: mode-k confusion matrix with element $D^{(k)}_{r_k,r_k'} = \frac{1}{d_k} \sum_{i_k=1}^{d_k} \mathbb{I}\{c^{(k)}_{i_k} = r_k, \hat{c}^{(k)}_{i_k} = r_k'\}$, can be seen as a function of $(\hat{m{c}}^{(1)},...,\hat{m{c}}^{(K)})$, $\forall k \in [K], \ r_k \in [R_k]$;

$$\mathcal{J}_{\tau} = \{(\hat{\boldsymbol{c}}^{(1)}, ..., \hat{\boldsymbol{c}}^{(K)}) : \hat{p}_{r_1}^{(1)}(\hat{\boldsymbol{c}}^{(1)}) > \tau, ..., \hat{p}_{r_K}^{(K)}(\hat{\boldsymbol{c}}^{(K)}) > \tau, r_k \in [R_k], k \in [K]\};$$

 $\mathcal{I}_d \subset 2^{[d_1]} \times \cdots \times 2^{[d_K]}$: is the set of all the blocks that satisfy that $p_{i_k}^{(k)} > \tau$, $\forall i_k \in [d_k], \ \forall k \in [K]$;

 $L_d = \inf\{|I| : I \in \mathcal{I}_d\};$

 $||\pmb{A}||_{\infty} = \max_{r_1,\dots,r_K} |\pmb{A}_{r_1,\dots,r_K}|$ for any tensor $\pmb{A} \in \mathbb{R}^{R_1 \times \dots \times R_K}$.

Remark. 1. $\mathbf{D}^{(k)}\mathbf{1} = \mathbf{p}^{(k)}, \mathbf{D}^{(k)^T}\mathbf{1} = \hat{\mathbf{p}}^{(k)}$. If $\mathbf{D}^{(k)}$ is diagonal, then the assigned labels match the true cluster in mode $k, \forall k \in [K]$.

2. Because our model satisfies the irreducible core assumption, there is always exists a τ such that our estimator $(\hat{c}^{(1)},...,\hat{c}^{(K)}) \in \mathcal{J}_{\tau}$. We denote it as marginal assumption in this proof.

2 Definition

$$\mathbf{CER}(\boldsymbol{M}_k, \boldsymbol{M}_k') = \frac{1}{d_k} \sum_{i \in [d_k]} \mathbb{I}\{\boldsymbol{M}_k(i) \neq \boldsymbol{M}_k'(i)\}$$

$$\mathbf{MCR}(\boldsymbol{M}_k, \boldsymbol{M}_k') = \max_{r_k \in [R_k]} \min_{a_k \neq a_k' \in [R_k]} \{\boldsymbol{D}_{a_k r_k}^{(k)}, \boldsymbol{D}_{a_k' r_k}^{(k)}\}$$

Remark. By the definition of MCR and the marginal assumption, obviously, when $MCR(\hat{M}_k, P_k M_{k,true})$ is small enough, the $CER(\hat{M}_k, P_k M_{k,true})$ would be very small, too.

3 Introduction

Theorem 3.1. Consider a sub-Gaussian tensor block model with variance parameter σ^2 and non-degenerate clusterings, $\delta_{min} = \min\{\min_{r_1 \neq r'_1} \max_{r_2, \dots, r_K} (c_{r_1, \dots, r_K} - c_{r'_1, \dots, r_K})^2, \dots, \min_{r_K \neq r'_K} \max_{r_1, \dots, r_{K-1}} (c_{r_1, \dots, r_K} - c_{r_1, \dots, r'_K})^2\}, \ \exists k \in [K],$

$$\mathbb{P}(\mathbf{MCR}(\hat{\boldsymbol{M}}_k, \boldsymbol{P}_k \boldsymbol{M}_{k,true}) \ge \varepsilon) \le 2^{1 + \sum_{k=1}^{K} d_k} \exp\left(-\frac{C_2 \varepsilon^2 \delta_{min}^2 \prod_{k=1}^{K} d_k}{\sigma^2}\right)$$

To prove the theorem, considering our least-square estimator

$$\begin{split} \hat{\Theta} &= & \underset{\Theta \in \mathcal{P}}{\operatorname{argmin}} \{-2 < \mathcal{Y}, \Theta > + ||\Theta||_F^2 \} \\ &= & \underset{\Theta \in \mathcal{P}}{\operatorname{argmax}} \{ < \mathcal{Y}, \Theta > - \frac{||\Theta||_F^2}{2} \} \end{split}$$

the $<\mathcal{Y},\Theta>-\frac{||\Theta||_F^2}{2}$ is the log-likelihood of the data tensor when our model is a Gaussian tensor block model.

Then the profile log-likelihood $F(\hat{m{c}}^{(1)},...,\hat{m{c}}^{(K)})$ satisfies

$$\begin{split} F(\hat{c}^{(1)},...,\hat{c}^{(K)}) &= \sup_{\Theta \in \mathcal{P}} \{ <\mathcal{Y},\Theta > -\frac{||\Theta||_F^2}{2} \} \\ &= \sup_{\Theta \in \mathcal{P}} \{ \sum_{i_1,...,i_K} y_{i_1,...,i_K} c_{r_1(i_1),...,r_K(i_K)} - \frac{1}{2} \sum_{i_1,...,i_K} c_{r_1(i_1),...,r_K(i_K)} \} \\ &= \sup_{\Theta \in \mathcal{P}} \{ \sum_{i_1,...,i_K} \overline{y_{r_1(i_1),...,r_K(i_K)}} c_{r_1(i_1),...,r_K(i_K)} - \frac{1}{2} \sum_{i_1,...,i_K} c_{r_1(i_1),...,r_K(i_K)}^2 \} \\ &= \sum_{i_1,...,i_K} \overline{y_{r_1(i_1),...,r_K(i_K)}}^2 - \frac{1}{2} \sum_{i_1,...,i_K} \overline{y_{r_1(i_1),...,r_K(i_K)}}^2 \\ &= \frac{1}{2} \sum_{i_1,...,i_K} \prod_{k=1}^K \hat{p}_{r_k}^{(k)} \overline{y_{r_1(i_1),...,r_K(i_K)}}^2 \\ &= \sum_{r_1,...,r_K} \prod_{k=1}^K \hat{p}_{r_k}^{(k)} \overline{y_{r_1(i_1),...,r_K(i_K)}} \end{split}$$

where $f(x) = \frac{x^2}{2}$. Thus our clustering estimator can be represented as

$$(\widehat{\hat{\boldsymbol{c}}^{(1)}}, ..., \widehat{\boldsymbol{c}}^{(K)}) = \underset{(\widehat{\boldsymbol{c}}^{(1)}, ..., \widehat{\boldsymbol{c}}^{(K)}) \in \mathcal{J}_{\tau}}{\operatorname{argmax}} F(\widehat{\boldsymbol{c}}^{(1)}, ..., \widehat{\boldsymbol{c}}^{(K)})$$
(1)

The error $||\hat{\Theta} - \Theta||_F^2$ comes from two aspects: noise and clustering. To measure the error which is from noise, we define a new function $G(\hat{c}^{(1)},...,\hat{c}^{(K)})$:

$$G(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)}) = \sum_{r_1,...,r_K} [\boldsymbol{D}^{(1)^T} \mathbf{1}]_{r_1} \cdots [\boldsymbol{D}^{(K)^T} \mathbf{1}]_{r_K} f(E_{r_1,...,r_K})$$

where $m{E}(m{\hat{c}^{(1)}},...,m{\hat{c}^{(K)}}) \in \mathbb{R}^{R_1 imes R_2 imes \cdots R_K}$,

$$E(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)})_{r_1,...,r_K} = \frac{\sum\limits_{i_1,...,i_K}\sum\limits_{j_1,...,j_K} c_{j_1,...,j_K} \mathbb{I}\{c_{i_1}^{(1)} = j_1,\hat{c}_{i_1}^{(1)} = r_1\} \cdots \mathbb{I}\{c_{i_K}^{(K)} = j_K,\hat{c}_{i_K}^{(K)} = r_K\}}{\sum_{i_1,...,i_K} \mathbb{I}\{\hat{c}_{i_1}^{(1)} = r_1,...,\hat{c}_{i_K}^{(K)} = r_K\}}$$

is the average value of $Ey_{i_1,...,i_K}$ over the block defined by labels $r_1,...,r_K$. Additionally, we define normalized residual matrix $\mathbf{R}(\hat{\mathbf{c}}^{(1)},...,\hat{\mathbf{c}}^{(K)}) \in \mathbb{R}^{R_1 \times \cdots \times R_K}$:

$$R(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)})_{r_1,...,r_K} = \overline{Y_{r_1,...,r_K}} - E(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)})_{r_1,...,r_K}$$

4 Proof

Under the condition of $\mathbf{MCR}(\hat{\boldsymbol{M}}_k, \boldsymbol{P}_k \boldsymbol{M}_{k,true}) < \varepsilon$ for all $k \in [K]$, the most of the error comes from the noise but not clustering. Because the ε is arbitrary, when ε is very small, we can convert our goal into finding the upper bound of $\mathbb{P}(G(\boldsymbol{D}^{(1)},...,\boldsymbol{D}^{(K)}) - \sum_{r_1,...,r_K} p_{r_1}^{(1)} \cdots p_{r_K}^{(K)} f(c_{r_1,...,r_K}) \le h(\varepsilon))$ where $h(\varepsilon)$ is a function of ε . Here is rigorous proof:

Lemma 4.1. For all $\tau > 0$, for $(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)}) \in \mathcal{J}_{\tau}$ and $\mathbf{MCR}(\hat{\boldsymbol{M}}_k,\boldsymbol{P}_k\boldsymbol{M}_{k,true}) \geq \varepsilon, \ \exists k \in [K]$,

$$G(\boldsymbol{D}^{(1)},...,\boldsymbol{D}^{(K)}) - \sum_{r_1,...,r_K} p_{r_1}^{(1)} \cdots p_{r_K}^{(K)} f(c_{r_1,...,r_K}) \le -\frac{\varepsilon \tau^{K-1} \delta_{min}}{4}$$

Proof. If $MCR(\hat{M}_1, P_1 M_{1,true}) \geq \varepsilon$, then for some r_1 and some $a_1 \neq a_1'$, $\min\{D_{a_1r_1}^{(1)}, D_{a_1'r_1}^{(1)}\} \geq \varepsilon$. Since the core tensor is irreducible according to our basic assumption in paper, there exist $a_2, ..., a_K$ such that $c_{a_1,...,a_K} \neq c_{a_1',...,a_K}$. Select the $a_2,...,a_K$ such that $(c_{a_1,...,a_K} - c_{a_1',...,a_K})^2 = \min_{a_1 \neq a_1'} \max_{a_2,...,a_K} (c_{a_1,...,a_K} - c_{a_1',...,a_K})^2$. Let

 $W = [\mathbf{D}^{(1)^T} \mathbf{1}]_{r_1} \cdots [\mathbf{D}^{(K)^T} \mathbf{1}]_{r_K}$, this is nonzero according to the selection of $r_1, ..., r_K$. Now, there exists $c_* \in \mathbb{R}$ such that

$$[N \times_{1} \mathbf{D}^{(1)^{T}} \times_{2} \cdots \times_{K} \mathbf{D}^{(K)^{T}}]_{r_{1},...,r_{K}} = D_{a_{1}r_{1}}^{(1)} \cdots D_{a_{K}r_{K}}^{(K)} f(c_{a_{1},...,a_{K}}) + D_{a_{1}'r_{1}}^{(1)} \cdots D_{a_{K}r_{K}}^{(K)} f(c_{a_{1}',...,a_{K}}) + (W - D_{a_{1}r_{1}}^{(1)} \cdots D_{a_{K}r_{K}}^{(K)} - D_{a_{1}'r_{1}}^{(1)} \cdots D_{a_{K}r_{K}}^{(K)}) f(c_{*})$$

Let $z = \frac{\left[\mathcal{C} \times_1 \mathbf{D}^{(1)^T} \times_2 \dots \times_K \mathbf{D}^{(K)^T}\right]_{r_1,\dots,r_K}}{W}$ and define $N = \left[\nu_{a_1,\dots,a_K}\right] \in \mathbb{R}^{R_1 \times \dots \times R_K}$ with $\nu_{a_1,\dots,a_K} = f(c_{a_1,\dots,a_K})$, then,

$$\begin{split} &\frac{[N\times_{1}\boldsymbol{D}^{(1)^{T}}\times_{2}\cdots\times_{K}\boldsymbol{D}^{(K)^{T}}]_{r_{1},\dots,r_{K}}}{W}-f(z)\\ \geq &\frac{1}{2}[\frac{D_{a_{1}r_{1}}^{(1)}\cdots D_{a_{K}r_{K}}^{(K)}}{W}(c_{a_{1},\dots,a_{K}}-z)^{2}+\frac{D_{a_{1}'r_{1}}^{(1)}\cdots D_{a_{K}r_{K}}^{(K)}}{W}(c_{a_{1}'\cdots a_{K}}-z)^{2}\\ &+\frac{W-D_{a_{1}r_{1}}^{(1)}\cdots D_{a_{K}r_{K}}^{(K)}-D_{a_{1}'r_{1}}^{(1)}\cdots D_{a_{K}r_{K}}^{(K)}}{W}(c_{*}-z)^{2}]\left(Taylor\ Series\right)\\ \geq &\frac{\min\{D_{a_{1}r_{1}}^{(1)},D_{a_{1}'r_{1}}^{(1)}\}D_{a_{2}r_{2}}^{(2)}\cdots D_{a_{K}r_{K}}^{(K)}}{W}[\frac{1}{2}(c_{a_{1},\dots,a_{K}}-z)^{2}+\frac{1}{2}(z-c_{a_{1}',\dots,a_{K}})^{2}]\\ \geq &\frac{\min\{D_{a_{1}r_{1}}^{(1)},D_{a_{1}'r_{1}}^{(1)}\}D_{a_{2}r_{2}}^{(2)}\cdots D_{a_{K}r_{K}}^{(K)}}{4W}(c_{a_{1},\dots,a_{K}}-c_{a_{1}',\dots,a_{K}})^{2}\left(Basic\ Inequality\right) \end{split}$$

Thus,

$$[\boldsymbol{D}^{(1)^{T}}\mathbf{1}]_{r_{1}}\cdots[\boldsymbol{D}^{(K)^{T}}\mathbf{1}]_{r_{K}}f(\frac{[\mathcal{C}\times_{1}\boldsymbol{D}^{(1)^{T}}\times_{2}\cdots\times_{K}\boldsymbol{D}^{(K)^{T}}]_{r_{1},\dots,r_{K}}}{[\boldsymbol{D}^{(1)^{T}}\mathbf{1}]_{r_{1}}\cdots[\boldsymbol{D}^{(K)^{T}}\mathbf{1}]_{r_{K}}})$$

$$-[N\times_{1}\boldsymbol{D}^{(1)^{T}}\times_{2}\cdots\times_{K}\boldsymbol{D}^{(K)^{T}}]_{r_{1},\dots,r_{K}}$$

$$= Wf(z) - [N\times_{1}\boldsymbol{D}^{(1)^{T}}\times_{2}\cdots\times_{K}\boldsymbol{D}^{(K)^{T}}]_{r_{1},\dots,r_{K}}$$

$$\leq -\frac{\min\{D_{a_{1}r_{1}}^{(1)},D_{a_{1}'r_{1}}^{(1)}\}D_{a_{2}r_{2}}^{(2)}\cdots D_{a_{K}r_{K}}^{(K)}}{4}(c_{a_{1},\dots,a_{K}}-c_{a_{1}',\dots,a_{K}})^{2}$$

$$\leq -\frac{\varepsilon D_{a_{2}r_{2}}^{(2)}\cdots D_{a_{K}r_{K}}^{(K)}}{4}(c_{a_{1},\dots,a_{K}}-c_{a_{1}',\dots,a_{K}})^{2}$$

It follows that,

$$G(\boldsymbol{D}^{(1)}(\hat{\boldsymbol{c}}^{(1)}), ..., \boldsymbol{D}^{(K)}(\hat{\boldsymbol{c}}^{(K)})) - \sum_{r_1, ..., r_K} \prod_{k=1}^K p_{r_k}^{(k)} f(c_{r_1, ..., r_K})$$

$$= \sum_{r_1, ..., r_K} [\boldsymbol{D}^{(1)^T} \mathbf{1}]_{r_1} \cdots [\boldsymbol{D}^{(K)^T} \mathbf{1}]_{r_K} f(\frac{[\mathcal{C} \times_1 \boldsymbol{D}^{(1)^T} \times_2 \cdots \times_K \boldsymbol{D}^{(K)^T}]_{r_1, ..., r_K}}{[\boldsymbol{D}^{(1)^T} \mathbf{1}]_{r_1} \cdots [\boldsymbol{D}^{(K)^T} \mathbf{1}]_{r_K}})$$

$$- \sum_{r_1, ..., r_K} [N \times_1 \boldsymbol{D}^{(1)^T} \times_2 \cdots \times_K \boldsymbol{D}^{(K)^T}]_{r_1, ..., r_K}$$

$$\leq -\varepsilon \sum_{r_2, ..., r_K} \frac{D_{a_2 r_2}^{(2)} \cdots D_{a_K r_K}^{(K)}}{4} (c_{a_1, ..., a_K} - c_{a_1', ..., a_K})^2$$

$$\leq -\frac{\varepsilon \tau^{K-1} \delta_{min}}{4} \left(because \sum_{r_k=1}^{R_k} D_{a_k r_k}^{(k)} = \hat{p}_{a_k}^{(k)} \geq \tau \right)$$

Similarly, if $\mathbf{MCR}(\hat{M}_k, P_k M_{k,true}) \geq \varepsilon$, $k \in [K]$, then the left hand side would be bounded by $-\frac{\varepsilon \tau^{2(K-1)}}{4\prod_{k=2}^K R_k^2} (c_{a_1,\dots,a_K} - c_{a_1',\dots,a_K})^2$. Thus,

$$G(\mathbf{D}^{(1)},...,\mathbf{D}^{(K)}) - \sum_{r_1,...,r_K} p_{r_1}^{(1)} \cdots p_{r_K}^{(K)} f(c_{r_1,...,r_K}) \le -\frac{\varepsilon \tau^{K-1} \delta_{min}}{4}$$

By lemma 4.1, we obtained

$$\begin{split} & & \mathbb{P}\left(\mathbf{MCR}(\hat{\boldsymbol{M}}_k, \boldsymbol{P}_k \boldsymbol{M}_{k,true}) \geq \varepsilon\right) \\ \leq & & \mathbb{P}\left(G(\boldsymbol{D}^{(1)}, ..., \boldsymbol{D}^{(K)}) - \sum_{r_1, ..., r_K} p_{r_1}^{(1)} \cdot \cdot \cdot p_{r_K}^{(K)} f(\boldsymbol{c}_{r_1, ..., r_K}) \leq -\frac{\varepsilon \tau^{K-1} \delta_{min}}{4}\right) \\ = & & \mathbb{P}\left(G(\boldsymbol{D}^{(1)}(\widehat{\boldsymbol{c}^{(1)}}), ..., \boldsymbol{D}^{(K)}(\widehat{\boldsymbol{c}^{(K)}})) - F(\boldsymbol{c}^{(1)}, ..., \boldsymbol{c}^{(K)}) \leq -\frac{\varepsilon \tau^{K-1} \delta_{min}}{4}\right) \end{split}$$

Additionally, we let $r_d = \sup_{\mathcal{I}_{\tau}} |F(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)}) - G(\boldsymbol{D}^{(1)}(\hat{\boldsymbol{c}}^{(1)}),...,\boldsymbol{D}^{(K)}(\hat{\boldsymbol{c}}^{(K)}))|,$

$$F(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)}) - F(\boldsymbol{c}^{(1)},...,\boldsymbol{c}^{(K)})$$

$$\leq |F(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)}) - G(\boldsymbol{D}^{(1)}(\hat{\boldsymbol{c}}^{(1)}),...,\boldsymbol{D}^{(K)}(\hat{\boldsymbol{c}}^{(K)}))|$$

$$+|F(\boldsymbol{c}^{(1)},...,\boldsymbol{c}^{(K)}) - G(\boldsymbol{D}^{(1)}(\boldsymbol{c}^{(1)}),...,\boldsymbol{D}^{(K)}(\boldsymbol{c}^{(K)}))|$$

$$+[G(\boldsymbol{D}^{(1)}(\hat{\boldsymbol{c}}^{(1)}),...,\boldsymbol{D}^{(K)}(\hat{\boldsymbol{c}}^{(K)})) - G(\boldsymbol{D}^{(1)}(\boldsymbol{c}^{(1)}),...,\boldsymbol{D}^{(K)}(\boldsymbol{c}^{(K)}))]$$

$$\leq 2r_d - \frac{\varepsilon\tau^{K-1}\delta_{min}}{4}$$

Thus,

$$\begin{split} & \mathbb{P}\left(\mathbf{MCR}(\hat{\boldsymbol{M}}_k, \boldsymbol{P}_k \boldsymbol{M}_{k,true}) \geq \varepsilon\right) \\ \leq & \mathbb{P}\left(F(\widehat{\hat{\boldsymbol{c}}^{(1)}}, ..., \widehat{\hat{\boldsymbol{c}}^{(K)}}) - F(\boldsymbol{c}^{(1)}, ..., \boldsymbol{c}^{(K)}) \leq 2r_d - \frac{\varepsilon \tau^{K-1} \delta_{min}}{4}\right) \\ \leq & \mathbb{P}\left(r_d \geq \frac{\varepsilon \tau^{K-1} \delta_{min}}{8}\right) \end{split}$$

Now we convert our problem into find the upper bound of $\mathbb{P}\left(r_d \geq \frac{\varepsilon \tau^{K-1} \delta_{min}}{8}\right)$. Consider $\mathbb{P}\left(r_d \leq t\right)$, because f is locally lipschitz continuous with lipschitz constant $c = \sup|f'(\mu)|$ for μ in a neighborhood of the convex hull of the entries of \mathcal{C} .

$$\begin{split} &|F(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)}) - G(\boldsymbol{D}^{(1)}(\hat{\boldsymbol{c}}^{(1)}),...,\boldsymbol{D}^{(K)}(\hat{\boldsymbol{c}}^{(K)}))| \\ &= &|\sum_{r_1,...,r_K} \hat{p}_{r_1}^{(1)}\hat{p}_{r_2}^{(2)}\cdots\hat{p}_{r_K}^{(K)}[f(\overline{Y_{r_1,...,r_K}}) - f(E_{r_1,...,r_K})]| \\ &\leq &\sum_{r_1,...,r_K} \hat{p}_{r_1}^{(1)}\hat{p}_{r_2}^{(2)}\cdots\hat{p}_{r_K}^{(K)}|f(\overline{Y_{r_1,...,r_K}}) - f(E_{r_1,...,r_K})| \\ &\leq &c\sum_{r_1,...,r_K} \hat{p}_{r_1}^{(1)}\hat{p}_{r_2}^{(2)}\cdots\hat{p}_{r_K}^{(K)}|R(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)})_{r_1,...,r_K}| \\ &\leq &c||\boldsymbol{R}(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)})||_{\infty} \end{split}$$

Therefore,

$$\mathbb{P}\left(\mathbf{MCR}(\hat{\boldsymbol{M}}_{k}, \boldsymbol{P}_{k}\boldsymbol{M}_{k,true}) \geq \varepsilon\right) \leq \mathbb{P}\left(||\boldsymbol{R}(\hat{\boldsymbol{c}}^{(1)}, ..., \hat{\boldsymbol{c}}^{(K)})||_{\infty} \geq \frac{\varepsilon\tau^{K-1}\delta_{min}}{8c}\right)$$
(2)

According to Hoeffding's inequality,

$$\mathbb{P}\left(|R(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)})_{r_{1},...,r_{K}}| \geq \frac{\varepsilon \tau^{K-1} \delta_{min}}{8c}\right) \\
= \mathbb{P}\left(|\overline{Y_{r_{1},...,r_{K}}} - E(\hat{\boldsymbol{c}}^{(1)},...,\hat{\boldsymbol{c}}^{(K)})_{r_{1},...,r_{K}}| \geq \frac{\varepsilon \tau^{K-1} \delta_{min}}{8c}\right) \\
\leq 2\exp\left(-\frac{\varepsilon^{2} \tau^{2(K-1)} \delta_{min}^{2} L_{d}}{128\sigma^{2} c^{2}}\right)$$

Combine the result with $L_d \ge \tau^K \prod_{k=1}^K d_k$,

$$\mathbb{P}\left(\mathbf{MCR}(\hat{\boldsymbol{M}}_{k}, \boldsymbol{P}_{k}\boldsymbol{M}_{k,true}) \geq \varepsilon\right) \leq 2^{1+\sum_{k=1}^{K} d_{k}} \exp\left(-\frac{\varepsilon^{2}\tau^{2(K-1)}\delta_{min}^{2}L_{d}}{128\sigma^{2}c^{2}}\right) \\
\leq 2^{1+\sum_{k=1}^{K} d_{k}} \exp\left(-\frac{\varepsilon^{2}\tau^{3K-2}\delta_{min}^{2}\prod_{k=1}^{K} d_{k}}{128\sigma^{2}c^{2}}\right)$$

Letting $C_2 = \frac{\tau^{3K-2}}{128c^2}$ yields the result.

References

[1] Cheryl J. Flynn and Patrick O. Perry. Consistent Biclustering. arXiv:1206.6927v3 [stat:ME]