



THE UNIVERSITY OF QUEENSLAND
A U S T R A L I A

COURSE NOTES FOR STAT3001
MATHEMATICAL STATISTICS

CONTRIBUTORS:

MICHAEL CICCOTOSTO-CAMP
NAME2

THE UNIVERSITY OF QUEENSLAND
SCHOOL OF MATHEMATICS AND PHYSICS

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SYMBOLS AND NOTATION

Matrices are capitalized bold face letters while vectors are lowercase bold face letters.

<i>Syntax</i>	<i>Meaning</i>
\triangleq	An equality which acts as a statement
$ \mathbf{A} $	The determinate of a matrix.
$\mathbf{x}^\top, \mathbf{X}^\top$	The transpose operator.
$\mathbf{x}^*, \mathbf{X}^*$	The hermitian operator.
$\mathbf{a}.*\mathbf{b}$ or $\mathbf{A}.*\mathbf{B}$	Element-wise vector (matrix) multiplication, similar to Matlab.
\propto	Proportional to.
∇ or $\nabla_{\mathbf{f}}$	The partial derivative (with respect to \mathbf{f}).
$\nabla\nabla$ or $H(f)$	The Hessian.
\sim	Distributed according to, example $X \sim \mathcal{N}(0, 1)$
$\overset{\text{iid}}{\sim}$	Identically and independently distributed according to, example $X_1, X_2, \dots, X_n \overset{\text{iid}}{\sim} \mathcal{N}(0, 1)$
$\mathbf{0}$ or $\mathbf{0}_n$ or $\mathbf{0}_{n \times m}$	The zero vector (matrix) of appropriate length (size) or the zero vector of length n or the zero matrix with dimensions $n \times m$.
$\mathbf{1}$ or $\mathbf{1}_n$ or $\mathbf{1}_{n \times m}$	The one vector (matrix) of appropriate length (size) or the one vector of length n or the one matrix with dimensions $n \times m$.
$\mathbb{1}_A(x)$	The indicator function. $\mathbb{1}_A(x) = 1$ if $x \in A$, 0 otherwise.

$\mathbf{A}_{(:,*)}$	Index slicing to extract a submatrix from the elements of $\mathbf{A} \in \mathbb{R}^{n \times m}$, similar to indexing slicing from the python and Matlab programming languages. Each parameter can receive a single value or a 'slice' consisting of a start and an end value separated by a semicolon. The first and second parameter describe what row and columns should be selected, respectively. A single value means that only values from the single specified row/column should be selected. A slice tells us that all rows/columns between the provided range should be selected. Additionally if now start and end values are specified in the slice then all rows/columns should be selected. For example, the slice $\mathbf{A}_{(1:3,j:j')}$ is the submatrix $\mathbb{R}^{3 \times (j'-j+1)}$ matrix containing the first three rows of \mathbf{A} and columns j to j' . As another example, $\mathbf{A}_{(:,j)}$ is the j^{th} column of \mathbf{A} .
\mathbf{A}^\dagger	Denotes the unique psuedo inverse or Moore-Penore inverse of \mathbf{A} .
\mathbb{C}	The complex numbers.
$\text{diag}(\mathbf{w})$	Vector argument, a diagonal matrix containing the elements of vector \mathbf{w} .
$\text{diag}(\mathbf{W})$	Matrix argument, a vector containing the diagonal elements of the matrix \mathbf{W} .
\mathbb{E} or $\mathbb{E}_{q(x)}[z(x)]$	Expectation, or expectation of $z(x)$ where $x \sim q(x)$.
\mathbb{R}	The real numbers.
$\text{tr}(\mathbf{A})$	The trace of a matrix.
\mathbb{V} or $\mathbb{V}_{q(x)}[z(x)]$	Variance, the variance of $z(x)$ when $x \sim q(x)$.
\mathbb{Z}	The integers, $\mathbb{Z} = \{\dots, -2, -1, 0, 1, 2, \dots\}$.
Ω	The sample space.

REVIEW

Theorems and definitions here are mostly concepts seen before from other courses.

Useful Formulae and Theorems.

(Geometric Series)
$$\sum_{k=0}^{n-1} r^k = \left(\frac{1 - r^n}{1 - r} \right)$$

or

$$\sum_{i=0}^{\infty} r^i = \frac{1}{1 - r} \quad \text{with} \quad |r| < 1$$

(Euler's formula)
$$e^{ix} = \cos x + i \sin x$$

(Newton's Binomial formula)
$$(a + b)^n = \sum_{k=0}^n \binom{n}{k} a^{n-k} b^k$$

Theorem 1 (Young's inequality for products). *If $a \geq 0$ and $b \geq 0$ are nonnegative real numbers and if $p > 1$ and $q > 1$ are real numbers such that $\frac{1}{p} + \frac{1}{q} = 1$, then*

$$ab \leq \frac{a^p}{p} + \frac{b^q}{q}.$$

Equality holds iff $a^p = b^q$.

Common Distributions. Common distributions seen from prior courses. Notations mostly borrowed from STAT2003.

<i>Name</i>	<i>Notation</i>	<i>Support</i>	<i>pf</i>	<i>Expectation</i>	<i>Variance</i>
Bernoulli	$\text{Ber}(p)$	$\{0, 1\}$	$p^k(1-p)^{1-k}$	p	$p(1-p)$
Binomial	$\text{Bin}(n, p)$	$\{0, \dots, n\}$	$\binom{n}{k} p^k (1-p)^{n-k}$	np	$np(1-p)$
Negative-Binomial	$\text{NB}(r, p)$	\mathbb{N}_0	$\binom{x+r-1}{x} p^x (1-p)^r$	$\frac{rp}{1-p}$	$\frac{rp}{(1-p)^2}$
Geometric	$\text{Geo}(n, p)$	\mathbb{N}_0	$(1-p)^k p$	$\frac{1-p}{p}$	$\frac{1-p}{p^2}$
Poisson	$\text{Poi}(\lambda)$	\mathbb{N}_0	$\frac{\lambda^x}{x!} e^{-\lambda}$	λ	λ
Uniform	$\text{U}[a, b]$	$[a, b]$	$\frac{1}{b-a}$	$\frac{a+b}{2}$	$\frac{(a-b)^2}{12}$
Exponential	$\text{Exp}(\lambda)$	\mathbb{R}^+	$\lambda e^{-\lambda x}$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$
Normal	$\text{N}(\mu, \sigma^2)$	\mathbb{R}	$\frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right)$	μ	σ^2
Gamma	$\text{Gam}(\alpha, \lambda)$	\mathbb{R}^+	$\frac{\lambda^\alpha x^{\alpha-1} \exp(-\lambda x)}{\Gamma(\alpha)}$	$\frac{\alpha}{\lambda}$	$\frac{\alpha}{\lambda^2}$
Chi-Squared	χ_n^2	\mathbb{R}^+	$\frac{x^{\frac{n}{2}-1} \exp(-\frac{1}{2}x)}{2^{\frac{n}{2}} \Gamma(\frac{n}{2})}$	n	$2n$
White-Noise	$\text{WN}(\mu, \sigma^2)$	NA	NA	μ	σ^2

Common Probabilistic Properties and Identities. Common probabilistic properties seen from prior courses.

Probabilistic Properties. For any random variables, the following hold.

$$(1) \quad \mathbb{E}(X) = \int_0^\infty (1 - F(X)) \, dx$$

$$(2) \quad \mathbb{E}(aX + b) = a\mathbb{E}X + b$$

$$(3) \quad \mathbb{E}(g(X) + h(X)) = \mathbb{E}g(X) + \mathbb{E}h(X)$$

$$(4) \quad \text{Var}(X) = \mathbb{E}X^2 - (\mathbb{E}X)^2$$

$$(5) \quad \text{Var}(aX + b) = a^2\text{Var}(X)$$

$$(6) \quad \text{Cov}(X, Y) = \mathbb{E}XY - \mathbb{E}X\mathbb{E}Y$$

$$(7) \quad \text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$$

$$(8) \quad \mathbb{E}[X] = \mathbb{E}[\mathbb{E}[X | Y]]$$

$$(9) \quad \text{Var}(Y) = \mathbb{E}[\text{Var}(Y|X)] + \text{Var}(\mathbb{E}[Y|X])$$

$$(10) \quad |\mathbb{E}(XY)|^2 \leq \mathbb{E}(X^2)\mathbb{E}(Y^2)$$

$$(11) \quad |\text{Cov}(XY)|^2 \leq \text{Var}(X)\text{Var}(Y)$$

$$(12) \quad \mathbb{P}(A | B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}$$

$$(\text{Bayes' Theorem}) \quad \mathbb{P}(A | B) = \frac{\mathbb{P}(B | A)\mathbb{P}(A)}{\mathbb{P}(B)}$$

$$(13) \quad \mathbb{P}(A_1, \dots, A_n) = \mathbb{P}(A_1) \mathbb{P}(A_2 | A_1) \mathbb{P}(A_3 | A_1, A_2) \cdots \mathbb{P}(A_n | A_1, A_2, \dots, A_{n-1})$$

$$(14)$$

Let $\Omega = \bigcup_{i=1}^n B_i$ (that is B_i partitions the sample space) then

$$(\text{TLoP}) \quad \mathbb{P}(A) = \sum_{i=1}^n \mathbb{P}(A | B_i)\mathbb{P}(B_i)$$

$$(\text{TLoE}) \quad \mathbb{E}(A) = \sum_{i=1}^n \mathbb{E}(A | B_i)\mathbb{P}(B_i)$$

which, when **TLoP** used in conjunction with Bayes' Rule gives

$$(15) \quad \mathbb{P}(B_i | A) = \frac{\mathbb{P}(A | B_i)\mathbb{P}(B_i)}{\sum_{j=1}^n \mathbb{P}(A | B_j)\mathbb{P}(B_j)}.$$

If $X_1, X_2, \dots, X_n \stackrel{\text{iid}}{\sim} \text{WN}(\mu, \sigma^2)$ and $S_n = \sum_{i=1}^n X_i$, then for all $\epsilon > 0$

$$(\text{Weak Law of Large Numbers}) \quad \mathbb{P}\left(\left|\frac{S_n}{n} - \mu\right| \geq \epsilon\right) = 0.$$

If $X_1, X_2, \dots, X_n \stackrel{\text{iid}}{\sim} \text{WN}(\mu, \sigma^2)$ and $S_n = \sum_{i=1}^n X_i$, then for all $x \in \mathbb{R}$

$$(CLT) \quad \mathbb{P}\left(\frac{S_n - n\mu}{\sigma\sqrt{n}} \leq x\right) = \Phi(x).$$

If X is a random variable and h is a convex function then

$$(\text{Jensens Inequality}) \quad h(\mathbb{E}(X)) \leq \mathbb{E}(h(X)).$$

Probabilistic Identities. If $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \text{Ber}(p)$ then

$$(16) \quad \sum_{i=1}^n X_i \sim \text{Bin}(n, p).$$

If $X \sim \text{Bin}(n, p)$ and $Y \sim \text{Bin}(m, p)$, then $X + Y \sim \text{Bin}(n + m, p)$.

If $X \sim \text{N}(\mu_X, \sigma_X^2)$ and $Y \sim \text{N}(\mu_Y, \sigma_Y^2)$, then $X + Y \sim \text{N}(\mu_X + \mu_Y, \sigma_X^2 + \sigma_Y^2)$.

If $X_1, X_2, \dots, X_n \stackrel{\text{iid}}{\sim} \mathcal{N}(0, 1)$ then

$$(17) \quad \sum_{i=1}^n X_i^2 = \chi_n^2.$$

POINT ESTIMATION

Methods of Finding Estimates Introduction.

Definition 2 (Statistic). Let X_1, \dots, X_n be a random sample of size n from a population and let $T(x_1, \dots, x_n)$ be a real-valued or vector-valued function whose domain includes the sample space of (X_1, \dots, X_n) . The random variable or random vector $Y = T(X_1, \dots, X_n)$ is called a **statistic**. The probability distribution of a statistic Y is called the **sampling distribution** of Y [Cas01, page 211].

Definition 3 (Sample Mean). The **sample mean** is the arithmetic average of the values in a random sample. It is usually denoted by

$$(18) \quad \bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

[Cas01, page 212].

Definition 4 (Sample Variance and Standard Deviation). The **sample variance** is the statistic defined by

$$(19) \quad S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2.$$

The **sample standard deviation** is the statistic defined by $S = \sqrt{S^2}$ [Cas01, page 212].

Definition 5 (Sufficient Statistic). A statistic $T(\mathbf{X})$ is a **sufficient statistic** for θ if the conditional distribution of the sample \mathbf{X} given the value of $T(\mathbf{X})$ does not depend on θ [Cas01, page 272].

Theorem 6. If $p(\mathbf{x} \mid \theta)$ is the joint pdf or pmf of \mathbf{X} and $q(\theta \mid \theta)$ is the pdf or pmf of $T(\mathbf{X})$, then $T(\mathbf{X})$ is a sufficient statistic for θ if, for every \mathbf{x} in the sample space, the ratio $p(\mathbf{x} \mid \theta)/q(T(\mathbf{x}) \mid \theta)$ is a constant function of θ [Cas01, page 274].

Theorem 7 (Factorization Theorem). Let $f(\mathbf{x} \mid \theta)$ denote the joint pdf or pmf of a sample \mathbf{X} . A statistic $T(\mathbf{X})$ is a sufficient statistic for θ , if and only if there exist function $g(t \mid \theta)$ and $h(\mathbf{x})$ such that, for all sample points \mathbf{x} and all parameter points θ ,

$$f(\mathbf{x} \mid \theta) = g(T(\mathbf{x}) \mid \theta)h(\mathbf{x})$$

[Cas01, page 276].

Example 8 (Uniform Sufficient Statistic). Example taken from [Cas01, page 277] and can also be found on tutorial sheet 3. Let X_1, \dots, X_n be iid observations from the discrete uniform distribution on $1, \dots, \theta$. That is, the unknown parameter, θ , is a positive integer and the pmf of X_i is

$$f(x \mid \theta) = \begin{cases} \frac{1}{\theta}, & x = 1, 2, \dots, \theta \\ 0, & \text{otherwise} \end{cases}.$$

The restriction $x_i \in \{1, \dots, \theta\}$ for $i = 1, \dots, n$ can be re-expressed as $x_i \in \{1, 2, \dots\}$ for $i = 1, \dots, n$ (note that there is no θ in this restriction) and $\max_i x_i \leq \theta$. If we define $T(\mathbf{x}) = \max_i x_i = x_{(n)}$,

$$h(\mathbf{x}) = \begin{cases} 1, & x_i \in \{1, \dots, \theta\} \text{ for } i = 1, \dots, n \\ 0, & \text{otherwise} \end{cases}$$

and

$$g(t \mid \theta) = \begin{cases} \theta^{-n} & t \leq \theta \\ 0, & \text{otherwise} \end{cases}.$$

It is easily verified that $f(\mathbf{x} \mid \theta) = g(T(\mathbf{x}) \mid \theta)$ for all \mathbf{x} and θ . Thus, according to Theorem 7, the largest order statistic, $T(\mathbf{X}) = X_{(n)}$, is a sufficient statistic in this problem. This type of analysis can sometimes be carried out more clearly and concisely using indicator function. Let \mathbb{N} be the set of natural numbers (discluding 0) and \mathbb{N}_θ be the natural numbers up to and including θ . Then the joint pmf of X_1, \dots, X_n is

$$f(\mathbf{x} \mid \theta) = \prod_{i=1}^n \theta^{-1} \mathbb{1}_{\mathbb{N}_\theta}(x_i) = \theta^{-n} \prod_{i=1}^n \mathbb{1}_{\mathbb{N}_\theta}(x_i).$$

Defining $T(\mathbf{x}) = x_{(n)}$, we see that

$$\prod_{i=1}^n \mathbb{1}_{\mathbb{N}_\theta}(x_i) = \left(\prod_{i=1}^n \mathbb{1}_{\mathbb{N}}(x_i) \right) \mathbb{1}_{\mathbb{N}_\theta}(T(\mathbf{x}))$$

thus providing the factorization

$$f(\mathbf{x} \mid \theta) = \theta^{-n} \mathbb{1}_{\mathbb{N}_\theta}(T(\mathbf{x})) \left(\prod_{i=1}^n \mathbb{1}_{\mathbb{N}}(x_i) \right).$$

The first factor depends on x_1, \dots, x_n only through the value of $T(\mathbf{x}) = x_{(n)}$, and the second factor does not depend on θ . Again, according to Theorem 7, $T(\mathbf{X}) = X_{(n)}$, is a sufficient statistic in this problem.

Definition 9 (Likelihood, Log-Likelihood and Score Function). *Let $f(\mathbf{x} \mid \theta)$ denote the joint pdf or pmf of the sample $\mathbf{X} = (X_1, \dots, X_n)$. Then, given that $\mathbf{X} = \mathbf{x}$ is observed, the function of θ defined by*

$$L(\theta \mid \mathbf{x}) = f(\mathbf{x} \mid \theta)$$

*is called the **likelihood function** [Cas01, page 290]. For a given outcome \mathbf{x} of \mathbf{X} , the **log-likelihood function**, denoted l , is the natural logarithm of the likelihood function*

$$l(\theta \mid \mathbf{x}) = \ln L(\theta \mid \mathbf{x}) = \ln f(\mathbf{x} \mid \theta).$$

*It's gradient with respect to θ , denoted S , is called the **score function***

$$S(\theta \mid \mathbf{x}) = \nabla_\theta l(\theta \mid \mathbf{x}) = \frac{\nabla_\theta f(\mathbf{x} \mid \theta)}{f(\mathbf{x} \mid \theta)}$$

[Kro13, page 165].

Theorem 10. *Under regularity conditions*

$$\mathbb{E}[S(\theta \mid \mathbf{x})] = 0$$

[Background Notes, page 10].

Proof. Since $L(\theta)$ is a density when viewed as a function of the observed data x_1, \dots, x_n we have the following identity in θ ,

$$\int \dots \int L(\theta) dx_1 \dots dx_n = 1.$$

On differentiating both sides of the above with respect to θ gives

$$\int \dots \int \left[\frac{\partial L(\theta)}{\partial \theta} \right] dx_1 \dots dx_n = 0.$$

Apply the chain rule to $\frac{\partial \ln L(\theta)}{\partial \theta}$ we find

$$\frac{\partial \ln L(\theta)}{\partial \theta} = \frac{\partial \ln L(\theta)}{\partial L(\theta)} \cdot \frac{\partial L(\theta)}{\partial \theta} = \frac{1}{L(\theta)} \frac{\partial L(\theta)}{\partial \theta}$$

meaning

$$\frac{\partial \ln L(\theta)}{\partial \theta} L(\theta) = \frac{\partial L(\theta)}{\partial \theta}$$

so that

$$\begin{aligned} \int \cdots \int \left[\frac{\partial L(\theta)}{\partial \theta} \right] dx_1 \cdots dx_n &= 0 \\ \int \cdots \int \left[\frac{\partial \ln L(\theta)}{\partial \theta} \right] L(\theta) dx_1 \cdots dx_n &= 0 \\ \mathbb{E}[S(\theta)] &= 0 \end{aligned}$$

as wanted. \square

Definition 11 (Exponential Family). In the case of p -dimensional observation $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n \in \mathbb{C}^p$, a d -dimensional parameter vector $\boldsymbol{\theta} \in \mathbb{C}^d$, and a q -dimensional sufficient statistic $T(\mathbf{x}_1, \dots, \mathbf{x}_n) \in \mathbb{C}^q$, the likelihood function $L(\boldsymbol{\theta})$ for the d -parameter vector $\boldsymbol{\theta}$ has the following form if it belongs to the d -parameter **exponential family**

$$L(\boldsymbol{\theta}) = b(\mathbf{x}_1, \dots, \mathbf{x}_n) \exp \{ c(\boldsymbol{\theta})^\top T(\mathbf{x}_1, \dots, \mathbf{x}_n) \} / a(\boldsymbol{\theta})$$

where $c(\boldsymbol{\theta}) \in \mathbb{C}^q$ and $b(\mathbf{x}_1, \dots, \mathbf{x}_n)$ and $a(\boldsymbol{\theta})$ are scalar functions [Cas01, page 279].

Theorem 12. Let $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_n$ be iid observations from a pdf or pmf $f(\mathbf{x} \mid \boldsymbol{\theta})$ that belongs to an exponential family as seen in Definition 11, then

$$T(\mathbf{X}_1, \dots, \mathbf{X}_n) = \left(\sum_{j=1}^n t_1(\mathbf{X}_j), \dots, \sum_{j=1}^n t_k(\mathbf{X}_j) \right)$$

is a sufficient statistic for $\boldsymbol{\theta}$ [Cas01, page 279].

Definition 13 (Minimal Sufficient Statistic). A sufficient statistic $T(\mathbf{X})$ is called a **minimal sufficient statistic** if, for any other sufficient statistic $T'(\mathbf{X})$, $T(\mathbf{x})$ is a function of $T'(\mathbf{x})$ [Cas01, page 280].

Theorem 14. Let $f(\mathbf{x} \mid \boldsymbol{\theta})$ be the pdf of a sample \mathbf{X} . Suppose there exists a function $T(\mathbf{x})$ such that, for every two sample points \mathbf{x} and \mathbf{y} , the ratio $f(\mathbf{x} \mid \boldsymbol{\theta}) / f(\mathbf{y} \mid \boldsymbol{\theta})$ is constant as a function of $\boldsymbol{\theta}$ if and only if $T(\mathbf{x}) = T(\mathbf{y})$. Then $T(\mathbf{X})$ is a minimal sufficient statistic [Cas01, page 281].

Example 15 (Normal Minimal Sufficient Statistic). Example taken from [Cas01, page 281]. Let $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, \sigma^2)$, where both μ and σ^2 unknown. Let \mathbf{x} and \mathbf{y} denote two sample points, and let (\bar{x}, s_x^2) and (\bar{y}, s_y^2) be the sample means and variances corresponding to the \mathbf{x} and \mathbf{y} samples, respectively. Then, the ratio of the densities becomes

$$\begin{aligned} \frac{f(\mathbf{x} \mid \mu, \sigma^2)}{f(\mathbf{y} \mid \mu, \sigma^2)} &= \frac{(2\pi\sigma^2)^{-n/2} \exp \left(- \left[n(\bar{x} - \mu)^2 + (n-1)s_x^2 \right] / (2\sigma^2) \right)}{(2\pi\sigma^2)^{-n/2} \exp \left(- \left[n(\bar{y} - \mu)^2 + (n-1)s_y^2 \right] / (2\sigma^2) \right)} \\ &= \exp \left(\left[-n(\bar{x}^2 - \bar{y}^2) + 2n\mu(\bar{x} - \bar{y}) - (n-1)(s_x^2 - s_y^2) \right] / (2\sigma^2) \right). \end{aligned}$$

This ratio will be constant as a function of μ and σ^2 if and only if $\bar{x} = \bar{y}$ and $s_x^2 = s_y^2$. Thus by Theorem 14, (\bar{X}, S^2) is a minimal sufficient statistic for (μ, σ^2) .

Definition 16 (Ancillary Statistic). A statistic $S(\mathbf{X})$ whose distribution does not depend on the parameter θ is called an ancillary statistic [Cas01, page 282].

Definition 17 (Complete Distributions and Statistics). Let $f(t | \theta)$ be a family of pdfs or pmfs for a statistic $T(\mathbf{X})$. The family of probability distributions is called **complete** if $\mathbb{E}_\theta g(T) = 0$ for all θ implies $\mathbb{P}(g(T) = 0) = 1$ for all θ . Equivalently, $T(\mathbf{X})$ is called a **complete statistic** [Cas01, page 285].

Example 18 (Binomial Complete Statistic). Example taken from [Cas01, page 285]. Suppose that T has a $\text{Bin}(n, p)$ distribution, $0 < p < 1$. Let g be a function such that $\mathbb{E}_p g(T) = 0$. Then

$$\begin{aligned} 0 = \mathbb{E}_p g(T) &= \sum_{t=0}^n g(t) \binom{n}{t} p^t (1-p)^{n-t} \\ &= (1-p)^n \sum_{t=0}^n g(t) \binom{n}{t} \left(\frac{p}{1-p}\right)^t \end{aligned}$$

for all p , $0 < p < 1$. The factor $(1-p)^n$ is not 0 for any p in this range. Thus it must be that

$$0 = \sum_{t=0}^n g(t) \binom{n}{t} \left(\frac{p}{1-p}\right)^t = \sum_{t=0}^n g(t) \binom{n}{t} r^t$$

for all, $0 < r < \infty$. But the last expression is a polynomial of degree n in r , where the coefficient of r^t is $g(t) \binom{n}{t}$. For the polynomial to be 0 for all r , each coefficient must be 0. Since none of the $\binom{n}{t}$ terms is 0, this implies that $g(t) = 0$ for $t = 0, 1, \dots, n$. Since T takes on the values $0, 1, \dots, n$ with probability 1, this means that $\mathbb{P}_p(g(T) = 0) = 1$ for all p , the desired conclusion. Hence, T is a complete statistic.

Definition 19 (Point Estimator). A **point estimator** is any function $W(X_1, \dots, X_n)$ of a sample; that is, any statistic (see Definition 2) is a point estimator [Cas01, page 311].

Definition 20 (Fisher Information Matrix). For the model $\mathbf{X} \sim f(\cdot; \theta)$, let $S(\theta)$ be the score function (see Definition 9) of θ . The covariance matrix of the random vector $S(\theta)$, denoted by $\mathcal{J}(\theta)$, is called the **Fisher Information Matrix** where

$$\mathcal{J}(\theta) = \mathbb{E}_\theta [S(\theta) S(\theta)^\top]$$

in the multivariate case and

$$\mathcal{J}(\theta) = \mathbb{E}_\theta \left(\frac{d}{d\theta} \ln f(\mathbf{X}; \theta) \right)^2$$

in the one-dimensional case. Note that under regularity conditions $\mathbb{E}[S(\theta)] = 0$ (see Theorem 10) so that

$$\begin{aligned} \mathcal{J}(\theta) &= \mathbb{E}_\theta \left[\frac{d}{d\theta} \ln f(\mathbf{X}; \theta) \right]^2 \\ &= \text{Var}_\theta \left(\frac{d}{d\theta} \ln f(\mathbf{X}; \theta) \right) + \left(\mathbb{E}_\theta \left[\frac{d}{d\theta} \ln f(\mathbf{X}; \theta) \right] \right)^2 \\ &= \text{Var}_\theta (S(\theta)) + (\mathbb{E}_\theta [S(\theta)])^2 \\ &= \text{Var}_\theta (S(\theta)) \end{aligned}$$

[Kro13, page 168].

Definition 21 (Observed Information). For the model $\mathbf{X} \sim f(\cdot; \boldsymbol{\theta})$, let $S(\boldsymbol{\theta})$ be the score function (see Definition 9) of $\boldsymbol{\theta}$. The negative of the Hessian of the random vector $S(\boldsymbol{\theta})$, denoted by $I(\boldsymbol{\theta})$, is called the **Observed Information** where

$$I(\boldsymbol{\theta}) = -\nabla \nabla S(\boldsymbol{\theta})$$

in the multivariate case and

$$I(\boldsymbol{\theta}) = -\frac{\partial^2}{\partial \theta^2} \ln f(\mathbf{X}; \boldsymbol{\theta})$$

in the one-dimensional case [Background Notes, page 8].

Theorem 22. Under regularity conditions, the following equality holds

$$\mathcal{J}(\boldsymbol{\theta}) = \mathbb{E}[I(\boldsymbol{\theta})]$$

[Kro13, page 169].

Theorem 23 (Fisher Information Matrix for iid Data). Let $\mathbf{X} = (X_1, \dots, X_n) \stackrel{iid}{\sim} f(x; \boldsymbol{\theta})$, and let $\mathring{\mathcal{J}}(\boldsymbol{\theta})$ be the information matrix corresponding to $X \sim f(x; \boldsymbol{\theta})$. Then the information matrix for \mathbf{X} is given by

$$\mathcal{J}(\boldsymbol{\theta}) = n\mathring{\mathcal{J}}(\boldsymbol{\theta})$$

[Kro13, page 170].

Theorem 24. If the $L(\boldsymbol{\theta})$ belongs to the regular exponential family, then the likelihood equation

$$\frac{d}{d\boldsymbol{\theta}} \ln L(\boldsymbol{\theta}) = \mathbf{0},$$

can be expressed as

$$T(\mathbf{x}_1, \dots, \mathbf{x}_n) = \mathbb{E}[T(\mathbf{X}_1, \dots, \mathbf{X}_n)]$$

[Lecture Notes 1, page 8].

Method of Moments.

Definition 25 (Method of Moments). Let X_1, \dots, X_n be a random sample of size n from a population with pf $f(x \mid \theta_1, \dots, \theta_k)$. Method of moments estimators are found by equating the first k sample moments to the corresponding k population moments, and solving the resulting system of simultaneous equations. More precisely, define

$$\begin{aligned} m_1 &= \frac{1}{n} \sum_{i=1}^n X_i^1, & \mu'_1 &= \mathbb{E}X^1 \\ m_2 &= \frac{1}{n} \sum_{i=1}^n X_i^2, & \mu'_2 &= \mathbb{E}X^2 \\ &\vdots \\ m_k &= \frac{1}{n} \sum_{i=1}^n X_i^k, & \mu'_k &= \mathbb{E}X^k. \end{aligned}$$

The population moment μ'_j will typically be a function of $\theta_1, \dots, \theta_k$, say $\mu'_j(\theta_1, \dots, \theta_k)$. The method of moments estimator $(\tilde{\theta}_1, \dots, \tilde{\theta}_k)$ of $(\theta_1, \dots, \theta_k)$ is obtained by solving the following system of equations for $(\theta_1, \dots, \theta_k)$ in terms of (m_1, \dots, m_k)

$$\begin{aligned} m_1 &= \mu'_1(\theta_1, \dots, \theta_k) \\ m_2 &= \mu'_2(\theta_1, \dots, \theta_k) \\ &\vdots \\ m_k &= \mu'_k(\theta_1, \dots, \theta_k) \end{aligned}$$

[Cas01, page 312].

Example 26 (Normal Methods of Moments). Example taken from [Cas01, page 313]. Suppose $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \mathbf{N}(\theta, \sigma^2)$. In the preceding notation, $\theta_1 = \theta$ and $\theta_2 = \sigma^2$. We have $m_1 = \bar{X}$, $m_s = (1/n) \sum X_i^2$, $\mu'_1 = \theta$, $\mu'_2 = \theta^2 + \sigma^2$, and hence we must solve

$$\bar{X} = \theta, \quad \frac{1}{n} \sum X_i^2 = \theta^2 + \sigma^2.$$

Solving for θ and σ^2 yields the methods of moments estimators

$$\tilde{\theta} = \bar{X} \quad \text{and} \quad \tilde{\sigma}^2 = \frac{1}{n} \sum X_i^2 - \bar{X}^2 = \frac{1}{n} \sum (X_i^2 - \bar{X}^2).$$

Maximum Likelihood Estimates.

Definition 27 (Maximum Likelihood Estimator). For each sample point \mathbf{x} , let $\hat{\theta}(\mathbf{x})$ be a parameter value at which $L(\theta | \mathbf{x})$ attains its maximum as a function of θ , with \mathbf{x} held fixed. A **maximum likelihood estimator (MLE)** of the parameter θ based on a sample \mathbf{X} is $\hat{\theta}(\mathbf{X})$ [Cas01, page 316].

Example 28 (Normal Likelihood). Example taken from [Cas01, page 316]. Suppose $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \mathcal{N}(\theta, 1)$, and let $L(\theta | \mathbf{x})$ denote the likelihood function. Then

$$L(\theta | \mathbf{x}) = \prod_{i=1}^n \frac{1}{(2\pi)^{1/2}} \exp\left(-(1/2)(x_i - \theta)^2\right) = \frac{1}{(2\pi)^{1/2}} \exp\left(-(1/2) \sum_{i=1}^n (x_i - \theta)^2\right).$$

The equation $(d/d\theta)L(\theta | \mathbf{x}) = 0$ reduces to

$$\sum_{i=1}^n (x_i - \theta) = 0,$$

which has the solution $\hat{\theta} = \bar{x}$. Hence, \bar{x} is a candidate for the MLE. To verify that \bar{x} is, in fact, a global maximum of the likelihood function, we can use the following argument. First, note that $\hat{\theta} = \bar{x}$ is the only solution to $\sum_{i=1}^n (x_i - \theta) = 0$; hence \bar{x} is the only zero of the first derivative. Second, verify that

$$\frac{d^2}{d\theta^2} L(\theta | \mathbf{x})|_{\theta=\bar{x}} < 0.$$

Thus, \bar{x} is the only extreme point in the interior and it is a maximum. To finally verify that \bar{x} is a global maximum, we must check the boundaries at $\pm\infty$. So $\hat{\theta} = \bar{x}$ is a global maximum and hence \bar{X} is the MLE.

Theorem 29. If $\hat{\theta}$ is the MLE of θ , then for any function $\tau(\theta)$, the MLE of $\tau(\theta)$ is $\tau(\hat{\theta})$ [Cas01, page 320].

Example 30 (Normal MLE, μ and σ unknown). Example taken from [Cas01, page 321]. Suppose $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \mathcal{N}(\theta, \sigma^2)$ with both μ and σ^2 unknown. Then

$$L(\theta | \mathbf{x}) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left(-(1/2) \sum_{i=1}^n (x_i - \theta)^2 / \sigma^2\right)$$

and

$$\ln L(\theta | \mathbf{x}) = -\frac{n}{2} \ln 2\pi - \frac{n}{2} \ln \sigma^2 - \frac{1}{2} \sum_{i=1}^n (x_i - \theta)^2 / \sigma^2.$$

The partial derivatives, with respect to θ and σ^2 are

$$\frac{\partial}{\partial \theta} \ln L(\theta | \mathbf{x}) = \frac{1}{\sigma^2} \sum_{i=1}^n (x_i - \theta)$$

and

$$\frac{\partial}{\partial \sigma^2} \ln L(\sigma^2 | \mathbf{x}) = -\frac{1}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^n (x_i - \theta)^2.$$

Setting the partial derivatives equal to 0 and solving for the solution $\hat{\theta} = \bar{x}$, $\hat{\sigma}^2 = n^{-1} \sum_{i=1}^n (x_i - \bar{x})^2$. To verify that this solution is, in fact, a global maximum, recall first that if $\theta \neq \bar{x}$, then $\sum (x_i - \theta)^2 >$

$\sum (x_i - \bar{x})^2$. Hence, for any value of σ^2 ,

$$\frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left(-(1/2) \sum_{i=1}^n (x_i - \bar{x})^2 / \sigma^2 \right) \geq \frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left(-(1/2) \sum_{i=1}^n (x_i - \theta)^2 / \sigma^2 \right).$$

Therefore, verifying that we have found the maximum likelihood estimators is reduced to a one-dimensional problem, verifying that $(\sigma^2)^{-n/2} \exp \left(-\frac{1}{2} \sum (x_i - \bar{x})^2 / \sigma^2 \right)$ achieves its global maximum at $\sigma^2 = n^{-1} \sum (x_i - \bar{x})^2$. This is straightforward to do using univariate calculus and, in fact, the estimators $(\bar{X}, n^{-1} \sum (X_i - \bar{X})^2)$ are the MLEs.

Methods of Evaluating Estimators.

Definition 31 (Mean Square Error). The **mean square error** (MSE) of an estimator W of a parameter θ is the function θ defined by $\mathbb{E}_\theta(W - \theta)^2$ [Cas01, page 330].

Definition 32 (Bias). The **bias** of an estimator W of a parameter θ is the difference between the expected value of W and θ ; that is $\text{Bias}_\theta W = \mathbb{E}_\theta W - \theta$. An estimator whose bias is identically (in θ) equal to 0 is called an **unbiased estimator** and satisfies $\mathbb{E}_\theta W = \theta$ for all θ [Cas01, page 330].

It is important to note that

$$\mathbb{E}_\theta (W - \theta)^2 = \text{Var}_\theta W + (\mathbb{E}_\theta W - \theta)^2 = \text{Var}_\theta W + (\text{Bias}_\theta W)^2.$$

Example 33 (Normal MSE). Example taken from [Cas01, page 331]. Let $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} N(\mu, \sigma^2)$. The statistics \bar{X} and S^2 are both unbiased estimators since

$$\mathbb{E}\bar{X} = \mu, \quad \mathbb{E}S^2 = \sigma^2, \quad \text{for all } \mu \text{ and } \sigma^2.$$

The MSEs of these estimators are given by

$$\begin{aligned} \mathbb{E}(\bar{X} - \mu)^2 &= \text{Var}\bar{X} = \frac{\sigma^2}{n} \\ \mathbb{E}(S^2 - \sigma^2)^2 &= \text{Var}S^2 = \frac{2\sigma^4}{n-1}. \end{aligned}$$

The MSE of \bar{X} remains σ^2/n even if the normality assumption is dropped. However, the above expression for the MSE of S^2 does not remain the same if the normality assumption is relaxed. An alternative estimator for σ^2 is the MLE $\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2 = \frac{n-1}{n} S^2$. It is straightforward to calculate

$$\mathbb{E}\hat{\sigma}^2 = \mathbb{E}\left(\frac{n-1}{n} S^2\right) = \frac{n-1}{n} \sigma^2,$$

so that $\hat{\sigma}^2$ is a biased estimator of σ^2 . The variance of $\hat{\sigma}^2$ can also be calculated as

$$\text{Var}\hat{\sigma}^2 = \text{Var}\left(\frac{n-1}{n} S^2\right) = \left(\frac{n-1}{n}\right)^2 \text{Var}S^2 = \frac{2(n-1)\sigma^4}{n^2},$$

and hence, its MSE is given by

$$\mathbb{E}(\hat{\sigma}^2 - \sigma^2)^2 = \frac{2(n-1)\sigma^4}{n^2} + \left(\frac{n-1}{n}\sigma^2 - \sigma^2\right)^2 = \left(\frac{2n-1}{n^2}\right)\sigma^4.$$

Thus we have

$$\mathbb{E}(\hat{\sigma}^2 - \sigma^2)^2 = \left(\frac{2n-1}{n^2}\right)\sigma^4 < \left(\frac{2}{n-1}\right)\sigma^4 = \mathbb{E}(S^2 - \sigma^2)^2,$$

showing that $\hat{\sigma}^2$ has a smaller MSE than S^2 . Thus, by trading off variance for bias, the MSE is improved.

Definition 34 (Best Unbiased Estimator). An estimator W^* is a **best unbiased estimator** of $\tau(\theta)$ if it satisfies $\mathbb{E}W^* = \tau(\theta)$ for all θ and, for any other estimator W with $\mathbb{E}W = \tau(\theta)$, we have $\text{Var}_\theta W^* \leq \text{Var}_\theta W$ for all θ . W^* is also called a **uniform minimum variance unbiased estimator** (UMVUE) of $\tau(\theta)$ [Cas01, page 334].

Theorem 35 (Cramer-Rao Inequality). Let X_1, \dots, X_n be a sample with pdf $f(\mathbf{x} \mid \theta)$, and let $W(\mathbf{X}) = W(X_1, \dots, X_n)$ be any estimator satisfying

$$\frac{d}{d\theta} \mathbb{E}_\theta W(\mathbf{X}) = \int_{\mathcal{X}} \frac{\partial}{\partial \theta} [W(\mathbf{x}) f(\mathbf{x} \mid \theta)]$$

and

$$\text{Var}_\theta W(\mathbf{X}) < \infty.$$

Then

$$\text{Var}_\theta(W(\mathbf{X})) \geq \frac{\left(\frac{d}{d\theta} \mathbb{E}_\theta W(\mathbf{X})\right)^2}{\mathbb{E}_\theta \left(\left(\frac{\partial}{\partial \theta} \ln f(\mathbf{X} | \theta)\right)^2\right)} = \frac{\left(\frac{d}{d\theta} \mathbb{E}_\theta W(\mathbf{X})\right)^2}{\mathcal{J}(\theta)}$$

[Cas01, page 335].

Corollary 36 (Cramer-Rao Inequality, iid Case). *If the assumptions of Theorem 35 are satisfied and, additionally, if X_1, \dots, X_n are iid with pdf $f(x | \theta)$, then*

$$\text{Var}_\theta(W(\mathbf{X})) \geq \frac{\left(\frac{d}{d\theta} \mathbb{E}_\theta W(\mathbf{X})\right)^2}{n \mathbb{E}_\theta \left(\left(\frac{\partial}{\partial \theta} \ln f(X | \theta)\right)^2\right)}$$

[Cas01, page 337].

Lemma 37. *If $f(x | \theta)$ satisfies*

$$\frac{d}{d\theta} \mathbb{E}_\theta \left(\frac{\partial}{\partial \theta} \ln f(X | \theta) \right) = \int \frac{\partial}{\partial \theta} \left[\left(\frac{\partial}{\partial \theta} \ln f(x | \theta) \right) f(x | \theta) \right] dx$$

(true for the exponential family), then

$$\mathbb{E}_\theta \left(\left(\frac{\partial}{\partial \theta} \ln f(X | \theta) \right)^2 \right) = -\mathbb{E}_\theta \left(\frac{\partial^2}{\partial \theta^2} \ln f(X | \theta) \right)$$

[Cas01, page 338].

Example 38 (Poisson Unbiased Estimate). Example taken from [Cas01, page 338]. Let $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \text{Poi}(\lambda)$, and let \bar{X} and S^2 be the sample mean and variance, respectively. Recall that for the Poisson pmf both the mean and variance are equal to λ . We have

$$\mathbb{E}_\lambda \bar{X} = \lambda, \quad \text{for all } \lambda,$$

$$\mathbb{E}_\lambda S^2 = \lambda, \quad \text{for all } \lambda,$$

so both \bar{X} and S^2 are unbiased estimators of λ . To determine the better estimator, \bar{X} or S^2 , we should now compare the variances. We have $\text{Var}_\lambda \bar{X} = \lambda/n$, but $\text{Var}_\lambda S^2$ is quite a lengthy calculation. Not only this, even if we can establish that \bar{X} is better than S^2 , consider the class of estimators

$$W_a(\bar{X}, S^2) = a\bar{X} + (1-a)S^2.$$

For every constant a , $\mathbb{E}_\lambda W_a = \lambda$, so now we have infinitely many unbiased estimators of λ . Instead, let us show that \bar{X} is the best estimator directly using the Cramer-Rao inequality. Here we are estimating $\tau(\lambda) = \lambda$, so that $\tau'(\lambda) = 1$. Also, since we have an exponential family, using Lemma 37 gives us

$$\begin{aligned} \mathbb{E}_\lambda \left(\left(\frac{\partial}{\partial \lambda} \ln f(X | \lambda) \right)^2 \right) &= -n \mathbb{E}_\lambda \left(\frac{\partial^2}{\partial \lambda^2} \ln f(X | \lambda) \right) \\ &= -n \mathbb{E}_\lambda \left(\frac{\partial^2}{\partial \lambda^2} \ln \left(\frac{e^{-\lambda} \lambda^X}{X!} \right) \right) \\ &= -n \mathbb{E}_\lambda \left(\frac{\partial^2}{\partial \lambda^2} (-\lambda + X \ln \lambda - \ln X!) \right) \end{aligned}$$

$$\begin{aligned}
&= -n\mathbb{E}_\lambda \left(-\frac{X}{\lambda^2} \right) \\
&= \frac{n}{\lambda}.
\end{aligned}$$

Hence for any unbiased estimator, W , of λ , from Corollary 36 we must have

$$\begin{aligned}
\text{Var}_\theta(W(\mathbf{X})) &\geq \frac{\left(\frac{d}{d\theta}\mathbb{E}_\theta W(\mathbf{X})\right)^2}{n\mathbb{E}_\theta \left(\left(\frac{\partial}{\partial\theta}\ln f(X|\theta)\right)^2\right)} \\
&= \frac{(1)^2}{\left(\frac{n}{\lambda}\right)} \\
&= \frac{\lambda}{n}.
\end{aligned}$$

Since $\text{Var}_\lambda \bar{X} = \lambda/n$, \bar{X} must be the best unbiased estimator.

Corollary 39 (Attainment). *Let X_1, \dots, X_n be a sample with pdf $f(x|\theta)$, where $f(x|\theta)$ satisfies the conditions of the Cramer-Rao Theorem. $L(\theta|\mathbf{x}) = \prod_{i=1}^n f(x_i|\theta)$ denote the likelihood function. If $W(\mathbf{X}) = W(X_1, \dots, X_n)$ is any unbiased estimator of $\tau(\theta)$, then $W(\mathbf{X})$ attains the Cramer-Rao Lower Bound if and only if*

$$a(\theta)[W(\mathbf{x}) - \tau(\theta)] = \frac{\partial}{\partial\theta} \ln L(\theta|\mathbf{x})$$

for some function $a(\theta)$ [Cas01, page 341].

Example 40 (Continuation of Example 30). Example taken from [Cas01, page 341]. Here we know

$$L(\mu, \sigma^2|\mathbf{x}) = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{1}{2}\sum_{i=1}^n (x_i - \mu)^2/\sigma^2\right),$$

and hence

$$\frac{\partial}{\partial\sigma^2} \ln L(\mu, \sigma^2|\mathbf{x}) = \frac{n}{2\sigma^4} \left(\sum_{i=1}^n \frac{(x_i - \mu)^2}{n} - \sigma^2 \right).$$

Thus, taking $a(\sigma^2) = n/(2\sigma^4)$ shows that the best unbiased estimator of σ^2 is $\frac{(x_i - \mu)^2}{n}$, which is calculable only if μ is known. If μ is not known, the bound cannot be attained.

Sufficiency and Unbiasedness.

Theorem 41 (Rao-Blackwell). *Let W be any unbiased estimator of $\tau(\theta)$, and let T be a sufficient statistic for θ . Define $\phi(T) = \mathbb{E}(W|T)$. Then $\mathbb{E}_\theta\phi(T) = \tau(\theta)$ and $\text{Var}_\theta\phi(T) \leq \text{Var}_\theta W$ for all θ ; that is, $\phi(T)$ is a uniformly better unbiased estimator of $\tau(\theta)$ [Cas01, page 342].*

Theorem 42. *If W is the best unbiased estimator of $\tau(\theta)$, then W is unique [Cas01, page 343].*

Theorem 43. *Let T be a complete sufficient statistic for a parameter θ , and let $\phi(T)$ be any estimator based only on T . Then $\phi(T)$ is the best unbiased estimator of its expected value [Cas01, page 347].*

Consistency.

Definition 44 (Consistency). A sequence of estimators T_n of $g(\boldsymbol{\theta})$ is said to be **consistent** if for every $\boldsymbol{\theta} \in \Omega$,

$$T_n \xrightarrow{\mathbb{P}} g(\boldsymbol{\theta}), \quad \text{as } n \rightarrow \infty$$

that is, given any $\varepsilon > 0$, then

$$\mathbb{P} [|T_n(\mathbf{X}_1, \dots, \mathbf{X}_n) - g(\boldsymbol{\theta})| \geq \varepsilon] \rightarrow 0, \quad \text{as } n \rightarrow \infty$$

[Kro13, page 176] [Background Notes, page 44].

Theorem 45. If $\text{Var}(T_n) \rightarrow 0$ and $\text{Bias}(T_n) \rightarrow 0$, as $n \rightarrow \infty$, then the sequence of estimates T_n is consistent for estimating $g(\boldsymbol{\theta})$ [Background Notes, page 44].

Proof. Let $f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta})$ denote the joint pdf of $\mathbf{X}_1, \dots, \mathbf{X}_n$. Then we have

$$\mathbb{P} [|T_n - g(\boldsymbol{\theta})| \geq \varepsilon] = \int \dots \int_{|T_n - g(\boldsymbol{\theta})| \geq \varepsilon} f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta}) d\mathbf{x}_1 \dots d\mathbf{x}_n.$$

On the region of integration in the above,

$$\begin{aligned} |T_n - g(\boldsymbol{\theta})| &\geq \varepsilon \\ (T_n - g(\boldsymbol{\theta}))^2 &\geq \varepsilon^2 \\ \frac{(T_n - g(\boldsymbol{\theta}))^2}{\varepsilon^2} &\geq 1, \end{aligned}$$

and since $f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta})$ is non-negative,

$$f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta}) \leq f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta}) \frac{(T_n - g(\boldsymbol{\theta}))^2}{\varepsilon^2}.$$

Thus

$$\begin{aligned} \mathbb{P} [|T_n - g(\boldsymbol{\theta})| \geq \varepsilon] &= \int \dots \int_{|T_n - g(\boldsymbol{\theta})| \geq \varepsilon} f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta}) d\mathbf{x}_1 \dots d\mathbf{x}_n \\ &\leq \int \dots \int_{|T_n - g(\boldsymbol{\theta})| \geq \varepsilon} f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta}) \frac{(T_n - g(\boldsymbol{\theta}))^2}{\varepsilon^2} d\mathbf{x}_1 \dots d\mathbf{x}_n \\ &\leq \frac{1}{\varepsilon^2} \int \dots \int f(\mathbf{x}_1, \dots, \mathbf{x}_n; \boldsymbol{\theta}) (T_n - g(\boldsymbol{\theta}))^2 d\mathbf{x}_1 \dots d\mathbf{x}_n \\ &\leq \frac{1}{\varepsilon^2} \text{MSE}(T_n) \\ &\leq \frac{1}{\varepsilon^2} [\text{Var}(T_n) + (\text{Bias}(T_n))^2] \end{aligned}$$

which tends to 0 as $n \rightarrow \infty$, since $\text{Var}(T_n)$ and $\text{Bias}(T_n)$ both tend to 0. \square

Example 46 (Continuation of Example 33). Example taken from Background Notes, page 44. The estimators

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2, \quad \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$$

are both consistent for σ^2 . This is easily seen with s^2 since

$$\mathbb{E}[s^2] = \sigma^2 \quad \text{and} \quad \text{Var}(s^2) \rightarrow 0$$

as $n \rightarrow \infty$. To show that $\hat{\sigma}^2$ is also a consistent estimator, note that

(see 17)
$$\frac{\sum_{j=1}^n (X_j - \bar{X})^2}{\sigma^2} \sim \chi_{n-1}^2$$

meaning

$$\mathbb{E} \left[\frac{\sum_{j=1}^n (X_j - \bar{X})^2}{\sigma^2} \right] = n - 1$$

and

$$\text{Var} \left[\frac{\sum_{j=1}^n (X_j - \bar{X})^2}{\sigma^2} \right] = 2(n - 1)$$

so that

$$\mathbb{E} \left[\sum_{j=1}^n (X_j - \bar{X})^2 \right] = (n - 1)\sigma^2$$

and

$$\text{Var} \left[\sum_{j=1}^n (X_j - \bar{X})^2 \right] = 2(n - 1)\sigma^4.$$

Hence

$$\begin{aligned} \mathbb{E}(\hat{\sigma}^2) &= \frac{n-1}{n}\sigma^2 = \sigma^2 - \frac{\sigma^2}{n} \\ \text{Var}(\hat{\sigma}^2) &= \frac{2(n-1)\sigma^4}{n^2} \end{aligned}$$

meaning $\mathbb{E}(\hat{\sigma}^2) \rightarrow \sigma^2$ and $\text{Var}(\hat{\sigma}^2) \rightarrow 0$ as $n \rightarrow \infty$. Therefore, by Theorem 45, $\hat{\sigma}^2$ is a consistent estimator of σ^2 .

Large-Sample Comparisons of Estimators.

Theorem 47 (Information Matrix for iid Data). *Suppose that $\hat{\theta}_n$ is a sequence of consistent ML estimates for θ . Then $\sqrt{n}(\hat{\theta}_n - \theta)$ converges in distribution to a $\mathcal{N}(\theta, \mathcal{J}^{-1}(\theta))$ distributed random vector as $n \rightarrow \infty$. In other words,*

$$\hat{\theta}_n \overset{\text{approx}}{\sim} \mathcal{N}(\theta, \mathcal{J}^{-1}(\theta)/n).$$

Definition 48 (Asymptotic Relative Efficiency). *Suppose that $\hat{\theta}_{n_1}$ and $\hat{\theta}_{n_2}$ are two single variable estimates such that*

$$\begin{aligned} \hat{\theta}_{n_1} &\overset{\text{approx}}{\sim} \mathcal{N}(\theta, \tau_1^2/n) \\ \hat{\theta}_{n_2} &\overset{\text{approx}}{\sim} \mathcal{N}(\theta, \tau_2^2/n). \end{aligned}$$

The **Asymptotic Relative Efficiency** (ARE) of $\hat{\theta}_{n_2}$ with respect to $\hat{\theta}_{n_1}$ is given by

$$\text{ARE}(\hat{\theta}_{n_2}) = \hat{\theta}_{n_1}/\hat{\theta}_{n_2}$$

[Background Notes, page 46].

Example 49 (Asymptotic Distribution of Bernoulli MLE). Example taken from [Kro13, page 177]. For $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \text{Ber}(p)$, the MLE for p is

$$\hat{p}_n = \bar{x} = \frac{1}{n} \sum_i x_i.$$

To compute the information number (see Definition 20) for p , note that regularity conditions hold so that

$$\mathring{\mathcal{J}}(p) = \text{Var}_p(S(p))$$

where

$$\begin{aligned} S(p) &= \frac{d}{dp} \ln(p^x(1-p)^{1-x}) \\ &= \frac{d}{dp} [x \cdot \ln(p) + (1-x) \ln(1-p)] \\ &= \frac{x}{p} - \frac{(1-x)}{1-p} = \frac{x}{p(1-p)}. \end{aligned}$$

This means that

$$\begin{aligned} \mathring{\mathcal{J}}(p) &= \text{Var}_p(S(p)) \\ &= \text{Var}_p\left(\frac{X}{p(1-p)}\right) \\ &= \frac{p(1-p)}{p^2(1-p)^2} = \frac{1}{p(1-p)}. \end{aligned}$$

Theorem 47 states that

$$\hat{p}_n \stackrel{\text{approx}}{\sim} \text{N}\left(p, \frac{p(1-p)}{n}\right).$$

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