

# Rank-based M-Estimation for Tail Dependence and Independence

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- 1 Introduction: Bivariate tails and Asymptotic independence
- 2 Non-parametric estimation of  $c$
- 3 Parametric estimation of  $c$

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- Our objective: Propose a unifying way to do so in both situations



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- $L$  is called *stable tail dependence function*, or simply the  $L$ -function ([Huang, 1992, de Haan and Ferreira, 2006])
- If  $F$  is in a MDA,  $L$ ,  $R$  and the exponent measure are all equivalent

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- $X$  and  $Y$  are then said to be *asymptotically independent* (AI). Otherwise, they are deemed *asymptotically dependent* (AD)
- Note that if  $(X, Y) \in \mathcal{D}(G)$  for a bivariate EVD  $G$ ,  $X$  and  $Y$  are AI iff the two components of  $G$  are independent

# Another representation of the extremal dependence

- Instead of the function  $R$ , assume the existence of

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- Note: For  $c$  to be unique, we assume  $c(1, 1) = 1$

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# The estimator

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- The definition of  $c$  suggests the “estimator”

$$\hat{c}_n(x, y) := \frac{1}{q(k/n)} \frac{1}{n} \sum_{i=1}^n \mathbb{1} \left\{ \hat{F}_1(X_i) \geq 1 - \frac{k}{n}x, \hat{F}_2(Y_i) \geq 1 - \frac{k}{n}y \right\},$$

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- It appears in [Draisma et al., 2004]

# Asymptotic normality of $\hat{c}_n$

- Assume that as  $t \rightarrow 0$ ,

$$\frac{1}{q(t)} \mathbb{P}(F_1(X) \geq 1 - tx, F_2(Y) \geq 1 - ty) = c(x, y) + O(q_1(t))$$

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- Under AI,  $\sqrt{m}(\hat{c}_n - c) \rightsquigarrow W^{(1)}$  (in  $\ell^\infty([0, T]^2)$ ).*
- Under AD,  $\sqrt{m}(\hat{c}_n - c) \rightsquigarrow W^{(2)}$  (in the topo. of hypi-convergence for locally bounded functions ([Bücher et al., 2014])).*

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$$\sqrt{m}(\hat{c}_n(x, y) - c(x, y)) = \underbrace{\text{Something}}_{\rightsquigarrow W^{(1)}} + \sqrt{m}(c(\hat{x}_n, \hat{y}_n) - c(x, y)),$$

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- The other term comes from the error in estimating the marginals
- Under AD, it converges to a non trivial limit
- Under AI, it disappears because convergence of  $\hat{x}_n$  and  $\hat{y}_n$  is faster than convergence of “Something” to  $W^{(1)}$  (based on more data)

# Example 1: Inverted max-stable distributions

Suppose that  $(1/X, 1/Y)$  has a bivariate max-stable distribution, with  $L$ -function  $L$ . Then under a mild smoothness assumption on  $L$ ,  $(X, Y)$  satisfies our assumptions, with

$$q(t) = t^{L(1,1)}, \quad c(x, y) = x^{L_1(1,1)} y^{L_2(1,1)}, \quad q_1(t) = \frac{1}{\log(1/t)}$$

## Example 2: A random scale construction

Suppose  $R \sim \text{Pareto}(\alpha)$ ,  $W_j \sim \text{Pareto}(1)$ , where  $R, W_1, W_2$  are independent. Then  $(X, Y) = R(W_1, W_2)$  satisfies our assumptions

Range of $\alpha$	$q(t)$	$c(x, y)$	$q_1(t)$
$(0, 1)$	$K_\alpha t$	$(1 - r(\alpha))(x \wedge y) + r(\alpha)(x \wedge y)^{1/\alpha}(x \vee y)^{1-1/\alpha}$	$t^{1/\alpha-1}$
1	$\frac{K_\alpha t}{\log(1/t) + \log \log(1/t)}$	$(x \wedge y) \left(1 + \frac{1}{2} \log \left(\frac{x \vee y}{x \wedge y}\right)\right)$	$\frac{1}{\log(1/t)}$
$(1, 2)$	$K_\alpha t^\alpha$	$(x \wedge y)(x \vee y)^{\alpha-1}$	$t^{(\alpha-1) \wedge (2-\alpha)}$
2	$K_\alpha t^2 \log(1/t)$	$xy$	$\frac{1}{\log(1/t)}$
$(2, \infty)$	$K_\alpha t^2$	$xy$	$t^{\alpha-2}$

$$r(\alpha) = \frac{\alpha}{2} \left(1 - (2 - \alpha)(1 - \alpha)^{1/\alpha-1}\right) \in (0, 1)$$

Only thing to know:  $\alpha < 1 \Rightarrow \text{AD}$  and  $\alpha \geq 1 \Rightarrow \text{AI}$

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- More importantly, recall that  $\hat{c}_n$  depends on the unknown scaling function  $q$  (through  $m = nq(k/n)$ )

# Why a parametric estimator?

- Parametric models often allow for a nice interpretation
- The non-parametric estimator  $\hat{c}_n$  is not a proper function  $c$
- More importantly, recall that  $\hat{c}_n$  depends on the unknown scaling function  $q$  (through  $m = nq(k/n)$ )
- The following parametric estimation procedure fixes this problem

# The M-estimator we need

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$$m\hat{c}_n(x, y) = \sum_{i=1}^n \mathbb{1} \left\{ \hat{F}_1(X_i) \geq 1 - \frac{k}{n}x, \hat{F}_2(Y_i) \geq 1 - \frac{k}{n}y \right\}$$

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- To adjust, multiply left integral by a new unknown parameter

# The M-estimator we deserve

- We obtain the following objective function:

$$\Psi_n(\theta, \sigma) :=$$

$$\left\| \sigma \int_{[0, T]^2} g(x, y) c_\theta(x, y) dx dy - m \int_{[0, T]^2} g(x, y) \hat{c}_n(x, y) dx dy \right\|$$

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- By minimizing this objective function, we hope that  $c_\theta$  will estimate  $c$  and  $\sigma$  will estimate  $m$

# Asymptotic normality of the M-estimator

- Suppose that the true function generating the data is  $c_{\theta_0}$ ,  $\theta_0 \in \Theta$ , and that the map

$$(\theta, \xi) \mapsto \xi \int_{[0, T]^2} g(x, y) c_{\theta}(x, y) dx dy$$

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**Theorem (L, Engelke and Volgushev (2019))**

*Then if  $(\hat{\theta}_n, \hat{\sigma}_n)$  is an estimator such that  $\Psi_n(\hat{\theta}_n, \hat{\sigma}_n) = o_P(\sqrt{m})$ ,*

$$\sqrt{m} \left( \begin{pmatrix} \hat{\theta}_n, \frac{\hat{\sigma}_n}{m} \end{pmatrix} - (\theta_0, 1) \right) \rightsquigarrow N(0, \Sigma(\theta_0)).$$

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**Thank you!**



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