

## **Research Note 2**

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# 1 Supervised Clustering with Normal Setting

**Settings and Assumptions** Consider a tensor  $\chi \in \mathbb{R}^{d_1 \times d_2 \times d_3}$  with continuous variables and a covariate matrix of the first mode  $X \in \mathbb{R}^{d_1 \times p}$ . And the noise in this setting would be i.i.d and follow a normal distribution with equal variance  $\sigma^2$

## Models and Estimation

- **Only consider the supervise part in the loss function**

Under this idea, we still have three membership matrix  $A, B, C$  on each mode of the tensor, however, we want to let  $A$  close to  $X$ .

First, we construct the model:

$$\chi = \mathcal{U} \times_1 A^T \times_2 B^T \times C^T + \epsilon$$

where  $\mathcal{U} \in \mathbb{R}^{k_1 \times k_2 \times k_3}$  in which each element  $\mu_{ijk}$  refers to the mean of each cluster and  $A \in \mathbb{R}^{d_1 \times k_1}, B \in \mathbb{R}^{d_2 \times k_2}, C \in \mathbb{R}^{d_3 \times k_3}$  are the membership matrix on each mode.

Then the optimization of loss function is:

$$\min_{\mathcal{U}, A, B, C} \|\chi - \mathcal{U} \times_1 A^T \times_2 B^T \times C^T\| + \lambda \|A - X\|_{0,1,2}$$

where  $\|\cdot\|_{0,1,2}$  refers to different penalty regularization.

- **Consider the covariate matrix as a part of factorization**

Under this idea, we may only do clustering on direction of mode  $B, C$  (the second and third mode). The supervised data on the first mode facilitate the clustering on the other mode.

Construct the model:

$$\chi = \mathcal{U} \times_1 X^T \times_2 B^T \times C^T + \epsilon$$

where  $\mathcal{U} \in \mathbb{R}^{p \times k_2 \times k_3}$  in which each element  $\mu_{pjk}$  refers to the mean of each cluster on mode  $B, C$  and how it effected by  $X$ . And  $B \in \mathbb{R}^{d_2 \times k_2}, C \in \mathbb{R}^{d_3 \times k_3}$  are the membership matrix on each mode.

Then the optimization of loss function is:

$$\min_{\mathcal{U}, B, C} \|\chi - \mathcal{U} \times_1 X^T \times_2 B^T \times C^T\|$$

## 2 Supervised Clustering with Binary Setting

**Settings and Assumptions** Consider a binary tensor  $\mathcal{X} \in \{0, 1\}^{d_1 \times d_2 \times d_3}$  and a covariate matrix of the first mode  $X \in \mathbb{R}^{d_1 \times p}$ .

### Model and Estimation

- **Only consider the supervise part in the loss function**

The utilization idea of supervised data has introduced above. Now assume the variables in tensor follow Bernoulli distribution and construct a model:

$$\begin{aligned} \chi_{ijk} &\sim Ber(p_{ijk}), \text{ and } \chi'_{ijk} \text{ s are independent of each other,} \\ \mathbb{E}\chi_{ijk} &= p_{ijk}, \quad P = \{p_{ijk}\} \in \mathbb{R}^{d_1 \times d_2 \times d_3} \\ \text{logit}(P) &= \log \frac{p_{ijk}}{1 - p_{ijk}} = \mathcal{U} \times_1 A^T \times_2 B^T \times C^T \end{aligned}$$

where  $\mathcal{U} \in \mathbb{R}^{k_1 \times k_2 \times k_3}$  in which each element  $\mu_{ijk}$  refers to the mean of each cluster and  $A \in \mathbb{R}^{d_1 \times k_1}, B \in \mathbb{R}^{d_2 \times k_2}, C \in \mathbb{R}^{d_3 \times k_3}$  are the membership matrix on each mode. The optimization would use penalty likelihood function:

$$\begin{aligned} \max_{\mathcal{U}, A, B, C} & \|\chi \circ \mathcal{U} \times_1 A^T \times_2 B^T \times C^T - \log(1 + \exp(\mathcal{U} \times_1 A^T \times_2 B^T \times C^T))\|_F \\ & - \lambda \|A - X\|_{0,1,2} \end{aligned}$$

- **Consider the covariate matrix as a part of factorization**

The assumption of tensor and the idea of using covariate matrix substitute the membership matrix are the same with previous part. Construct the model:

$$\begin{aligned} \chi_{ijk} &\sim_{i.i.d} Ber(p_{ijk}), \quad \mathbb{E}\chi_{ijk} = p_{ijk}, \quad P = \{p_{ijk}\} \in \mathbb{R}^{d_1 \times d_2 \times d_3} \\ \text{logit}(P) &= \log \frac{p_{ijk}}{1 - p_{ijk}} = \mathcal{U} \times_1 X^T \times_2 B^T \times C^T \end{aligned}$$

where  $\mathcal{U} \in \mathbb{R}^{p \times k_2 \times k_3}$  in which each element  $\mu_{pjk}$  refers to the mean of each cluster on mode  $B, C$  and how it effected by  $X$ . And  $B \in \mathbb{R}^{d_2 \times k_2}, C \in \mathbb{R}^{d_3 \times k_3}$  are the membership matrix on each mode.

The optimization would use penalty likelihood function:

$$\max_{\mathcal{U}, B, C} \|\langle \chi, \mathcal{U} \times_1 X^T \times_2 B^T \times C^T \rangle - \log(1 + \exp(\mathcal{U} \times_1 X^T \times_2 B^T \times C^T))\|_F$$

t.b.c