



Active Steering Dolly for Long Combination Vehicles

Design of a Real-Time Control Interface for a steerable Dolly Master's thesis in Automotive Engineering

SEBASTIAN FRANZ MICHAEL HOFMANN

Department of Applied Mechanics CHALMERS UNIVERSITY OF TECHNOLOGY Göteborg, Sweden 2015

MASTER'S THESIS IN AUTOMOTIVE ENGINEERING

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Some explanation

Chalmers Reproservice Göteborg, Sweden 2015 Active Steering Dolly for Long Combination Vehicles
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Abstract

Keywords: Some stuff, More stuff, Stuff

PREFACE

ACKNOWLEDGEMENTS

Nomenclature

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1 Introduction

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