



$$x_A + x_B = 10 R_{\odot}$$

from JP's Thesis

$$M_A x_A = M_B x_B \quad \text{by definition of center of mass}$$

$$\Rightarrow x_B = \frac{M_A}{M_B} x_A$$

Substitute

$$x_A + \frac{M_A}{M_B} x_A = 10 R_{\odot}$$

$$\Rightarrow x_A = \frac{10 R_{\odot}}{1 + \frac{M_A}{M_B}}$$

Then the speed of A is

$$v_A = \sqrt{\frac{G(M_A + M_B)(1+e)}{x_A}}$$

eccentricity from JP's Thesis = 0.01

So components are (initially)

$$\vec{v}_A = \left( 0, -\sqrt{\frac{G(M_A + M_B)(1+e)}{x_A}}, 0 \right)$$

$$\text{and } \vec{v}_B = -\frac{M_A}{M_B} \vec{v}_A$$