Summary of Sparse Biclustering of Transposable Data

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1 Biclustering

Biclustering, block clustering, co-clustering, or two-mode clustering is a data mining technique which allows simultaneous clustering of the rows and columns of matrix.

2 Assumptions

- each matrix element is normally distributed with a bicluster-specific mean;
- the biclusters partition the rows and columns of the matrix.

3 Sparse biclustering

3.1 Model assumptions

- The biclusters all are constant biclusters, in which all elements take on approximately a constant value.
- $X_{ij} \sim N(\mu_{kr}, \sigma^2)$ for $i \in C_k, j \in D_r, k = 1, ..., K$ and r = 1, ..., R, and they are independent with each other.

3.2 Model

The model is:

$$X_{ij} = \mu_{kr} + \varepsilon_{ij} \text{ where } \varepsilon_{ij} \sim N(0, \sigma^2)$$

Given parameters: K, R, λ ;

Unknown parameters: μ_{kr} , $\{C_k\}$, $\{D_r\}$.

Maximizing the log likelihood of the data under the model with inducing sparsity by using a LASSO penalty, we arrived at:

$$\underset{C_1, \dots, C_K, D_1, \dots, D_R, \mu \in \mathbb{R}^{K \times R}}{\text{minimize}} \left\{ \frac{1}{2} \sum_{k=1}^K \sum_{r=1}^R \sum_{i \in C_k} \sum_{j \in D_r} (X_{ij} - \mu_{kr})^2 + \lambda \sum_{k=1}^K \sum_{r=1}^R |\mu_{kr}| \right\} \tag{1}$$

where λ is a non-negative tuning parameter.

3.3 An extension to tensor

3.3.1 Model assumptions

- The clusters all are constant clusters, in which all elements take on approximately a constant value.
- $X_{ijm} \sim N(\mu_{krm}, \sigma^2)$ for $i \in C_k, j \in D_r, m \in E_l, k = 1, ..., K, r = 1, ..., R, l = 1, ..., L$, and they are independent with each other.

3.3.2 Model

The model is:

$$X_{ijm} = \mu_{krl} + \varepsilon_{ijm} \text{ where } \varepsilon_{ijm} \sim N(0, \sigma^2)$$

Given parameters: K, R, L, λ ;

Unknown parameters: μ_{krl} , $\{C_k\}$, $\{D_r\}$, $\{E_l\}$.

Maximizing the log likelihood of the data under the model with inducing sparsity by using a LASSO penalty, we arrived at:

$$\underset{C_{1},...,C_{K},D_{1},...,D_{R},E_{1},...,E_{L},\mu\in R^{K\times R\times L}}{\text{minimize}} \left\{ \frac{1}{2} \sum_{k=1}^{K} \sum_{r=1}^{R} \sum_{l=1}^{L} \sum_{i\in C_{k}} \sum_{j\in D_{r}} \sum_{m\in E_{l}} (X_{ijm} - \mu_{krl})^{2} + \lambda \sum_{k=1}^{K} \sum_{r=1}^{R} \sum_{l=1}^{L} |\mu_{krl}| \right\}$$

$$(2)$$

where λ is a non-negative tuning parameter.

3.3.3 Algorithm

4 A spectral interpretation for biclustering

The optimization problem

$$\underset{A^T A = I_K, B^T B = I_K}{\text{maximize}} ||A^T X B||_F^2 \tag{4}$$

under two additional constraints:

- The elements of the kth column of A are 0 or $\frac{1}{\sqrt{n_k}}$ with $n_k \in \mathbb{Z}^+, \sum_{k=1}^K n_k = n$.
- The elements of the kth column of B are 0 or $\frac{1}{\sqrt{p_r}}$ with $p_r \in Z^+, \sum_{r=1}^K p_r = p$.

makes (2) equivalent to the biclustering optimization problem (1) when $\lambda = 0, K = R$. So, with K = R, the biclustering problem (1) when $\lambda = 0$ can be relaxed in order to yield the SVD.

5 Tuning parameter selection

$$BIC = np \times log(RSS) + (q+1)log(np)$$

Algorithm 1 Selecting k,r,l

1

for each $time \in [1, T]$ (T-cross validation) do

- (a) Let M denote a set containing npq/T elements of the form (i, j, m), where M is disjoint for each iteration.
- (b) Construct a new $n \times p \times q$ array, X^* , for which the elements in M are "missing" and are imputed using the mean of the non-missing values:

(c)

for each value (k, r, l) of interest: do

- i. Perform sparse tensor clustering of X^* with k mode 1, r mode 2, l mode 3 clusters.
- ii. Construct a $n \times p \times q$ array A whose (i, j, m)th element equals the estimated value of μ_{krl} , where $i \in C_k$, $j \in D_r$ and $m \in E_L$.

Calculate the mean squared error that results from estimating the "missing" elements using the corresponding cluster means.

$$\sum_{(i,j,m)\in M} (X_{ijm} - A_{ijm})^2 / |M| \tag{3}$$

end for

end for

- 2. For each value (k, r, l) that was considered in Step 1(c), compute $m_{k,r,l}$, the mean of the quantity (3) across all T iterations, as well as $s_{k,r,l}$, its standard error.
- 3. Identify the (k, r, l) for which $m_{k,r,l} \leq m_{k+1,r+1,l+1} + s_{k+1,r+1,l+1}$.
- 4. Select the (k, r, l) from step 3 for which k + r + l is smallest.

Algorithm 2 Classifying the labels

Initialize $C_1, ..., C_K, D_1, ..., D_R$ and $E_1, ..., E_L$ by performing one-way k-means clustering on the columns and on the rows of the data matrix X.

repeat

- (a) Holding $C_1, ..., C_K, D_1, ..., D_R$ and $E_1, ..., E_L$ fixed, solve (1) with respect to μ using LASSO regression.
- (b) Holding μ , $D_1, ..., D_R$ and $E_1, ..., E_L$ fixed, solve (1) with respect to $C_1, ..., C_K$, by assigning the *i*th observation to the row cluster for which $\sum_{r=1}^R \sum_{l=1}^L \sum_{j \in D_r} \sum_{m \in E_l} (X_{ijm} \mu_{krl})^2$ is smallest.
- (c) repeat (a).
- (d) Holding μ , $C_1, ..., C_K$ and $E_1, ..., E_L$ fixed, solve (1) with respect to $D_1, ..., D_R$, by assigning the *i*th observation to the column cluster for which $\sum_{k=1}^K \sum_{l=1}^L \sum_{i \in C_k} \sum_{m \in E_l} (X_{ijm} \mu_{krl})^2$ is smallest.
- (e) repeat (a).
- (f) Holding μ , $C_1,...,C_K$ and $D_1,...,D_R$ fixed, solve (1) with respect to $E_1,...,E_L$, by assigning the *i*th observation to the cluster of the third dimension for which $\sum_{k=1}^K \sum_{r=1}^R \sum_{i \in C_k} \sum_{j \in D_r} (X_{ijm} \mu_{krl})^2$ is smallest.

until Convergence

6 Simulation study

Standard: clustering error rate(CER), sparsity rate, sparsity error rate, proportion of correctly identified zeros(C.Zeros) and non-zeros(C.Non-zeros).

6.1 Definitions

Clustering error rate (CER):

Using adjusted rand index to measure the agreement between any two partitions for the data tensor. In this case, we have three kinds of CER in total: rowCER, columnCER and the CER of the third dimension. To be more specific, consider the rowCER. Denote S as the set of rows. T is the true partition of S and J is the clustering result with respect to rows. Here,

- a, the number of pairs of elements/labels in S that in the same subset in T and in the same subset in J.
- b, the number of pairs of elements/labels in S that in the different subsets in T and in the different subset in J.

$$rowCER = \frac{a+b}{C_n^2}$$

Intuitively, a + b can be considered as the number of agreements between T and J and c + d as the number of disagreements between T and J.

6.2 No bicluster means exactly equal to zero

Conclusions: The biclustering with $\lambda = 0,200$ leads to consistently better results than independent clustering of the rows and columns.

6.3 Some bicluster means exactly equal to zero

Conclusions: IP fails to identify any biclusters in this simulation set-up. SSVD and LAS perform comparably in this setting. But by far the best overall performance is achieved by sparse biclustering proposal with a large value of λ .

6.4 Multiplicative biclusters

Conclusions: SSVD has the best results in this simulation set-up, as in this set-up there are multiplicative biclusters.

6.5 Overlapping multiplicative biclusters

Conclusions: Both SSVD and sparse biclustering performs pretty good though the set-up violates the assumptions of sparse biclustering.

A Additional biclustering results of Table 2

True value of (K,R)	n	р	Overall Accuracy	Selected K	Selected R
K=2, R=4	250	100	74%	2(0.0000)	3.7(0.0769)
K=2, R=4	20	50	16%	2.02(0.0318)	2.74(0.1090)

B Additional simulation biclusterung results of Table 3

Method	n	p	Row CER	Column CER	Sparsity Rate
k-means	20	50	0.3621(0.0223)	0.3407(0.0046)	0
Bicluster $\lambda = 0$	20	50	0.3509(0.0220)	0.3217(0.0058)	0
Bicluster $\lambda = 200$	20	50	0.3654(0.0206)	0.4136(0.0155)	0.4455(0.0260)
Bicluster $\lambda = 400$	20	50	0.4841(0.0099)	0.6751(0.0217)	0.8074(0.0553)
Bicluster $\lambda = 800$	20	50	0.4909(0.0061)	0.7478(0.0017)	1(0)
k-means	250	100	0.1202(0.0188)	0.1649(0.0089)	0
Bicluster $\lambda = 0$	250	100	0.1077(0.0177)	0.0958(0.0103)	0
Bicluster $\lambda = 200$	250	100	0.1104(0.0178)	0.0982(0.0105)	0.0610(0.0123)
Bicluster $\lambda = 400$	250	100	0.1119(0.0181)	0.1074(0.0097)	0.1192(0.0161)
Bicluster $\lambda = 800$	250	100	0.1171(0.0185)	0.1358(0.0098)	0.1889(0.0212)

C Simulation tensor clustering result when k,r,l are given

n	p	q	k	r	1	noise	lambda	iteration	model CER	modeII CER	modeIII CER
50	20	20	5	2	2	2	0.01	50	0.1164082	0	0
50	20	20	5	2	2	2	0	50	0.02844082	0	0
50	20	20	5	2	2	0	0	50	0	0	0
50	50	50	3	3	3	0	0	50	0	0	0
50	50	50	3	3	3	3	0	50	0.005240816	0.010693878	0.010318367

Table 1: The simulation result in tensor clustering

D Two results in tensor clustering under noise = 2

Both of the result are of 0 CERs in three modes.

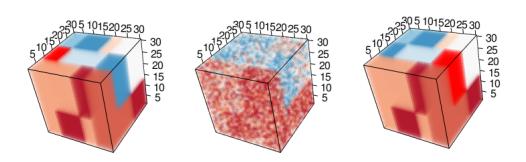


Figure 1: first simulation (truth, input, output)

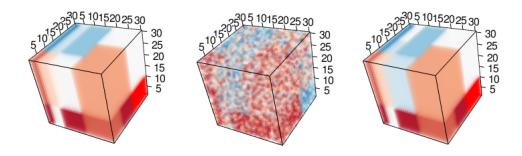


Figure 2: second simulation (truth, input, output)

E Three examples of selecting k,r,l

Example 1:

```
K = 4 113.7263 123.2596 120.3845
, , L = 3
         R = 2 \qquad R = 3 \qquad R = 4
K = 2 146.6639 144.8598 147.0858
K = 3 141.6482 144.5811 135.6438
K = 4 140.5085 144.1642 150.5537
, , L = 4
         R = 2
                 R = 3
                          R = 4
K = 2 144.8609 145.5596 152.6614
K = 3 138.9845 140.0927 138.1418
K = 4 \ 136.4456 \ 148.6868 \ 140.0982
$results.mean
, , L = 2
         R = 2
                 R = 3
                          R = 4
K = 2 27632.04 27655.18 27665.42
K = 3 27253.61 27260.49 27288.64
K = 4 27272.04 27291.61 27297.49
, , L = 3
         R = 2
                 R = 3
                          R = 4
K = 2 24671.30 24688.94 24712.19
K = 3 22635.90 22645.72 22676.05
K = 4 22647.39 22672.96 22674.25
, , L = 4
         R = 2
                 R = 3
                          R = 4
K = 2 24684.75 24704.75 24716.35
K = 3 22655.69 22672.62 22700.28
K = 4 22677.69 22694.95 22698.40
Example 2:
True k,r,l: 4,3,2;
Estimated k,r,l: 4,4,4.
n=40;p=30;q=20;k=4;r=3;l=2
data = get.data(n,p,q,k,r,l,error=2,sort=TRUE)
test = data$x
range.k = 2:4; range.r = 2:4; range.1 = 2:4
sparse.choosekrl(test,range.k,range.r,range.l,trace=TRUE)
$bestK
[1] 4
```

```
$bestR
[1] 4
$bestL
[1] 4
Example 3:
True k,r,l: 3,3,3
Estimated k,r,l: 3,3,3
n=30;p=30;q=30;k=3;r=3;1=3
data = get.data(n,p,q,k,r,l,error=2,sort=TRUE)
test = data$x
range.k = 2:4; range.r = 2:4; range.1 = 2:4
sparse.choosekrl(test,range.k,range.r,range.l,trace=TRUE)
$estimated_krl
    [,1] [,2] [,3]
     3 3 3
[1,]
$results.se
, , L = 2
         R = 2
                R = 3
                          R = 4
K = 2 219.9770 149.3796 148.4654
K = 3 215.8733 157.0098 158.6694
K = 4 \ 215.5330 \ 153.5680 \ 153.0606
, , L = 3
         R = 2
                 R = 3
                          R = 4
K = 2 298.1318 231.2240 232.7078
K = 3 \ 261.5005 \ 202.5743 \ 201.8399
K = 4 260.5464 199.7686 195.5321
, , L = 4
         R = 2 \qquad R = 3
                          R = 4
K = 2 296.5098 225.4298 231.0916
K = 3 267.6983 197.6522 209.2797
K = 4 258.7976 197.9091 198.2777
$results.mean
, , L = 2
         R = 2
                 R = 3
                          R = 4
K = 2 34958.74 30413.91 30427.48
K = 3 32687.69 27287.17 27309.28
K = 4 32693.21 27291.23 27302.11
, , L = 3
```

R = 2 R = 3 R = 4 K = 2 31339.87 26439.73 26458.68 K = 3 28157.20 22273.70 22298.02 K = 4 28160.83 22278.93 22293.68

, , L = 4