

Oracle analysis hDCBM algorithm

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1 Oracle analysis

Suppose we have p nodes from r communities and observe the adjacent tensor $\mathcal{Y} \in \{0, 1\}^{p \times p \times p}$ whose entry \mathcal{Y}_{ijk} refers to the connection of the triplet (i, j, k) . Let $\theta = (\theta_1, \dots, \theta_p) \in \mathbb{R}^p$ denote the degree-corrected parameters and $z = (z_1, \dots, z_p) \in [r]^p$ denote the clustering assignment. Consider the hDCBM model

$$\mathbb{E}[\mathcal{Y}] = \mathcal{S} \times_1 \Theta \mathbf{M} \times_2 \Theta \mathbf{M} \times_3 \Theta \mathbf{M},$$

where $\mathcal{S} \in \mathbb{R}^{r \times r \times r}$ is the symmetric core tensor, $\Theta = \text{diag}(\theta) \in \mathbb{R}^{p \times p}$ and $\mathbf{M} \in \mathbb{R}^{p \times r}$ is the hard membership matrix based on z . [Algorithms 1, 2 are modified slightly for this simpler setting.](#)

Suppose we have the noiseless observation

$$\mathcal{Q} = \mathcal{S} \times_1 \Theta \mathbf{M} \times_2 \Theta \mathbf{M} \times_3 \Theta \mathbf{M}.$$

We study the output of the initialization algorithm [1](#) and the iteration algorithm [2](#). Without the loss of generality, we use SCORE function $h(x) = \|x\|_F$.

1.1 Initialization

Note that \mathcal{Q} is symmetric. So, the intermediate parameters $\tilde{\mathbf{U}}_k, \hat{\mathbf{U}}_k, z_k^{(0)}$ in Algorithm [1](#) are the same on d modes. For simplicity, let $\tilde{\mathbf{U}}, \hat{\mathbf{U}}, z^{(0)}$ denote the common parameters.

1. The very first step in Algorithm [1](#) is HOSVD factor $\tilde{\mathbf{U}}$. Following the tensor algebra in [Han et al. \(2020\)](#), we have

$$\tilde{\mathbf{U}} = \text{SVD}_r(\mathcal{M}_1(\mathcal{Q})) = \text{SVD}_r(\Theta \mathbf{M} \mathcal{M}_1(\mathcal{S})(\Theta \mathbf{M} \otimes \Theta \mathbf{M})^T). \quad (1)$$

By the Lemma 3.1 in [Ke et al. \(2019\)](#), we have

$$\tilde{\mathbf{U}} = \Theta \mathbf{M} \mathbf{D}^{-1} \mathbf{B},$$

where $\mathbf{D} = \text{diag}(d), d = (d_1, \dots, d_r) \in \mathbb{R}^r$, $d_k = (\sum_{z_i=k} \theta_i^2)^{1/2}$, \mathbf{B} is an orthonormal matrix, i.e., $\mathbf{B}^T \mathbf{B} = \mathbf{1}_r$. Thus, we also have $\tilde{\mathbf{U}}^T \tilde{\mathbf{U}} = \mathbf{1}_r$.

2. Secondly, we improve the SVD estimation via

$$\begin{aligned}\hat{\mathbf{U}} &= \text{SVD}_r \left(\mathcal{M}_1(\mathcal{Q} \times_2 \tilde{\mathbf{U}}^T \times_3 \tilde{\mathbf{U}}^T) \right) \\ &= \text{SVD}_r \left(\Theta \mathbf{M} \mathcal{M}_1(\mathcal{S})(\tilde{\mathbf{U}}^T \Theta \mathbf{M} \otimes \tilde{\mathbf{U}}^T \Theta \mathbf{M})^T \right).\end{aligned}\quad (2)$$

Note that $\tilde{\mathbf{U}}, \hat{\mathbf{U}}$ refer to the left singular space, both of them are orthonormal, and the right hand side in equation (1) and (2) share the same column space. Therefore, we have $\tilde{\mathbf{U}} = \hat{\mathbf{U}}$. However, the equivalence is not true for noisy observation.

3. Thirdly, we calculate the projected matrix

$$\begin{aligned}\hat{\mathbf{Y}}_1 &= \hat{\mathbf{U}} \hat{\mathbf{U}}^T \mathcal{M}_1(\mathcal{Q} \times_2 \tilde{\mathbf{U}}^T \times_3 \tilde{\mathbf{U}}^T) \\ &= [\Theta \mathbf{M} \mathbf{D}^{-1} \mathbf{B}] [\mathbf{B}^T \mathbf{D}^{-1} \mathbf{M}^T \Theta] \Theta \mathbf{M} \mathcal{M}_1(\mathcal{S})(\tilde{\mathbf{U}}^T \Theta \mathbf{M} \otimes \tilde{\mathbf{U}}^T \Theta \mathbf{M})^T \\ &= \Theta \mathbf{M} \mathbf{V},\end{aligned}$$

where $\mathbf{V} = \mathbf{B} \mathbf{B}^T \mathcal{M}_1(\mathcal{S})(\tilde{\mathbf{U}}^T \Theta \mathbf{M} \otimes \tilde{\mathbf{U}}^T \Theta \mathbf{M})^T \in \mathbb{R}^{r \times r^2}$ since $\mathbf{M}^T \Theta \mathbf{M} = \mathbf{D}^2$.

4. Last, we apply SCORE normalization to $\hat{\mathbf{Y}}_1$. Let $\hat{\mathbf{Y}}_{1,j}$ denote the j -th row or $\hat{\mathbf{Y}}_1$ for $j \in [p]$, and \mathbf{V}_u denote the u -th row of \mathbf{V} for $u \in [r]$. Then, for $z_j = u$, we have normalized row

$$\hat{\mathbf{Y}}_{1,j}^s = \frac{\hat{\mathbf{Y}}_{1,j}}{\|\hat{\mathbf{Y}}_{1,j}\|} = \frac{\theta_j \mathbf{V}_u}{\theta_j \|\mathbf{V}_u\|_F} = \frac{\mathbf{V}_u}{\|\mathbf{V}_u\|_F}.$$

Hence, the normalized $\hat{\mathbf{Y}}_1^s$ only has r distinct rows, and thus the k -means clustering exactly covers the true membership, i.e., $z^{(0)} = z^*$.

1.2 Iteration

Take the true assignment $z^{(0)} = z^*$ and the true signal \mathcal{Q} as input of the iteration Algorithm 2.

1. The first step imposes the SCORE normalization on all modes. Note that \mathcal{Q} is symmetric. Let \mathbf{Q}_k denote the k -th matriciation of \mathcal{Q} . We have

$$\hat{\theta}_j = \|\mathbf{Q}_{1,j}\| = \theta_j \|\mathbf{V}_{z_j^*}\|_F,$$

where $\mathbf{V} = \mathcal{M}_1(\mathcal{S})(\Theta \mathbf{M} \otimes \Theta \mathbf{M})^T$. Let $\tilde{\mathbf{V}} = \text{diag}(\|\mathbf{V}_1\|_F, \dots, \|\mathbf{V}_r\|_F)$.

2. Secondly, we apply the SCORE normalization to \mathcal{Q} . Note that

$$\begin{aligned}\hat{\Theta} &= \Theta \text{diag} \left(\|\mathbf{V}_{z_1^*}\|_F, \dots, \|\mathbf{V}_{z_p^*}\|_F \right) \\ \mathcal{Q}^s &= \mathcal{Q} \times_1 \hat{\Theta}^{-1} \times_2 \dots \times_3 \hat{\Theta}^{-1} \\ &= \mathcal{S} \times_1 \mathbf{M} \tilde{\mathbf{V}} \times_2 \mathbf{M} \tilde{\mathbf{V}} \times_2 \mathbf{M} \tilde{\mathbf{V}} \\ &= \tilde{\mathcal{S}} \times_1 \mathbf{M} \times_2 \mathbf{M} \times_3 \mathbf{M},\end{aligned}$$

where $\tilde{\mathcal{S}} = \mathcal{S} \times_1 \tilde{\mathbf{V}} \times_2 \tilde{\mathbf{V}} \times_3 \tilde{\mathbf{V}}$.

3. Last, note that \mathcal{Q}^s is completely separated. The HLloyd algorithm will return the true assignment, i.e., $z^{(T)} = z^*$.

Algorithm 1 High-order degree-corrected spectral clustering (HDCSC)

Input: Observation $\mathcal{Y} \in \mathbb{R}^{p \times \dots \times p}$, r , relaxation factor in k -means $M > 1$, SCORE normalization function h

- 1: Compute $\tilde{\mathbf{U}}_k = \text{SVD}_{r_k}(\mathcal{M}_k(\mathcal{Y}))$ for $k \in [d]$
- 2: **for** $k \in [d]$ **do**
- 3: Estimate the singular space $\hat{\mathbf{U}}_k$ via

$$\hat{\mathbf{U}}_k = \text{SVD}_r(\mathcal{M}_k(\mathcal{Y} \times_1 \tilde{\mathbf{U}}_1^T \times \dots \times_{k-1} \tilde{\mathbf{U}}_{k-1}^T \times_{k+1} \tilde{\mathbf{U}}_{k+1}^T \times \dots \times_d \tilde{\mathbf{U}}_d^T))$$

4: **end for**

5: **for** $k \in [d]$ **do**

6: Calculate $\hat{\mathbf{Y}}_k$ via $\hat{\mathbf{Y}}_k = \hat{\mathbf{U}}_k \hat{\mathbf{U}}_k^T \mathcal{M}_k(\mathcal{Y} \times_1 \hat{\mathbf{U}}_1^T \times \dots \times_{k-1} \hat{\mathbf{U}}_{k-1}^T \times_{k+1} \hat{\mathbf{U}}_{k+1}^T \times \dots \times_d \hat{\mathbf{U}}_d^T)$

7: Let $\hat{\mathbf{Y}}_{kj}$ denote the rows of $\hat{\mathbf{Y}}_k$ for $j \in [p_k]$. Obtain the SCORE normalized $\hat{\mathbf{Y}}_k^s$ via $\hat{\mathbf{Y}}_{kj}^s = \frac{\hat{\mathbf{Y}}_{kj}}{h(\mathbf{Y}_{kj})}$

8: Find the initial assignment $z_k^{(0)} \in [r_k]^{p_k}$ and centroids $\hat{x}_1, \dots, \hat{x}_{r_k} \in \mathbb{R}^{r-k}$ such that

$$\sum_{j=1}^{p_k} \left\| (\hat{\mathbf{Y}}_{kj}^s)^T - \hat{x}_{(z_k^{(0)})_j} \right\|^2 \leq M \min_{x_1, \dots, x_{r_k}, z_k} \sum_{j=1}^{p_k} \left\| (\hat{\mathbf{Y}}_{kj}^s)^T - x_{(z_k^{(0)})_j} \right\|^2$$

9: **end for**

10: Find the average of $z_k^{(0)}, k \in [d]$, $z^{(0)}$.

Output: $\{z^{(0)} \in [r]^p\}$

Algorithm 2 High-order degree-corrected Lloyd Algorithm (HDCLloyd)

Input: Observation $\mathcal{Y} \in \mathbb{R}^{p \times \dots \times p}$, initialization $\{z^{(0)} \in [r]^p\}$, iteration number T , SCORE normalization function h

1: Let \mathbf{Y}_k denote the k -th model matricization of \mathcal{Y} and $\mathbf{Y}_{k,j}$ denote the j -th column of \mathbf{Y}_k . Find the surrogate estimation of θ via

$$\hat{\theta}_j = \frac{1}{d} \left\| \sum_{k=1}^d \mathbf{Y}_{k,j} \right\|_F$$

2: Let $\hat{\Theta} = \text{diag}(\hat{\theta})$. Apply SCORE normalization to \mathcal{Y} via

$$\mathcal{Y}^s = \mathcal{Y} \times_1 \hat{\Theta}^{-1} \times \dots \times_d \hat{\Theta}^{-1}$$

3: Apply HLloyd with \mathcal{Y}^s , initialization $\{z^{(0)} \in [r]^p\}$, and iteration number T .

Output: $\{z^{(T)} \in [r]^p\}$

References

- Han, R., Luo, Y., Wang, M., and Zhang, A. R. (2020). Exact clustering in tensor block model: Statistical optimality and computational limit. [arXiv preprint arXiv:2012.09996](#).
- Ke, Z. T., Shi, F., and Xia, D. (2019). Community detection for hypergraph networks via regularized tensor power iteration. [arXiv preprint arXiv:1909.06503](#).