Statistics for idaholab/presentations

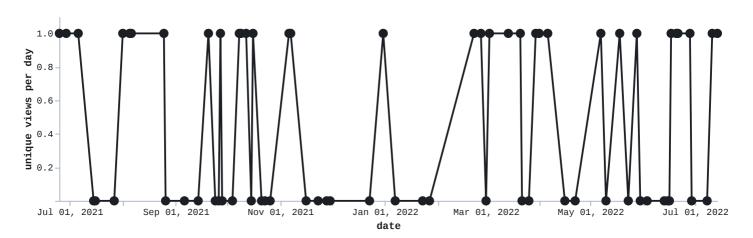
Generated for idaholab/presentations with jgehrcke/github-repo-stats at 2022-07-20 04:50 UTC.

Table of contents:

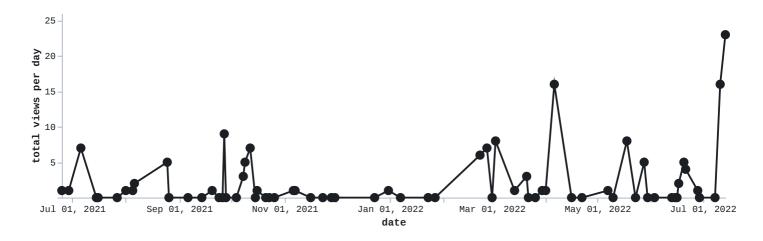
- Views
- Clones
- Stargazers
- Forks
- Top referrers and paths

Views

Unique visitors

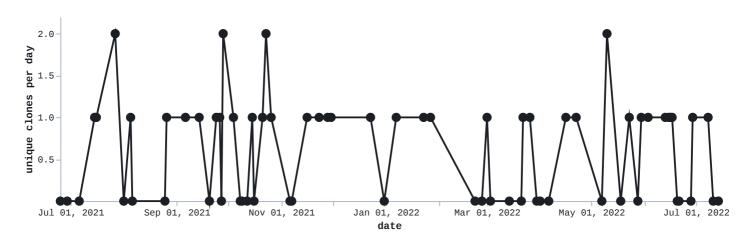


Total views

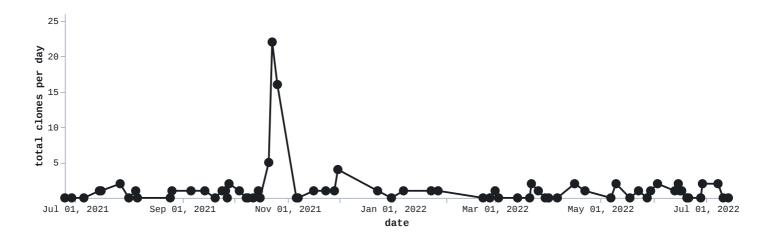


Clones

Unique cloners



Total clones



Stargazers

Each data point corresponds to at least one stargazer event. The time resolution is one day.



Forks

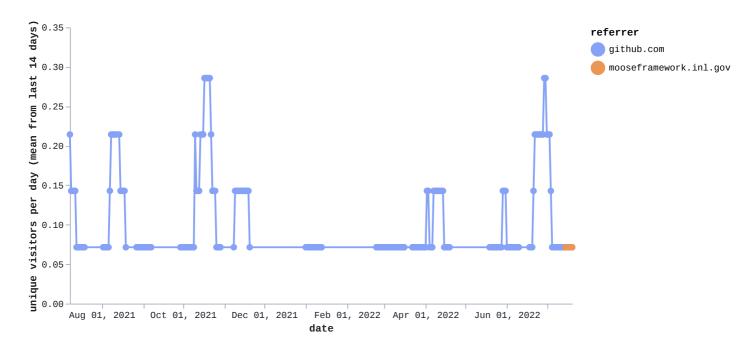
Each data point corresponds to at least one fork event. The time resolution is one day.



Top referrers and paths

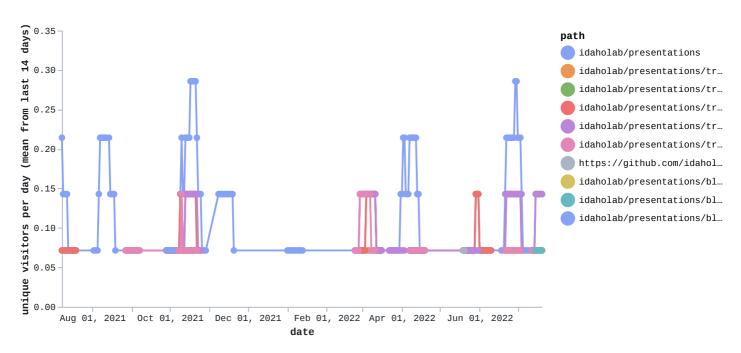
Note: Each data point in the plots shown below is influenced by the 14 days leading up to it. Each data point is the arithmetic mean of the "unique visitors per day" metric, built from a time window of 14 days width, and plotted at the right edge of that very time window. That is, these plots respond slowly to change (narrow peaks are smoothed out).

Top referrers



Top 15 referrers: 01: github.com, 02: mooseframework.inl.gov

Top paths



Top 15 paths: 01: idaholab/presentations, 02: idaholab/presentations/tree/master/moose_workshop/input, 03: idaholab/presentations/tree/master/moose_tms_2016/input, 04:

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idaholab/presentations/tree/master/moose\_tms\_2016\ , 05: \\ idaholab/presentations/tree/master/moose\_workshop\ , 06: \\ idaholab/presentations/tree/master/moose\_workshop/videos\ , 07: \\ https://github.com/idaholab/presentations\ , 08: \\ idaholab/presentations/blob/master/moose\_workshop/pics/bridge.png\ , 09: \\ idaholab/presentations/blob/master/moose\_workshop/pics/bridge-von-mises.png\ , 10: \\ idaholab/presentations/blob/master/moose\_tms\_2016/input/multiapps.i\ , 11: \\ idaholab/presentations/blob/master/moose\_tms\_2016/input/dampers.i\ , 12: \\ idaholab/presentations/blob/master/moose\_workshop/pics/close\_pack\_3d\_trans.png\ , 13: \\ idaholab/presentations/blob/master/moose\_workshop/build.py\ , 14: \\ idaholab/presentations/tree/master/blaster/slides\ , 15: \\ idaholab/presentations/blob/master/blaster/slides/RemarkSlide.py \\ \label{eq:control_def}
```